

FedHD: Federated Learning with Hyperdimensional Computing

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ABSTRACT

Federated Learning (FL) is a widely adopted distributed learning paradigm for its privacy-preserving and collaborative nature. In FL, each client trains and sends a local model to the central cloud for aggregation. However, FL systems using neural network (NN) models are expensive to deploy on constrained edge devices regarding computation and communication. In this demo, we present FedHD, a FL system using Hyperdimensional Computing (HDC). In contrast to NN, HDC is a brain-inspired and lightweight computing paradigm using high-dimensional vectors and associative memory. Our measurements indicate that FedHD is 3.2×, 3.2×, 5× better on performance, energy and communication efficiency respectively compared to NN-based FL systems whilst maintaining similar accuracy to the state of the art. Our code is available on GitHub¹.

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1 INTRODUCTION

Federated Learning (FL) is a distributed paradigm which trains models collaboratively without sharing data. FL boasts widespread popularity in many applications such as healthcare [5], smart cities [12], and self-driving vehicles [2]. Traditional FL systems adopt neural network (NN) based models, which are expensive to compute and communicate. Table 1 shows that NN models take 350 seconds per round of training

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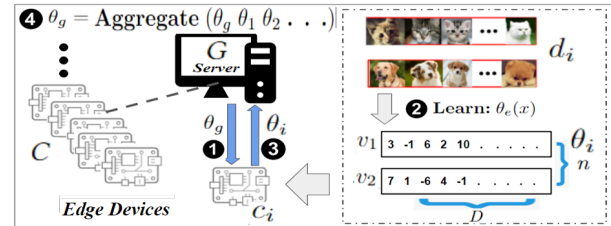


Figure 1: FedHD workflow in 4 stages. (1) Server sends global hypervectors to each client. (2) Clients train local class hypervectors using encoded local data. (3) Models are sent back to the server. (4) Server aggregates received class hypervectors.

on average with a model size of 8MB. Consequently, resource limitations present a major challenge when deploying FL on edge devices [18]. Unreliable wireless channels may also add noise during transmission and degrade model accuracy [3].

Hyperdimensional computing (HDC) is a lightweight computing paradigm that encodes data into hypervectors (high dimensional vectors > 1000 bit) [13]. Learning is performed through simple arithmetic operations (addition, multiplication, nearest neighbor search), reducing power and memory usage [17] [9] [20]. HDC is also robust against noise due to its high dimensionality. Previous works on HDC primarily focus on non-FL settings [19] [8] [17]. In this demo, we present FedHD, an implementation of FL using HDC for low-power devices. FedHD is lightweight in computation and communication, and robust against unreliable communication.

Dataset	Time/Round (Second)	Energy/Round (Joule)	Model Size (Megabyte)
MNIST [15]	73/276	350/1325	1.99/9.95
FMNIST [21]	71/395	341/1896	1.90/9.91
HAR [4]	68/121	326/581	1.99/1.67
CIFAR10 [14]	388/591	1862/2837	1.90/12.3

Table 1: Measurement results: HDC/Baseline NN

2 METHOD AND IMPLEMENTATION

Figure 1 shows the FedHD workflow. Each class is represented as a class hypervector that encodes generic class features. The system consists of a server G and a set of edge devices $C = \{c_1, c_2, \dots\}$. The hypervector dimensionality and the number of classes are D, n , respectively. Each client c_i

¹<https://github.com/QuanlingZhao/FedHD>

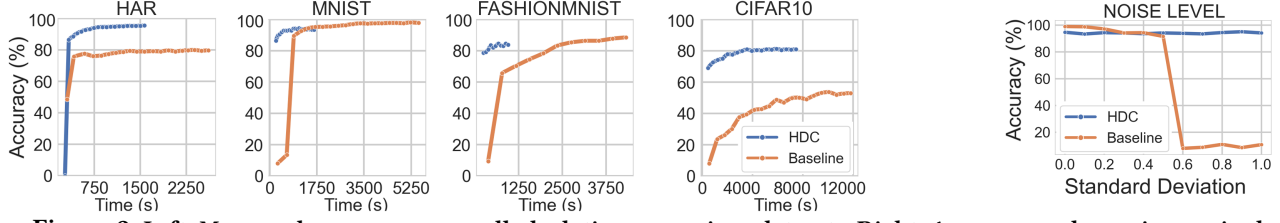


Figure 2: Left: Measured accuracy over wall-clock time on various datasets. Right: Accuracy under various noise levels.

holds a θ_i , a HD classifier defined by a set of class hypervectors $\{v_1 \dots v_n\}$ and a similarity checker. d_i denotes local training samples. Likewise, $G = (\theta_g, d_g)$ denotes the servers. Both the server and the clients have access to an HDC encoder, θ_e .

2.1 HDC Learner

Learning in HDC consists of encoding raw data into hypervectors, adding hypervectors that belong to the same class together, and performing a few rounds of retraining if needed. Classification is done by comparing a query hypervector to the stored class hypervectors.

HDC Encoding: We use a random binary projection encoder which performs well on many datasets [6]. For any $(x, y) \in d_i$, a random projection encoder $\theta_e(x) \rightarrow \{0, 1\}^D$ computes sample hypervector H by $\theta_e(x) = \beta(\mathbf{E}x)$, where $\mathbf{E} \in M^{D \times |x|}$ is a randomly generated binary matrix and β is an element-wise sign function.

HDC Training: Initial class hypervectors are generated by summing the sample hypervectors from the same class: $v_j = \sum_{(x,y) \in d_i | y=j} \theta_e(x)$. For all subsequent rounds, local class hypervectors are re-trained with local samples as shown below. The process iterates over all n classes and across multiple rounds, such that the class hypervectors gradually converge to a global optimal.

$$\forall (x, y) \in d_i | \theta_i(\theta_e(x)) \neq y \begin{cases} v_j - \theta_e(x) & \forall j \neq y \\ \text{Negative reinforce incorrect } v \\ v_j + \theta_e(x) & j = y \\ \text{Reinforce correct } v \end{cases}$$

HDC Classification: Each class in the HDC model is represented as a class hypervector $\{v_1 \dots v_n\}$. Classification is done by checking the cosine similarity between the encoded sample and each class hypervector, then choosing the class with the greatest similarity: $\arg \max_{j=1}^n \cos(H, v_j) = \frac{H \cdot v_j}{\|H\| \|v_j\|}$.

2.2 FedHD

HDC Aggregation: In FL, locally trained models are exchanged each round. After the server collects all locally trained HDC models, a global HDC model θ_g can be aggregated: $\theta_g = \frac{\theta'_g + \sum_i^{C} \theta_i}{|C|+1}$. The global model from the previous round θ'_g is also included in aggregation process as a stabilizing factor to prevent an abrupt change in class hypervectors, which prevents catastrophic model failure.

FedHD Implementation: We implemented FedHD using

FedML [10], an open-source FL framework that allows us to add and deploy HDC components on IoT devices.

3 DEMONSTRATION

Our demo uses Raspberry Pis [1] and Kubernetes cluster as clients with $D=10000$ and 500 local samples per client. A desktop is used as the server for model aggregation. A state of the art NN with FedAvg FL algorithm [16] is used as a baseline. The experimental setup is shown in Table 2.

Dataset	Client #	Method	Baseline
MNIST [15]	30	HDC	CNN w/ 2HL ²
FMNIST [21]	30	HDC	CNN w/ 2HL ²
HAR [4]	30	HDC	2FCL ³
CIFAR10 [14]	7	SimCLR [7]+HDC	ResNet-18 [11]

Table 2: Experimental Setup. For complex image datasets, HDC requires a feature extractor trained by SimCLR [7].

Accuracy & Efficiency: Experimental results are shown in Fig. 2 and Table 1. FedHD achieves comparable or higher accuracy across all datasets while being 3.2x faster than the baseline. While the size of NN models grow dramatically with task complexity, the HDC model maintains communication efficiency by scaling linearly with the number of classes.

Robustness: We evaluate FedHD’s robustness by directly applying additive Gaussian noise to both the HDC model [6] and the NN baseline while increasing noise standard deviation σ . Fig. 2b shows model performance of our method compared with the baseline on MNIST with varying levels of noise. When $\sigma > 0.5$, FedHD’s accuracy is unaffected whereas the baseline suffers from catastrophic failure.

4 CONCLUSION

In this demo, we proposed FedHD, an efficient and robust FL system using HDC. Our results address two bottlenecks in current FL systems by greatly reducing computation and communication overhead and bolstering the robustness to remain nearly unaffected against unreliable communication.

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²HL: Hidden Layer.

³FCL: Fully Connected Layer.

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