

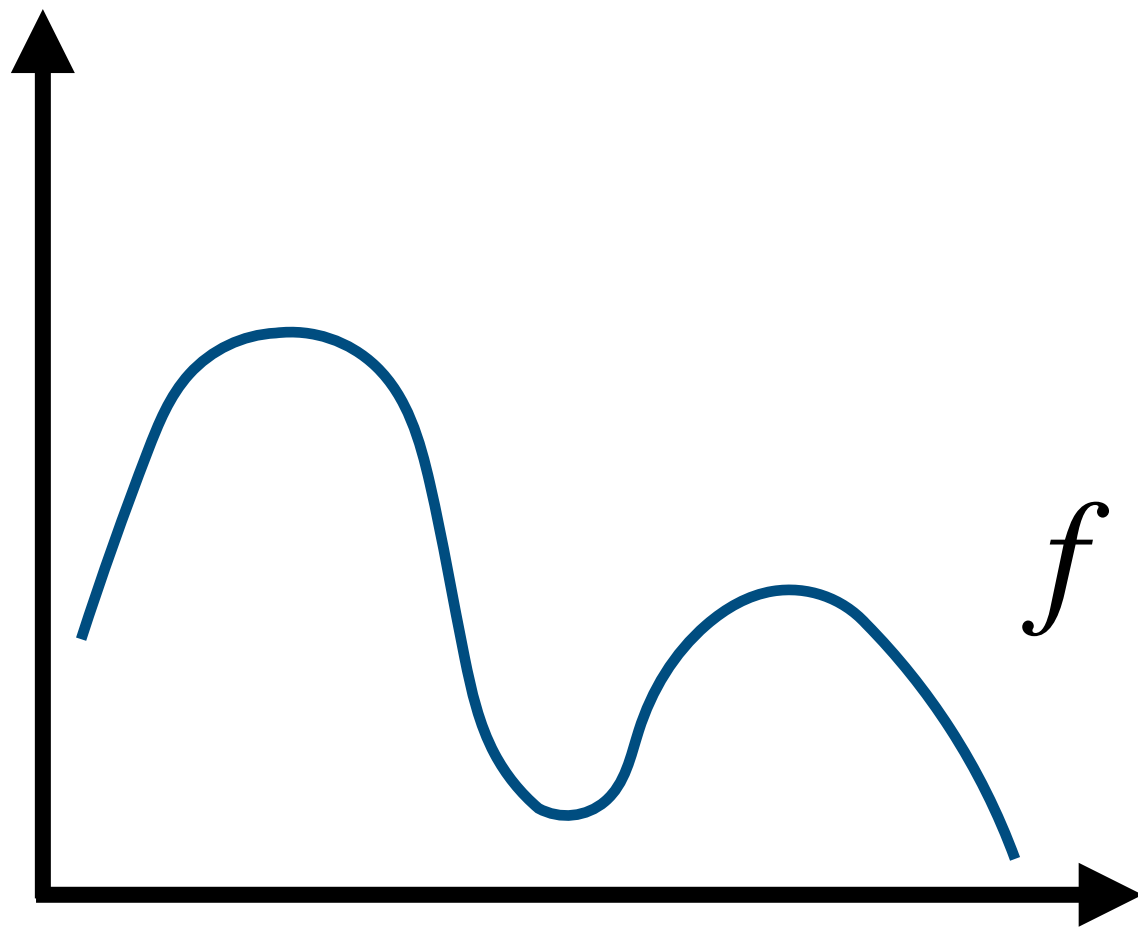
Multiple importance sampling++

UCSD CSE 272

Advanced Image Synthesis

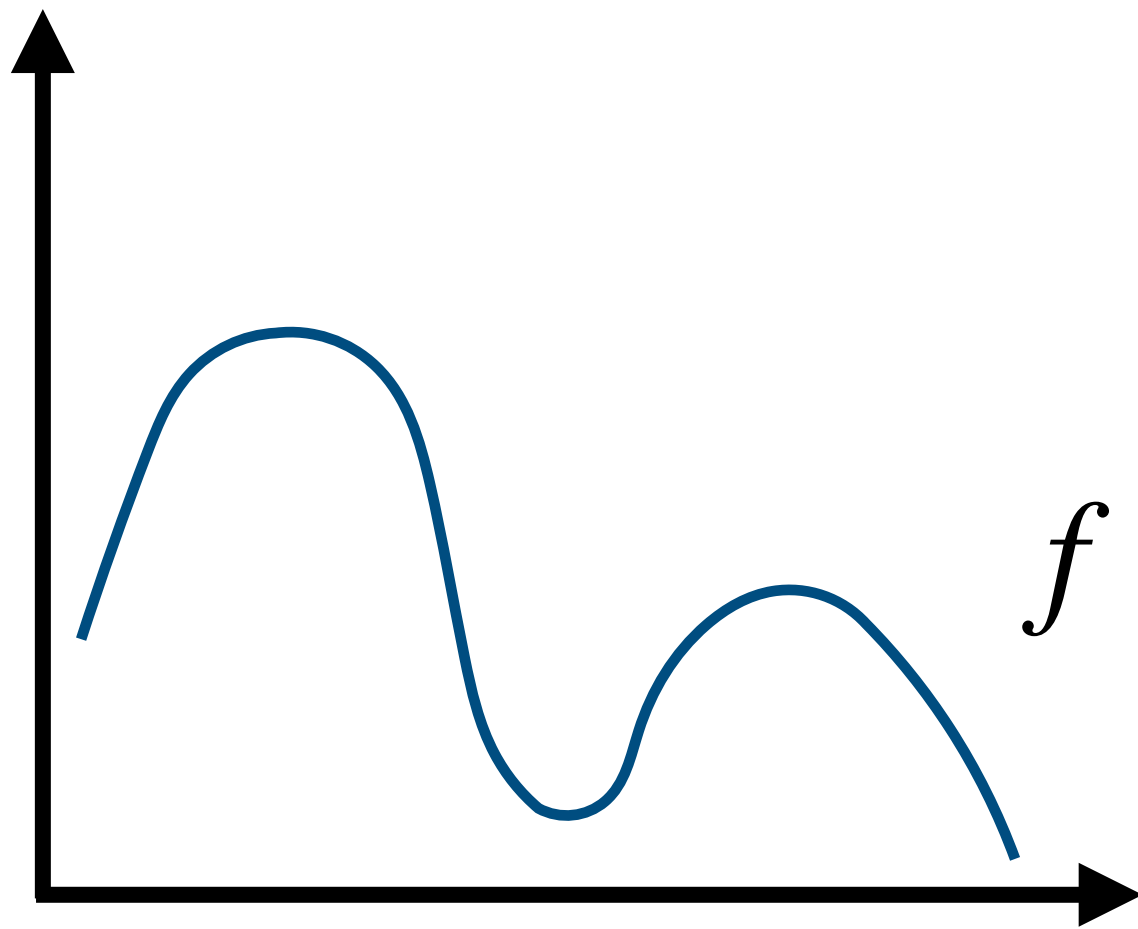
Tzu-Mao Li

Monte Carlo integration

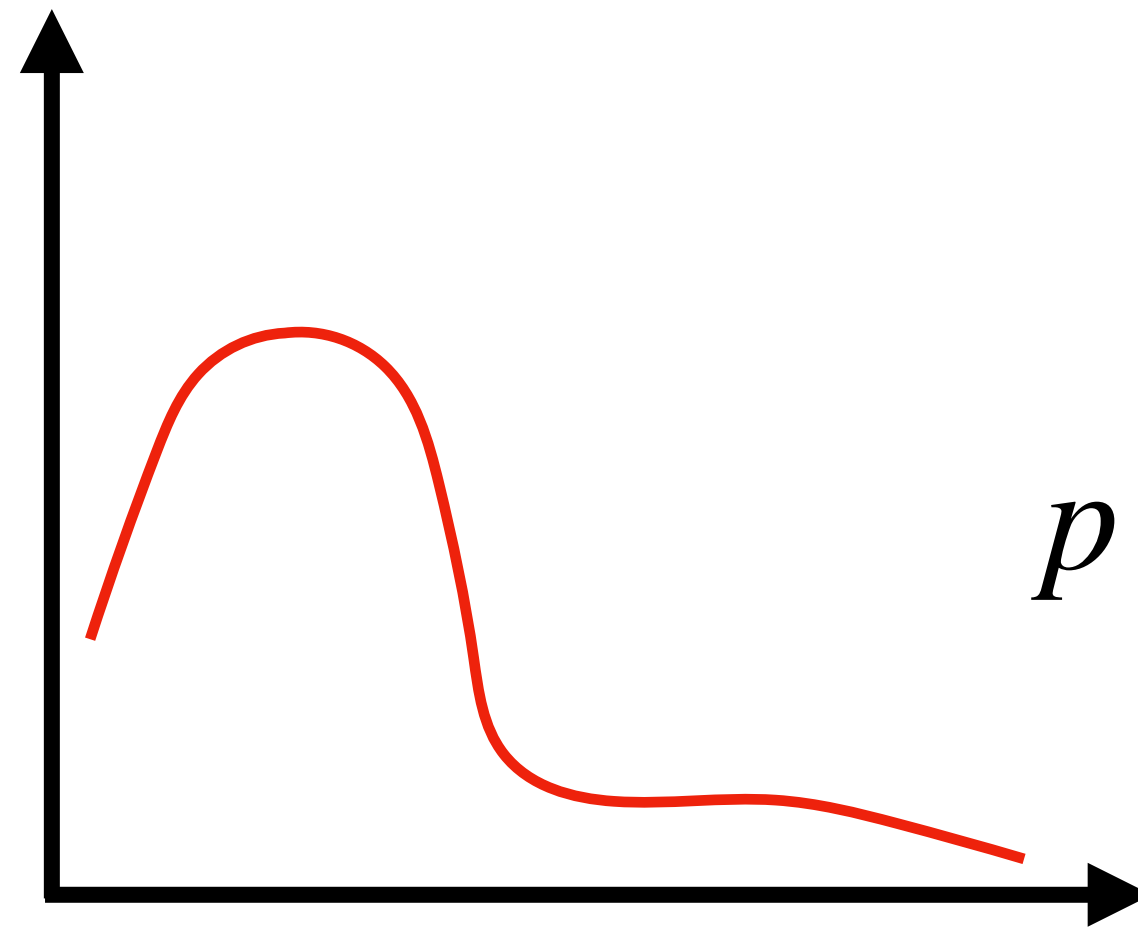


$$F = \int f(x) dx$$

Monte Carlo integration



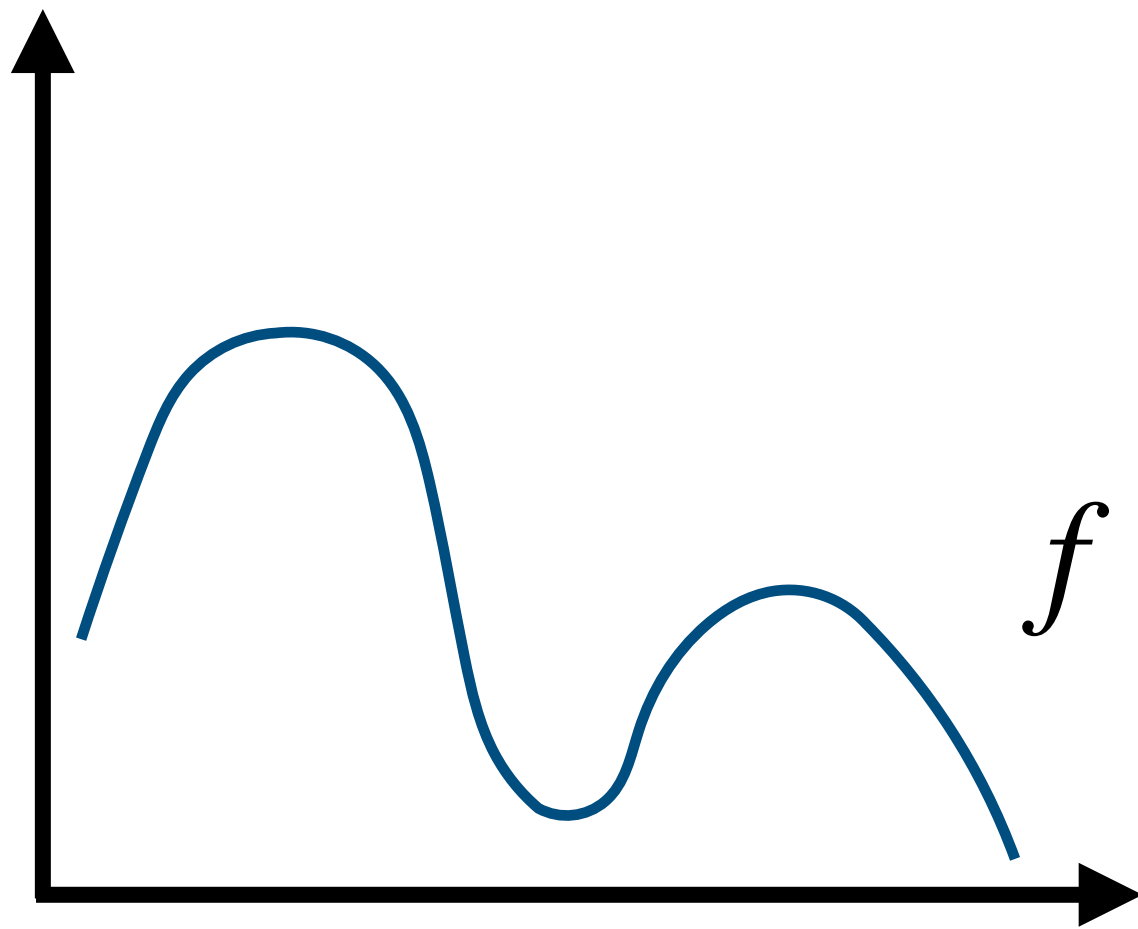
$$F = \int f(x) dx$$



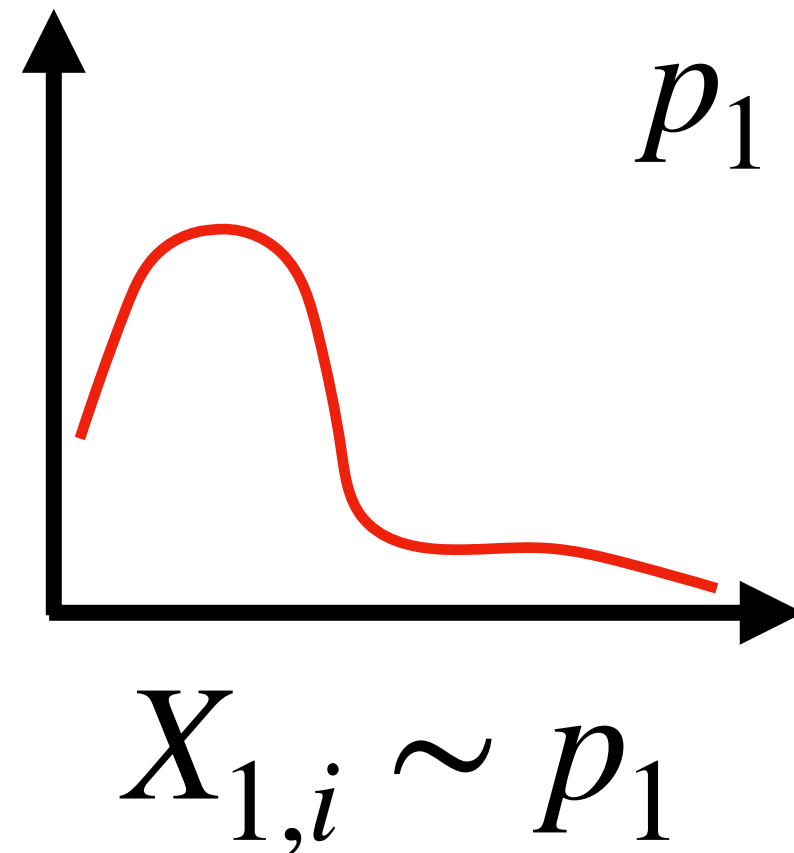
$$X_i \sim p$$

$$\langle F \rangle = \frac{1}{N} \sum_i \frac{f(X_i)}{p(X_i)}$$

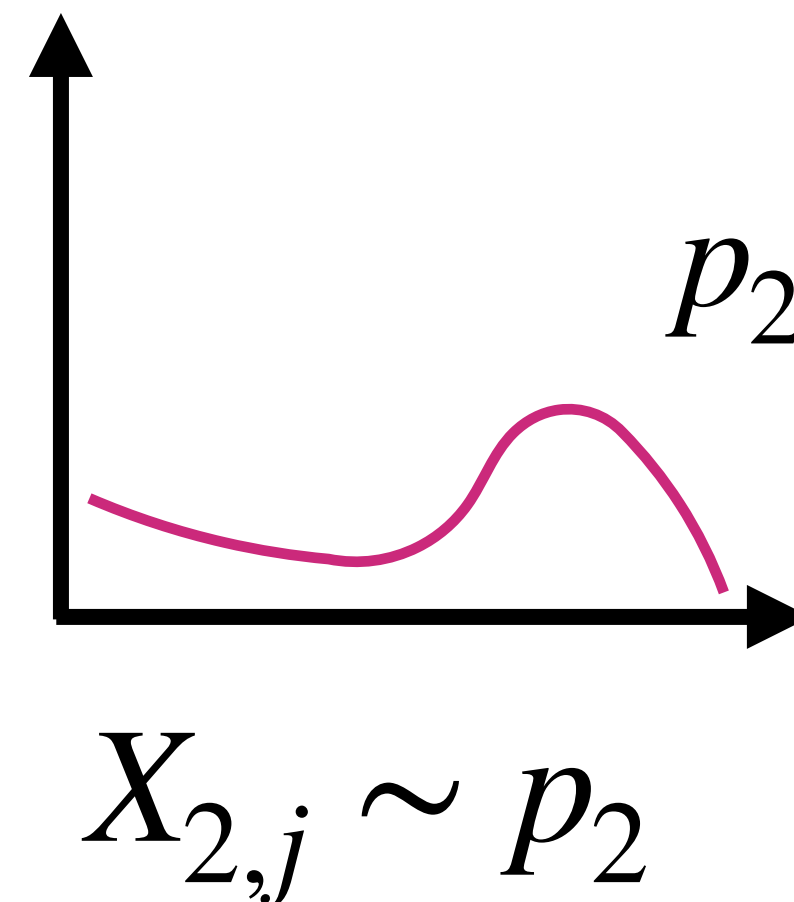
Monte Carlo integration



$$F = \int f(x) dx$$



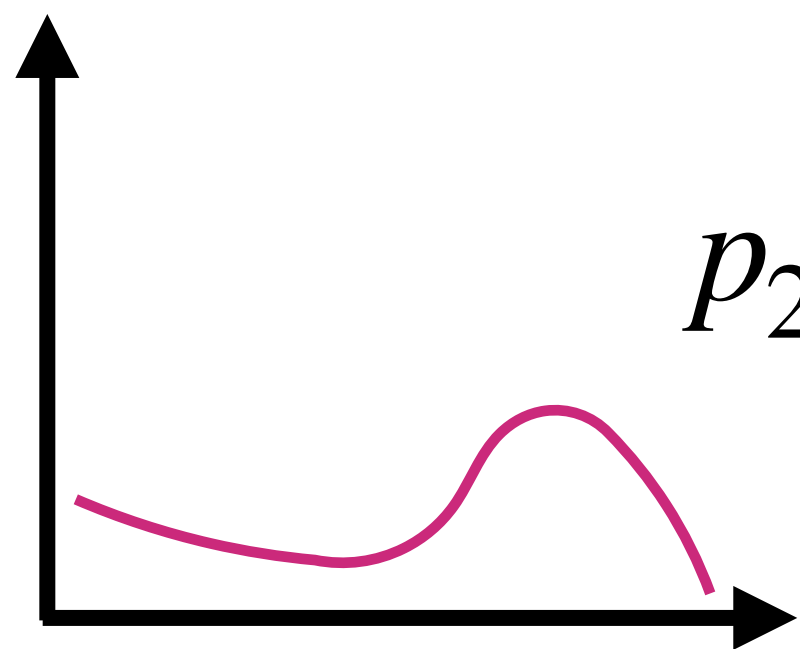
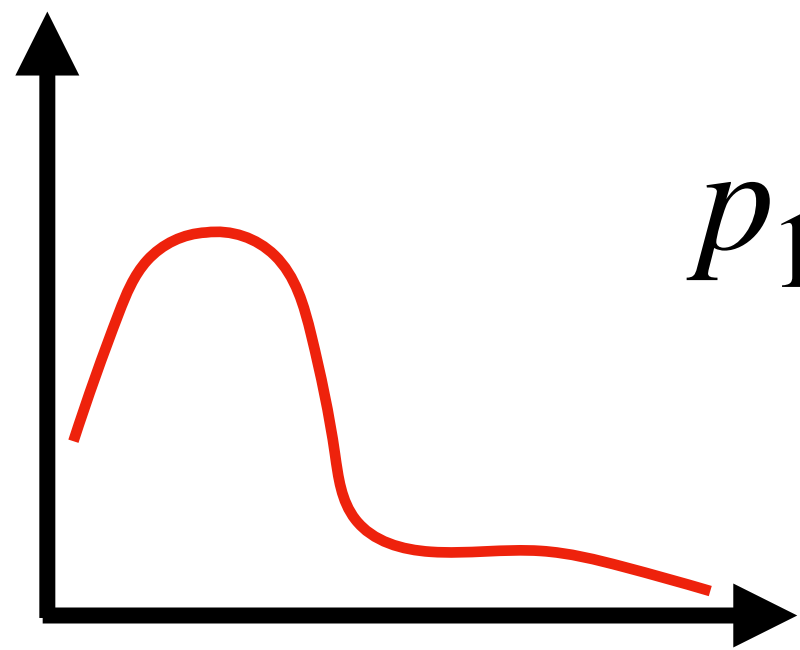
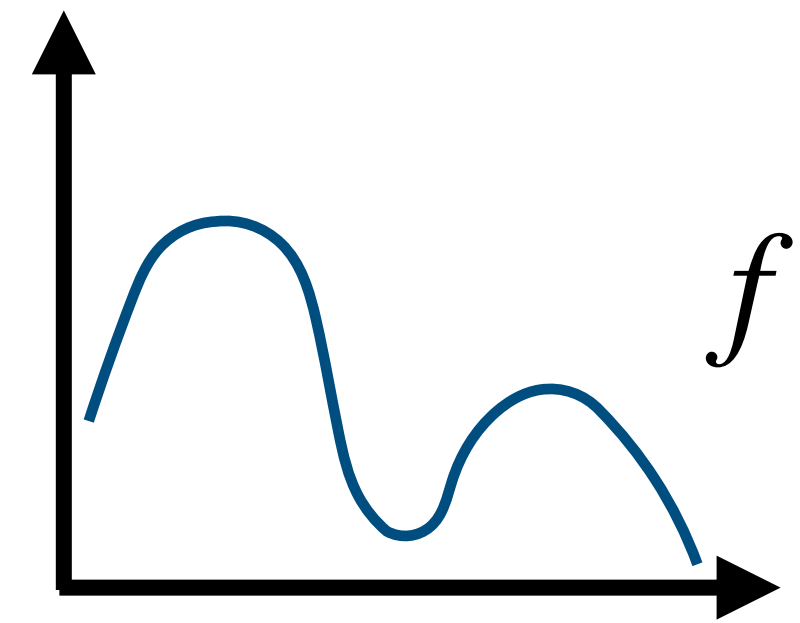
$$\langle F \rangle_1 = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})}$$



$$\langle F \rangle_2 = \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})}$$

Multiple importance sampling

idea: weighted average of the two estimators



$$\begin{aligned} \langle F \rangle &= \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i}) \\ &+ \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j}) \end{aligned}$$

**Optimally Combining Sampling Techniques
for Monte Carlo Rendering**

Eric Veach

Leonidas J. Guibas

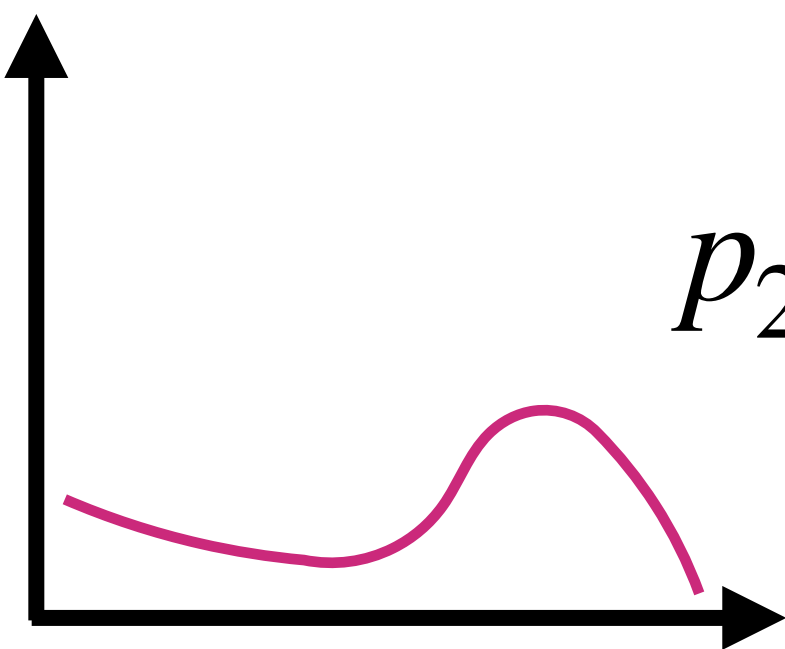
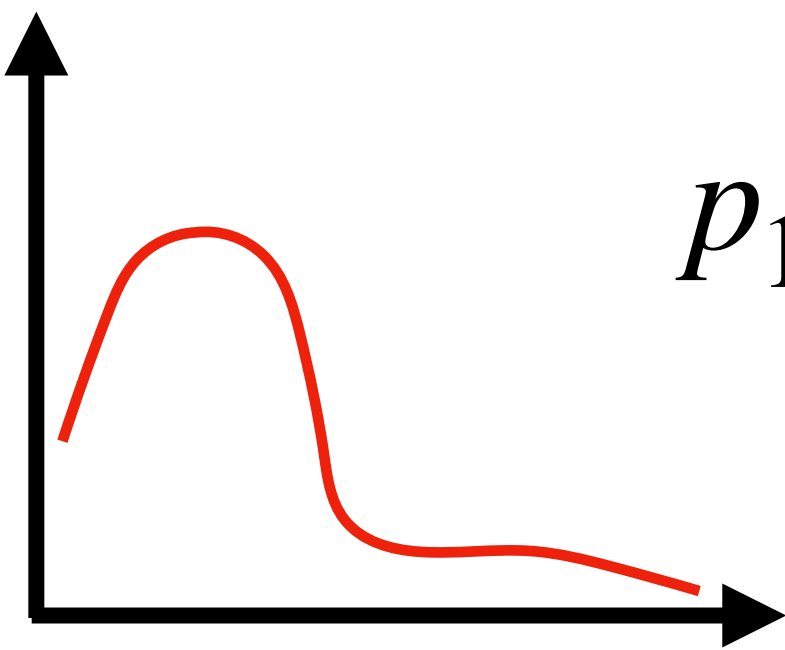
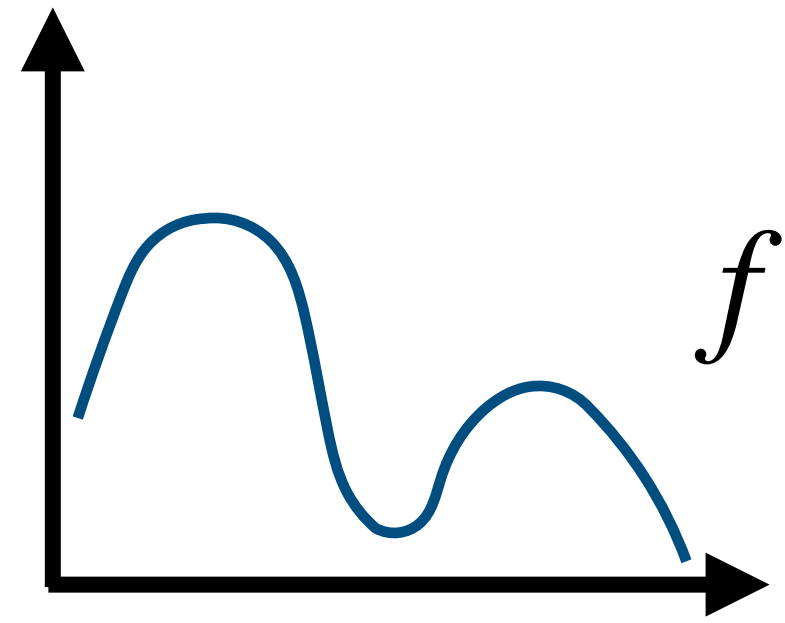
Computer Science Department
Stanford University

Multiple importance sampling

idea: weighted average of the two estimators

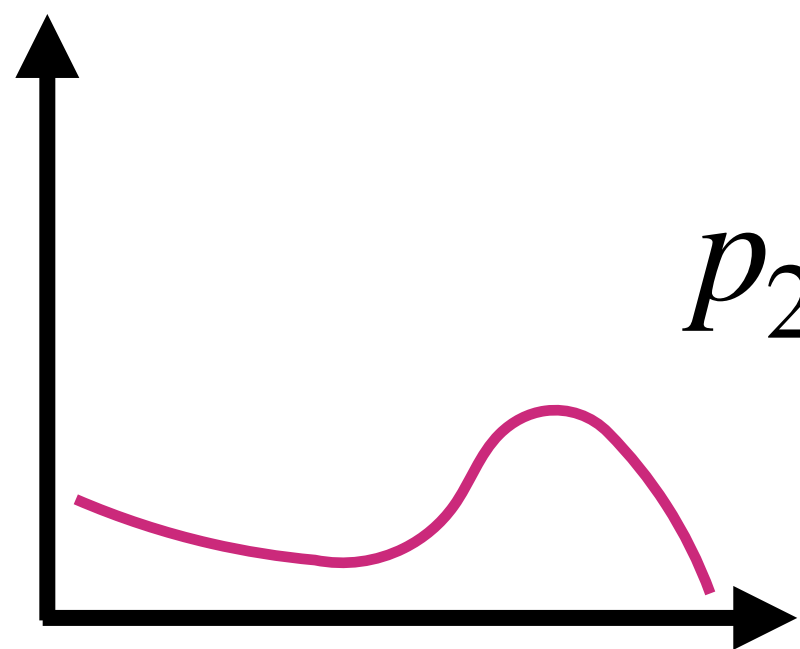
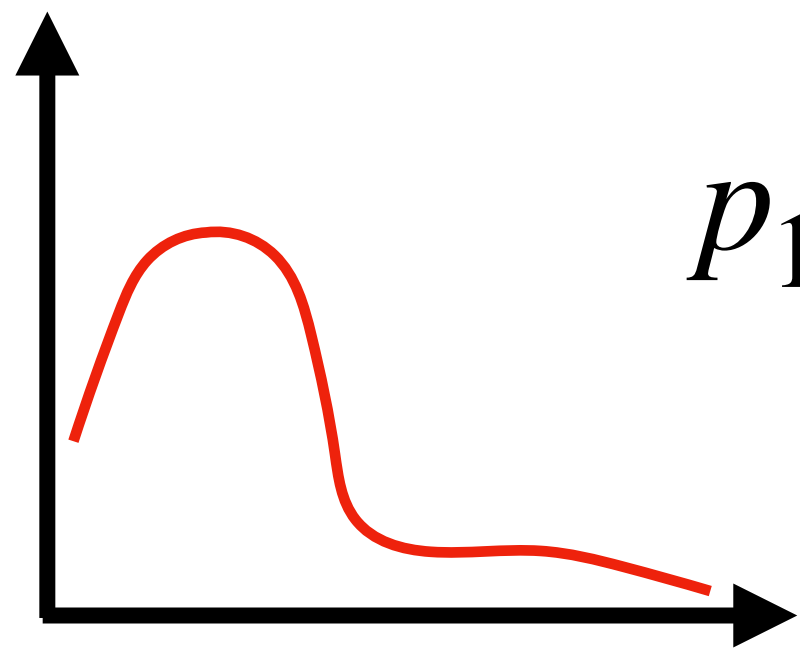
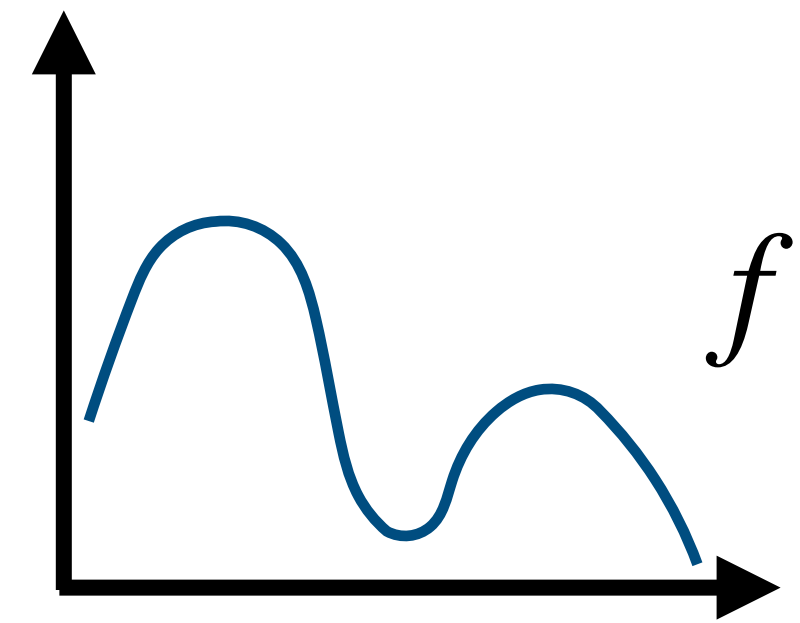
$$\langle F \rangle = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i}) + \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$

quiz: when will $\langle F \rangle$ be an unbiased estimator?



Multiple importance sampling

idea: weighted average of the two estimators

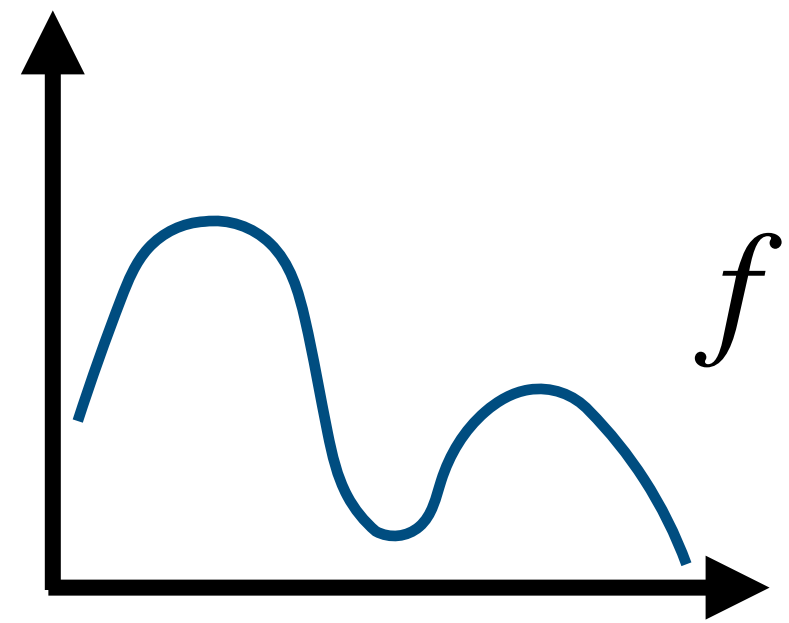


$$\begin{aligned} \langle F \rangle &= \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i}) \\ &+ \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j}) \end{aligned}$$

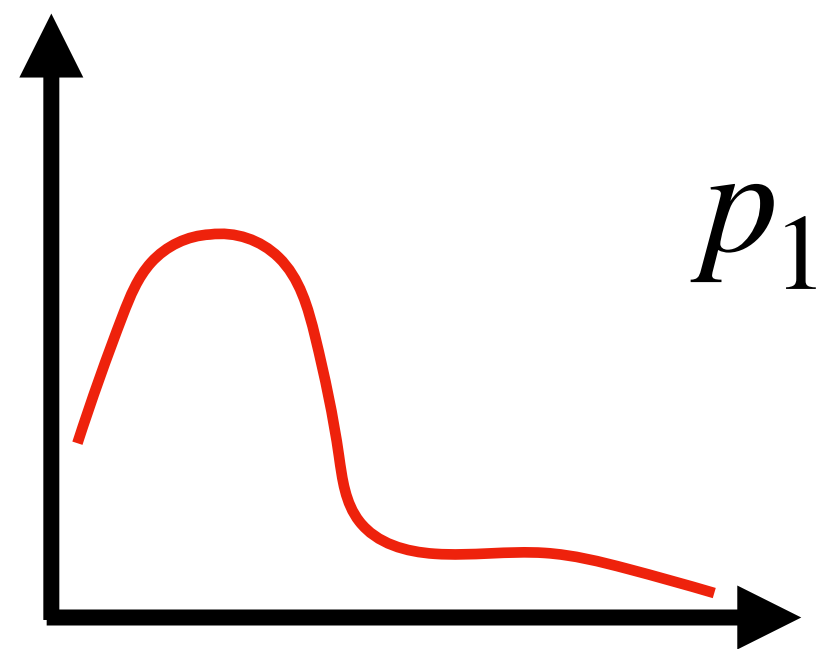
if $w_1(x) + w_2(x) = 1$,

$$E \left[w_1 \frac{f(x(u_1))}{p_1(x(u_1))} + w_2 \frac{f(x(u_2))}{p_2(x(u_2))} \right] = w_1 E \left[\frac{f(x(u_1))}{p_1(x(u_1))} \right] + w_2 E \left[\frac{f(x(u_2))}{p_2(x(u_2))} \right] = \int f(x) dx$$

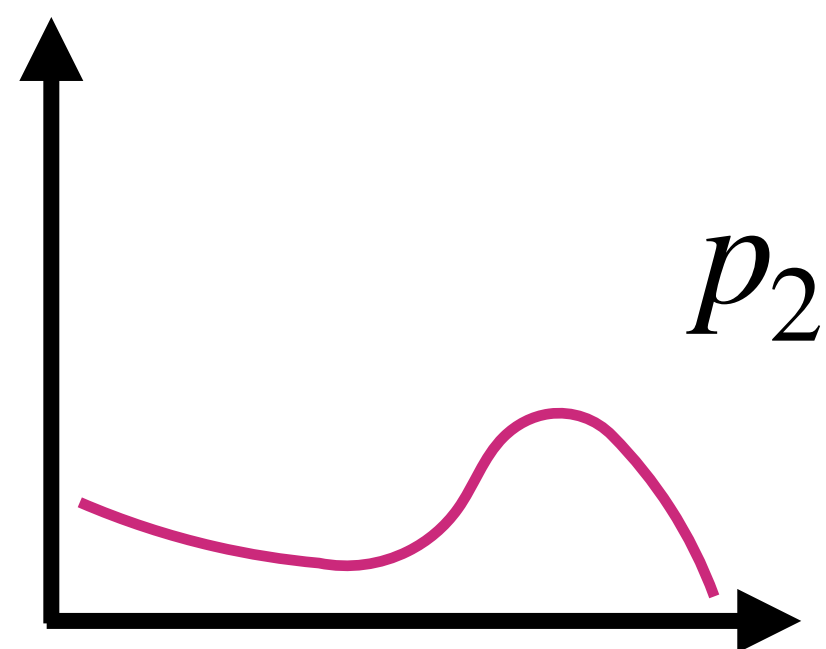
How do we determine w_1 and w_2 ?



$$\langle F \rangle = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i})$$

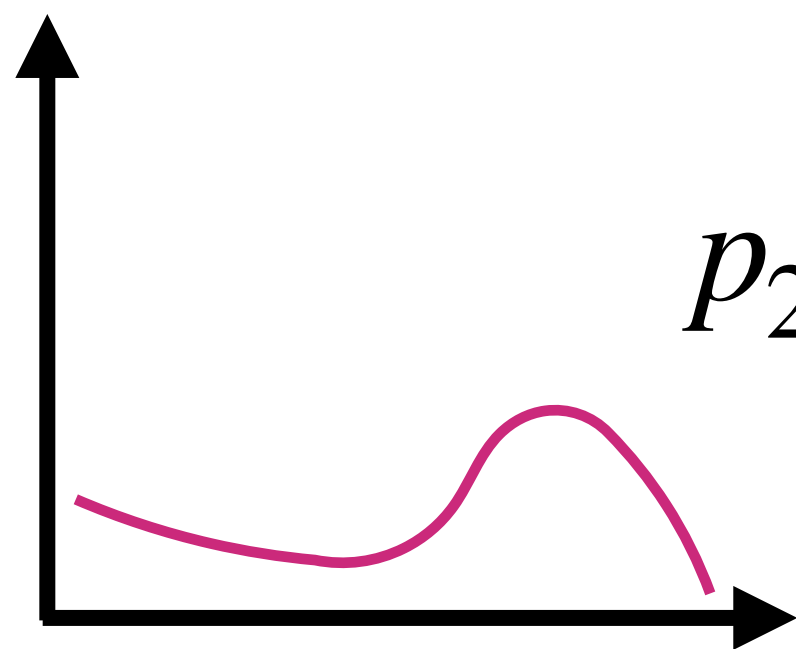
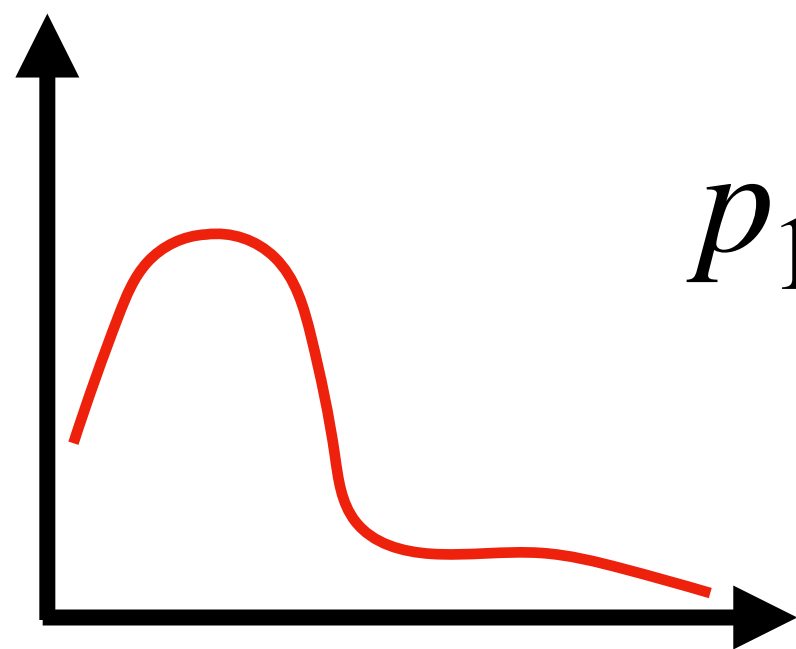
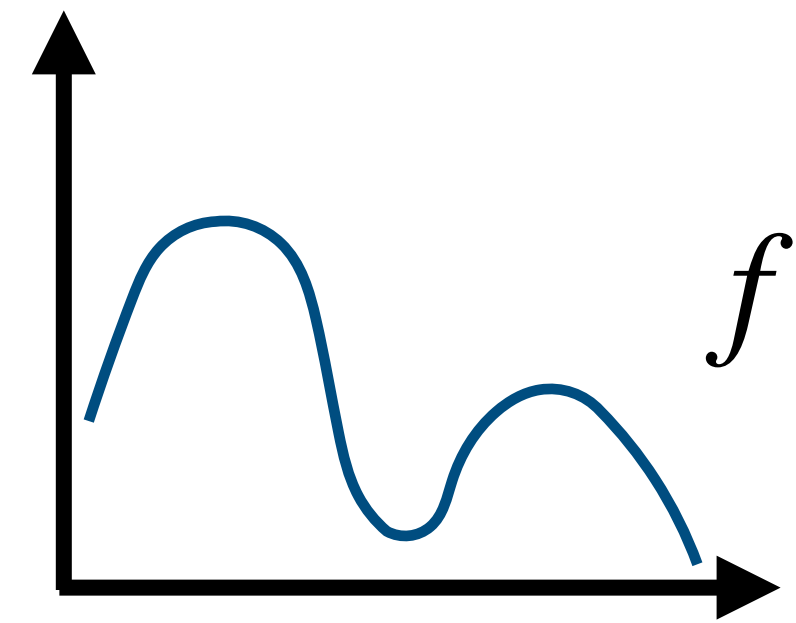


$$+ \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$



How do we determine w_1 and w_2 ?

goal: choose w_1 and w_2 such that $\text{Var} [\langle F \rangle]$ is minimized



$$\langle F \rangle = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i}) + \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$

Veatch's strategy

trick 1: assuming $X_{1,i}$ and $X_{2,j}$ are uncorrelated

$$\langle F \rangle = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i}) \\ + \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$

$$\text{Var}[\langle F \rangle] = \text{Var} \left[\frac{1}{N_1} \sum \frac{fw_1}{p_1} \right] + \text{Var} \left[\frac{1}{N_2} \sum \frac{fw_2}{p_2} \right]$$

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trick 2: minimize upper bound of the variance

$$\text{Var}[X] = E[X^2] - E[X]^2 \leq E[X^2]$$

$w_i \propto N_i p_i$ is a good choice [Veach 1995]

aka balance heuristic

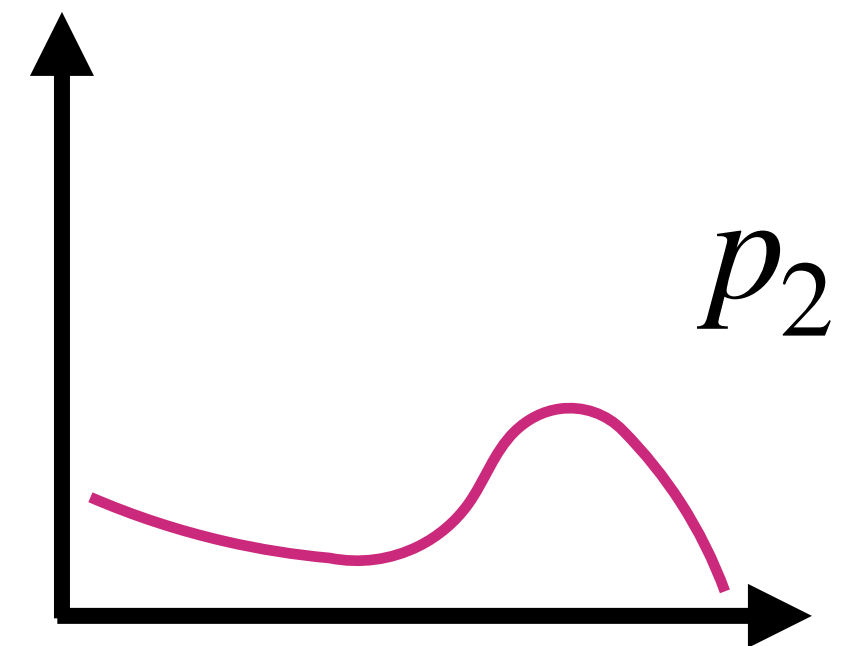
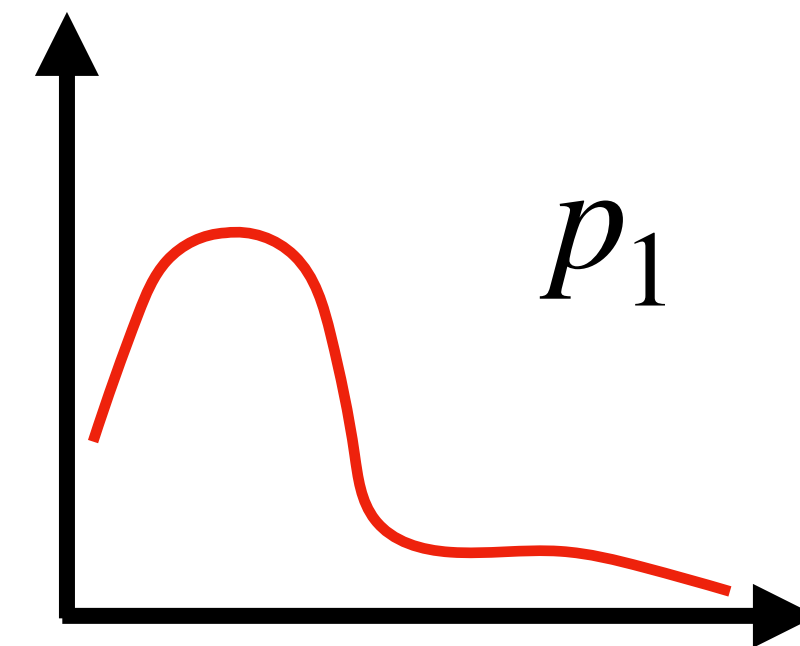
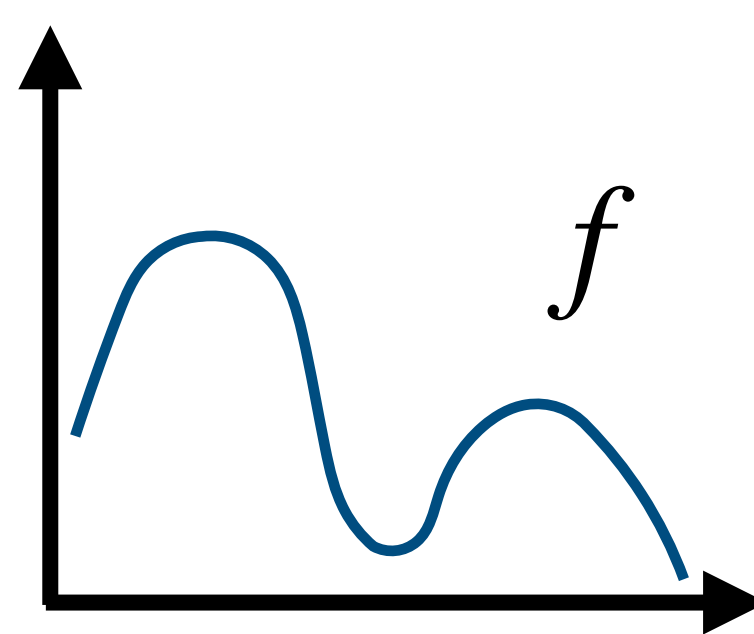
$$w_1(x) = \frac{N_1 p_1(x)}{N_1 p_1(x) + N_2 p_2(x)} \quad \text{and} \quad w_2(x) = \frac{N_2 p_2(x)}{N_1 p_1(x) + N_2 p_2(x)}$$

minimizes $E[\langle F \rangle^2]$

intuition: higher weight for higher sampling density

$$\langle F \rangle = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i}) + \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$

see CSE 168 for the proof



Can we do better than Veach?

trick 1: assuming $X_{1,i}$ and $X_{2,j}$ are uncorrelated

$$\langle F \rangle = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i}) \\ + \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$

$$\text{Var}[\langle F \rangle] = \text{Var} \left[\frac{1}{N_1} \sum \frac{fw_1}{p_1} \right] + \text{Var} \left[\frac{1}{N_2} \sum \frac{fw_2}{p_2} \right]$$

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Can we do better than Veach?

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$$\langle F \rangle = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i}) + \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$

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trick 2: minimize upper bound of the variance

$$\text{Var}[X] = E[X^2] - E[X]^2 \leq E[X^2]$$

can we minimize variance directly?

Optimal Multiple Importance Sampling

IVO KONDAPANENI*, Charles University, Prague

PETR VÉVODA*, Charles University, Prague and Render Legion, a. s.

PASCAL GRITTMANN, Saarland University

TOMÁŠ SKŘIVAN, IST Austria

PHILIPP SLUSALLEK, Saarland University and DFKI

JAROSLAV KŘIVÁNEK, Charles University, Prague and Render Legion, a. s.

Minimizing variance for multiple importance sampling

goal: choose w_1 and w_2 to minimize $\text{Var} [\langle F \rangle]$ s.t. $w_1 + w_2 = 1$

$$\langle F \rangle = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i}) + \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$

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$$\langle F \rangle = \frac{f(X_1)}{p_1(X_1)} w_1(X_1) + \frac{f(X_2)}{p_2(X_2)} w_2(X_2)$$

simplified without loss
of generality

Minimizing variance for multiple importance sampling

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$$\langle F \rangle = \frac{f(X_1)}{p_1(X_1)} w_1(X_1) + \frac{f(X_2)}{p_2(X_2)} w_2(X_2)$$

$$\text{Var} [\langle F \rangle] = \sum_i \int w_i^2 \frac{f^2}{p_i} - \left[\int w_i f \right]^2$$

simplified without loss
of generality

Minimizing variance for multiple importance sampling

choose w_i to minimize

$$\text{Var} [\langle F \rangle] = \sum_i \int w_i^2 \frac{f^2}{p_i} - \left[\int w_i f \right]^2$$

s.t.

$$\sum w_i = 1$$

Minimizing variance for multiple importance sampling

choose w_i and λ to minimize

$$V = \sum_i \int w_i^2 \frac{f^2}{p_i} - \left[\int w_i f \right]^2 + \lambda \left(\sum_i w_i - 1 \right)$$

Minimizing variance for multiple importance sampling

choose w_i and λ to minimize

$$V = \sum_i \int w_i^2 \frac{f^2}{p_i} - \left[\int w_i f \right]^2 + \lambda \left(\sum_i w_i - 1 \right)$$

need to solve this using “calculus of variations”

https://en.wikipedia.org/wiki/Calculus_of_variations

generalizes differentiation with **vectors** to differentiation with **functions**

Minimizing variance for multiple importance sampling

choose w_i and λ to minimize

$$V = \sum_i \int w_i^2 \frac{f^2}{p_i} - \left[\int w_i f \right]^2 + \lambda \left(\sum_i w_i - 1 \right)$$

set derivatives to zero

$$\frac{\partial V}{\partial w_i} = 2w_i \frac{f^2}{p} - 2f \int w_i f + \lambda = 0$$

$$\frac{\partial V}{\partial \lambda} = \sum_i w_i - 1 = 0$$

Minimizing variance for multiple importance sampling

choose w_i and λ to solve

$$2w_i \frac{f^2}{p} - 2f \int w_i f + \lambda = 0$$

$$\sum_i w_i - 1 = 0$$

Minimizing variance for multiple importance sampling

choose w_i and λ to solve

$$2w_i \frac{f^2}{p} - 2fa_i + \lambda = 0 \quad a_i = \int w_i f$$

$$\sum_i w_i - 1 = 0$$

Minimizing variance for multiple importance sampling

choose w_i and λ to solve

$$w_i = \frac{p_i}{f} a_i - \frac{1}{2} \frac{p_i}{f^2} \lambda \qquad a_i = \int w_i f$$

$$\sum_i w_i - 1 = 0$$

Minimizing variance for multiple importance sampling

choose w_i and λ to solve

$$w_i = \frac{p_i}{f} a_i - \frac{1}{2} \frac{p_i}{f^2} \lambda \qquad a_i = \int w_i f$$

$$\sum_i \frac{p_i}{f} a_i - \frac{1}{2} \frac{p_i}{f^2} \lambda = 1$$

Minimizing variance for multiple importance sampling

choose w_i and λ to solve

$$w_i = \frac{p_i}{f} a_i - \frac{1}{2} \frac{p_i}{f^2} \lambda \qquad a_i = \int w_i f$$

$$\lambda = \frac{2 \sum_i p_i a_i f - f^2}{\sum_i p_i}$$

Minimizing variance for multiple importance sampling

choose w_i to solve

$$w_i = \frac{p_i}{f} a_i - p_i \frac{\sum_j \frac{p_j}{f} a_j - 1}{\sum_j p_j} \quad a_i = \int w_i f$$

Minimizing variance for multiple importance sampling

choose w_i to solve

$$w_i = \frac{p_i}{f} a_i - p_i \frac{\sum_j \frac{p_j}{f} a_j - 1}{\sum_j p_j} \quad a_i = \int w_i f$$

integrate both side with f

$$\int w_i f = a_i = a_i \int p_i - \int p_i \frac{\sum_j p_j a_j - f}{\sum_j p_j}$$

Minimizing variance for multiple importance sampling

choose w_i to solve

$$w_i = \frac{p_i}{f} a_i - p_i \frac{\sum_j \frac{p_j}{f} a_j - 1}{\sum_j p_j} \quad a_i = \int w_i f$$

$$\int p_i \frac{\sum_j p_j a_j}{\sum_j p_j} = \int \frac{f p_i}{\sum_j p_j}$$

Minimizing variance for multiple importance sampling

choose w_i to solve

$$w_i = \frac{p_i}{f} a_i - p_i \frac{\sum_j \frac{p_j}{f} a_j - 1}{\sum_j p_j}$$

$$\begin{bmatrix} A_{00} & A_{01} \\ A_{10} & A_{11} \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \end{bmatrix}$$

$$A_{ij} = \int \frac{p_i p_j}{\sum_k p_k}$$

$$b_i = \int \frac{f p_i}{\sum_k p_k}$$

Minimizing variance for multiple importance sampling

the MIS weight that minimizes the variance!

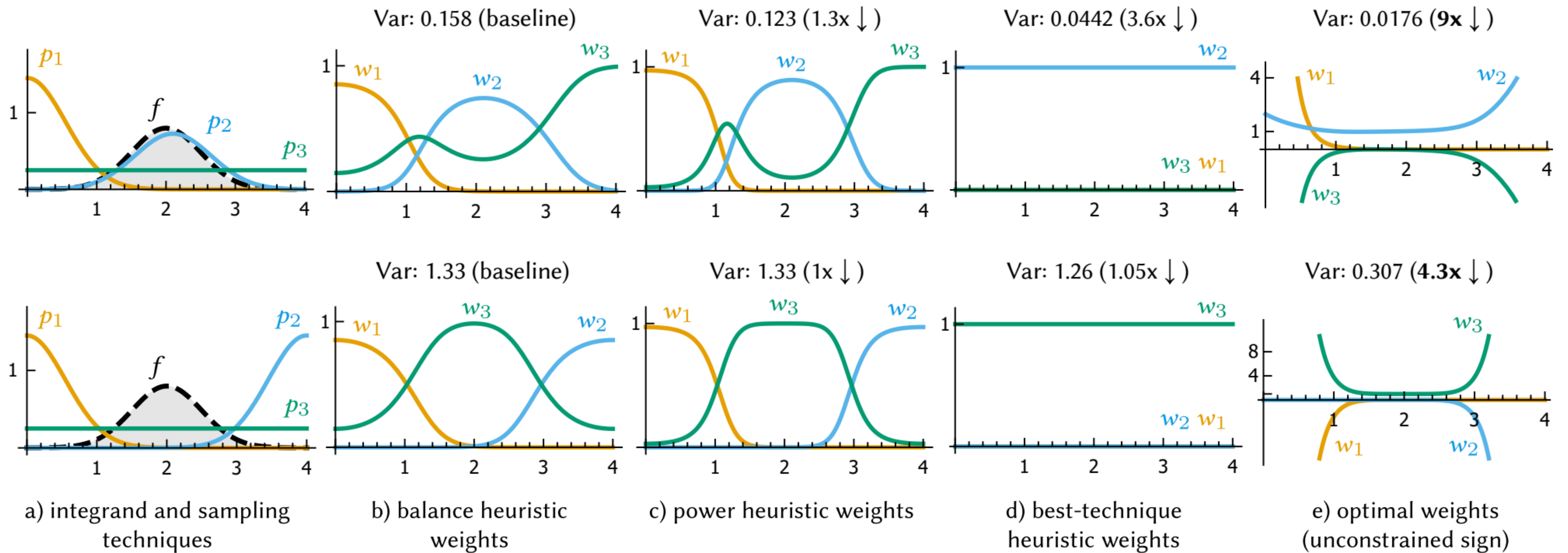
$$w_i = \frac{p_i}{f} a_i - p_i \frac{\sum_j \frac{p_j}{f} a_j - 1}{\sum_j p_j}$$

$$\begin{bmatrix} A_{00} & A_{01} \\ A_{10} & A_{11} \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \end{bmatrix}$$

$$A_{ij} = \int \frac{p_i p_j}{\sum_k p_k}$$

$$b_i = \int \frac{f p_i}{\sum_k p_k}$$

Optimal MIS weight requires negative weights



Inuition: control variates of mixture PDFs lead to optimal MIS

control variates: variance reduction using known integrals

$$\int f(x)dx = \int f(x) - g(x)dx + \int g(x)dx = \int f(x) - g(x)dx + G$$

Inuition: control variates of mixture PDFs lead to optimal MIS

control variates: variance reduction using known integrals

$$\int f(x)dx = \int f(x) - \sum_i \alpha_i p_i(x) dx + \sum_i \alpha_i$$

Inuition: control variates of mixture PDFs lead to optimal MIS

control variates: variance reduction using known integrals

$$\int f(x)dx = \int f(x) - \sum_i \alpha_i p_i(x) dx + \sum_i \alpha_i$$

optimal α_i satisfies

$$\begin{bmatrix} \int \frac{p_1 p_1}{p_1 + p_2} & \int \frac{p_1 p_2}{p_1 + p_2} \\ \int \frac{p_2 p_1}{p_1 + p_2} & \int \frac{p_2 p_2}{p_1 + p_2} \end{bmatrix} \alpha = \begin{bmatrix} \int \frac{f p_1}{p_1 + p_2} \\ \int \frac{f p_2}{p_1 + p_2} \end{bmatrix}$$

Inuition: control variates of mixture PDFs lead to optimal MIS

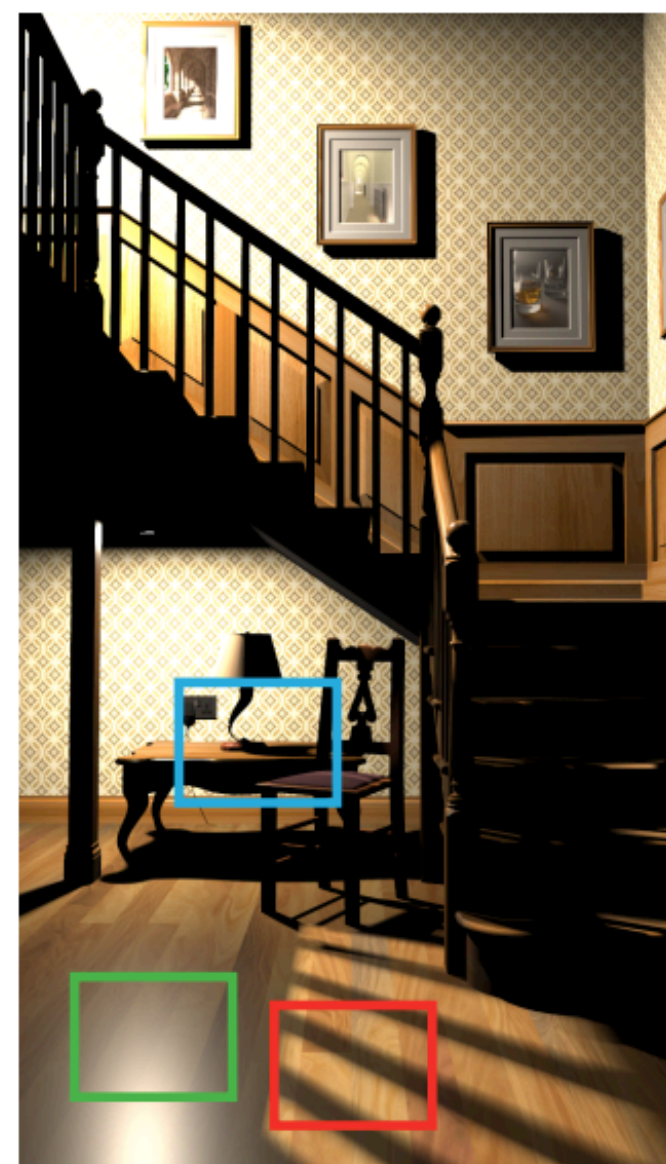
control variates: variance reduction using known integrals

$$\int f(x)dx = \int f(x) - \sum_i \alpha_i p_i(x) dx + \sum_i \alpha_i$$

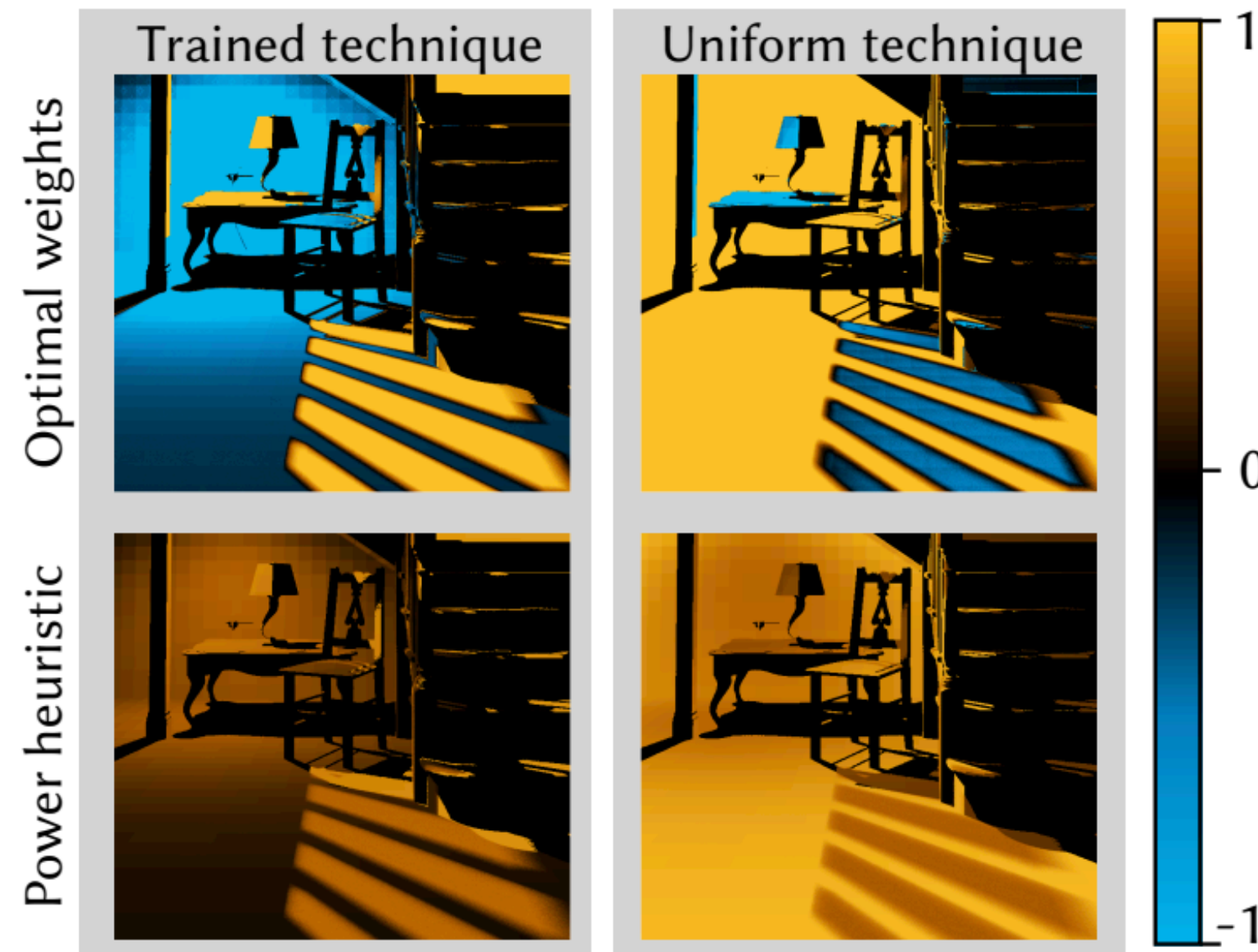
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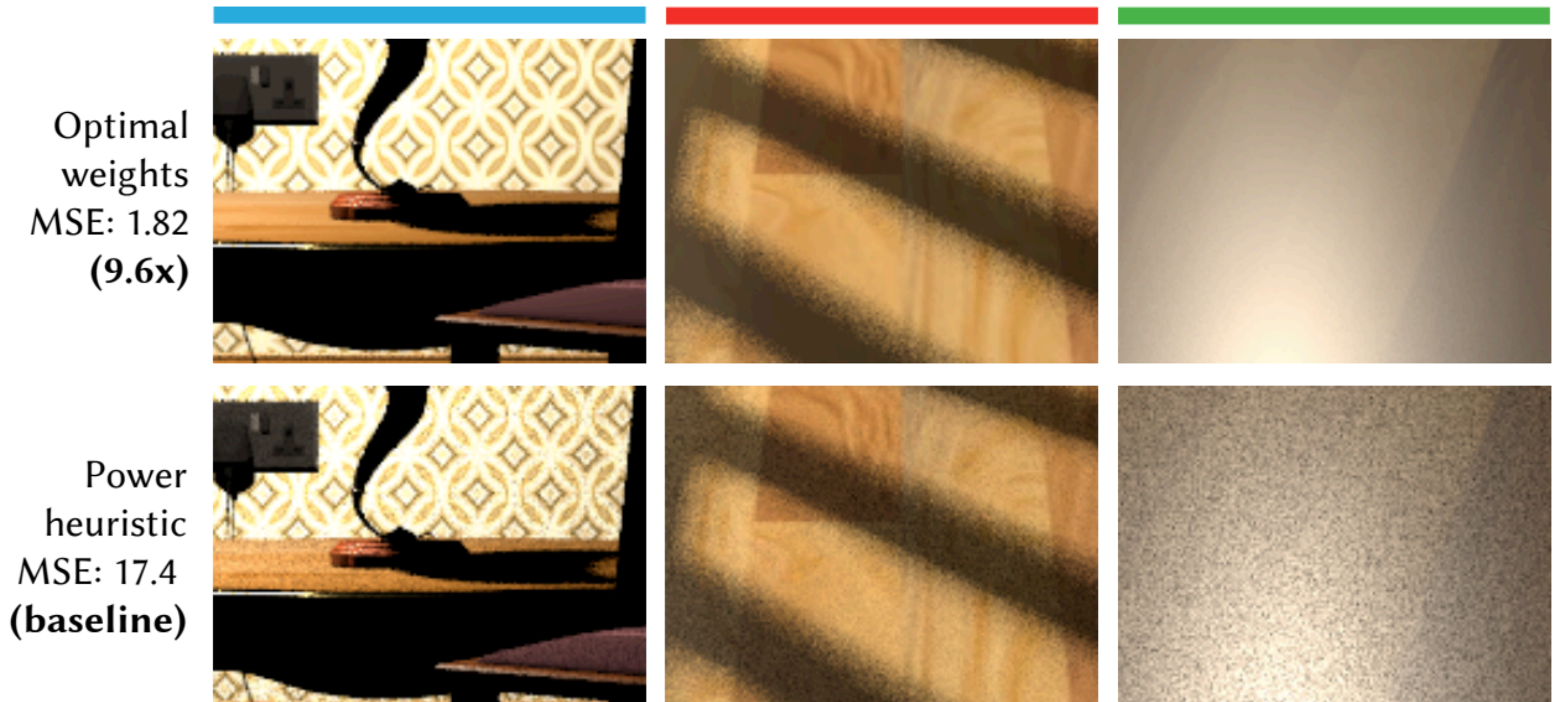
Optimal MIS can outperform MIS



a) Reference



b) MIS weights



c) Equal-sample comparison

Downside of Optimal MIS

Downside of Optimal MIS

computing the weights requires solving integrals!

$$w_i = \frac{p_i}{f} a_i - p_i \frac{\sum_j \frac{p_j}{f} a_j - 1}{\sum_j p_j}$$

$$A_{ij} = \int \frac{p_i p_j}{\sum_k p_k}$$

$$\begin{bmatrix} A_{00} & A_{01} \\ A_{10} & A_{11} \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \end{bmatrix}$$

$$b_i = \int \frac{f p_i}{\sum_k p_k}$$

Variance-aware MIIIS

- combine balance heuristic with empirical variance

$$w_1 = \frac{\nu_1 p_1}{\nu_1 p_1 + \nu_2 p_2}$$

$$\nu_i = \frac{E \left[\left(\frac{f_i}{p_i} \right)^2 \right]}{\text{Var} \left[\frac{f_i}{p_i} \right]}$$

if $\nu_i = 1$, balance heuristic is optimal, if $\nu_i \rightarrow 0$, variance is high and we should distrust technique i

Variance-Aware Multiple Importance Sampling

PASCAL GRITTMANN, Saarland University, Germany

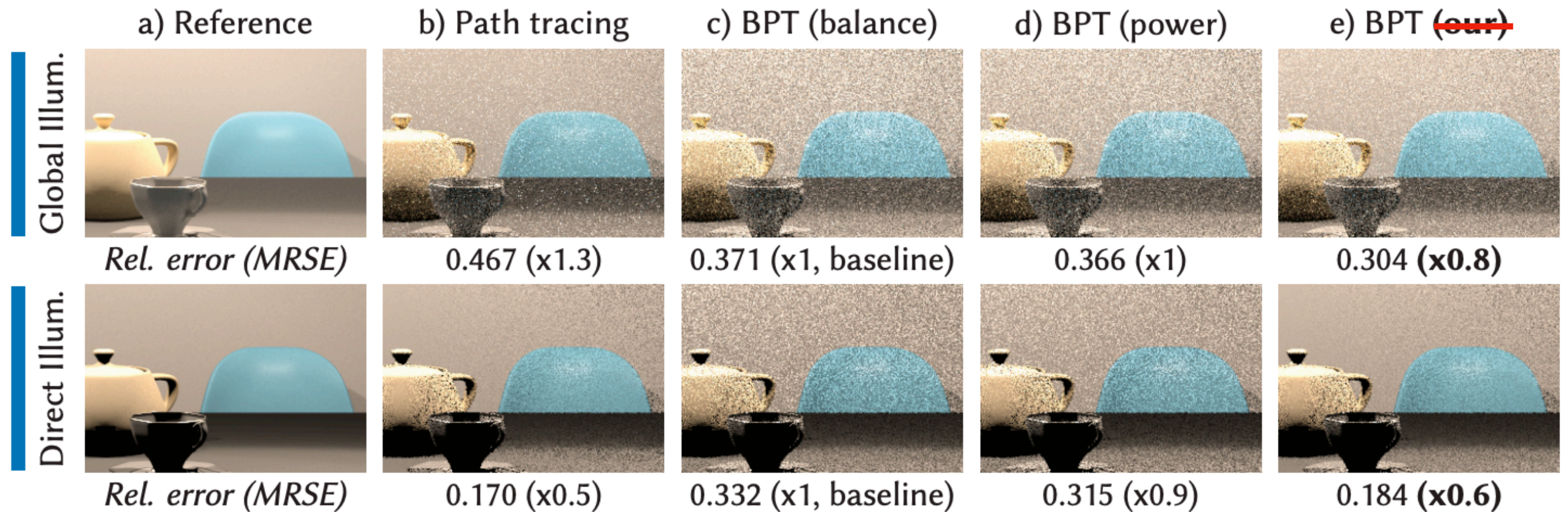
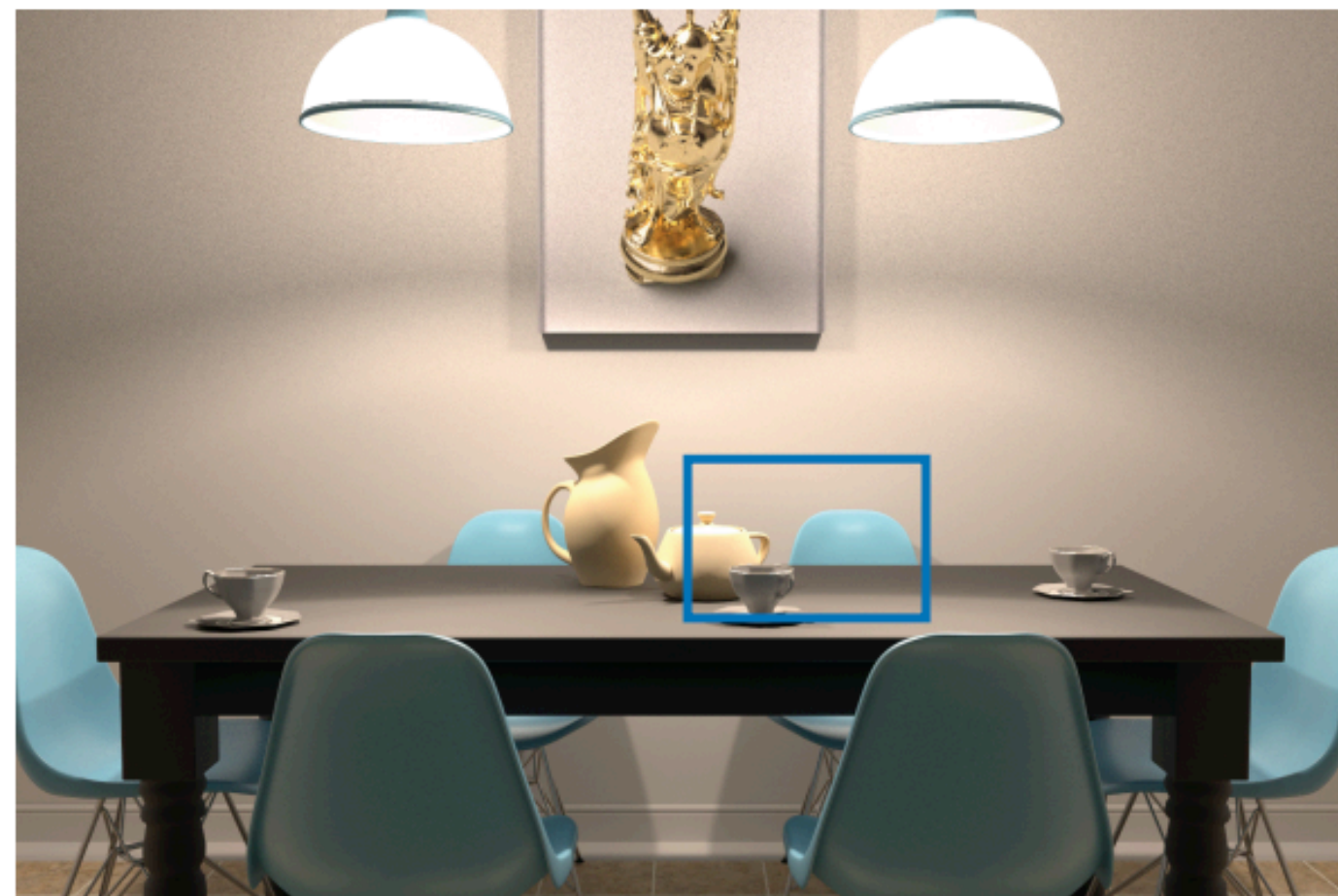
ILIJAN GEORGIEV, Autodesk, United Kingdom

PHILIPP SLUSALLEK, DFKI and Saarland University, Germany

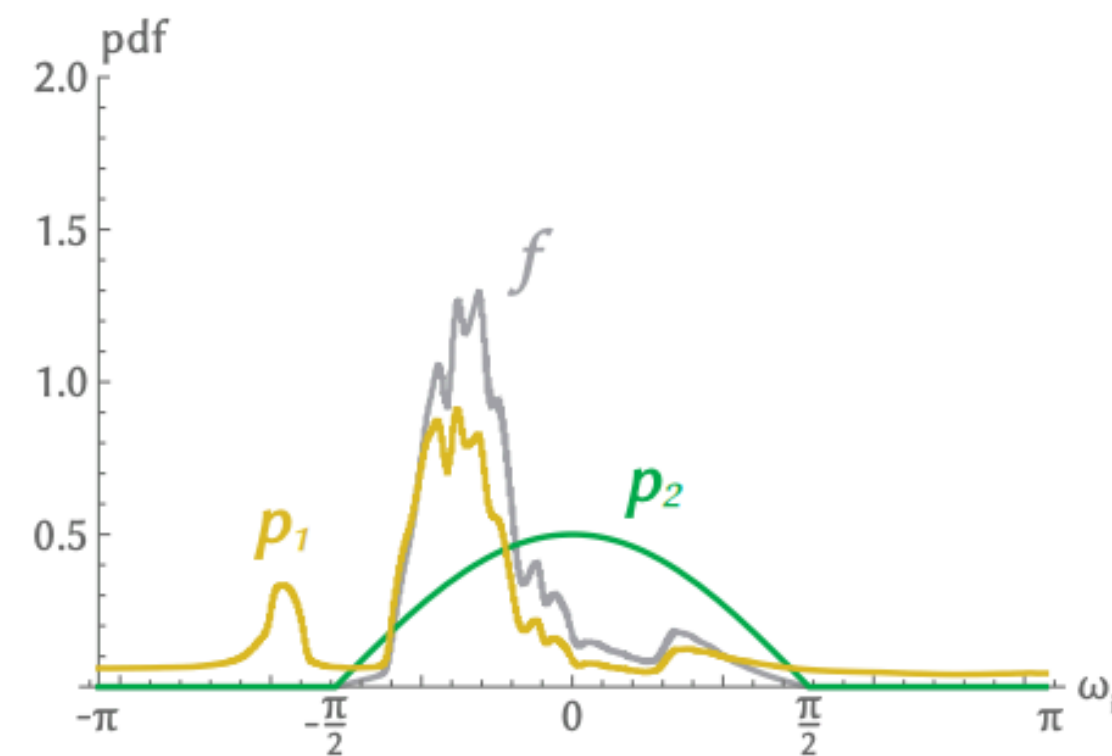
JAROSLAV KŘIVÁNEK, Charles University and Chaos Czech a. s., Czech Republic

Variance-aware MIS takes stratification into consideration

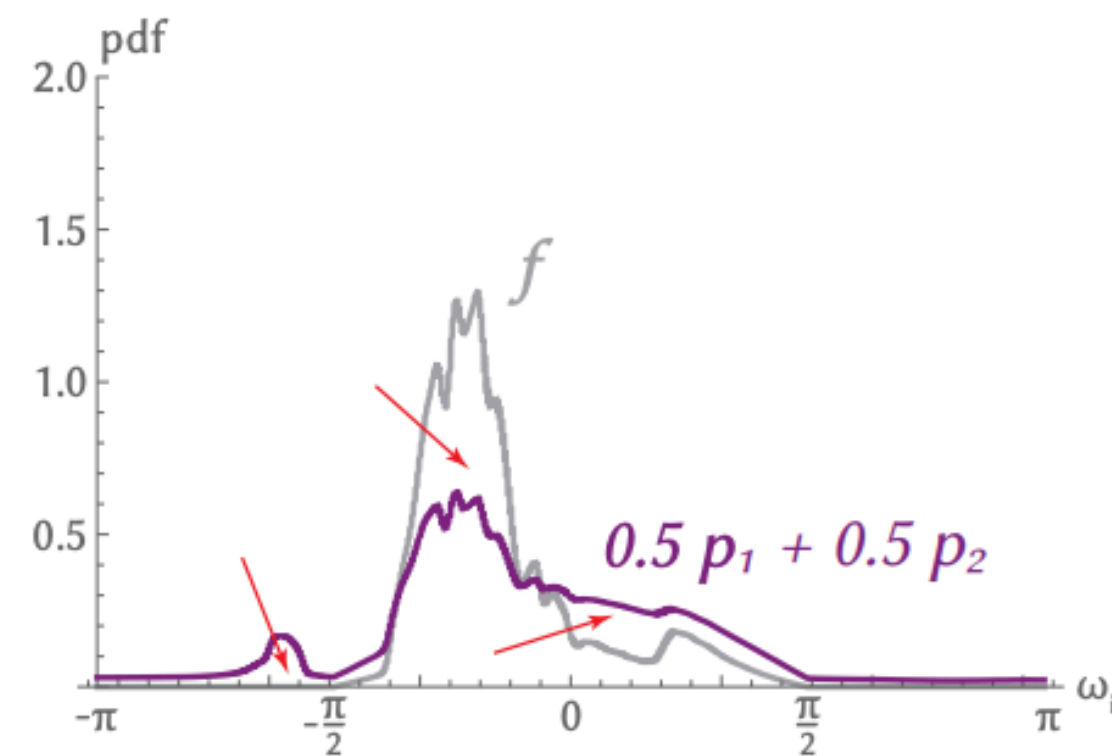
(Gritmann et al.)



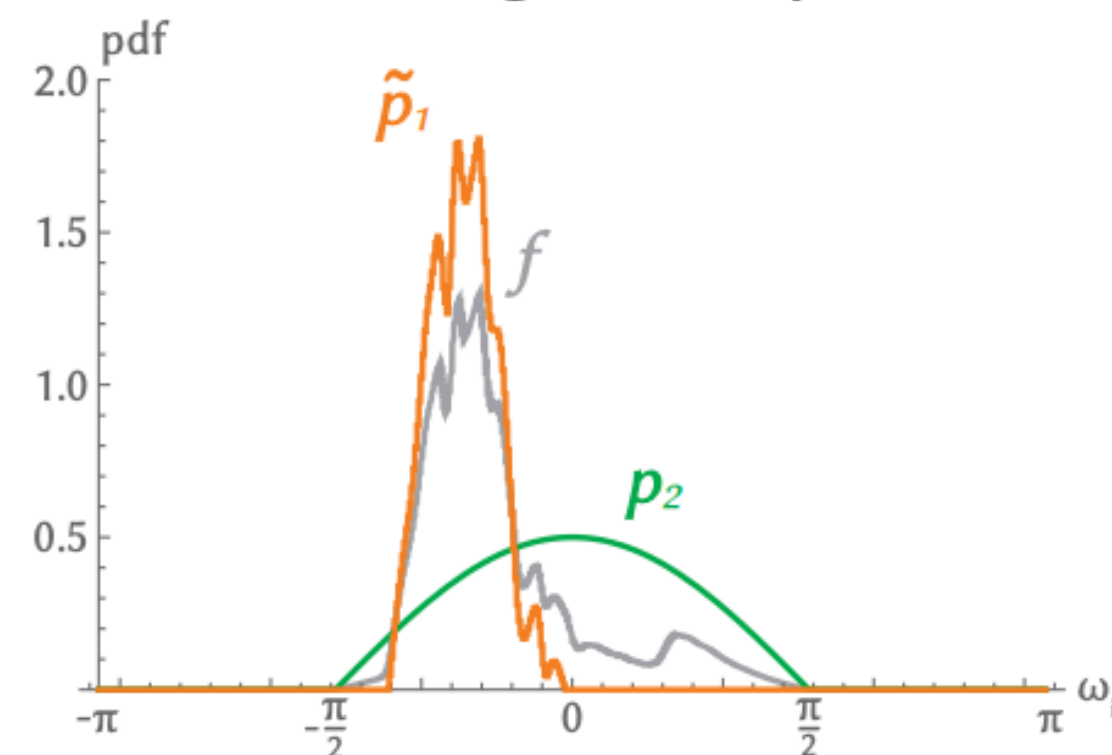
MIS compensation: modify a PDF based on other techniques



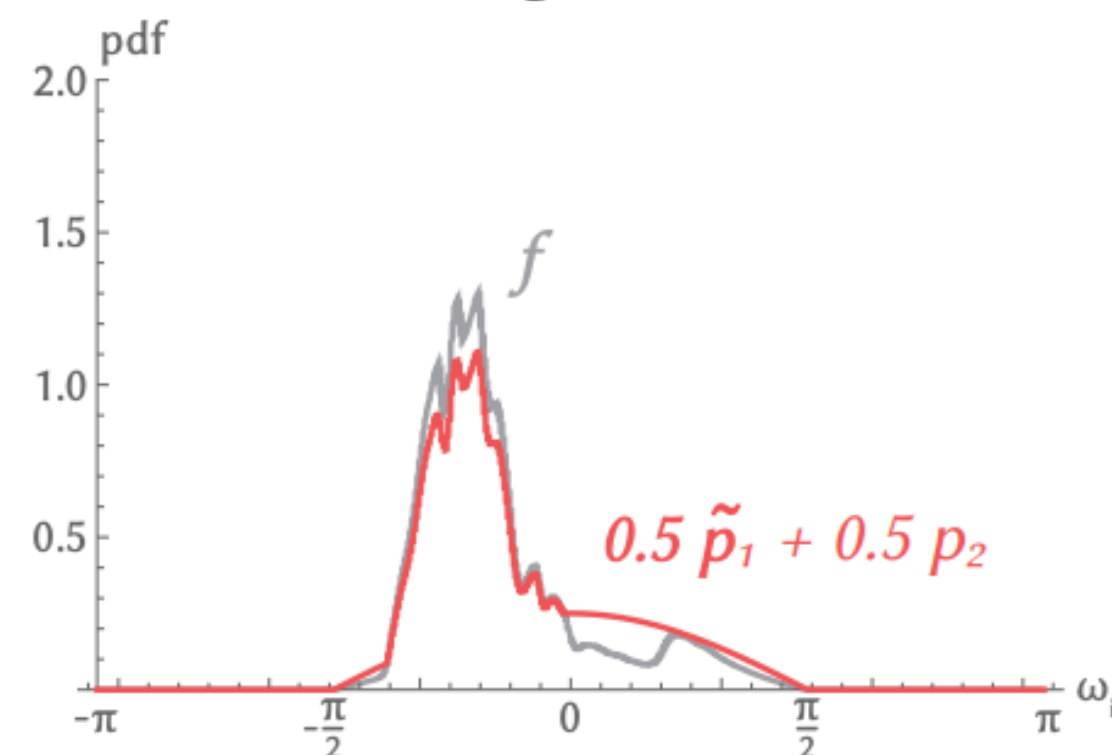
a) Original setup



b) Original MIS



c) Setup with the optimized technique



d) MIS with the optimized technique

MIS Compensation: Optimizing Sampling Techniques in Multiple Importance Sampling

ONDŘEJ KARLÍK, Chaos Czech a. s.

MARTIN ŠIK, Chaos Czech a. s.

PETR VÉVODA, Charles University, Prague and Chaos Czech a. s.

TOMÁŠ SKŘIVAN, IST Austria

JAROSLAV KŘIVÁNEK, Charles University, Prague and Chaos Czech a. s.

MIS compensation: modify a PDF based on other techniques

super simple to implement for discrete PMFs!

```
void MIS_compensation()
{
    for (int i = 0; i < N; ++i) {
        probability[i] = max(probability[i] - averageValue, 0.f);
    }
}
```

https://www.iliyan.com/publications/RenderingCourse2020/RenderingCourse2020_Notes_rev1.pdf

MIS Compensation: Optimizing Sampling Techniques in Multiple Importance Sampling

ONDŘEJ KARLÍK, Chaos Czech a. s.

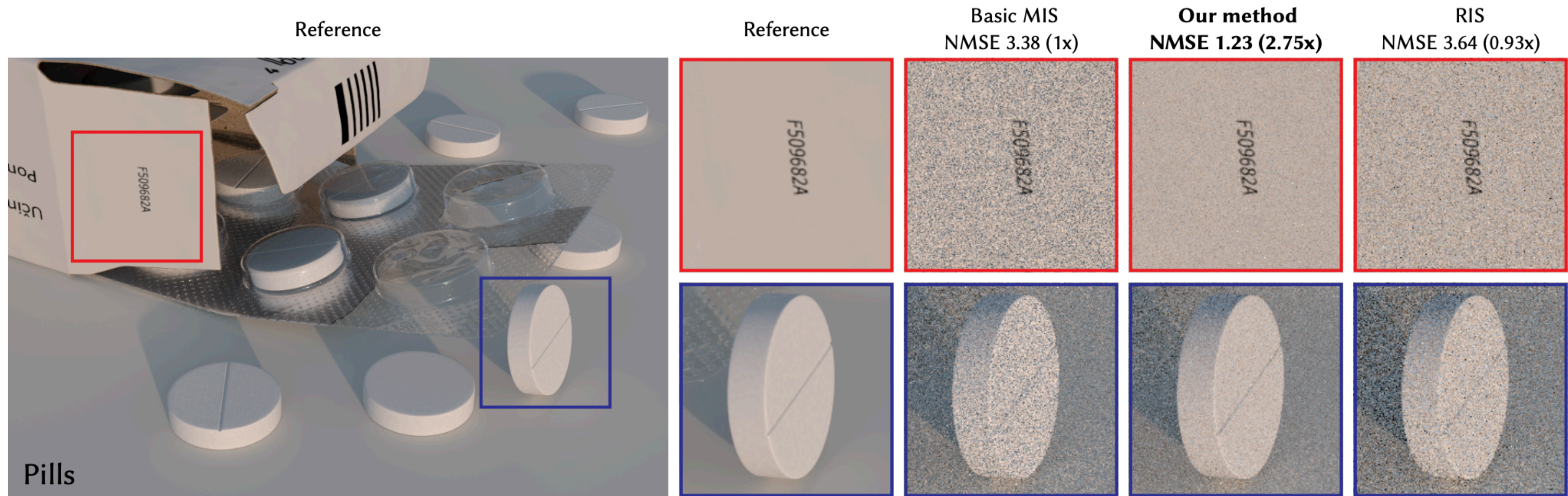
MARTIN ŠIK, Chaos Czech a. s.

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TOMÁŠ SKŘIVAN, IST Austria

JAROSLAV KŘIVÁNEK, Charles University, Prague and Chaos Czech a. s.

MIS compensation: modify a PDF based on other techniques



Original HDR map



Pdf used by MIS



Our pdf

Can we do better than Veach?

trick 1: assuming $X_{1,i}$ and $X_{2,j}$ are uncorrelated

$$\langle F \rangle = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i}) \\ + \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$

$$\text{Var}[\langle F \rangle] = \text{Var} \left[\frac{1}{N_1} \sum \frac{fw_1}{p_1} \right] + \text{Var} \left[\frac{1}{N_2} \sum \frac{fw_2}{p_2} \right]$$

trick 2: minimize upper bound of the variance

$$\text{Var}[X] = E[X^2] - E[X]^2 \leq E[X^2]$$

Can we do better than Veach?

trick 1: assuming $X_{1,i}$ and $X_{2,j}$ are uncorrelated

$$\langle F \rangle = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i}) + \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$

$$\text{Var}[\langle F \rangle] = \text{Var} \left[\frac{1}{N_1} \sum \frac{fw_1}{p_1} \right] + \text{Var} \left[\frac{1}{N_2} \sum \frac{fw_2}{p_2} \right]$$

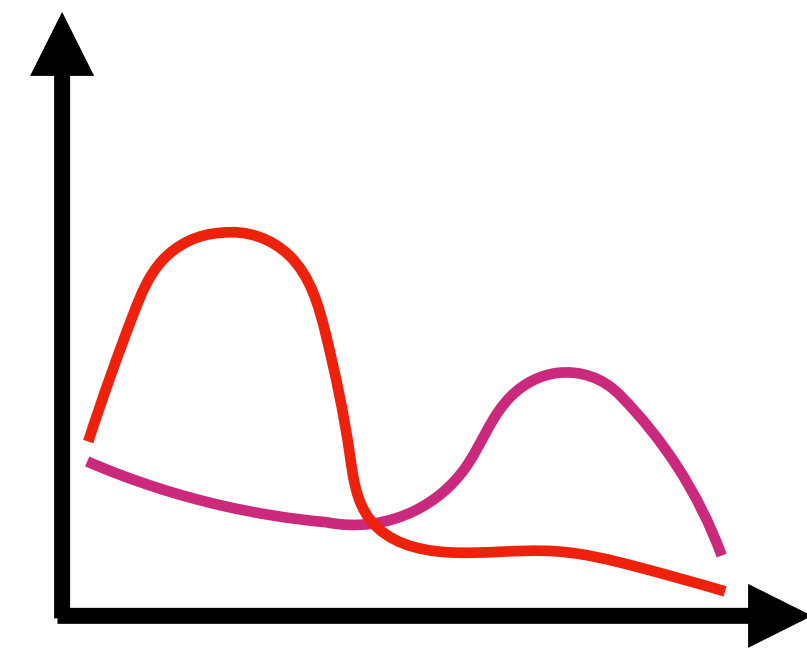
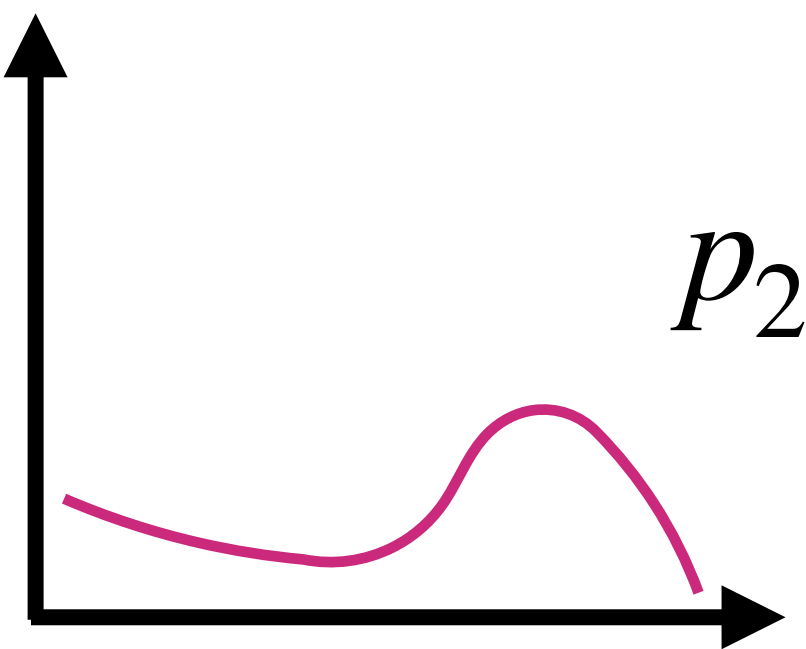
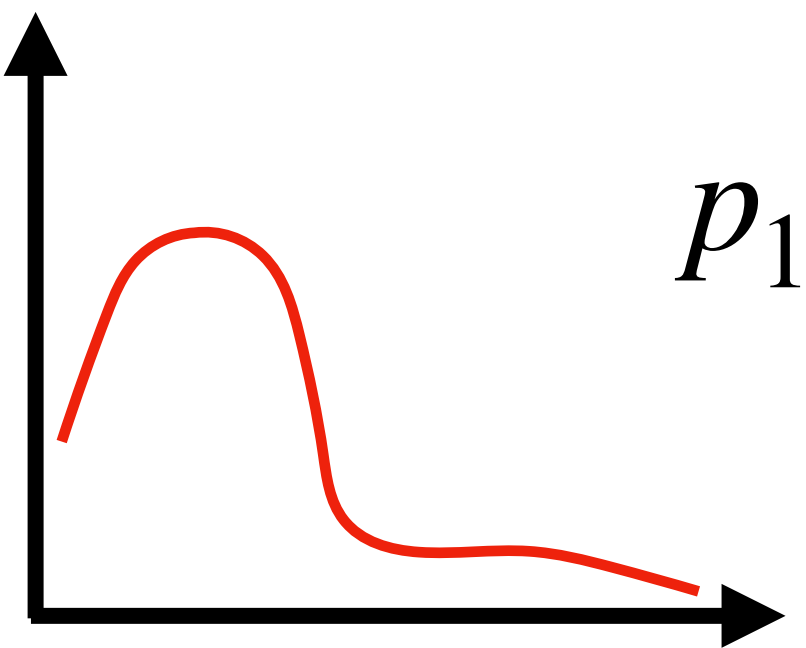
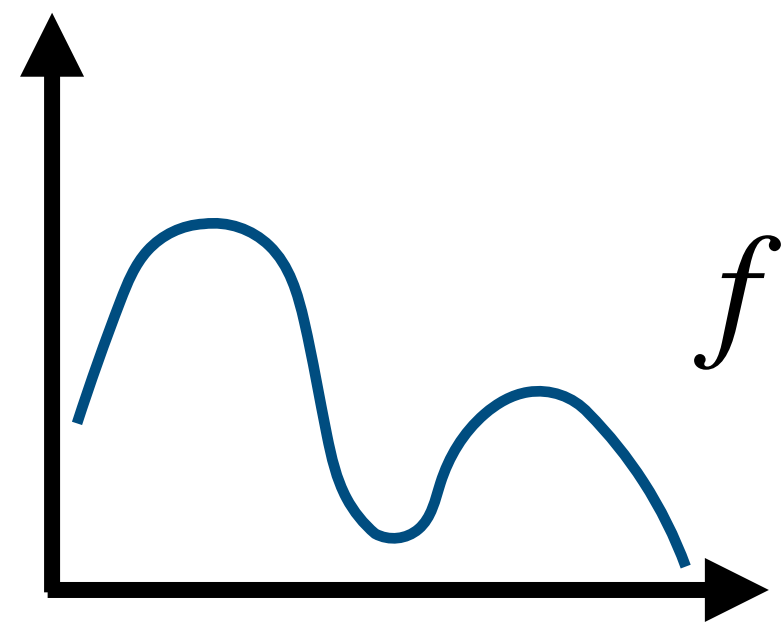
trick 2: minimize upper bound of the variance

$$\text{Var}[X] = E[X^2] - E[X]^2 \leq E[X^2]$$

how do we choose N_1 and N_2 ?

Can we randomly choose one technique?

effectively blending the two PDFs into one



$$\langle F \rangle = \frac{1}{N} \sum_i \frac{f(X_i)}{p(X_i)}$$

$$p = \frac{w_1 p_1 + w_2 p_2}{2}$$

One-sample MIS

- instead of sampling from both p_1 and p_2 , we randomly choose one of them

$$\langle F \rangle_{\text{ms}} = \frac{f}{p_1} w_1 + \frac{f}{p_2} w_2$$

“multi-sample” MIS

$$\langle F \rangle_{\text{os}} = w_i \frac{f}{\frac{1}{2} p_i}$$

“one-sample” MIS

Balance heuristic is optimal in one-sample MIS

$$\langle F \rangle_{\text{OS}} = w_i \frac{f}{\frac{1}{2} p_i}$$

$$w_i = \frac{p_i}{p_1 + p_2}$$

Balance heuristic is optimal in one-sample MIS

$$\langle F \rangle_{\text{OS}} = w_i \frac{f}{\frac{1}{2} p_i} = \frac{f}{\frac{1}{2} (p_1 + p_2)}$$

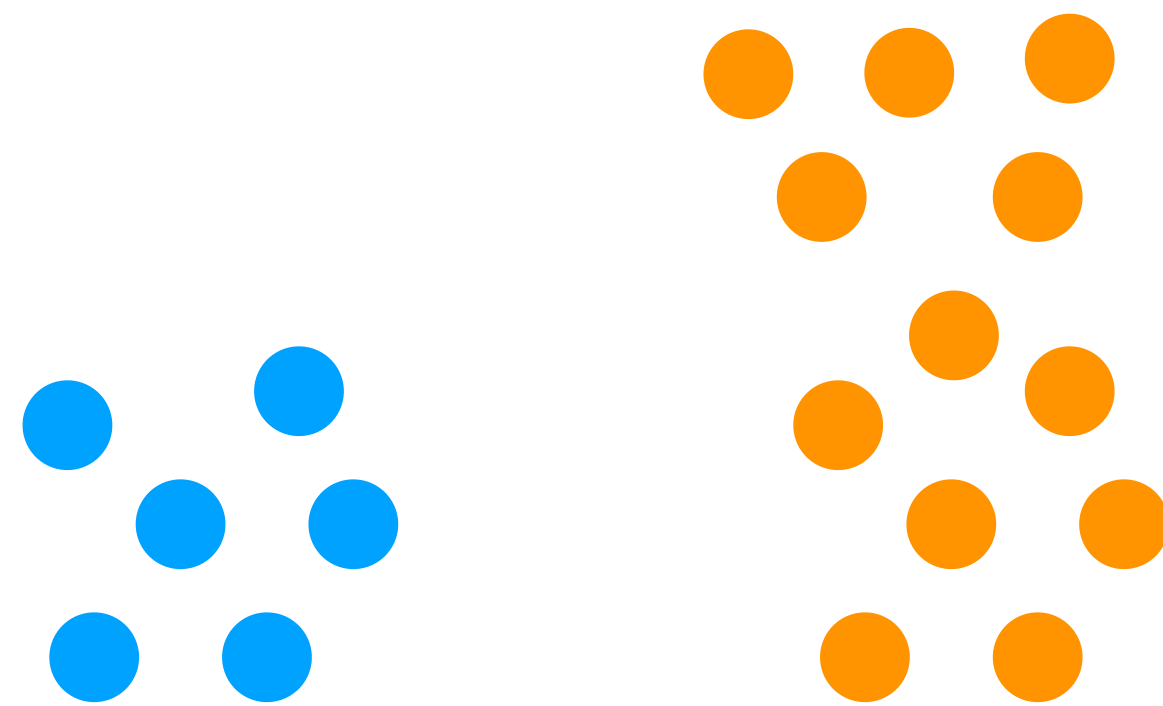
$$w_i = \frac{p_i}{p_1 + p_2}$$

- one-sample MIS = just average the distribution
- not really doing anything!

MIS is helpful because of stratification!

- stratification ensures we have the same amount of samples for each sampling distribution

one-sample MIS

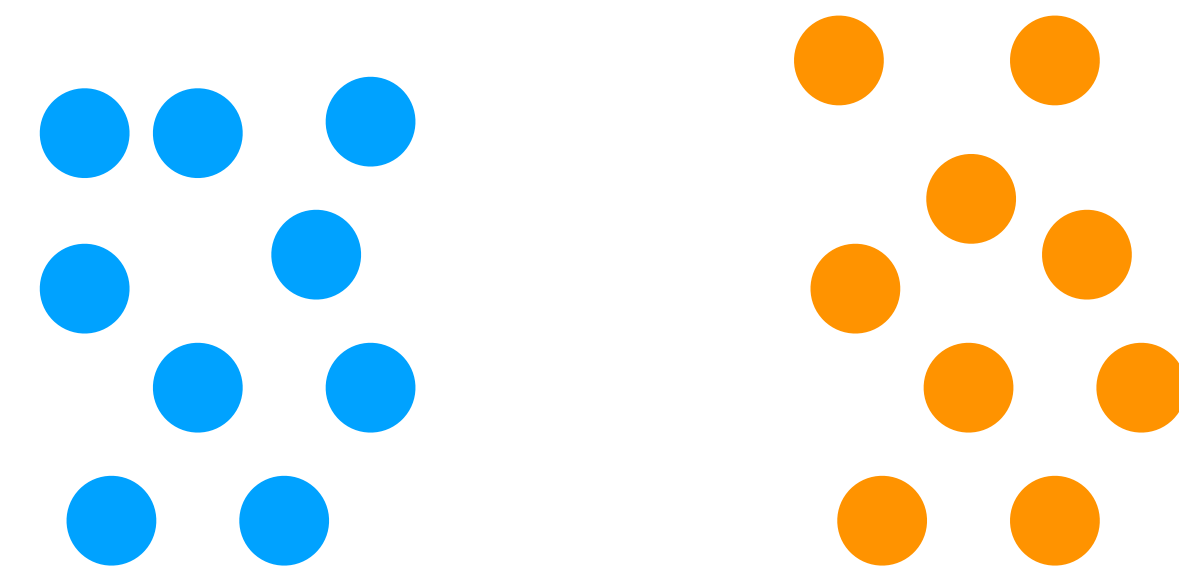


p_1

p_2

extra variance comes from
uneven sample counts

multi-sample MIS



p_1

p_2

more variance reduction

Many alternatives between one-sample and multi-sample

\mathcal{W}_1 : $\varphi_{\mathcal{P}_n}(\mathbf{x}_n) = \varphi_{j_{1:n-1}}(\mathbf{x}_n) = p(\mathbf{x}_n | j_{1:n-1})$

Since the sampling process is sequential, this option is of particular interest. It interprets the proposal pdf as the conditional density of \mathbf{x}_n given all the previous proposal indexes of the sampling process.

\mathcal{W}_2 : $\varphi_{\mathcal{P}_n}(\mathbf{x}_n) = \varphi_{j_n}(\mathbf{x}_n) = p(\mathbf{x}_n | j_n) = q_{j_n}(\mathbf{x}_n)$

It interprets that if the index j_n is known, $\varphi_{\mathcal{P}_n}$ is the proposal q_{j_n} .

\mathcal{W}_3 : $\varphi_{\mathcal{P}_n}(\mathbf{x}_n) = p(\mathbf{x}_n)$

It interprets that \mathbf{x}_n is a realization of the marginal $p(\mathbf{x}_n)$. This is probably the most “natural” option (as it does not assume any further knowledge in the generation of \mathbf{x}_n) and is a usual choice for the calculation of the weights in some of the existing MIS schemes (see Section 5).

\mathcal{W}_4 : $\varphi_{\mathcal{P}_n}(\mathbf{x}_n) = \varphi_{j_{1:N}}(\mathbf{x}_n) = f(\mathbf{x}_n | j_{1:N}) = \frac{1}{N} \sum_{k=1}^N q_{j_k}(\mathbf{x}_n)$

This interpretation makes use of the distribution of the r.v. \mathbf{X} conditioned on the whole set of indexes (defined in Section 3.5).

\mathcal{W}_5 : $\varphi_{\mathcal{P}_n}(\mathbf{x}_n) = \varphi(\mathbf{x}_n) = f(\mathbf{x}_n) = \frac{1}{N} \sum_{k=1}^N q_k(\mathbf{x}_n)$

This option considers that all the \mathbf{x}_n are realizations of the r.v. \mathbf{X} defined in Section 3.5 (see Appendix A for a thorough discussion of this interpretation).

[R1]: *Sampling with replacement, \mathcal{S}_1 , and weight denominator \mathcal{W}_2 :*

For the weight calculation of the n -th sample, only the proposal selected for generating the sample is evaluated in the denominator.

[R2]: *Sampling with replacement, \mathcal{S}_1 , and weight denominator \mathcal{W}_4 :*

With the N selected indexes j_n , for $n = 1, \dots, N$, one forms a mixture comprising all the corresponding proposal pdfs. The weight calculation of the n -th sample considers this *a posteriori* mixture evaluated at the n -th sample in the denominator, i.e., some proposals might be used more than once while other proposals might not be used.

[R3]: *Sampling with replacement, \mathcal{S}_1 , and weight denominator \mathcal{W}_1 , \mathcal{W}_3 , or \mathcal{W}_5 :*

For the weight calculation of the n -th sample, the denominator applies the value of the n -th sample to the whole mixture ψ composed of the set of initial proposal pdfs (i.e., the function in the denominator of the weight does not depend on the sampling process). This is the approach followed by the so called mixture PMC method [Cappé et al., 2008].

[N1]: *Sampling without replacement (random or deterministic), \mathcal{S}_2 or \mathcal{S}_3 , and weight denominator \mathcal{W}_2 (for \mathcal{S}_2) or \mathcal{W}_1 , \mathcal{W}_2 , or \mathcal{W}_3 (for \mathcal{S}_3):*

For calculating the denominator of the n -th weight, the specific proposal used for the generation of the sample is used. This is the approach frequently used in particle filtering [Gordon et al., 1993] and in the standard MIS method [Cappé et al., 2004].

[N2]: *Sampling without replacement (random), \mathcal{S}_2 , and weight denominator \mathcal{W}_3 :*

This MIS implementation draws one sample from each proposal, and the order matters (it must be random) since the calculation of the n -th weight uses for the evaluation of the denominator the mixture pdf formed by the proposal pdfs that were still available at the generation of the n -th sample.

[N3]: *Sampling without replacement (random or deterministic), \mathcal{S}_2 or \mathcal{S}_3 , and weight denominator \mathcal{W}_3 , \mathcal{W}_4 , or \mathcal{W}_5 (for \mathcal{S}_2), or \mathcal{W}_4 or \mathcal{W}_5 (for \mathcal{S}_3):*

In the calculation of the n -th weight, one uses for the denominator the whole mixture. This is the approach, for instance, of [Martino et al., 2012; Cornuet et al., 2012]. As shown in Section 6, this scheme has several advantages over the others.

Generalized Multiple Importance Sampling

Víctor Elvira^{1*}, Luca Martino², David Luengo³, and Mónica F. Bugallo⁴

¹University of Edinburgh (United Kingdom), ²Universidad Rey Juan Carlos (Spain),

³Universidad Politécnica de Madrid (Spain), ⁴Stony Brook University (USA)

Choosing N_i to minimize variance

$$\langle F \rangle = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i})$$
$$+ \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$

can we pick optimal N_i ?

Choosing N_i to minimize variance

$$\langle F \rangle = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i})$$
$$+ \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$

need to jointly optimize w_i and N_i
(given a total budget N)

Choosing N_i to minimize variance

$$\langle F \rangle = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i}) + \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$

need to jointly optimize w_i and N_i
(given a total budget N)

Many people have shown that this can be formulated as a convex optimization problem!

On Learning the Best Local Balancing Strategy

D. Murray¹ and S. Benzait¹ and R. Pacanowski² and X. Granier^{2,3}

Optimal Deterministic Mixture Sampling

Optimal mixture weights in multiple importance sampling

Mateu Sbert¹ & Vlastimil Havran² & László Szirmay-Kalos³

Hera Y. He
Stanford University

Art B. Owen
Stanford University

Choosing N_i to minimize efficiency

$$\langle F \rangle_{N_1, N_2} = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i}) + \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$

minimize

$$C(N_1, N_2) \text{Var} \left[\langle F \rangle_{N_1, N_2} \right]$$

C = how long it takes to render

Efficiency-aware multiple importance sampling for bidirectional rendering algorithms

PASCAL GRITTMANN, Saarland University, Germany

ÖMERCAN YAZICI, Saarland University, Germany

ILIJAN GEORGIEV, Autodesk, United Kingdom

PHILIPP SLUSALLEK, Saarland University, Germany and DFKI, Germany

Grittmann et al.'s strategy: just try out different combinations of Ns!

$$\langle F \rangle_{N_1, N_2} = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i}) \\ + \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$

estimate

$$C(10\%, 90\%) \text{Var} \left[\langle F \rangle_{10\%, 90\%} \right] \\ C(30\%, 70\%) \text{Var} \left[\langle F \rangle_{30\%, 70\%} \right] \\ \dots$$

minimize

$$C(N_1, N_2) \text{Var} \left[\langle F \rangle_{N_1, N_2} \right]$$

C = how long it takes to render

Efficiency-aware multiple importance sampling for bidirectional rendering algorithms

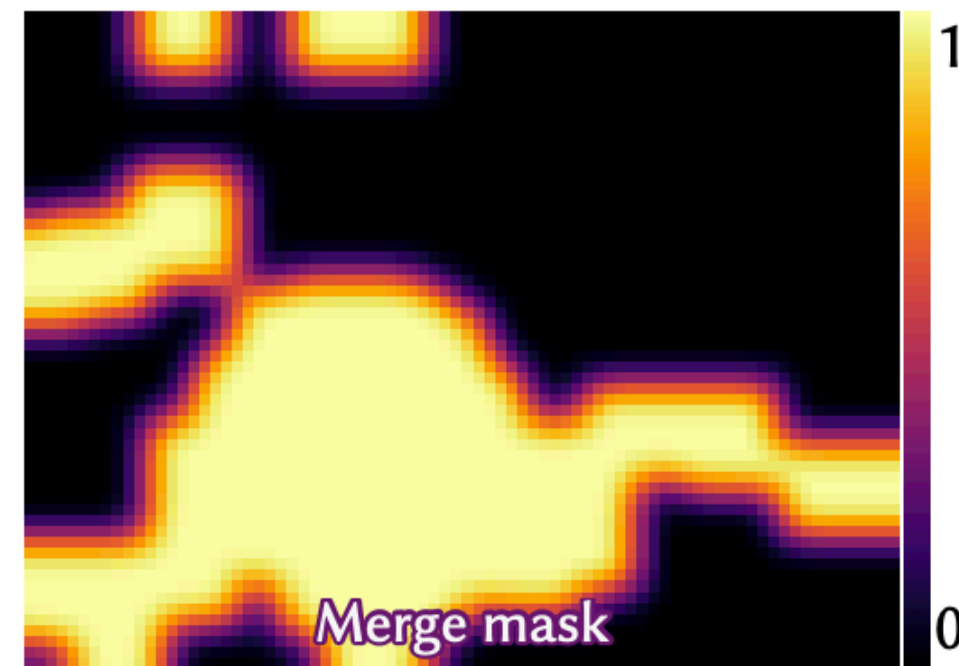
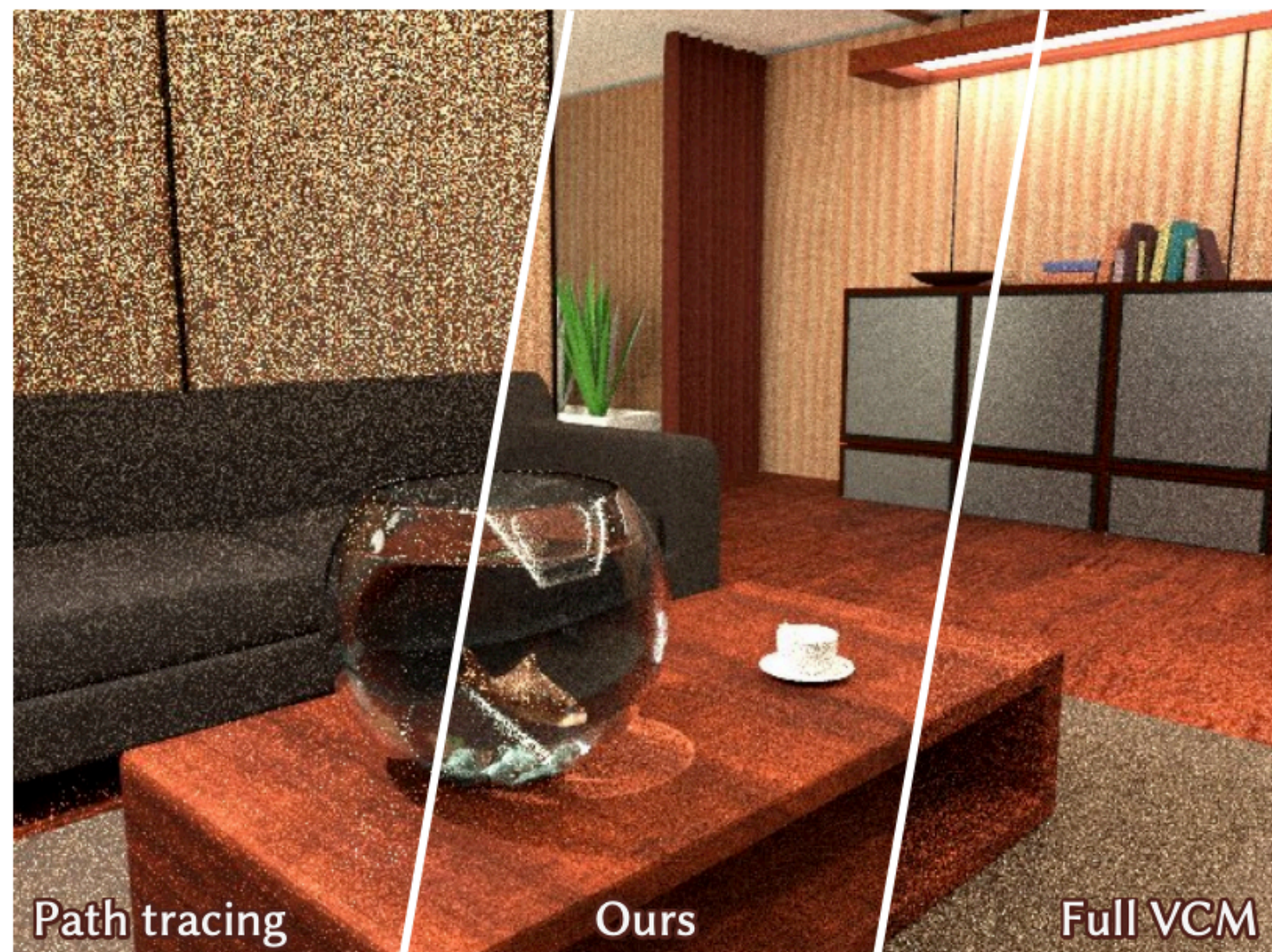
PASCAL GRITTMANN, Saarland University, Germany

ÖMERCAN YAZICI, Saarland University, Germany

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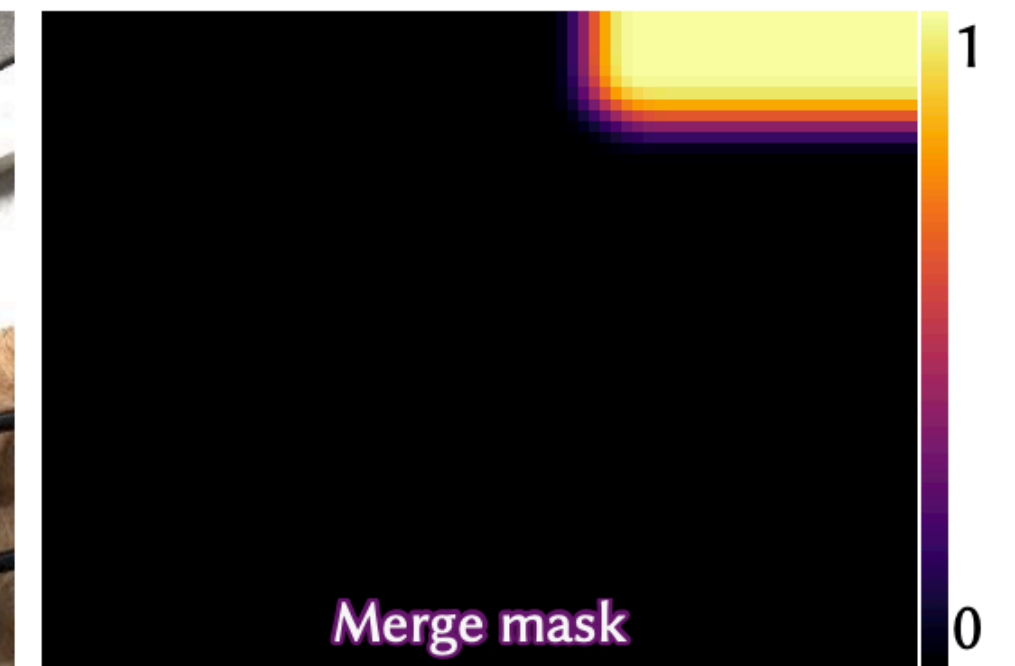
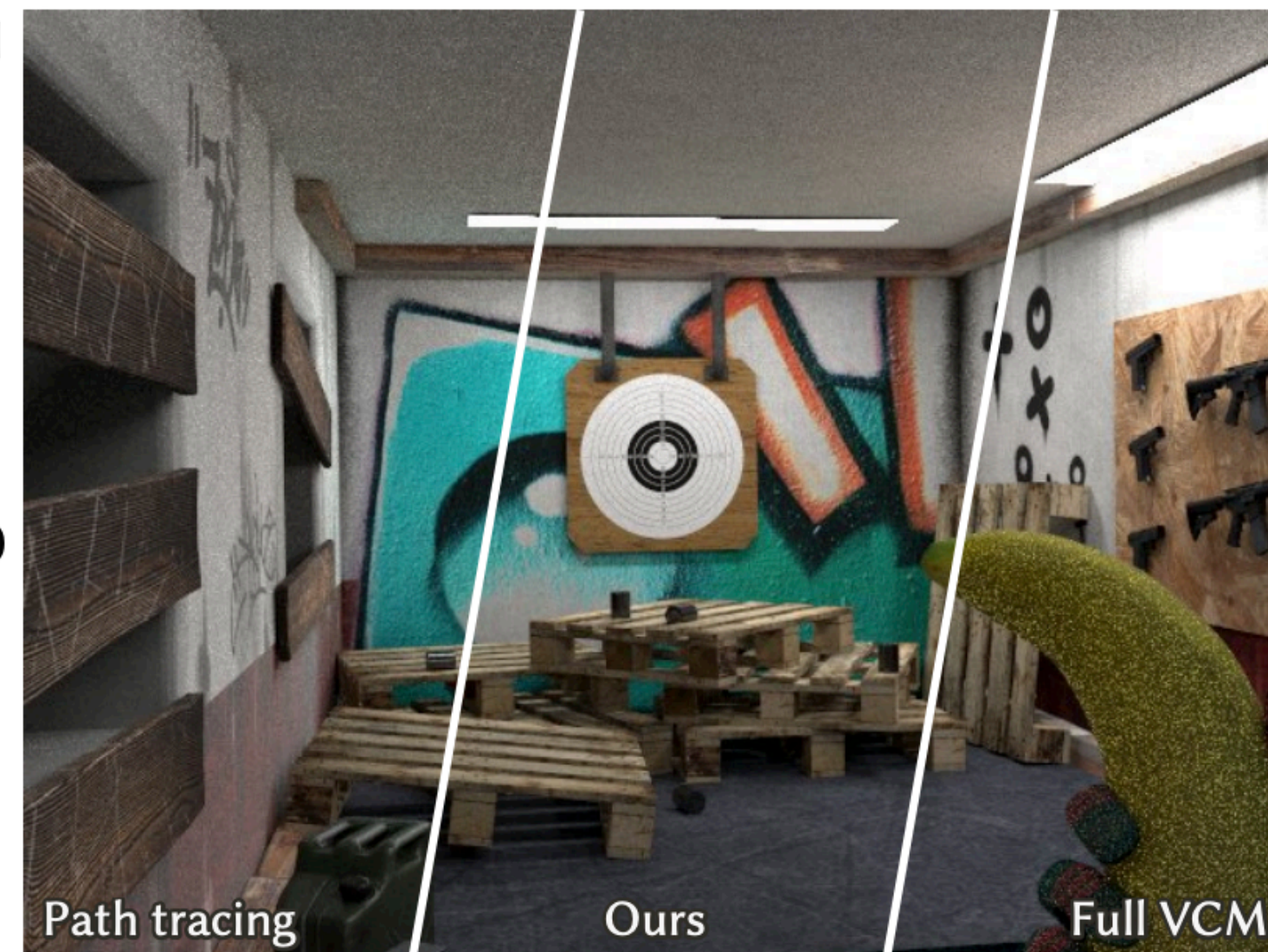
Choosing number of samples for MIS is crucial for bidirectional methods



FISH

153k light paths
8 connections

10.89× faster than PT
2.71× faster than VCM



TARGET PRACTICE

153k light paths
0 connections

1.72× faster than PT
3.54× faster than VCM

Can we do better than Veach?

trick 1: assuming $X_{1,i}$ and $X_{2,j}$ are uncorrelated

$$\langle F \rangle = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i}) \\ + \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$

$$\text{Var}[\langle F \rangle] = \text{Var} \left[\frac{1}{N_1} \sum \frac{fw_1}{p_1} \right] + \text{Var} \left[\frac{1}{N_2} \sum \frac{fw_2}{p_2} \right]$$

trick 2: minimize upper bound of the variance

$$\text{Var}[X] = E[X^2] - E[X]^2 \leq E[X^2]$$

Can we do better than Veach?

what if the samples are correlated?

$$\langle F \rangle = \frac{1}{N_1} \sum_i \frac{f(X_{1,i})}{p_1(X_{1,i})} w_1(X_{1,i}) + \frac{1}{N_2} \sum_j \frac{f(X_{2,j})}{p_2(X_{2,j})} w_2(X_{2,j})$$

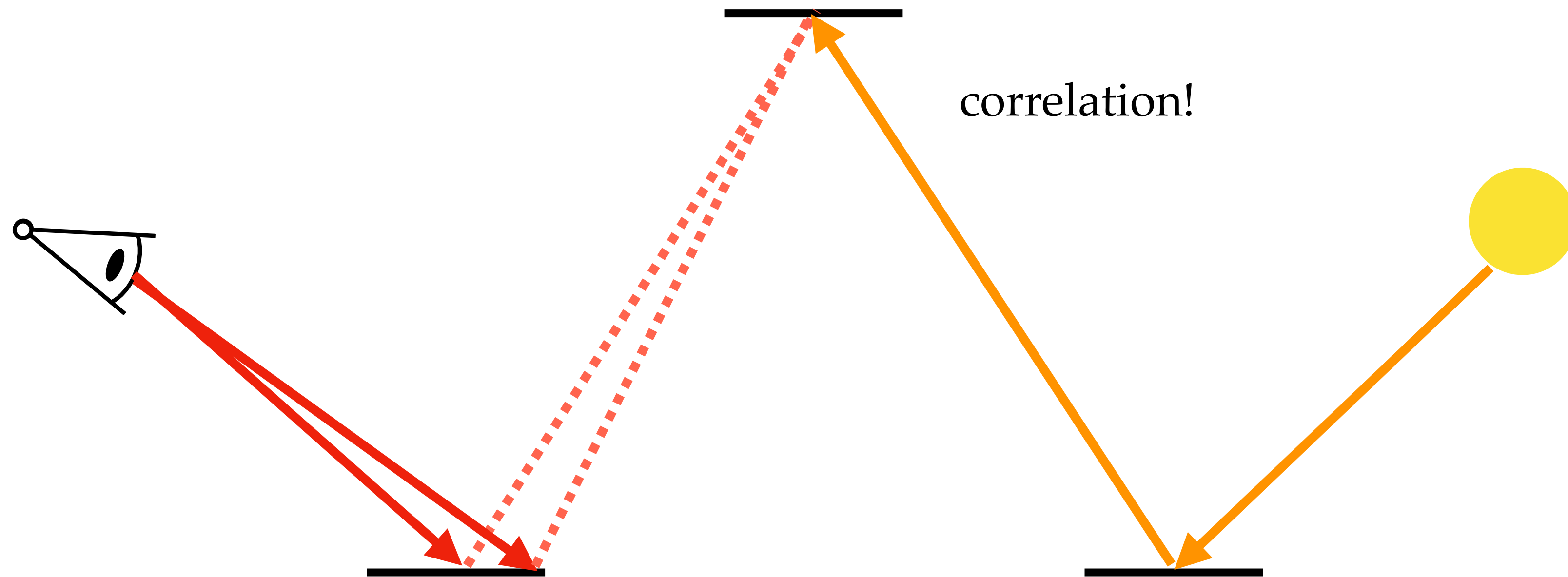
trick 1: assuming $X_{1,i}$ and $X_{2,j}$ are uncorrelated

$$\text{Var}[\langle F \rangle] = \text{Var} \left[\frac{1}{N_1} \sum \frac{fw_1}{p_1} \right] + \text{Var} \left[\frac{1}{N_2} \sum \frac{fw_2}{p_2} \right]$$

trick 2: minimize upper bound of the variance

$$\text{Var}[X] = E[X^2] - E[X]^2 \leq E[X^2]$$

Correlation occurs in bidirectional path tracing when camera subpaths are shared by a light subpath



Correlation-aware MIS

- no satisfactory solution yet, only heuristics exist

Probabilistic Connections for Bidirectional Path Tracing

Stefan Popov¹ Ravi Ramamoorthi² Fredo Durand³ George Drettakis¹

¹Inria ²UC San Diego ³MIT CSAIL

minimize a very loose upper bound

$$V[\tilde{I}_l] \leq \sum_{i \in S_u} \frac{1}{n_i} V[F_{i1}] + \sum_{i \in S_c} V[F_{i1}]$$

Correlation-Aware Multiple Importance Sampling for Bidirectional Rendering Algorithms

Pascal Grittmann¹ Iliyan Georgiev² Philipp Slusallek^{1,3}

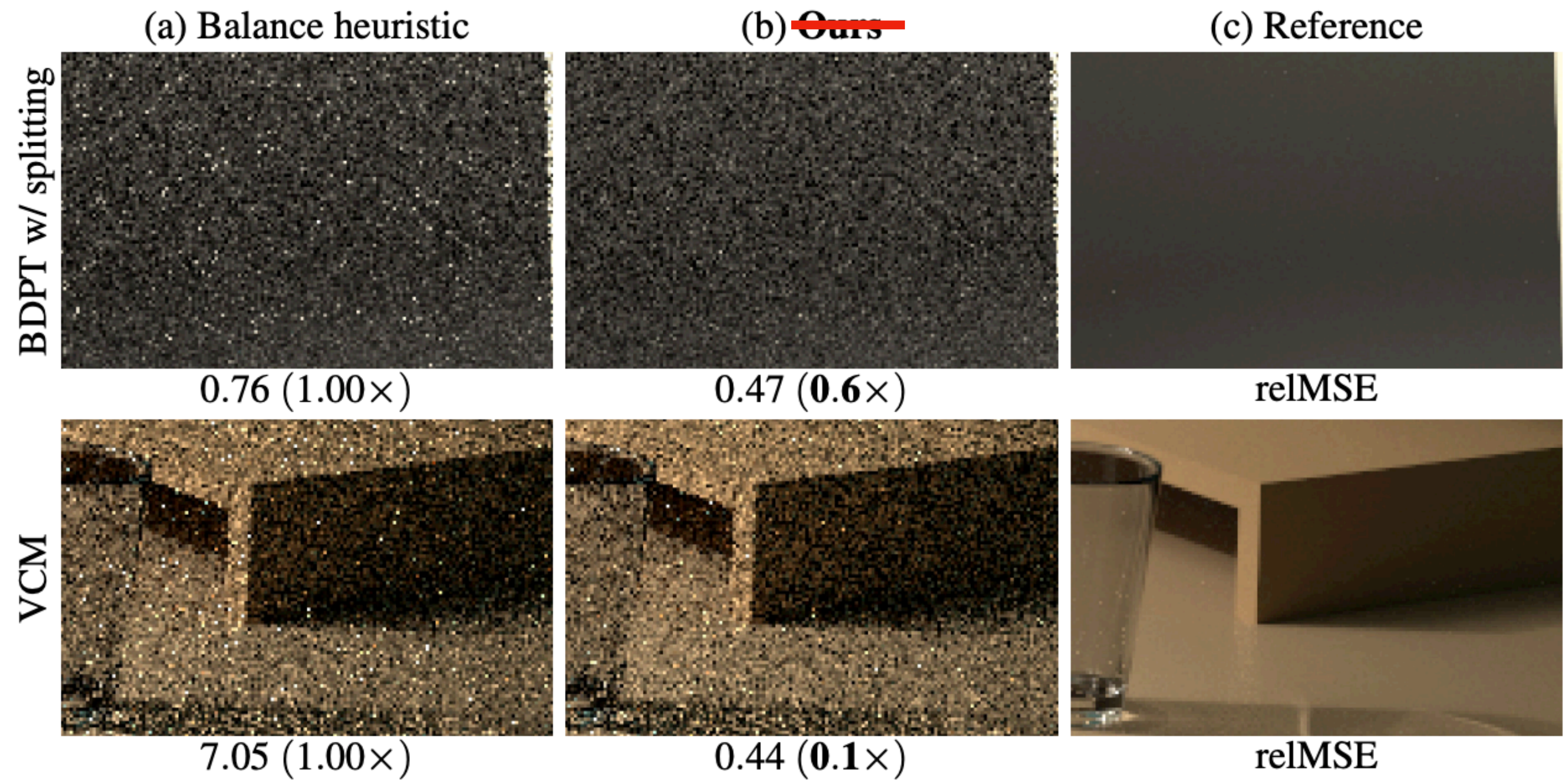
¹Saarland University, Germany ²Autodesk, United Kingdom ³DFKI, Germany

add a “correlation factor” c

$$w_t(\bar{\mathbf{x}}) = \frac{c_t(\bar{\mathbf{x}})n_t p_t(\bar{\mathbf{x}})}{\sum_k c_k(\bar{\mathbf{x}})n_k p_k(\bar{\mathbf{x}})}$$

Correlation-aware MIS

Grittmann et al.'s



Correlation-Aware Multiple Importance Sampling for Bidirectional Rendering Algorithms

Pascal Grittmann¹ Iliyan Georgiev² Philipp Slusallek^{1,3}

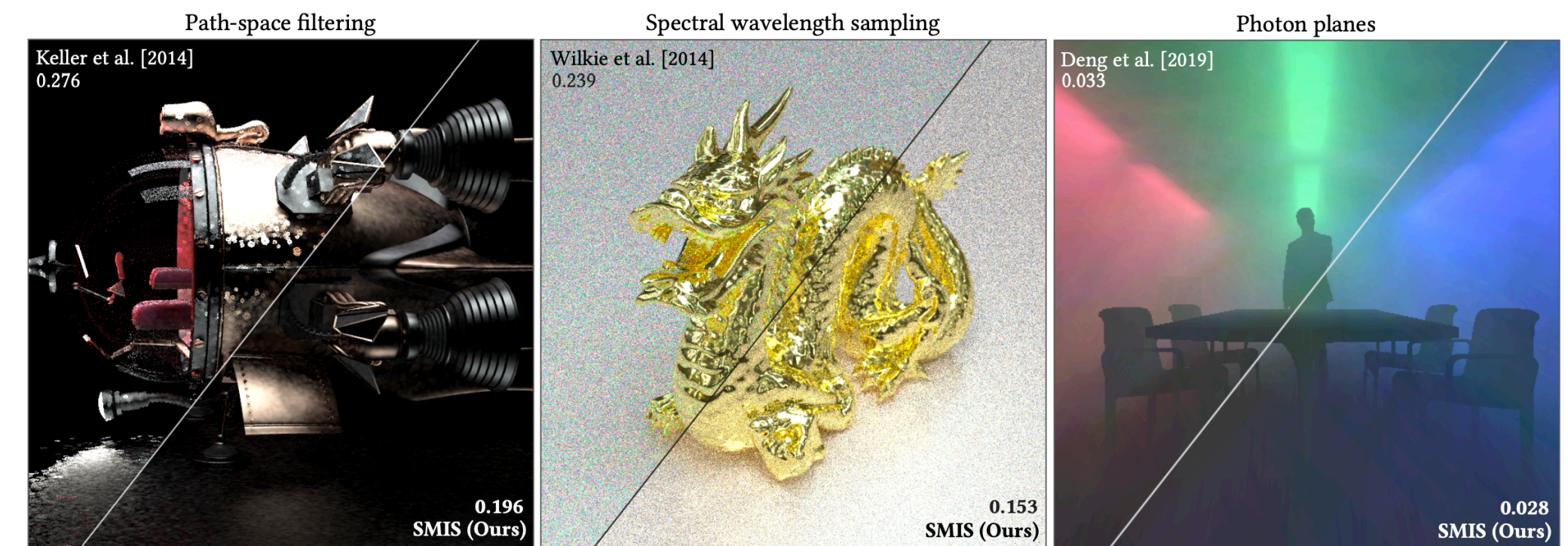
¹Saarland University, Germany ²Autodesk, United Kingdom ³DFKI, Germany

Continuous MIS

- instead of a finite amount of distributions, we can consider uncountably many distributions

$$\langle F \rangle_{\text{MIS}} = \sum \frac{f}{p_i} w_i$$

$$\langle F \rangle_{\text{CMIS}} = \int \frac{f}{p(i)} w(i)$$



Continuous Multiple Importance Sampling

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ADRIEN GRUSON, McGill University, Canada

TOSHIYA HACHISUKA, The University of Tokyo, Japan

MIS is frequently used in Bayesian inference

Adaptive Multiple Importance Sampling

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Generalized Multiple Importance Sampling

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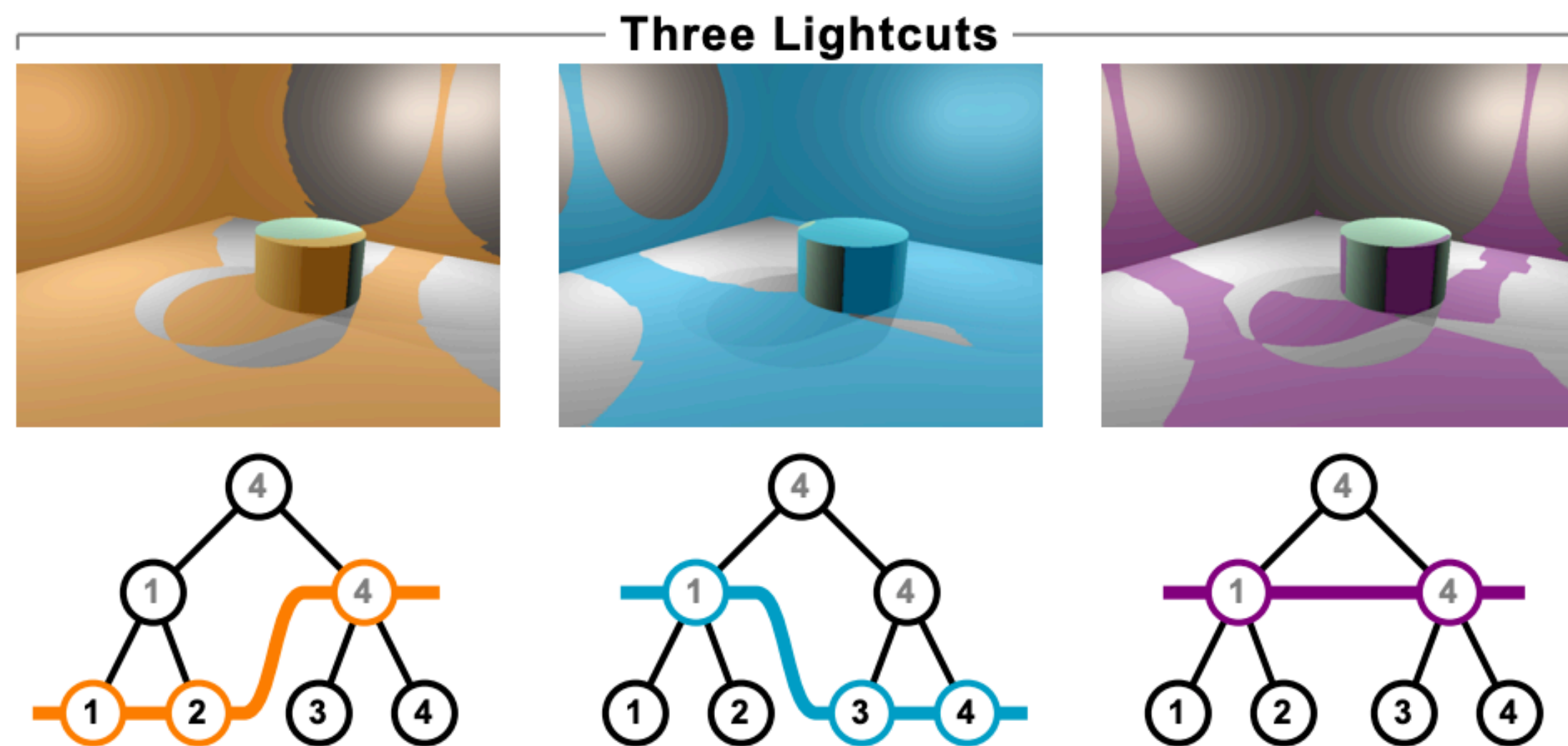
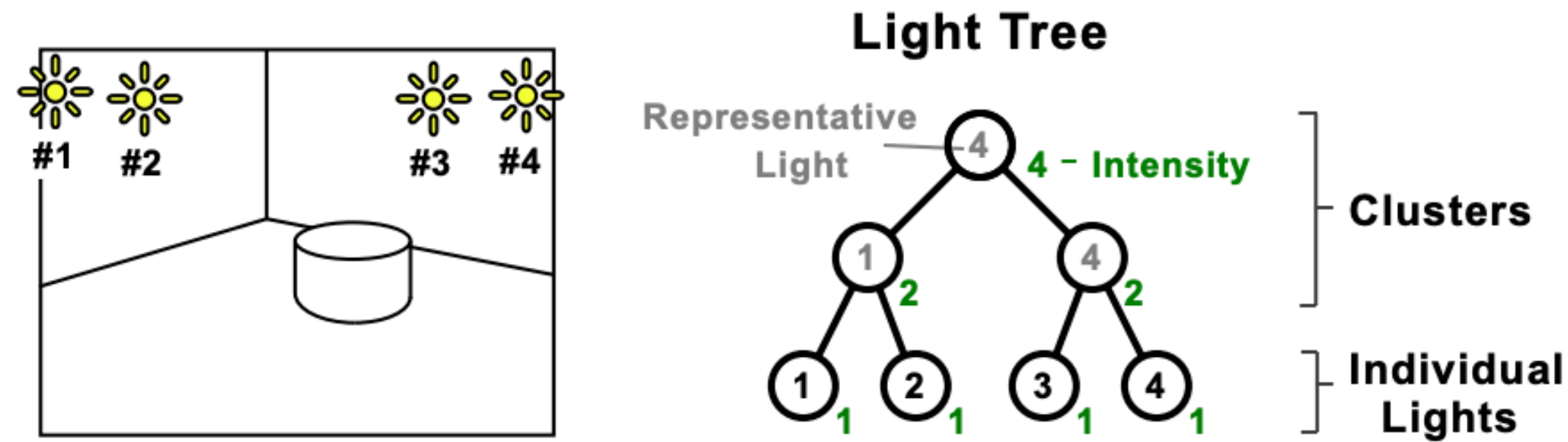
Implicitly adaptive importance sampling

Topi Paananen¹  · Juho Piironen¹  · Paul-Christian Bürkner¹  · Aki Vehtari¹ 

A layered multiple importance sampling scheme for focused optimal Bayesian experimental design*

Chi Feng* and Youssef M. Marzouk[†]

Next: many-lights sampling



Lightcuts: A Scalable Approach to Illumination