

Low-discrepancy sequences (aka Quasi Monte Carlo methods)

UCSD CSE 272
Advanced Image Synthesis

Tzu-Mao Li

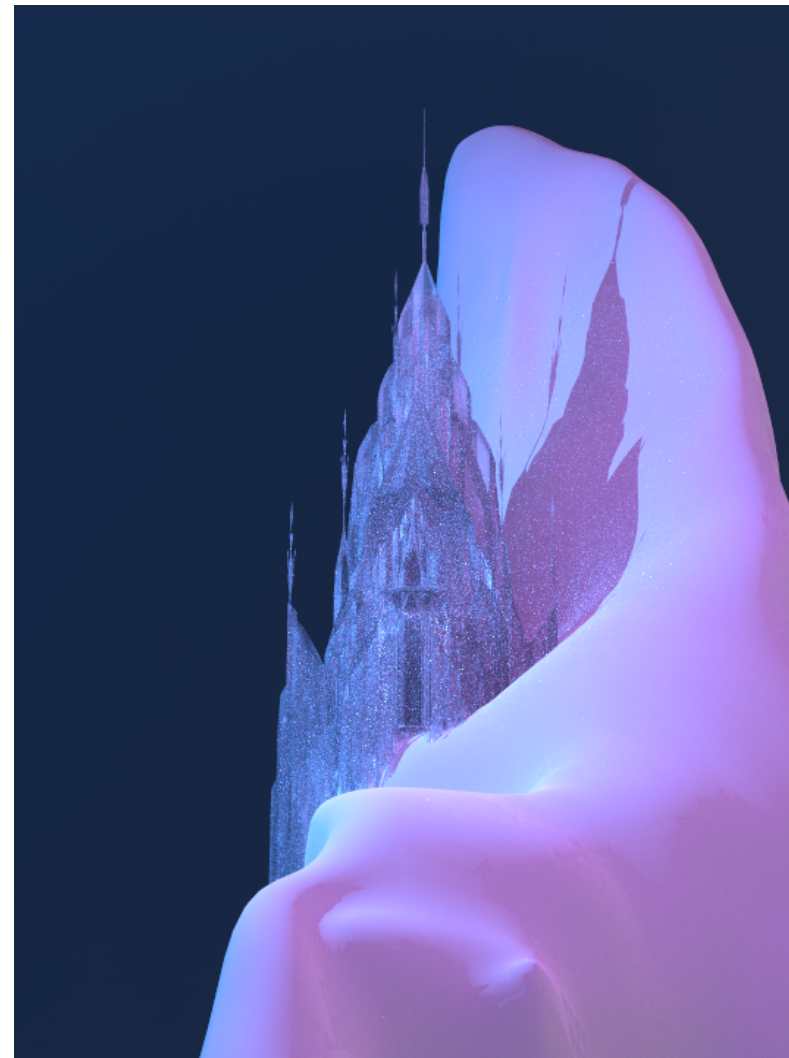
slides are largely inspired by Wojciech Jarosz and Lois Paulin

HW1 graded



Haolin Lu

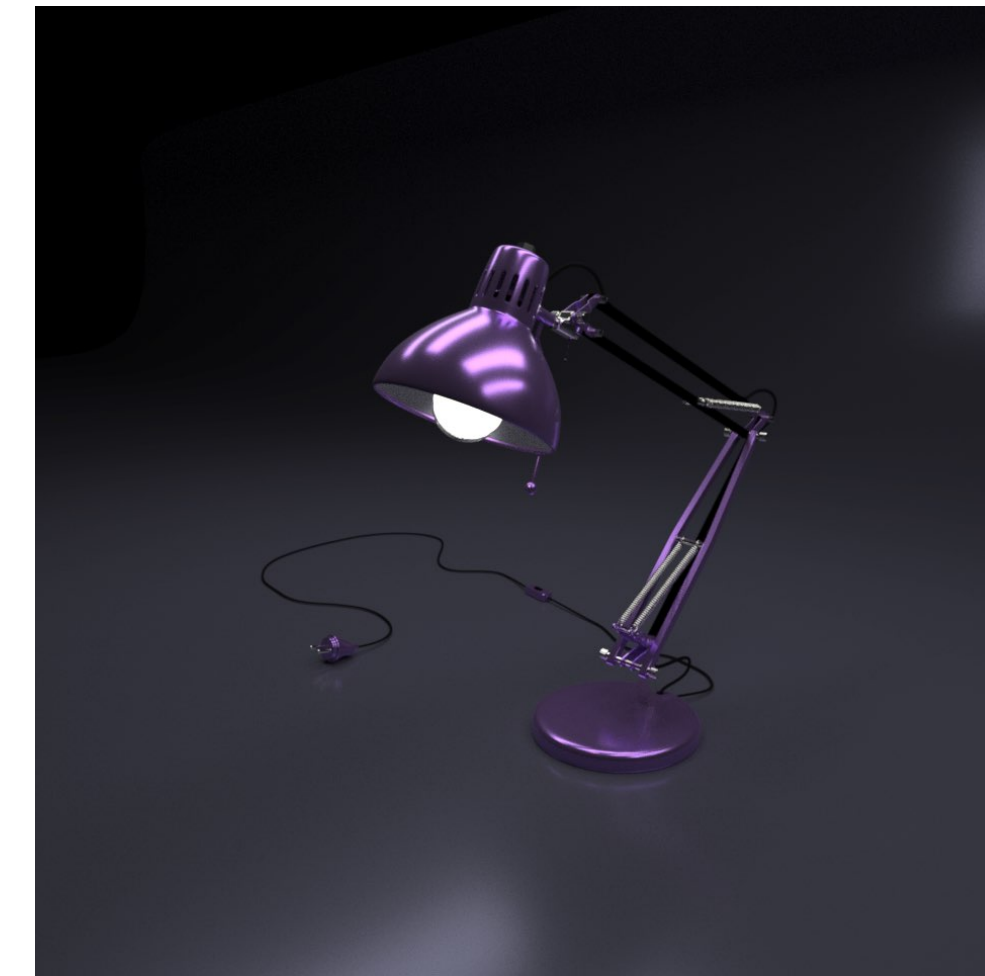
some cool images



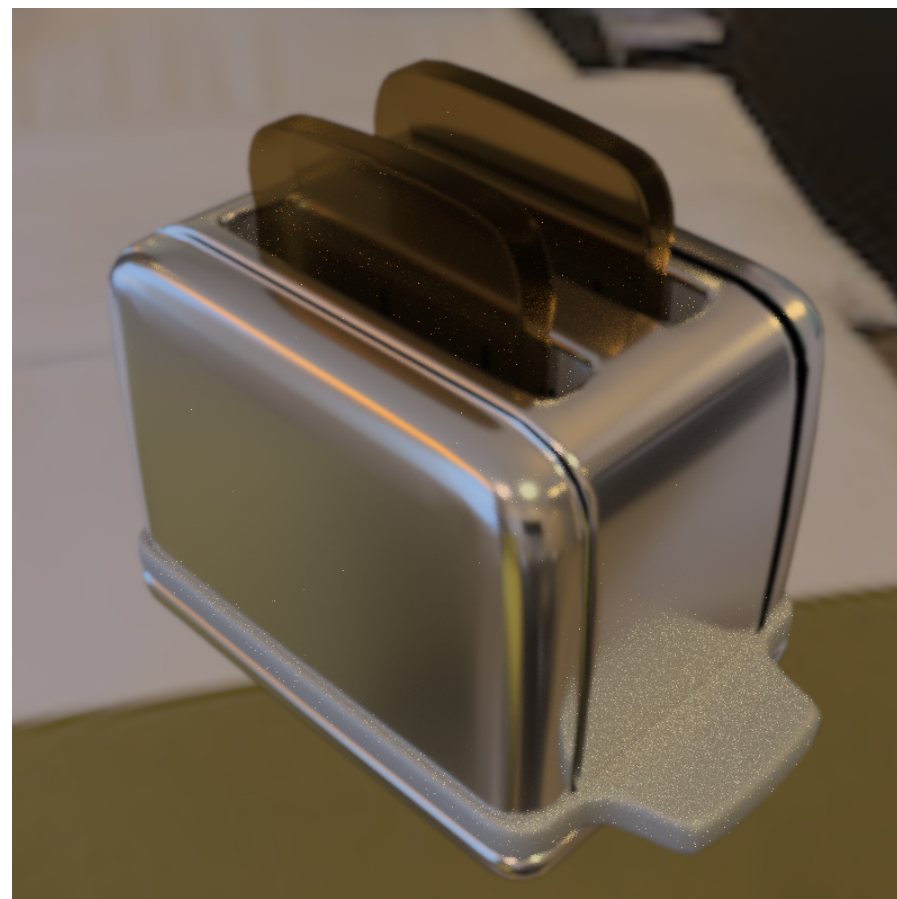
Peter Wu



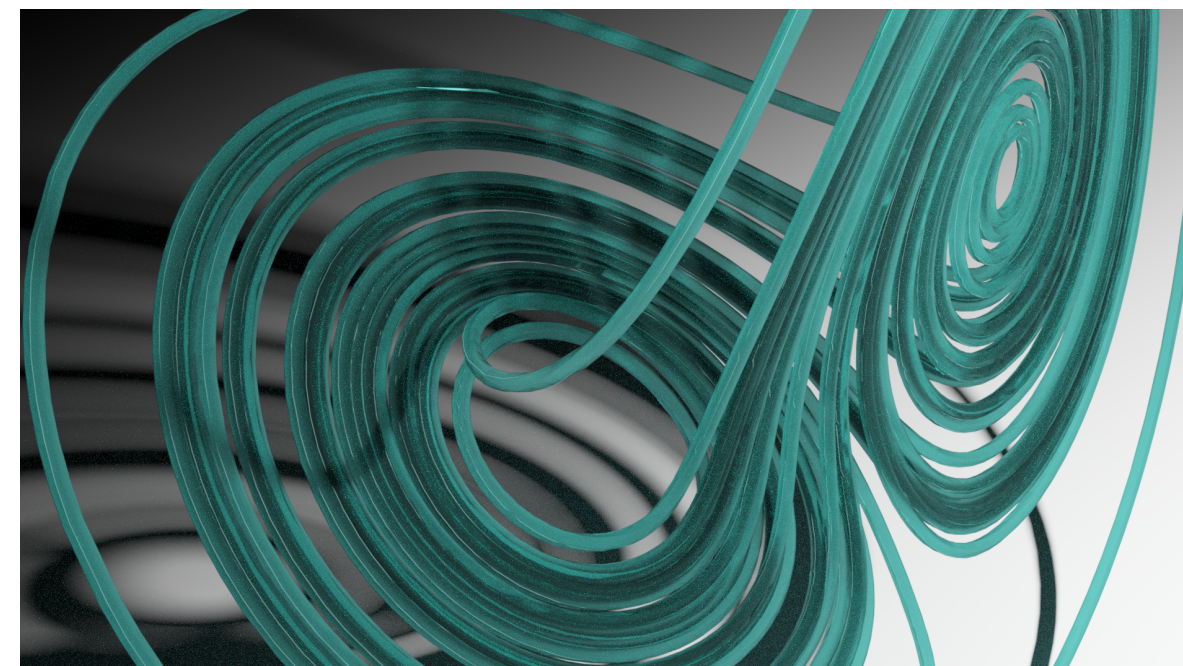
Keli Wang



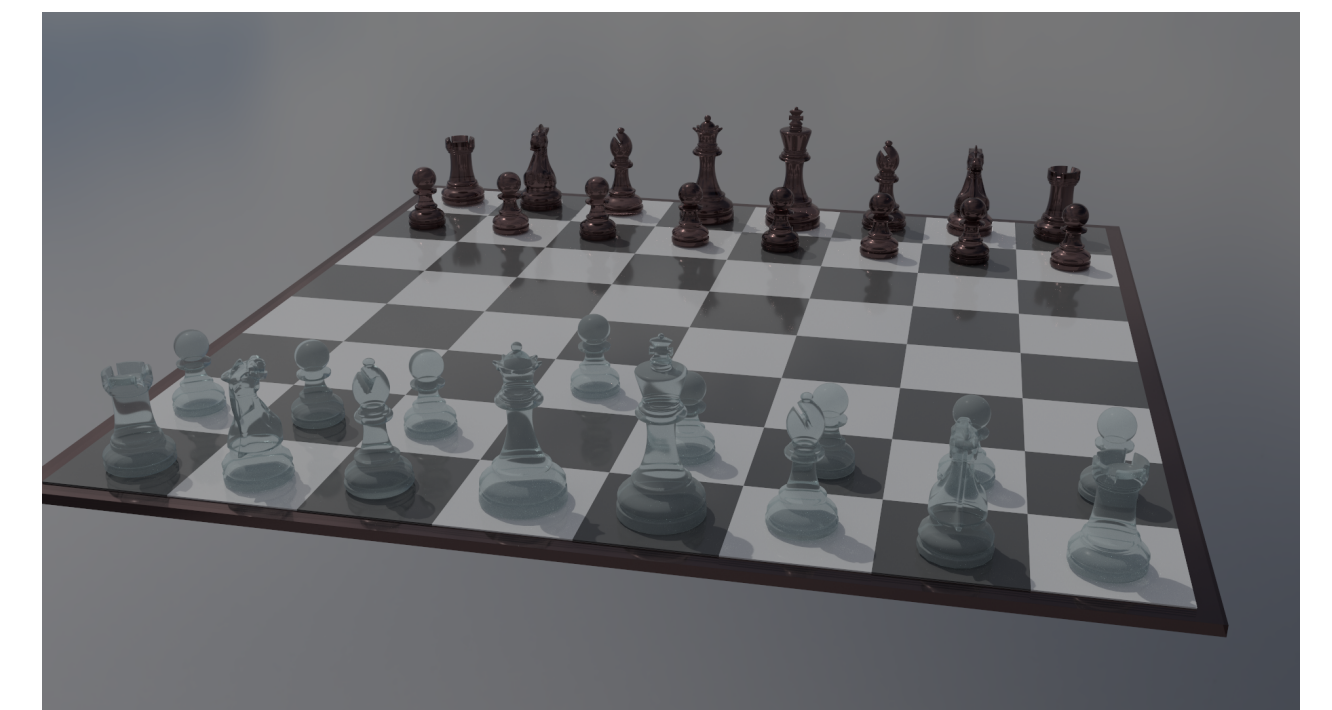
Issac Nealey



Alexander Mai



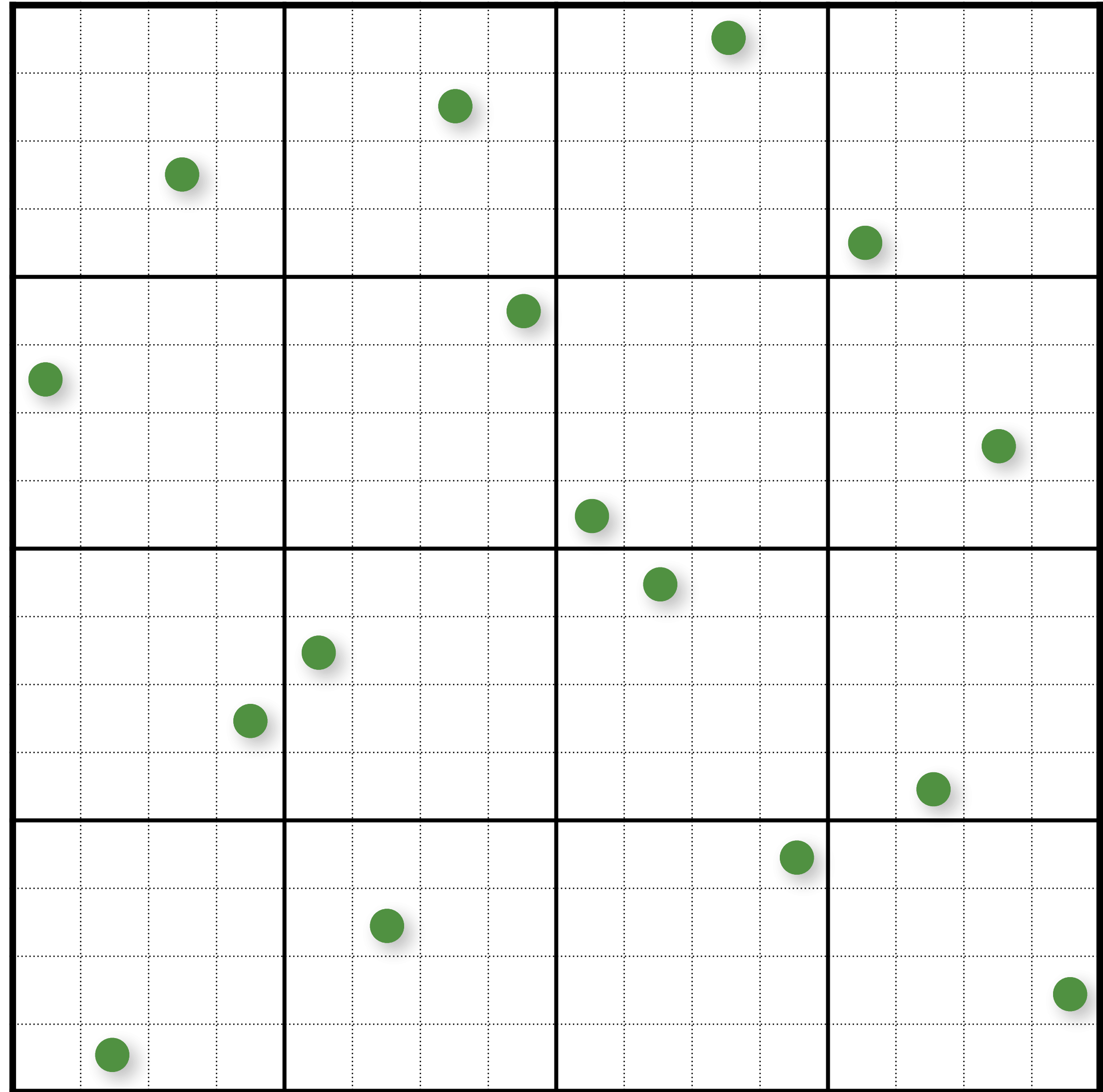
Zimu Guan



Pasha Bouzarjomehri

Multi-jittered sampling

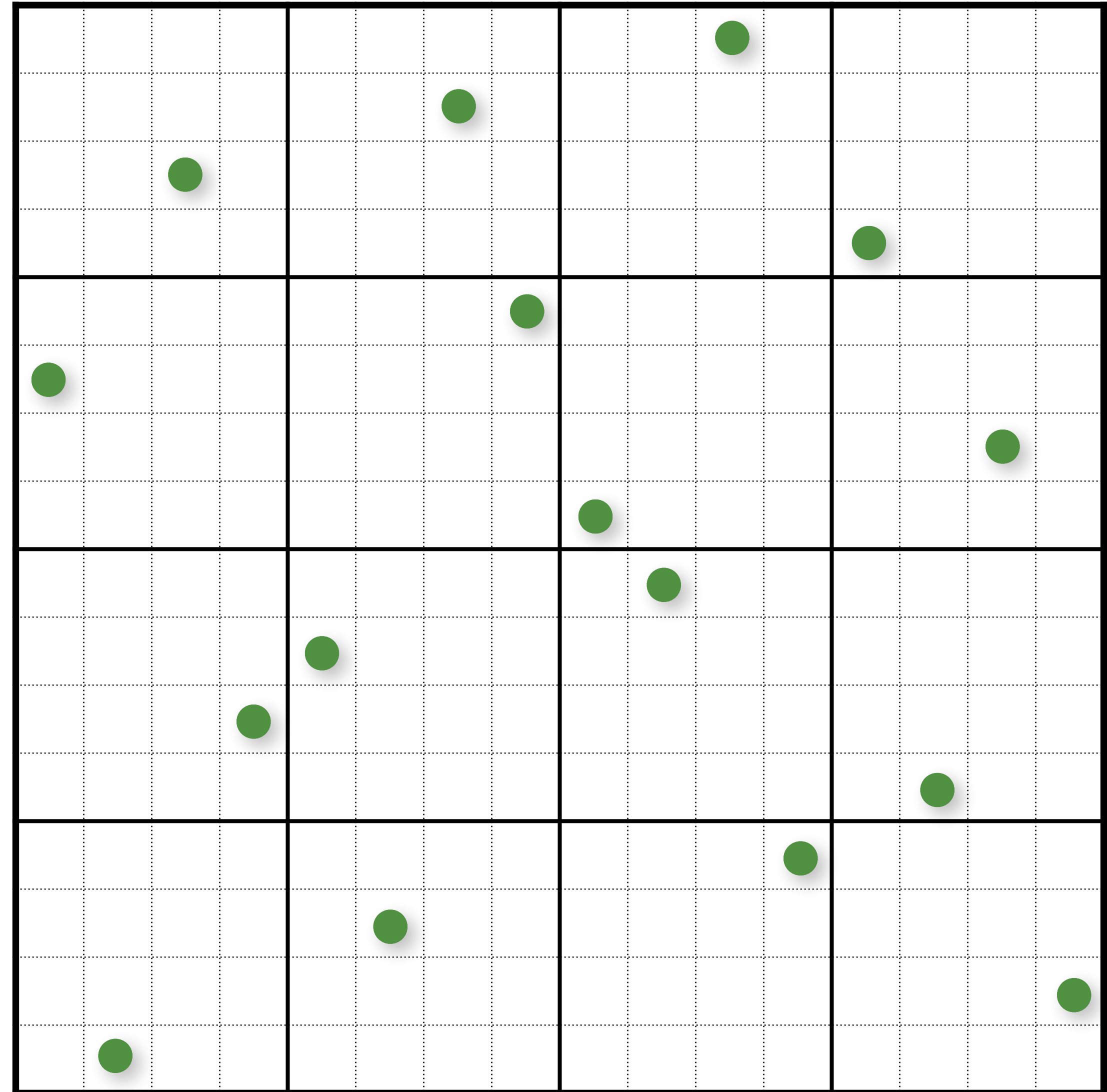
- one sample in each square
- one sample in each row
- one sample in each column



Multi-jittered sampling

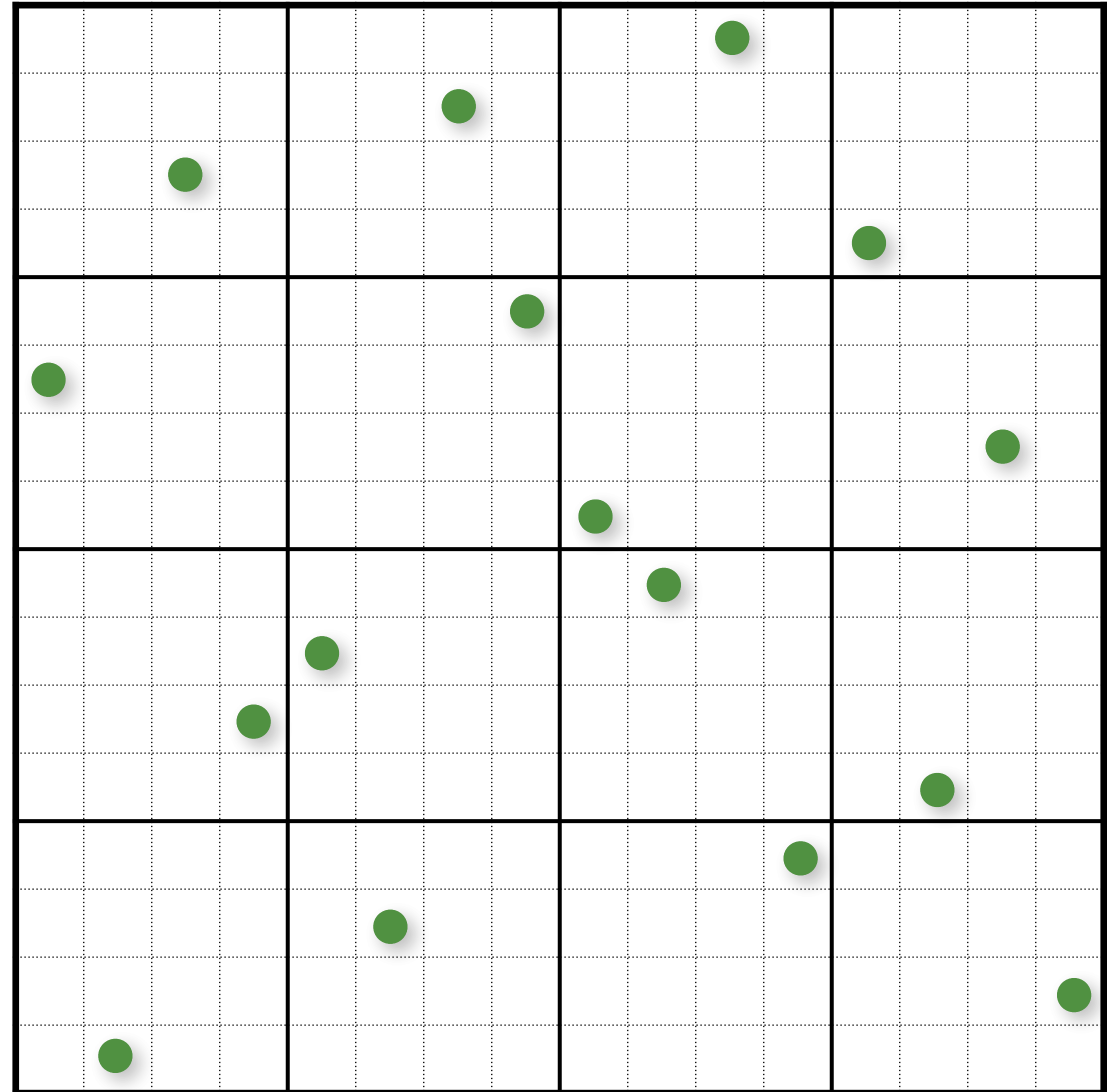
- one sample in each square
- one sample in each row
- one sample in each column

quiz: can we add more constraints to the point set?



Digital nets (aka (t,m,s) nets)

- one sample in all rectangular partition of the space



63

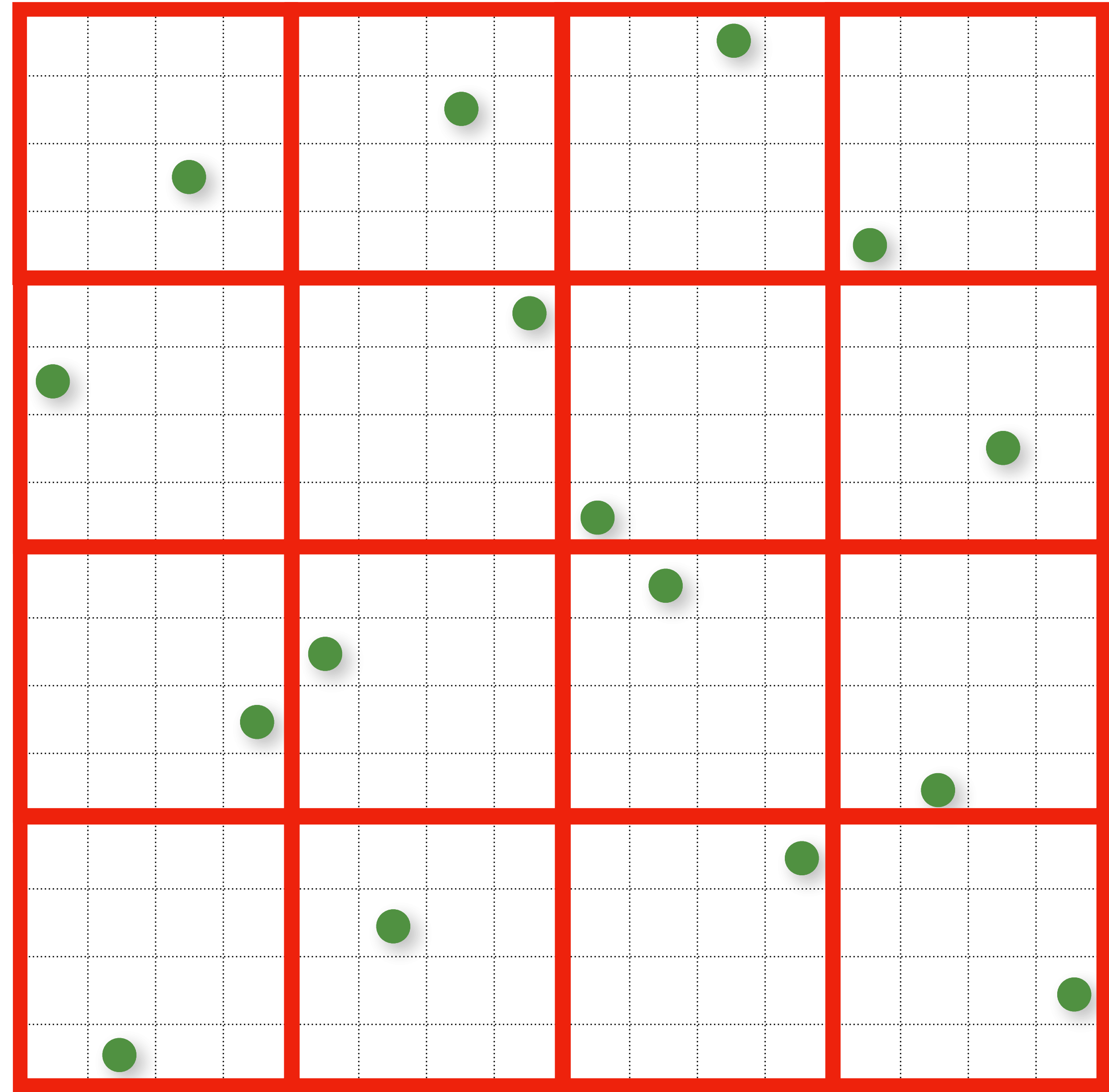
Random Number
Generation and
Quasi-Monte Carlo
Methods

HARALD NIEDERREITER
Austrian Academy of Sciences

Digital nets (aka (t,m,s) nets)

- one sample in all rectangular partition of the space

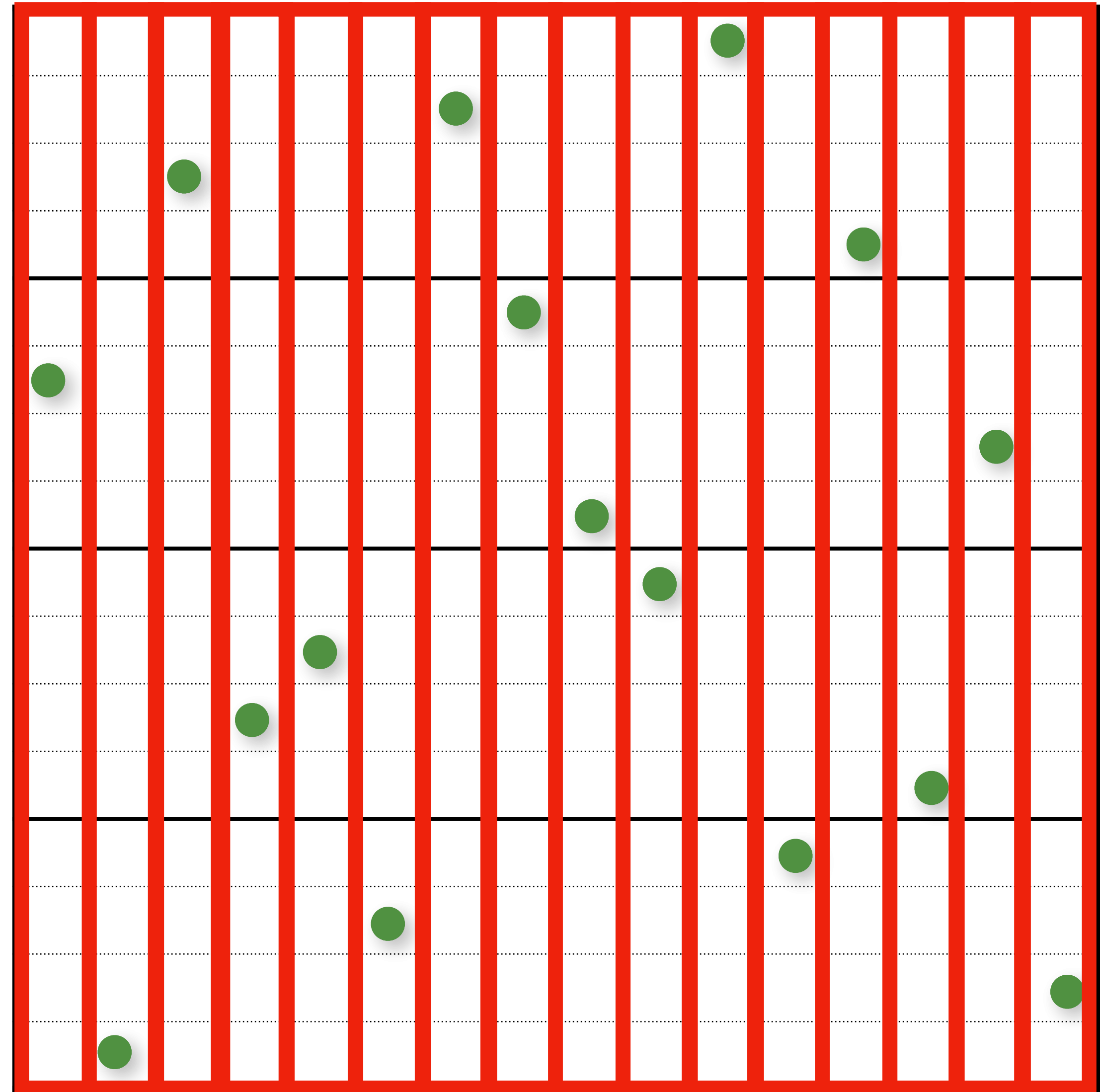
partition of 16 4×4 rectangles



Digital nets (aka (t,m,s) nets)

- one sample in all rectangular partition of the space

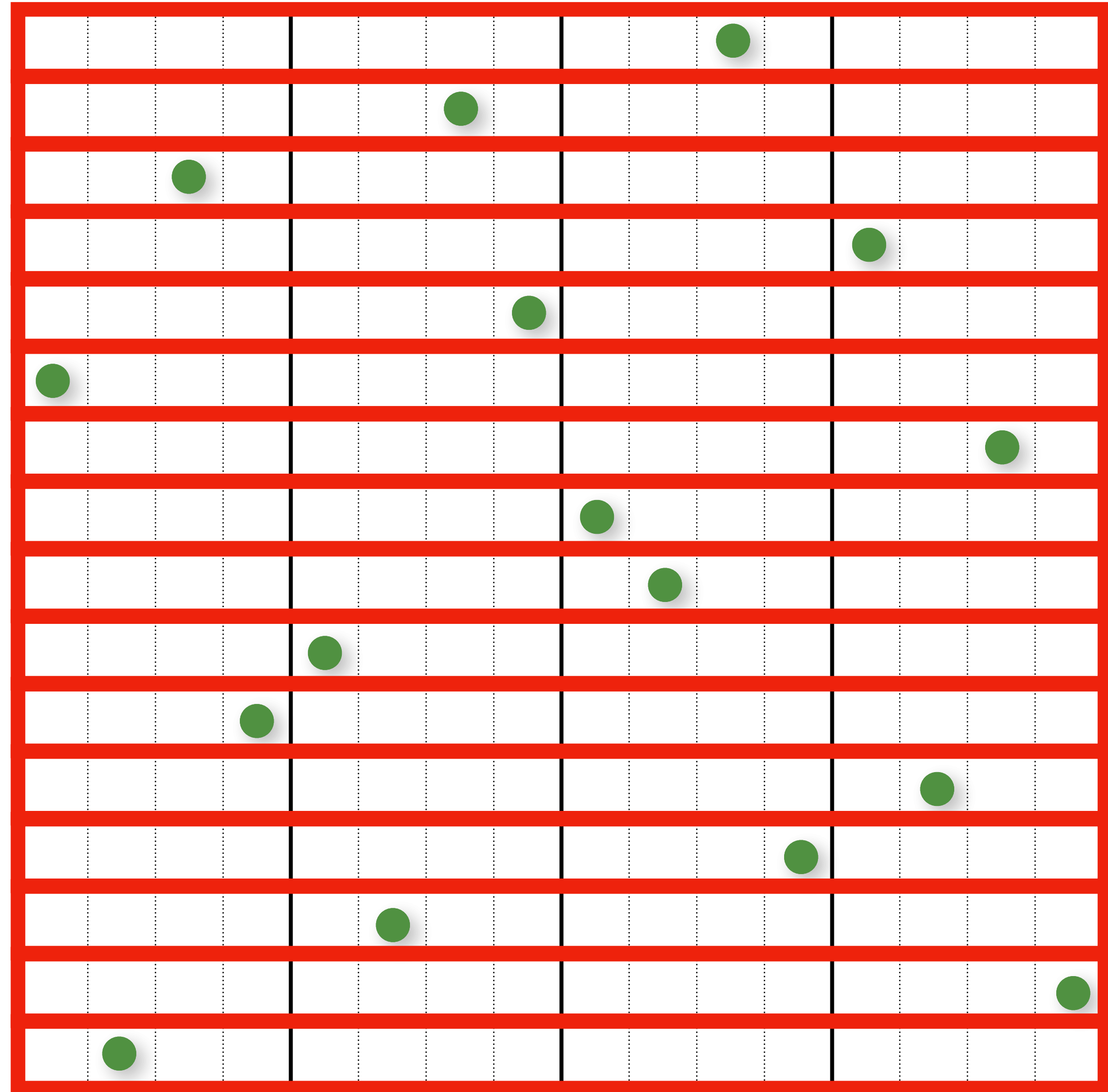
partition of 16 16×1 rectangles



Digital nets (aka (t,m,s) nets)

- one sample in all rectangular partition of the space

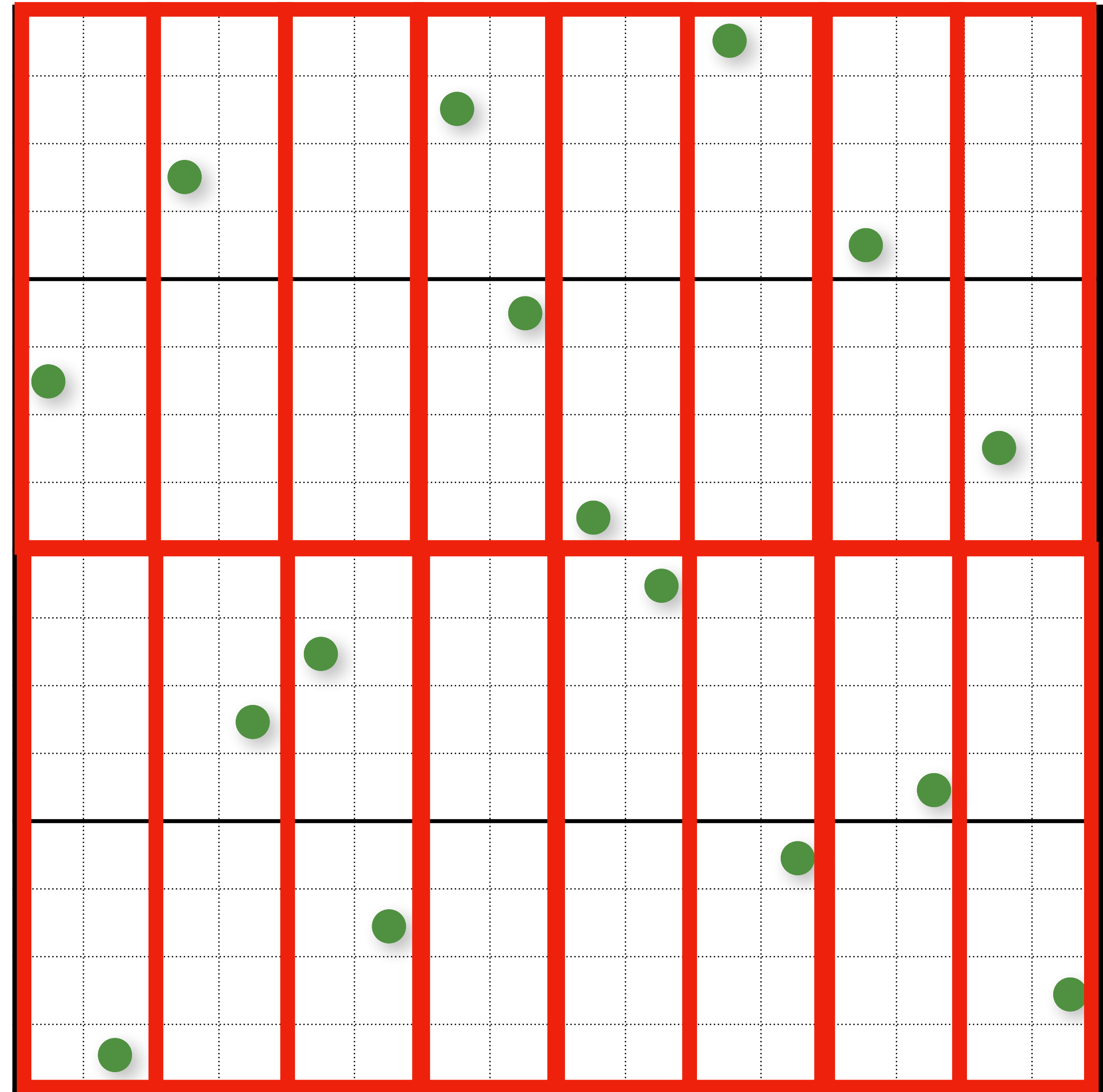
partition of 16 1×16 rectangles



Digital nets (aka (t,m,s) nets)

- one sample in all rectangular partition of the space

partition of 16 8x2 rectangles

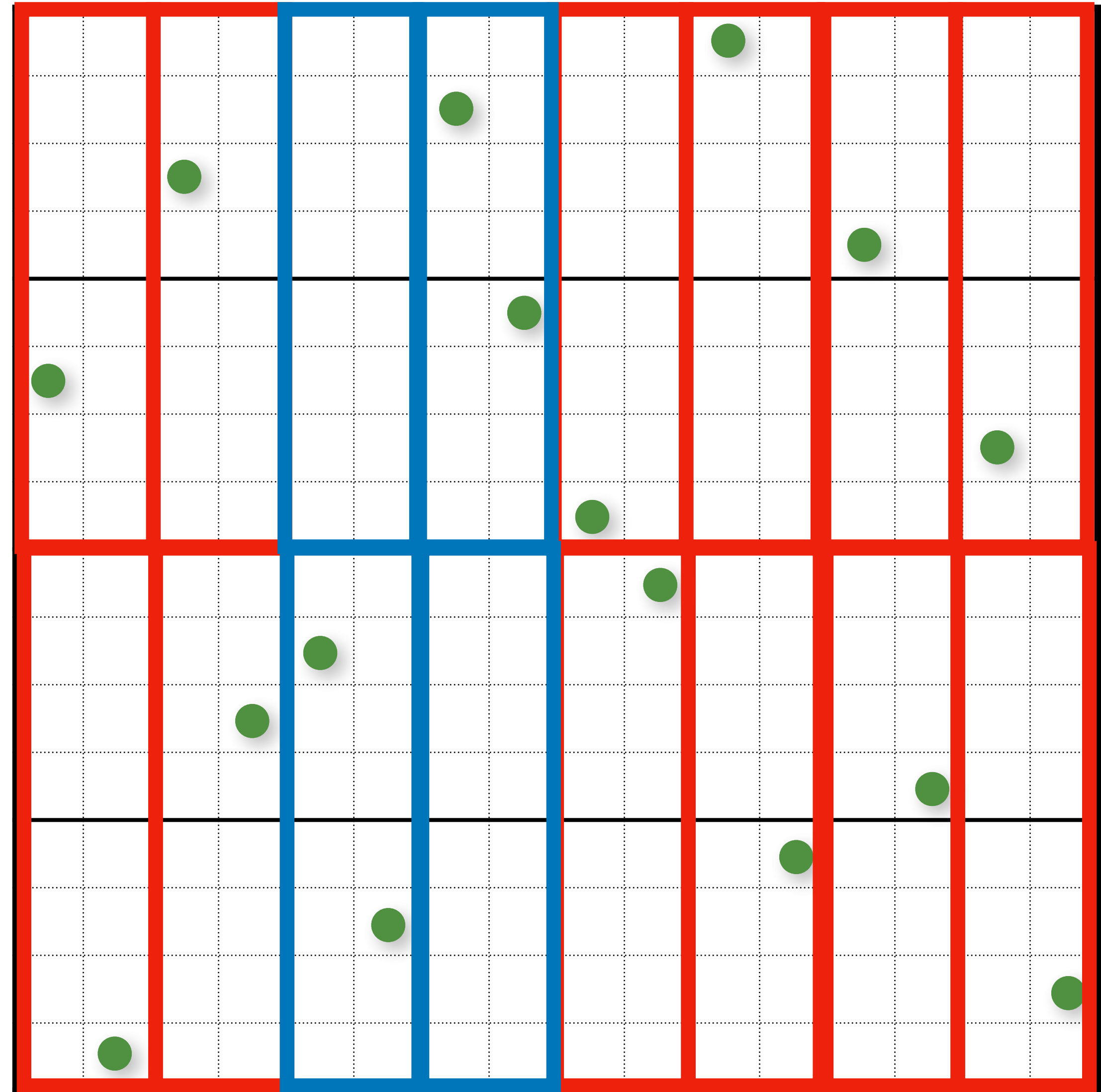


Digital nets (aka (t,m,s) nets)

- one sample in all rectangular partition of the space

partition of 16 8×2 rectangles

multi-jittered sampling fails to satisfy the digital nets property!

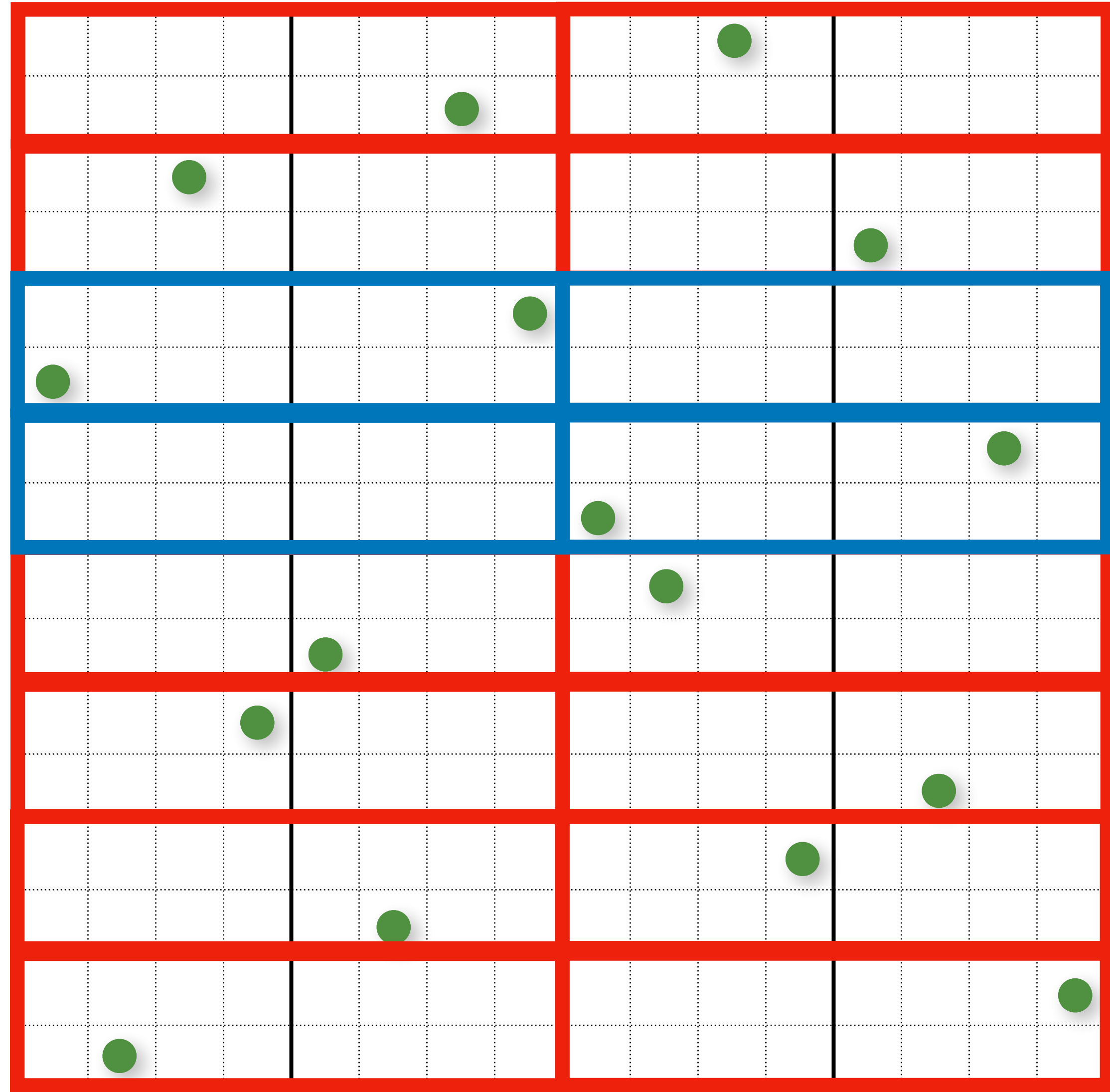


Digital nets (aka (t,m,s) nets)

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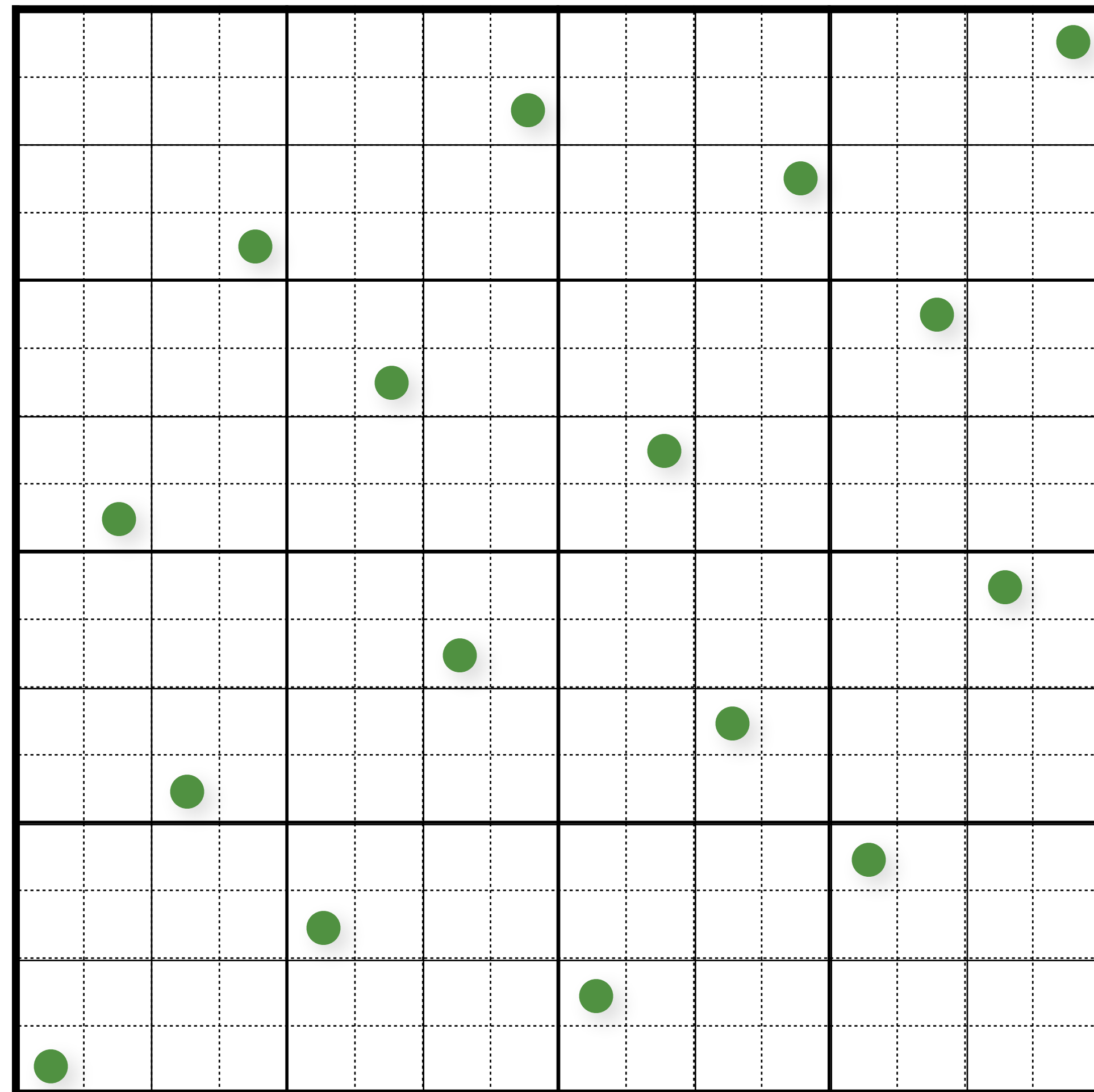
partition of 16 2×8 rectangles

multi-jittered sampling fails to satisfy the digital nets property!



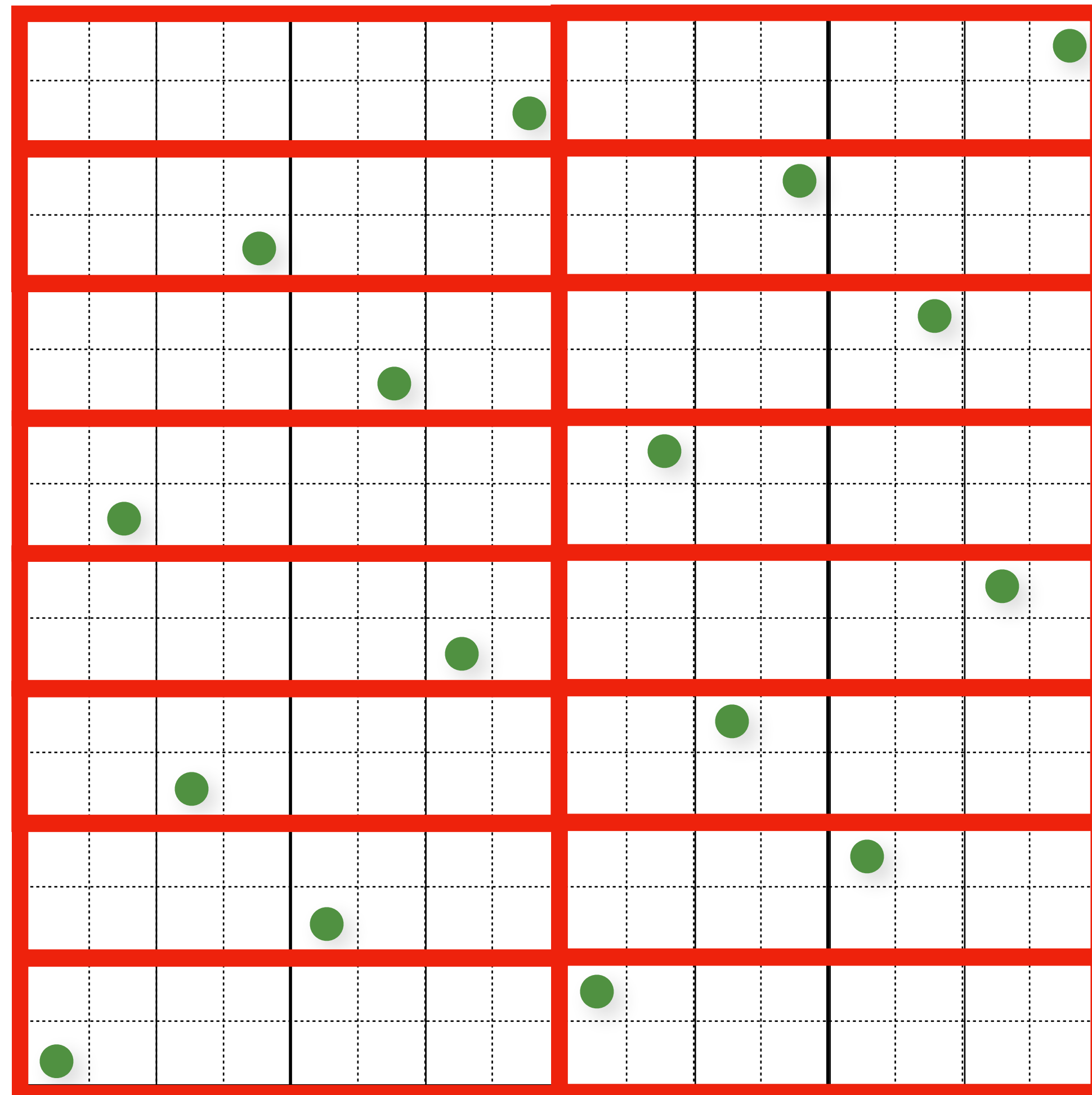
A point set that satisfies the digital net property

- one sample in all rectangular
partition of the space



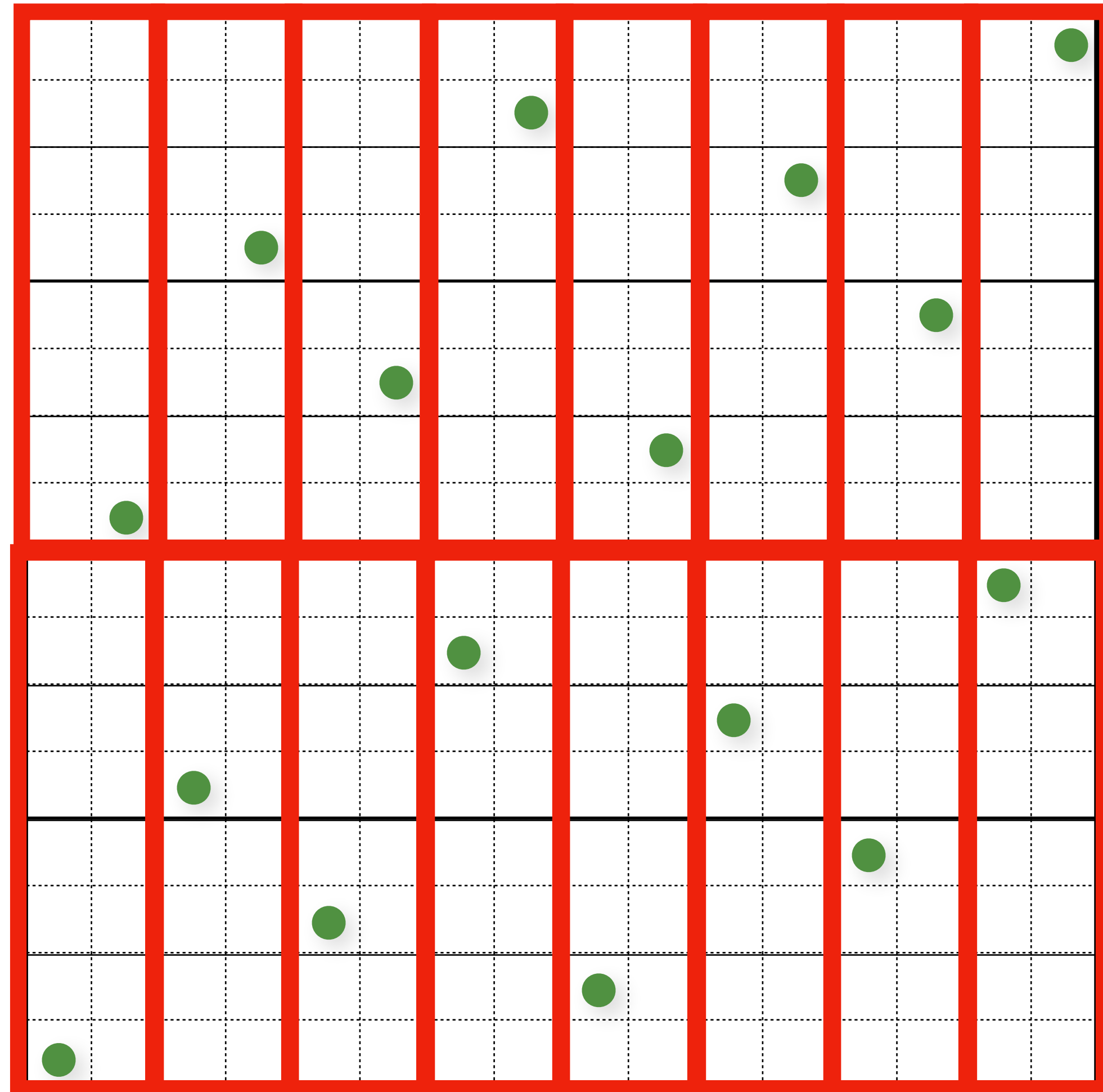
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A point set that satisfies the digital net property

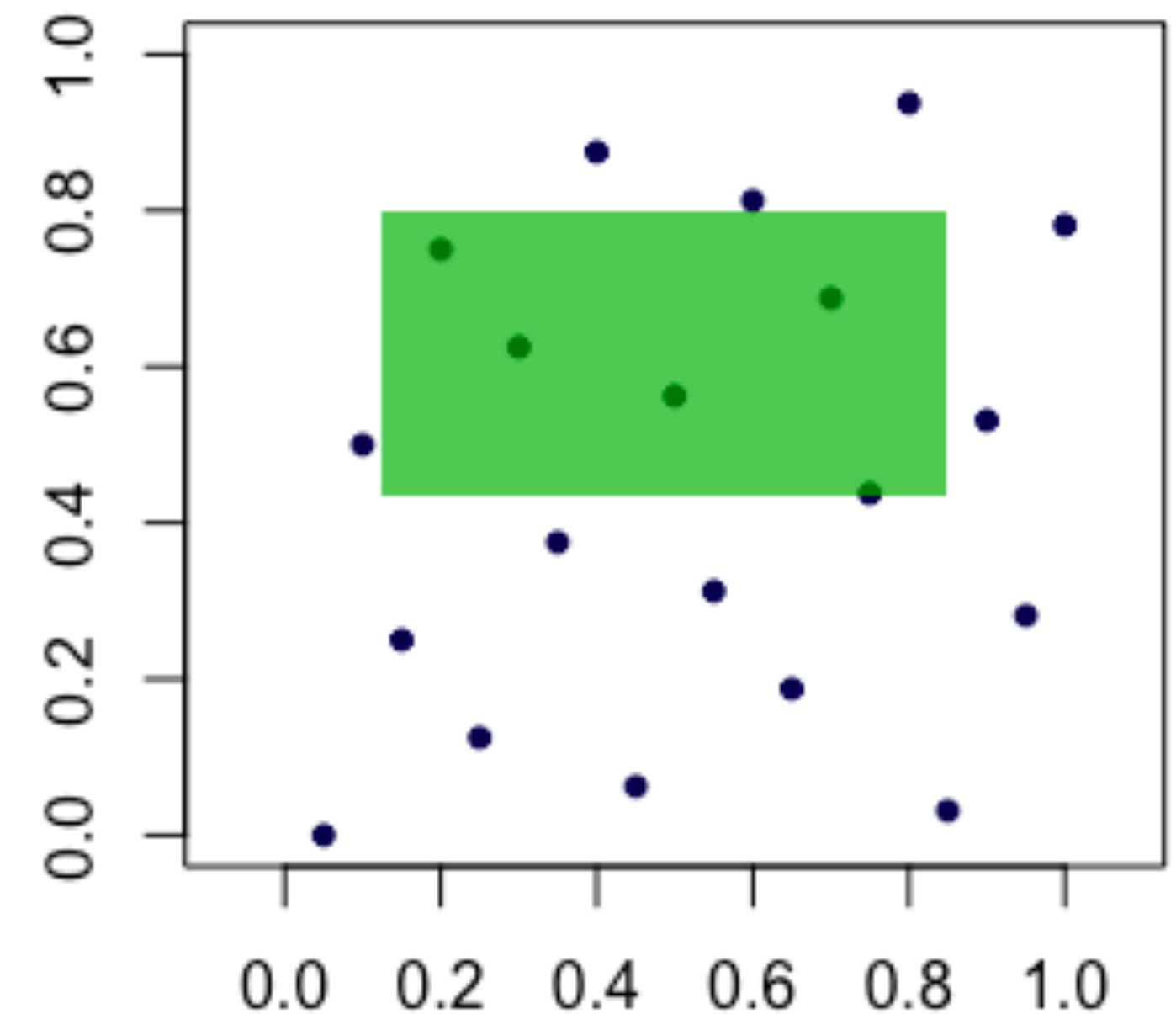
- one sample in all rectangular
partition of the space



Low-discrepancy sequences

- deterministic & progressive Latin hypercube samples based on the minimization of **discrepancy**
- entire field of study called “Quasi-Monte-Carlo”

$$D_n = \max_{\text{all rectangles}} \left| \frac{\text{no. of points in the rectangle}}{n} - \text{area}(\text{rectangle}) \right|$$



Koksma-Hlawka inequality

- discrepancy is the upper bound of the absolute estimation error!

$$\left| \frac{1}{n} \sum_{i=0}^n f(x_i) - \int f(x) dx \right| \leq V(f) D_n^*(x_1, x_2, \dots, x_n)$$

V: the "total variation" of f

star discrepancy: only consider rectangles with one vertex at the origin

$$D_n = \max_{\text{all rectangles}} \left| \frac{\text{no. of points in the rectangle}}{n} - \text{area}(\text{rectangle}) \right|$$

The van der Corput sequence Φ_b

the simplest low-discrepancy sequence in 1D

define a sequence for a base b

k	Base 2	Φ_b
1	1	$.1_2 = 1/2$
2	10	$.01_2 = 1/4$
3	11	$.11_2 = 3/4$
4	100	$.001_2 = 1/8$
5	101	$.101_2 = 5/8$
6	110	$.011_2 = 3/8$
7	111	$.111_2 = 7/8$
...		



The van der Corput sequence Φ_b

the simplest low-discrepancy sequence in 1D

define a sequence for a base b

k	Base 3	Φ_b
1	1	$.1_3 = 1/3$
2	2	$.2_3 = 2/3$
3	10	$.01_3 = 1/9$
4	11	$.11_3 = 4/9$
5	12	$.21_3 = 7/9$
6	20	$.02_3 = 2/9$
7	21	$.12_3 = 5/9$
...		

The van der Corput sequence Φ_b

subdivide the 1D space
into b regions



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sample the boundaries



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recurse into each region



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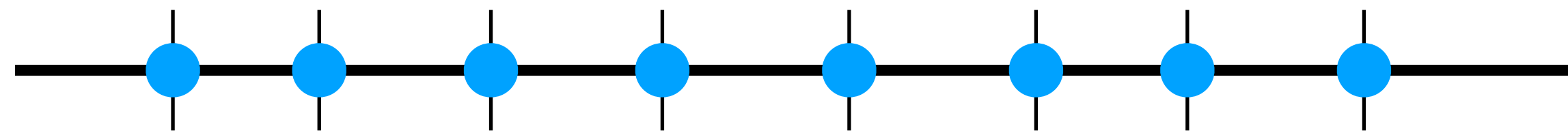
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3	10	$.01_3 = 1/9$
4	11	$.11_3 = 4/9$
5	12	$.21_3 = 7/9$
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...		

The van der Corput sequence Φ_b

subdivide the 1D space
into b regions

sample the boundaries

recurse into each region

k	Base 10	Φ_b
1	1	$.1_{10} = 1/10$
5	5	$.5_{10} = 5/10$
9	9	$.9_{10} = 9/10$
10	10	$.01_{10} = 1/100$
11	11	$.11_{10} = 11/100$
12	12	$.21_{10} = 21/100$
21	21	$.12_{10} = 12/100$
...		

High-dimensional generalization of van der Corput sequence: Halton sequence

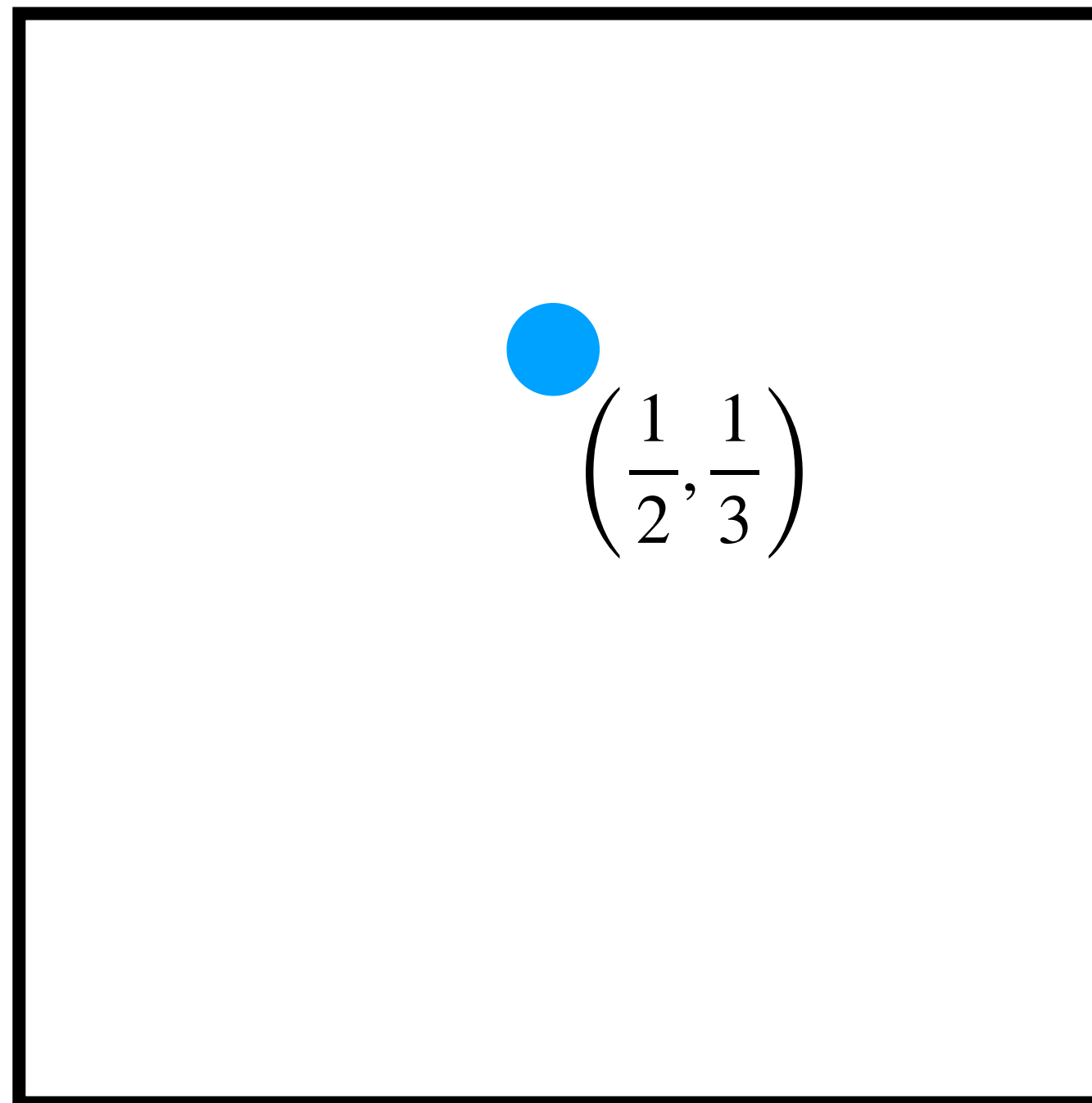
$$\text{Halton}(k) = (\Phi_2(k), \Phi_3(k), \Phi_5(k), \dots)$$

concatenate van der Corput sequences with co-prime bases into a vector

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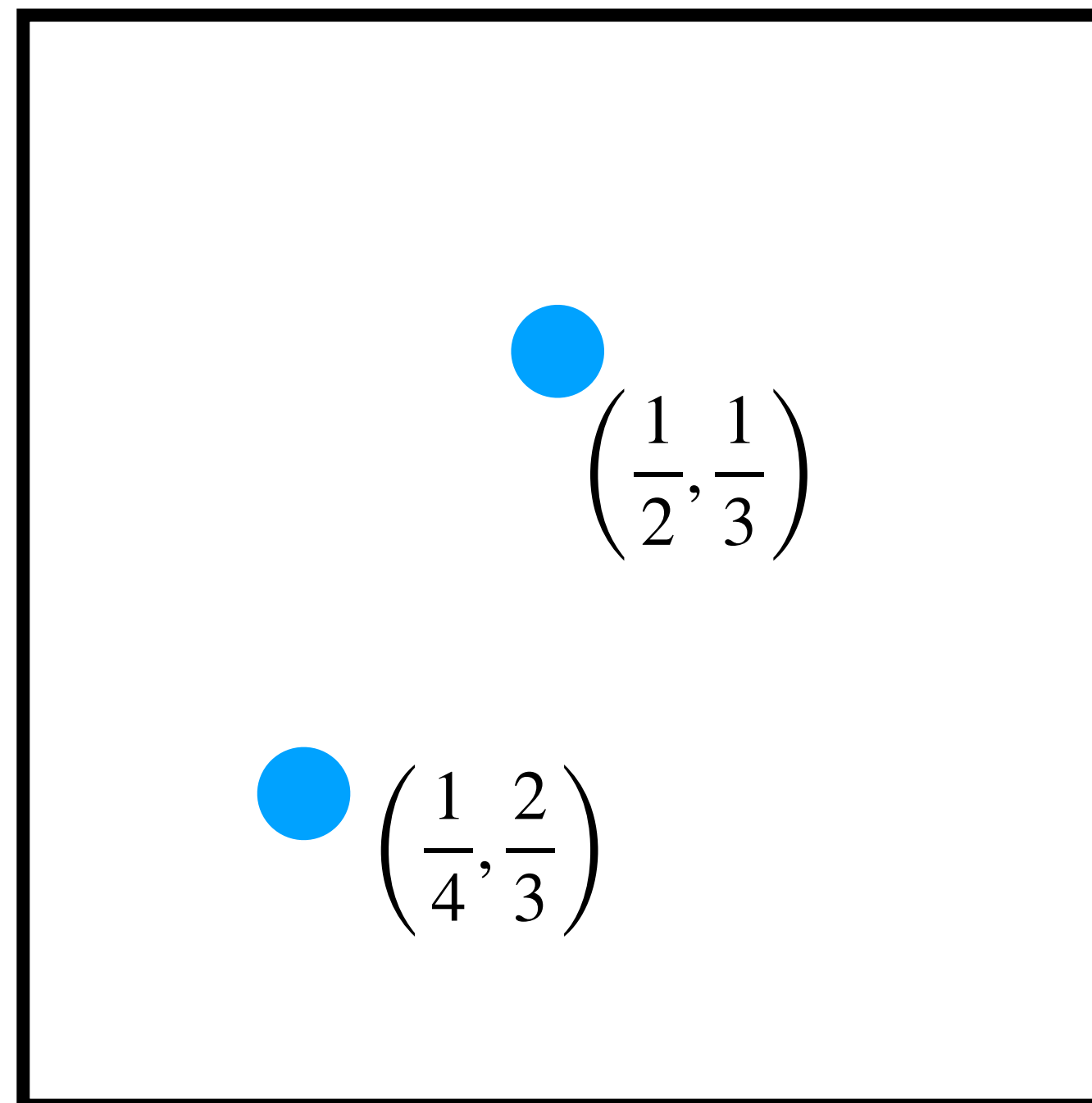


ALGORITHM 247
RADICAL-INVERSE QUASI-RANDOM POINT
SEQUENCE [G5]
J. H. HALTON AND G. B. SMITH (Recd. 24 Jan. 1964 and
21 July 1964)
Brookhaven National Laboratory, Upton, N. Y., and
University of Colorado, Boulder, Colo.

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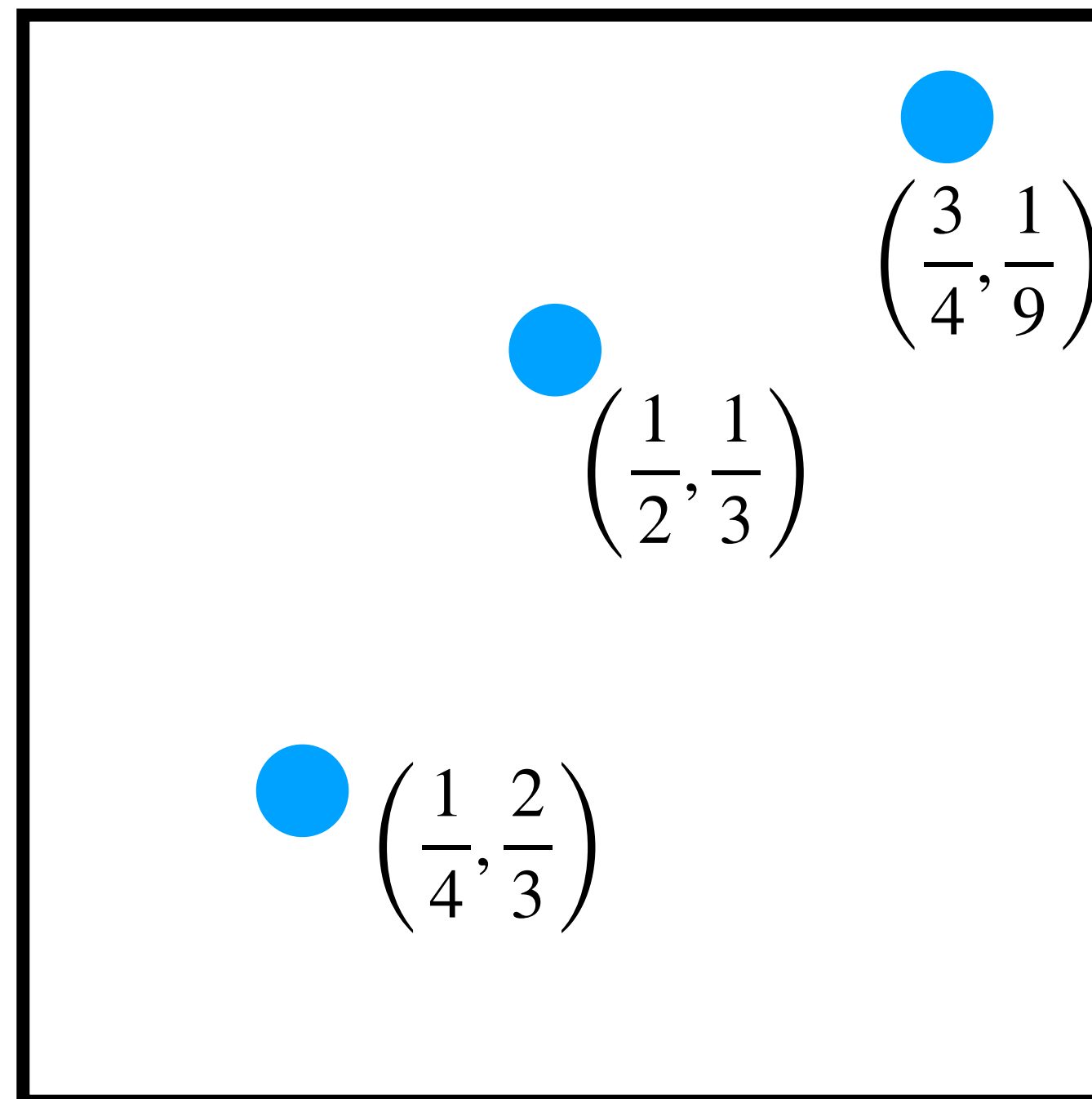


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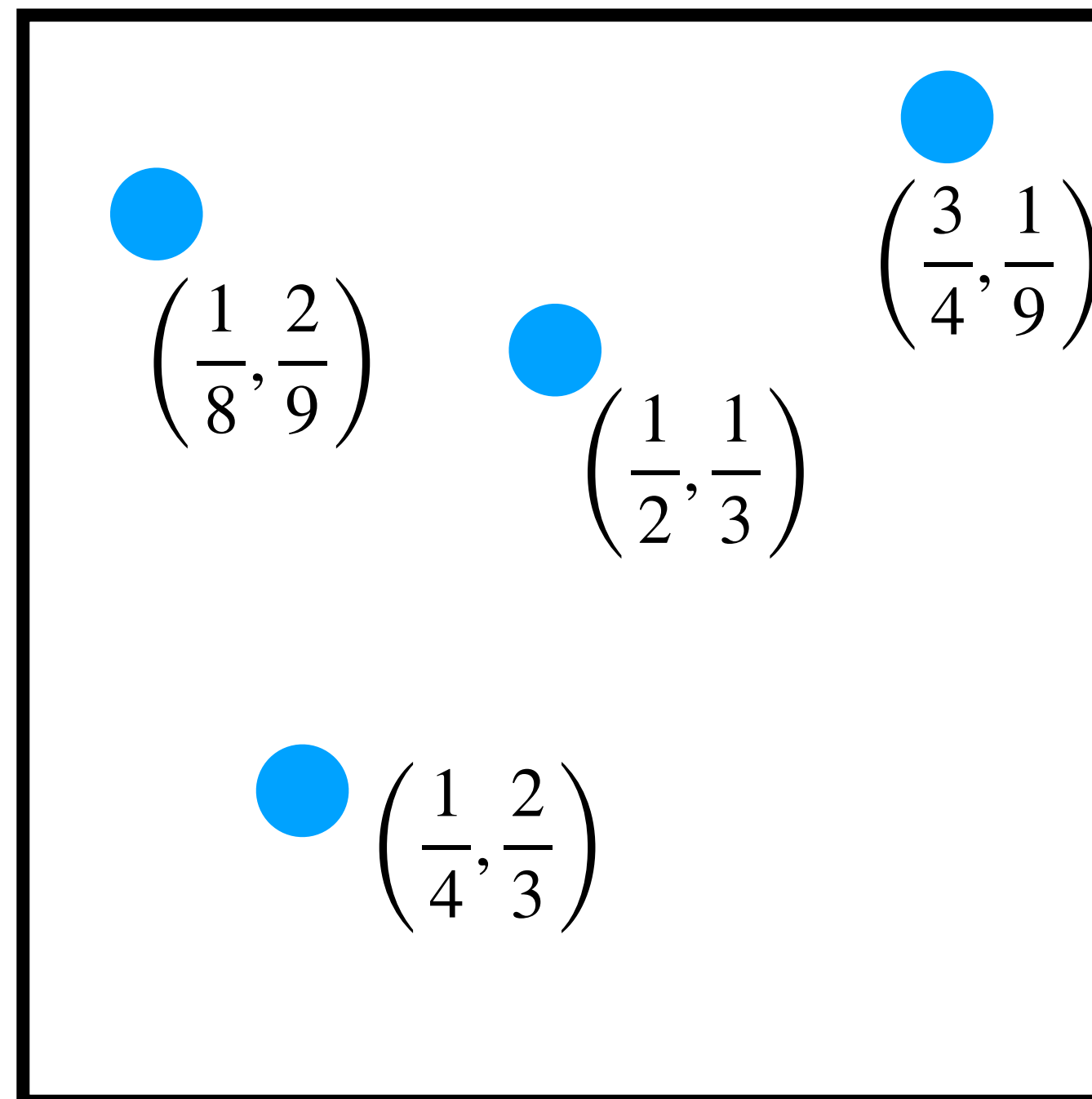


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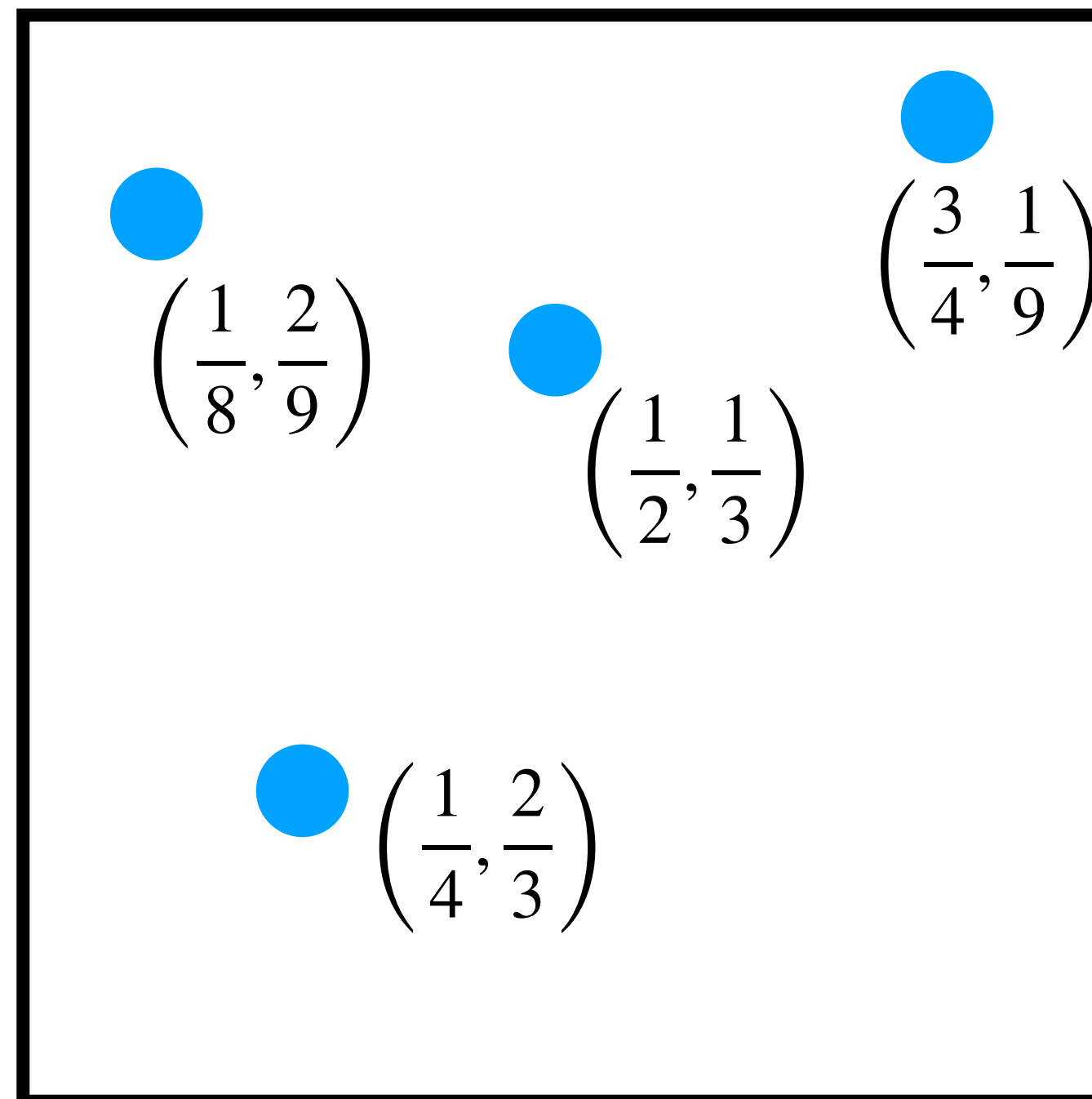
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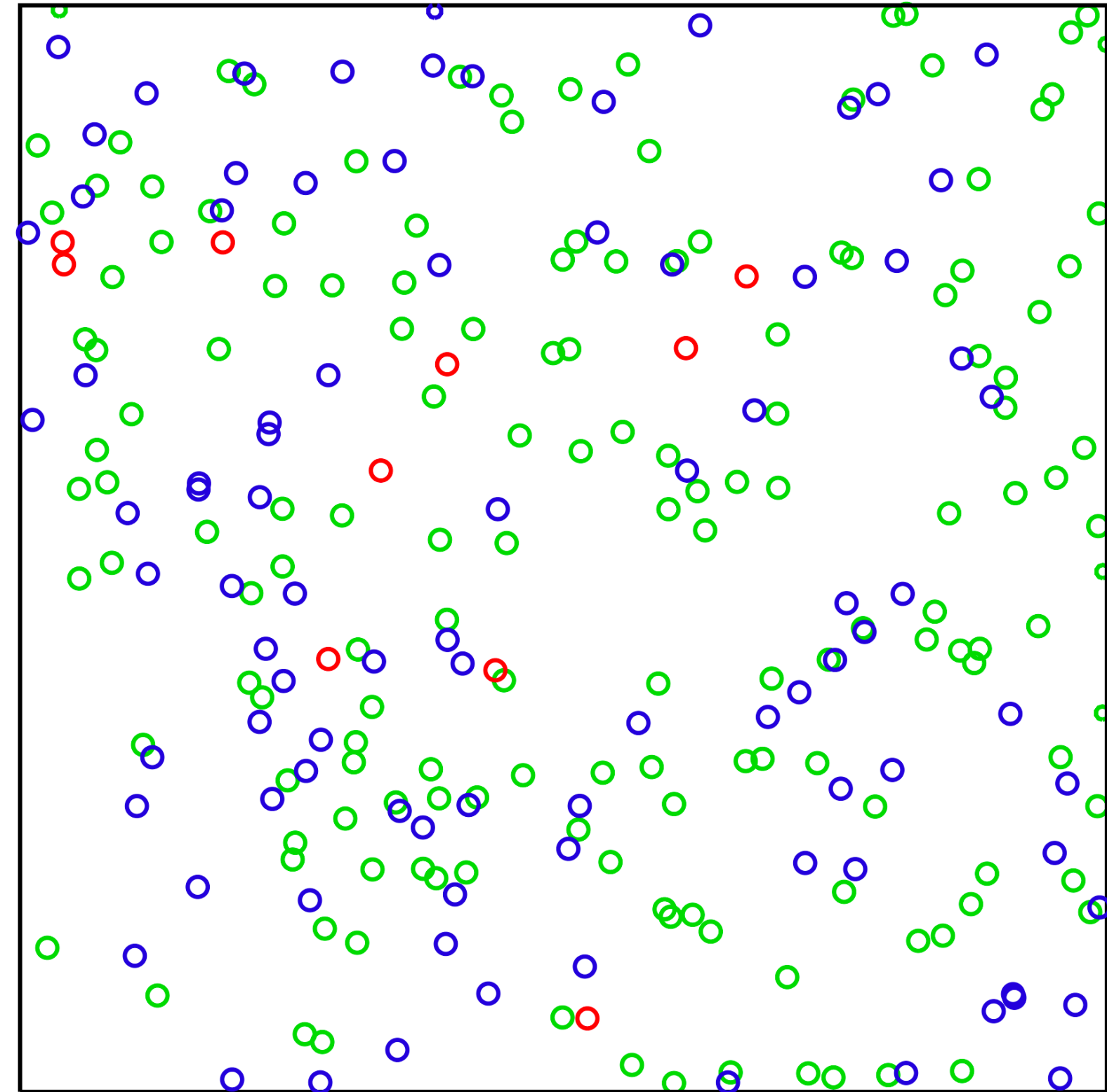
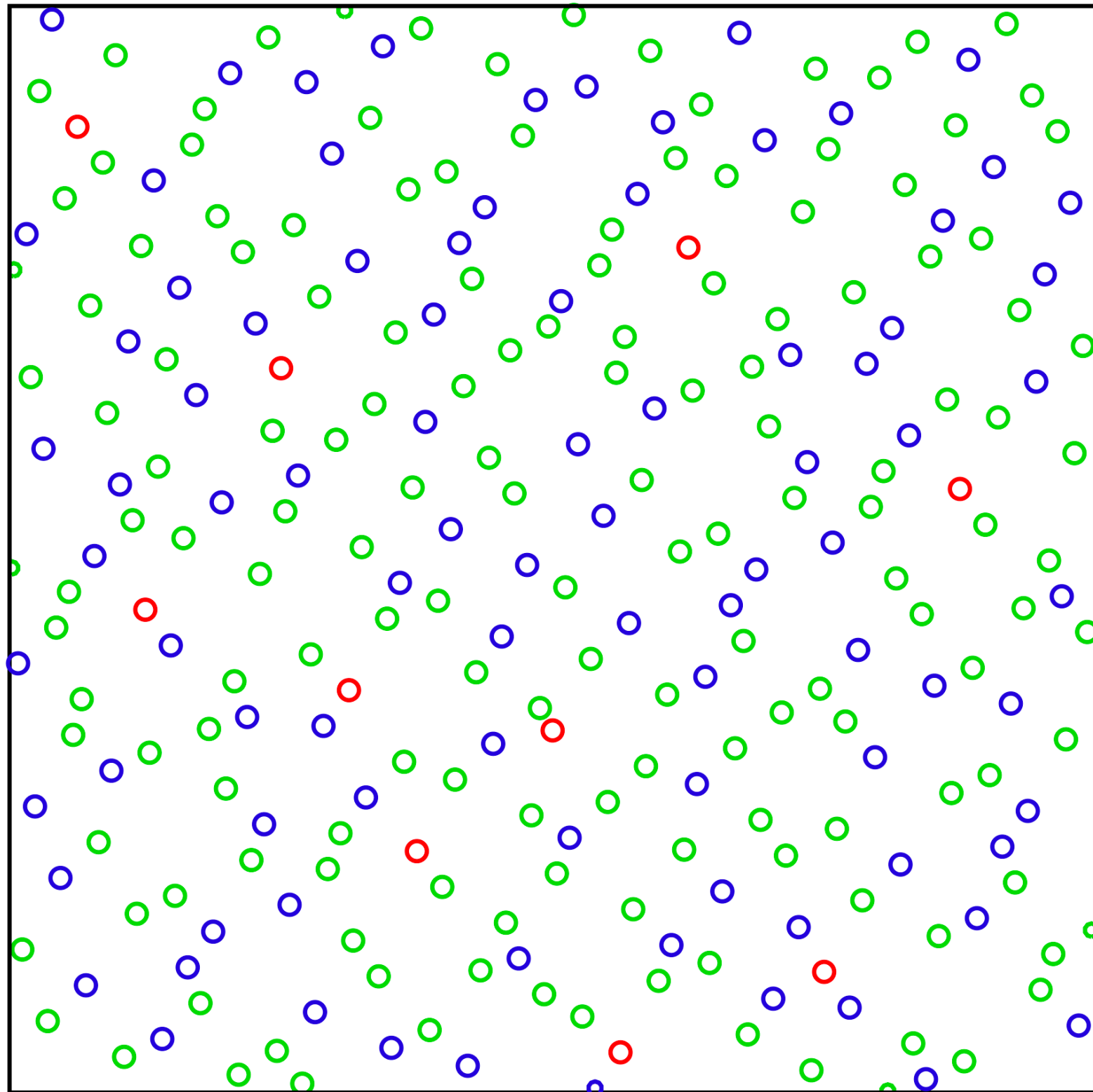
concatenate van der Corput sequences with co-prime bases into a vector

progressive &
naturally generalize to
higher dimension!



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RADICAL-INVERSE QUASI-RANDOM POINT
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Halton sequence vs independent noise



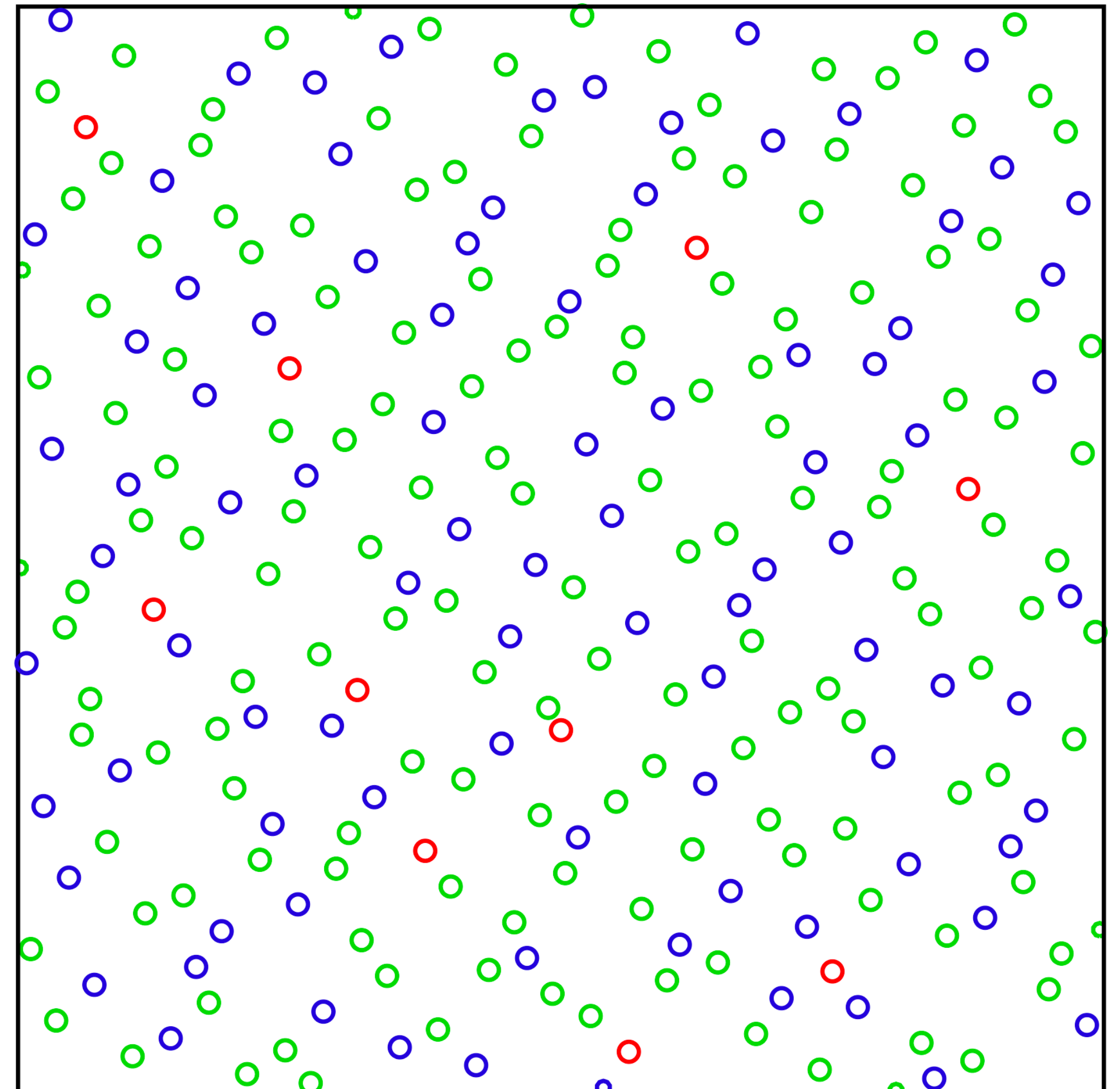
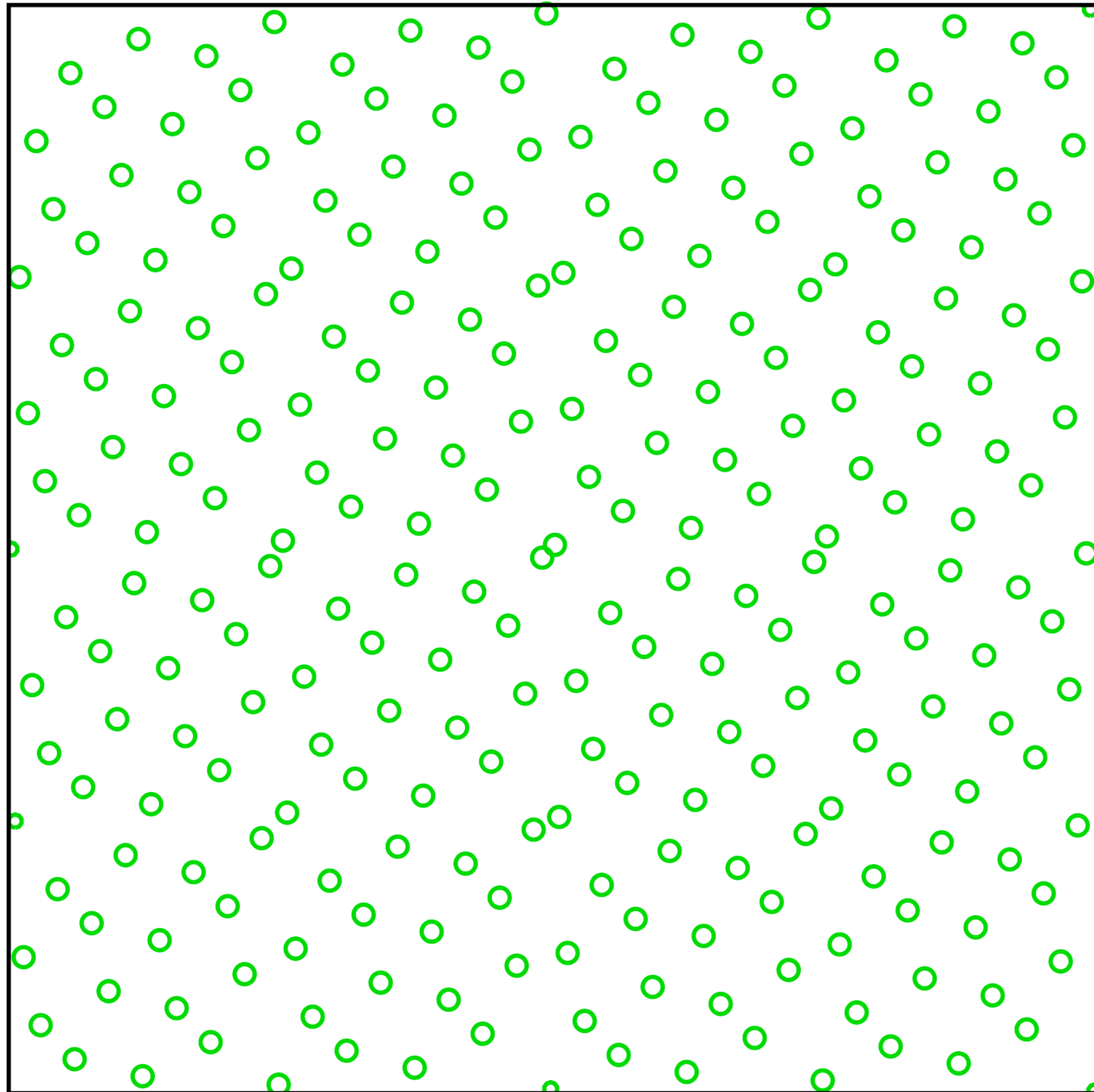
Hammersley sequence

- append Halton sequence with $\frac{k}{N}$, N is the total number of samples
- not progressive anymore, but more evenly distributed

$$\text{Halton}(k) = (\Phi_2(k), \Phi_3(k), \Phi_5(k), \dots)$$

$$\text{Hammersley}(k) = \left(\frac{k}{N}, \Phi_2(k), \Phi_3(k), \Phi_5(k), \dots \right)$$

Hammersley vs Halton sequences



https://en.wikipedia.org/wiki/Low-discrepancy_sequence

Discrepancies of Halton / Hammersley sequence

Koksma-Hlawka inequality

$$D_n^* = O\left(\frac{(\log N)^d}{N}\right)$$

$$\left| \frac{1}{n} \sum_{i=0}^n f(x_i) - \int f(x) dx \right| \leq V(f) D_n^*(x_1, x_2, \dots, x_n)$$

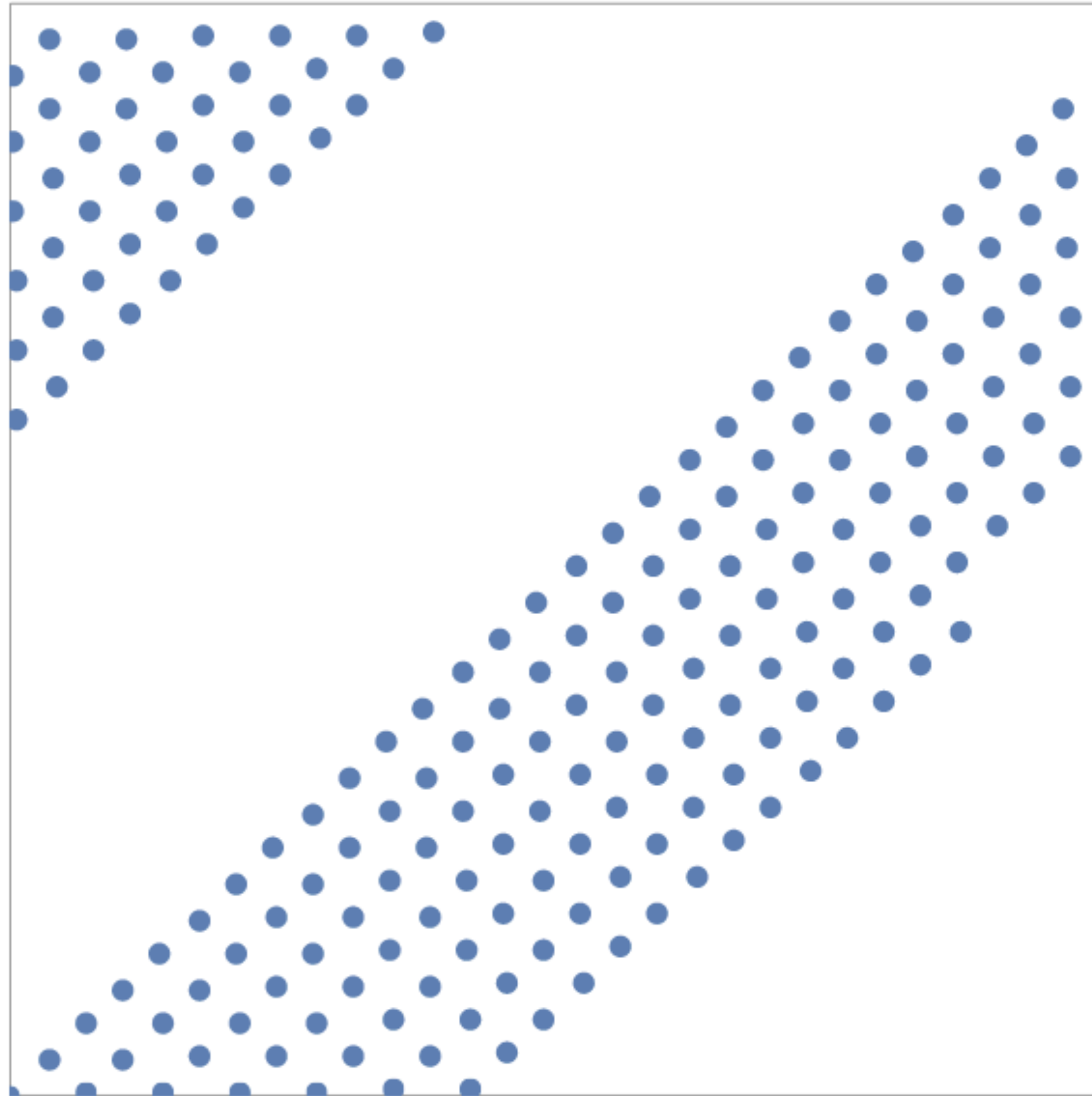
Convergence rates compared (2D)

Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
Jitter	$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-2})$
Poisson Disk	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
CCVT	$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-3})$

$$o\left(\frac{(\log N)^2}{N}\right)$$

for large N, low-discrepancy sequences win
(though note that V(f) is often unbounded in rendering)

Issues of Halton / Hammersley sequences: correlated pattern in high dimension



$$(\Phi_{29}, \Phi_{31})$$

A solution: scramble the digits of each coordinate

scrambling preserves (often improves) discrepancy!

$$\Phi_{29}(k) = 0.abcdefg_{29}$$



scramble

$$\Phi_{29}(k) = 0.cdabgfe_{29}$$

apply the same scramble to all k !

1992

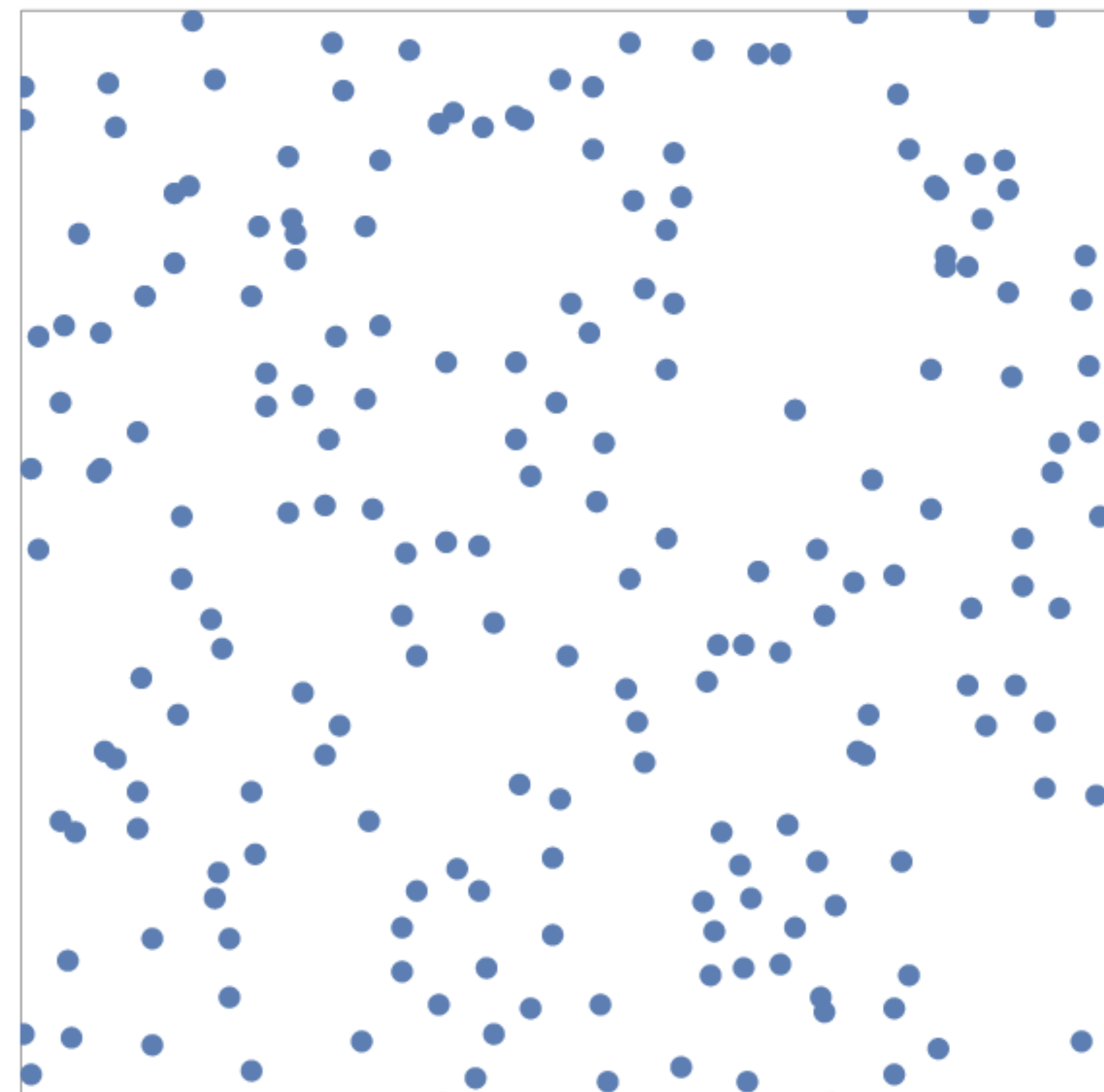
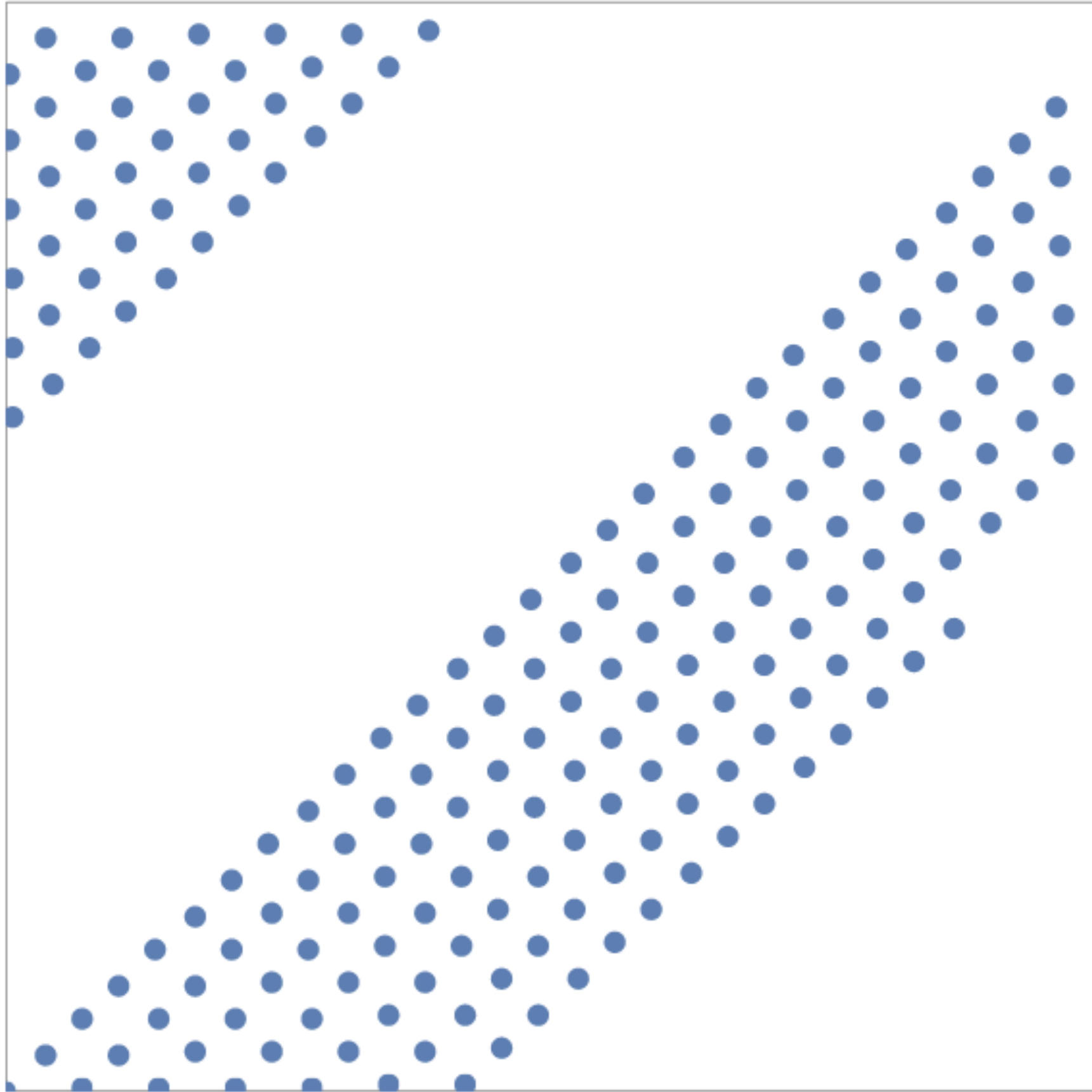
Good Permutations for Extreme Discrepancy

HENRI FAURE

*Mathématiques Informatique, Université de Provence,
3, Place Victor-Hugo, 13331 Marseille, Cedex 3, France*

Scrambling fixes the regularity issue

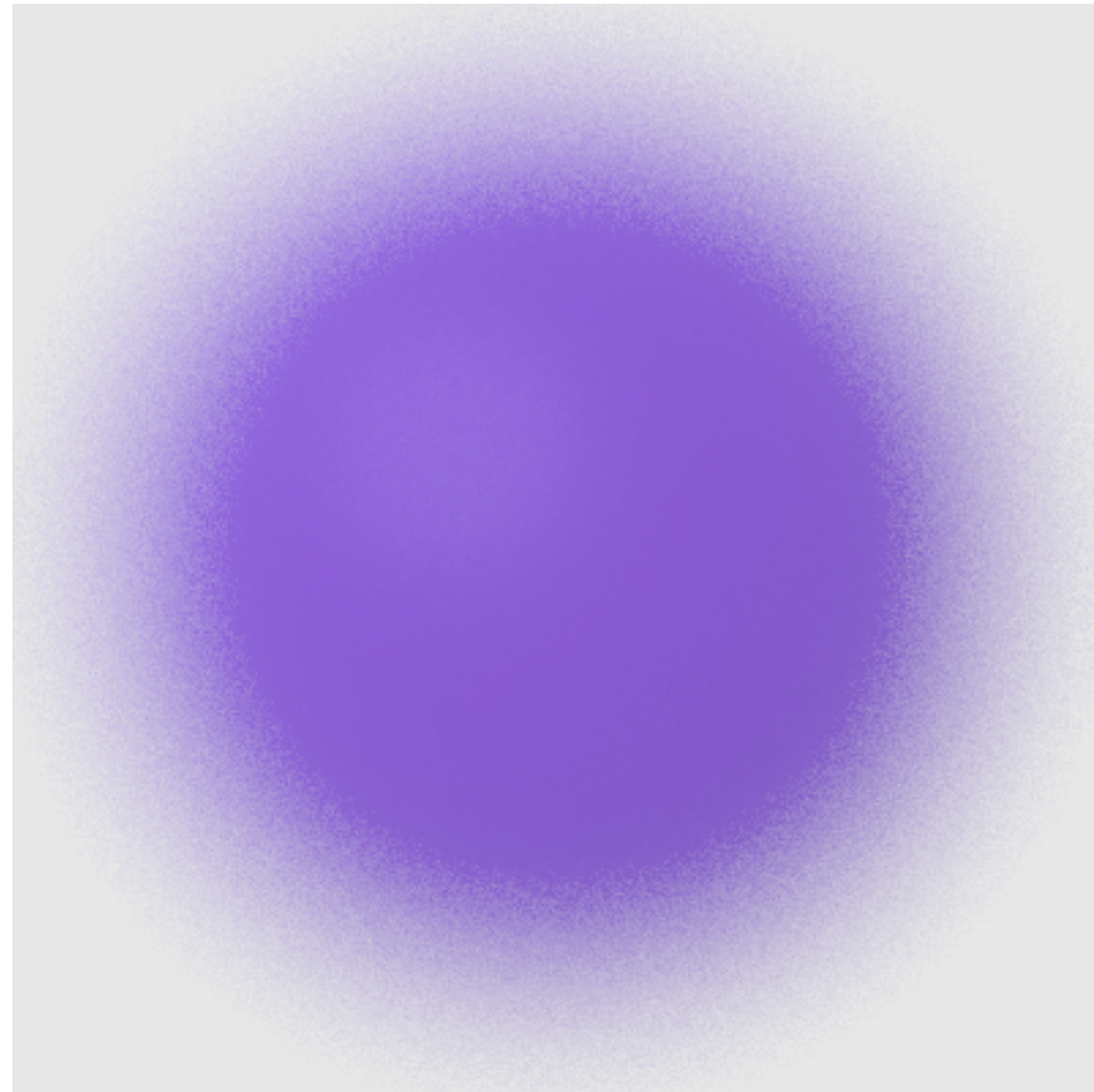
(the clumping might look bad, but note that this is a projection of a high-dimensional point set)



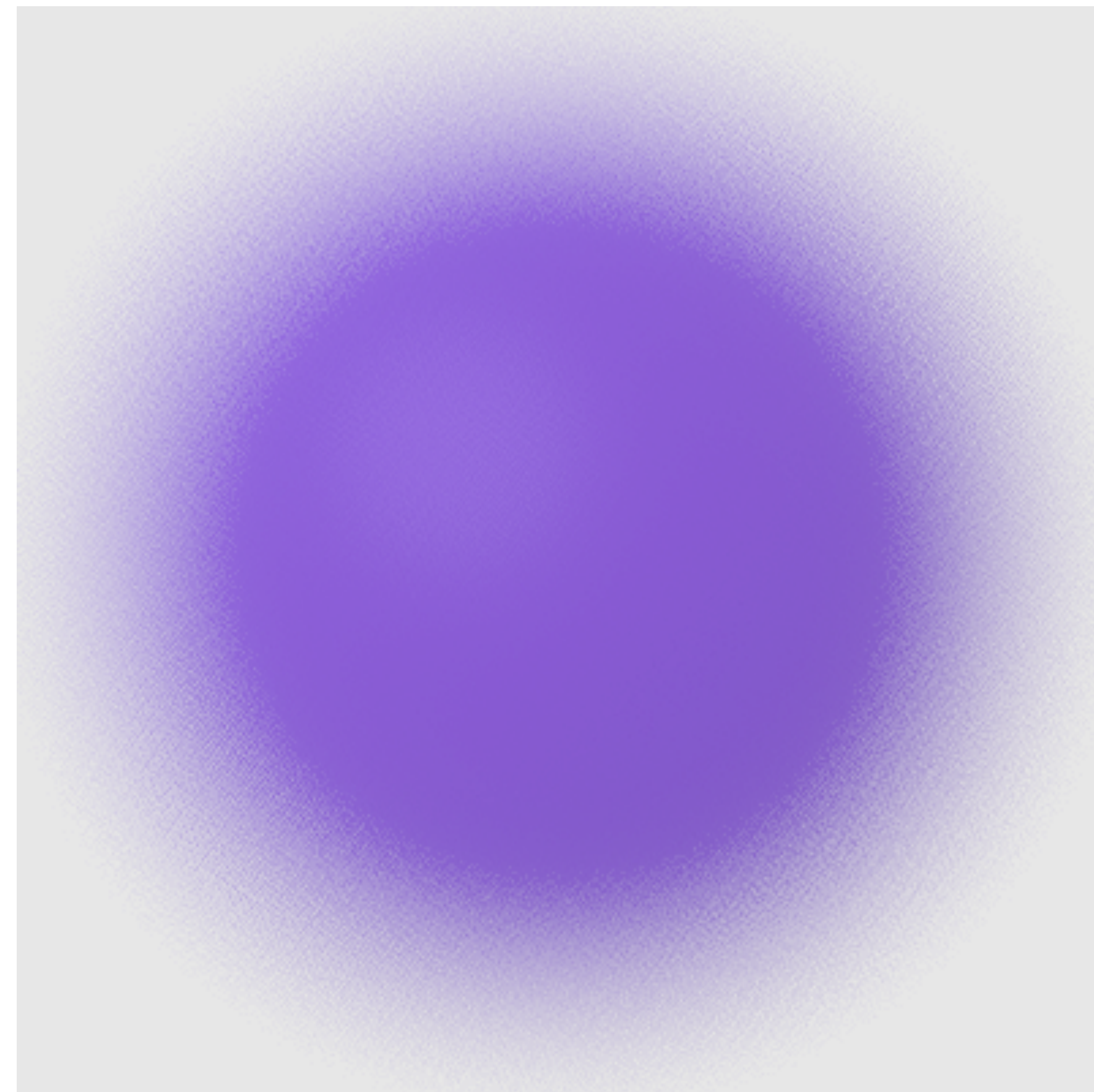
(Φ_{29}, Φ_{31})

Jittered vs Halton

4D integral



jittered

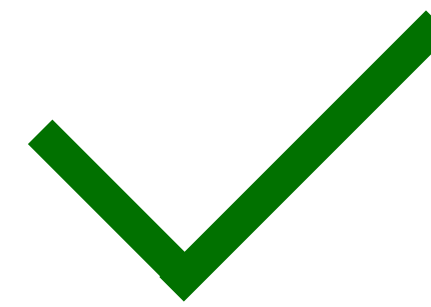


Halton

Another solution to the correlation problem: don't use high bases!

digital nets: low discrepancy sequences constructed only using low number bases

$$\Phi_2(k)$$

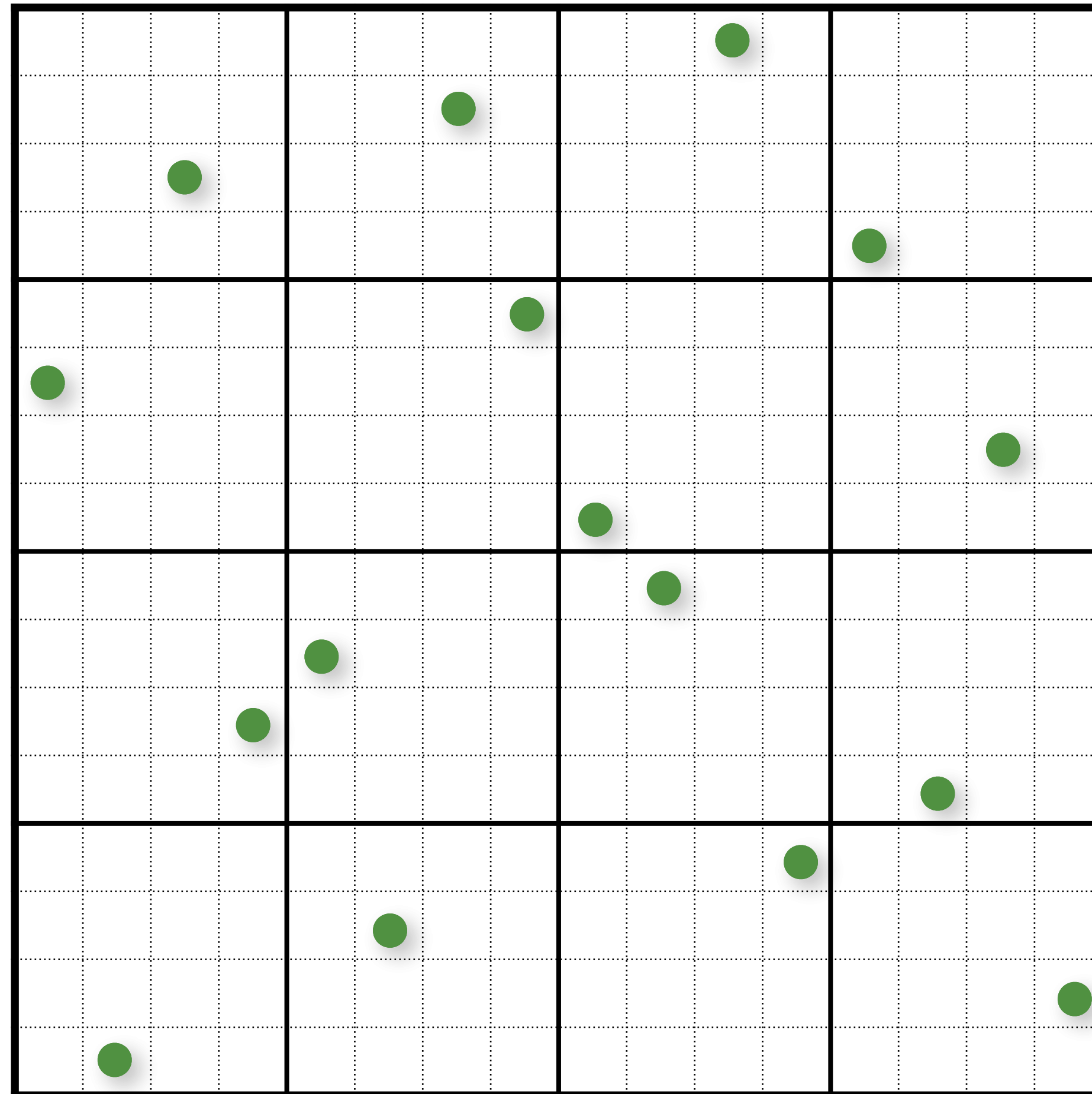


$$\Phi_{29}(k)$$



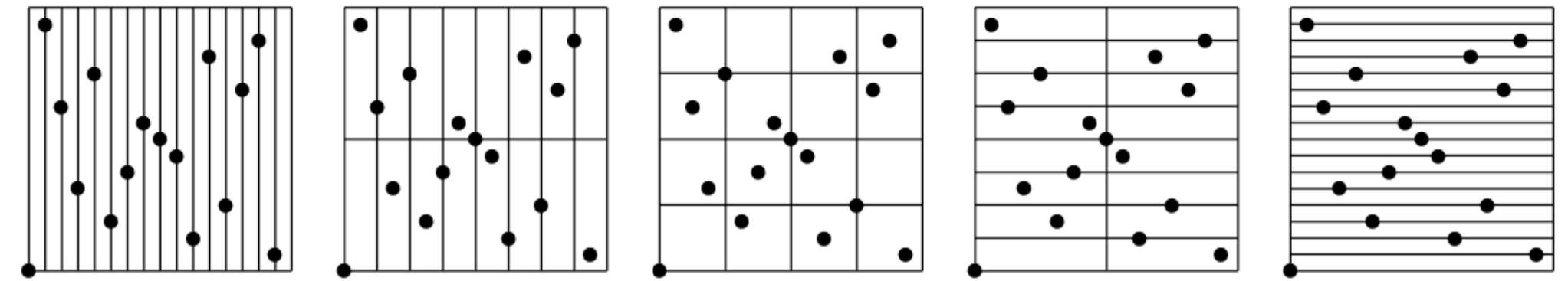
The first two dimensions of Hammersley sequence follows the digital nets property

higher dimensions do not follow the same property
due to the large base b



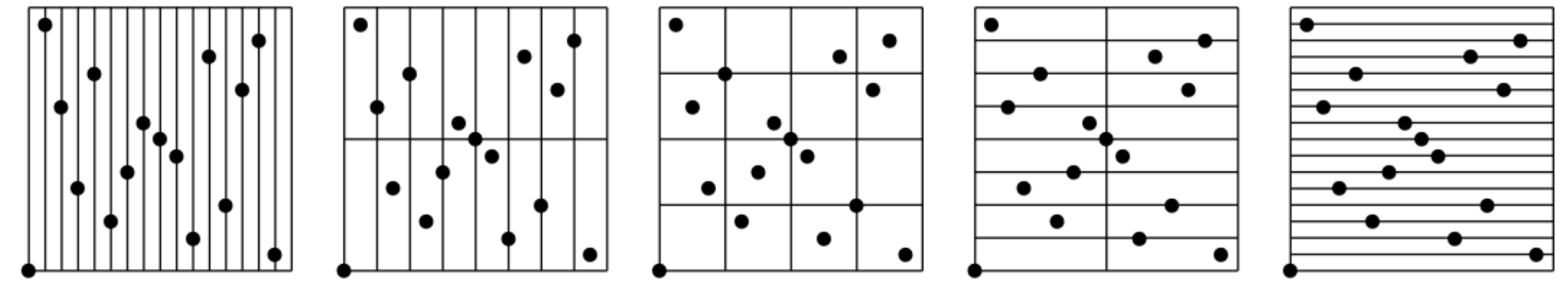
Definition of digital nets

elementary interval: partition of space into equal-size rectangles



Definition of digital nets

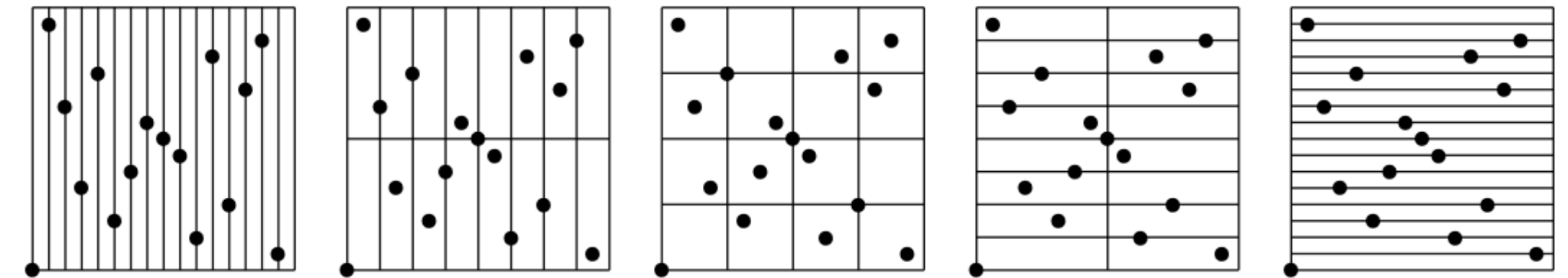
elementary interval: partition of space into equal-size rectangles



digital nets: for two non-negative integers $t \leq m$, a (t, m, s) -net in base b is a finite point set with b^m points with s dimensions where each elementary interval of volume b^{t-m} contains exactly b^t points

Definition of digital nets

elementary interval: partition of space into equal-size rectangles



digital nets: for two non-negative integers $t \leq m$, a (t, m, s) -net in base b is a finite point set with b^m points with s dimensions where each elementary interval of volume b^{t-m} contains exactly b^t points

a **(t, s)-sequence** is an infinite point sequence whose subsequences form a digital net

Sobol' sequence satisfies digital nets property

aka Faure or Niederreiter or digital sequence

want to find a function $y_d = f_d(k)$ that will output a number y_d in base b for each dimension d

Sobol' sequence satisfies digital nets property

aka Faure or Niederreiter or digital sequence

want to find a function $y_d = f_d(k)$ that will output a number y_d in base b for each dimension d

represents k and y in terms of their digits

$$k = k_1 k_2 k_3 \dots k_{m_b} \qquad y = 0.y_1 y_2 y_3 \dots y_{m_b}$$

Sobol' sequence satisfies digital nets property

aka Faure or Niederreiter or digital sequence

want to find a function $y_d = f_d(k)$ that will output a number y_d in base b
for each dimension d

turn the digits into vectors

$$y = 0.y_1y_2y_3\cdots y_{mb}$$

$$\begin{bmatrix} k_1 \\ k_2 \\ \vdots \\ k_m \end{bmatrix}$$

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

Sobol' sequence satisfies digital nets property

aka Faure or Niederreiter or digital sequence

want to find a function $y_d = f_d(k)$ that will output a number y_d in base b for each dimension d

let f be a linear function (!?) applied to the k vector

$$y = 0.y_1y_2y_3 \dots y_{mb}$$

$$\begin{bmatrix} c_{1,1} \cdots c_{1,m} \\ c_{2,1} \cdots c_{2,m} \\ \vdots \\ c_{m,1} \cdots c_{m,m} \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ \vdots \\ k_m \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

(need to take modulo of b after multiplication)

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“generator matrix”

$$\begin{bmatrix} c_{1,1} & \dots & c_{1,m} \\ c_{2,1} & \dots & c_{2,m} \\ \vdots & & \vdots \\ c_{m,1} & \dots & c_{m,m} \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ \vdots \\ k_m \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

(need to take modulo of b after multiplication)

Intuition of the generator matrix

generator matrix can be seen as a generalization of “scrambling”
before we apply the van der Corput sequence transformation (as opposed to post scrambling)

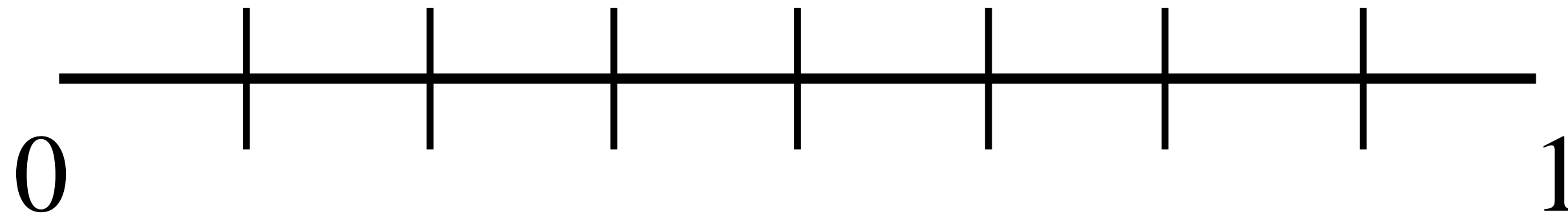
can be a permutation matrix!

$$y = 0.y_1y_2y_3\cdots y_{m_b}$$

$$\begin{bmatrix} c_{1,1} & \cdots & c_{1,m} \\ c_{2,1} & \cdots & c_{2,m} \\ \vdots & & \vdots \\ c_{m,1} & \cdots & c_{m,m} \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ \vdots \\ k_m \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

Intuition of the generator matrix

focus on base 2 for now — k_i and y_i are either 0 or 1



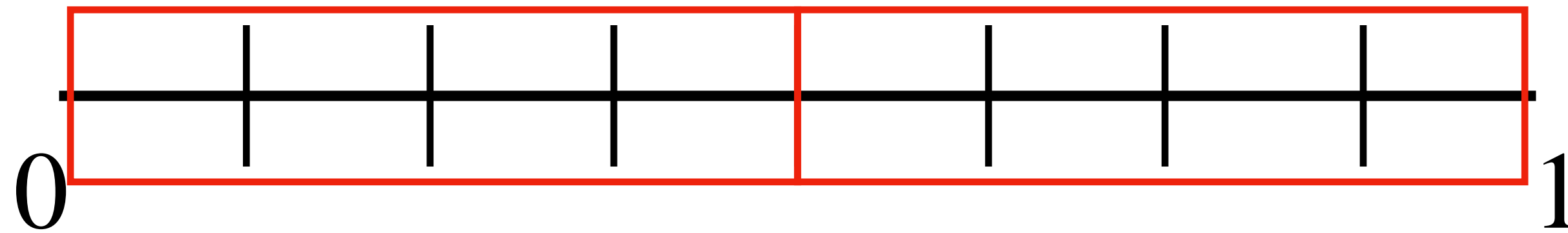
$$y = 0.y_1y_2y_3\cdots y_{m_b}$$

$$\begin{bmatrix} c_{1,1} & \cdots & c_{1,m} \\ c_{2,1} & \cdots & c_{2,m} \\ \vdots & & \vdots \\ c_{m,1} & \cdots & c_{m,m} \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ \vdots \\ k_m \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

Intuition of the generator matrix

1D elementary intervals

focus on base 2 for now — k_i and y_i are either 0 or 1



$$\begin{bmatrix} c_{1,1} \cdots c_{1,m} \\ c_{2,1} \cdots c_{2,m} \\ \vdots \\ c_{m,1} \cdots c_{m,m} \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ \vdots \\ k_m \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

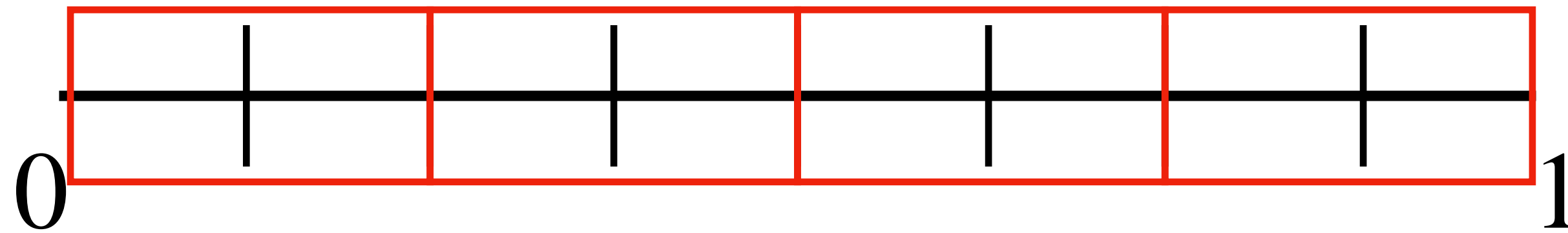
$$y = 0.y_1y_2y_3 \cdots y_{m_b}$$

first row is responsible for the first digit of y

Intuition of the generator matrix

1D elementary intervals

focus on base 2 for now — k_i and y_i are either 0 or 1



$$\begin{bmatrix} c_{1,1} & \cdots & c_{1,m} \\ c_{2,1} & \cdots & c_{2,m} \\ \vdots & & \vdots \\ c_{m,1} & \cdots & c_{m,m} \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ \vdots \\ k_m \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

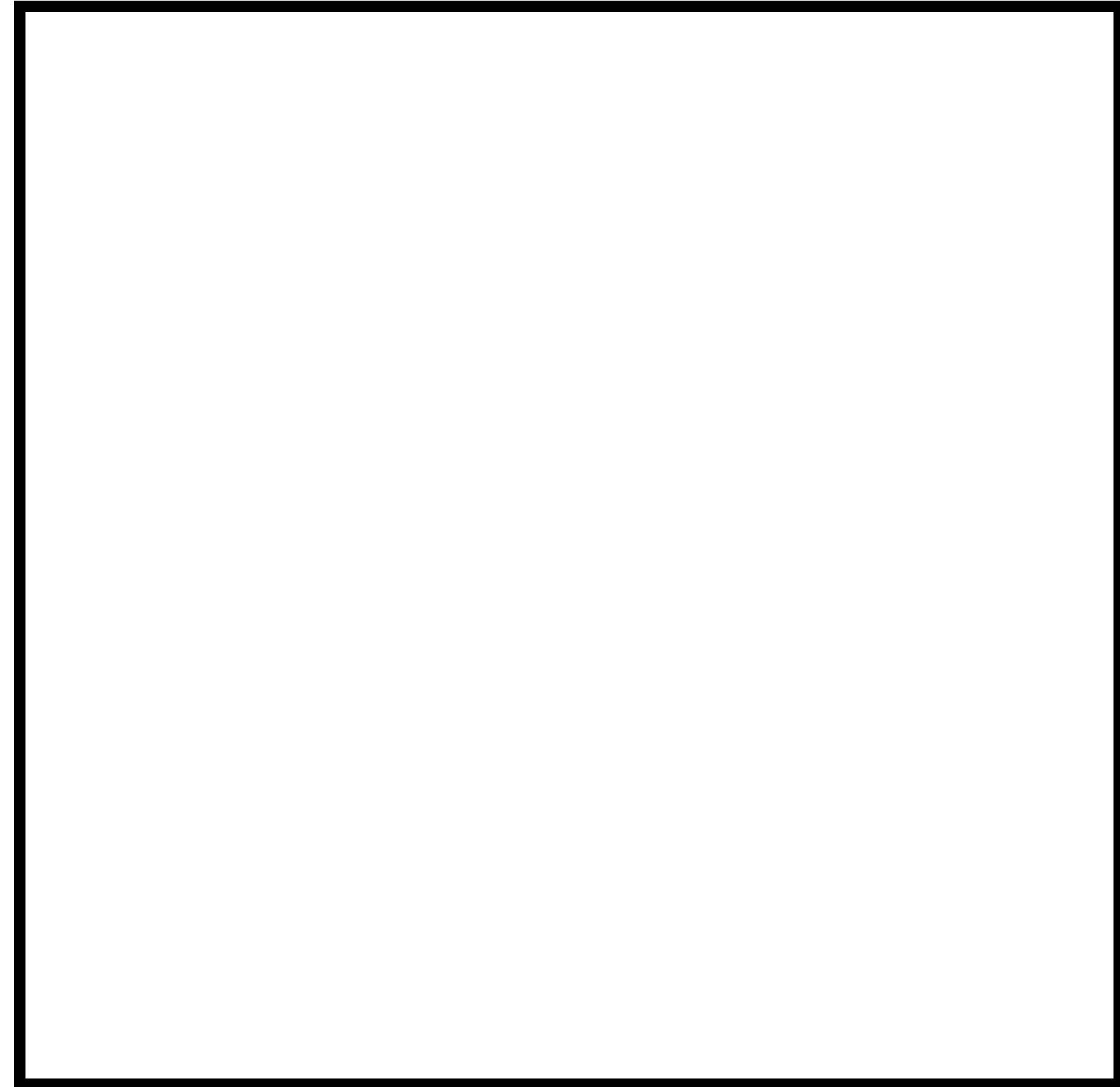
$$y = 0.y_1y_2y_3\cdots y_{m_b}$$

first two rows are responsible for the first two digits of y

Intuition of the generator matrix — 2D

$$\begin{bmatrix} c_{1,1} & c_{1,2} & c_{1,3} \\ c_{2,1} & c_{2,2} & c_{2,3} \\ c_{3,1} & c_{3,2} & c_{3,3} \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$

$$\begin{bmatrix} c'_{1,1} & c'_{1,2} & c'_{1,3} \\ c'_{2,1} & c'_{2,2} & c'_{2,3} \\ c'_{3,1} & c'_{3,2} & c'_{3,3} \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = \begin{bmatrix} y'_1 \\ y'_2 \\ y'_3 \end{bmatrix}$$



Intuition of the generator matrix — 2D

$$\begin{bmatrix} c_{1,1} & c_{1,2} & c_{1,3} \\ c_{2,1} & c_{2,2} & c_{2,3} \\ c_{3,1} & c_{3,2} & c_{3,3} \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$

$$\begin{bmatrix} c'_{1,1} & c'_{1,2} & c'_{1,3} \\ c'_{2,1} & c'_{2,2} & c'_{2,3} \\ c'_{3,1} & c'_{3,2} & c'_{3,3} \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = \begin{bmatrix} y'_1 \\ y'_2 \\ y'_3 \end{bmatrix}$$

11	110	111
10	100	101
01	010	011
00	000	001
	0	1

Intuition of the generator matrix — 2D

$$\boxed{[c_{1,1} \ c_{1,2} \ c_{1,3}]} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = \boxed{[y_1]}$$

$$\boxed{\begin{bmatrix} c'_{1,1} & c'_{1,2} & c'_{1,3} \\ c'_{2,1} & c'_{2,2} & c'_{2,3} \end{bmatrix}} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = \boxed{\begin{bmatrix} y'_1 \\ y'_2 \end{bmatrix}}$$

11	110	111
10	100	101
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Intuition of the generator matrix — 2D

$$\begin{bmatrix} c_{1,1} & c_{1,2} & c_{1,3} \\ c'_{1,1} & c'_{1,2} & c'_{1,3} \\ c'_{2,1} & c'_{2,2} & c'_{2,3} \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = \begin{bmatrix} y_1 \\ y'_1 \\ y'_2 \end{bmatrix}$$

11	110	111
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$$\begin{bmatrix} c_{1,1} & c_{1,2} & c_{1,3} \\ c'_{1,1} & c'_{1,2} & c'_{1,3} \\ c'_{2,1} & c'_{2,2} & c'_{2,3} \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = \begin{bmatrix} y_1 \\ y'_1 \\ y'_2 \end{bmatrix}$$

digital nets property = bijection between two vectors

11	110	111
10	100	101
01	010	011
00	000	001
	0	1

Intuition of the generator matrix — 2D

$$\begin{bmatrix} c_{1,1} & c_{1,2} & c_{1,3} \\ c'_{1,1} & c'_{1,2} & c'_{1,3} \\ c'_{2,1} & c'_{2,2} & c'_{2,3} \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = \begin{bmatrix} y_1 \\ y'_1 \\ y'_2 \end{bmatrix}$$

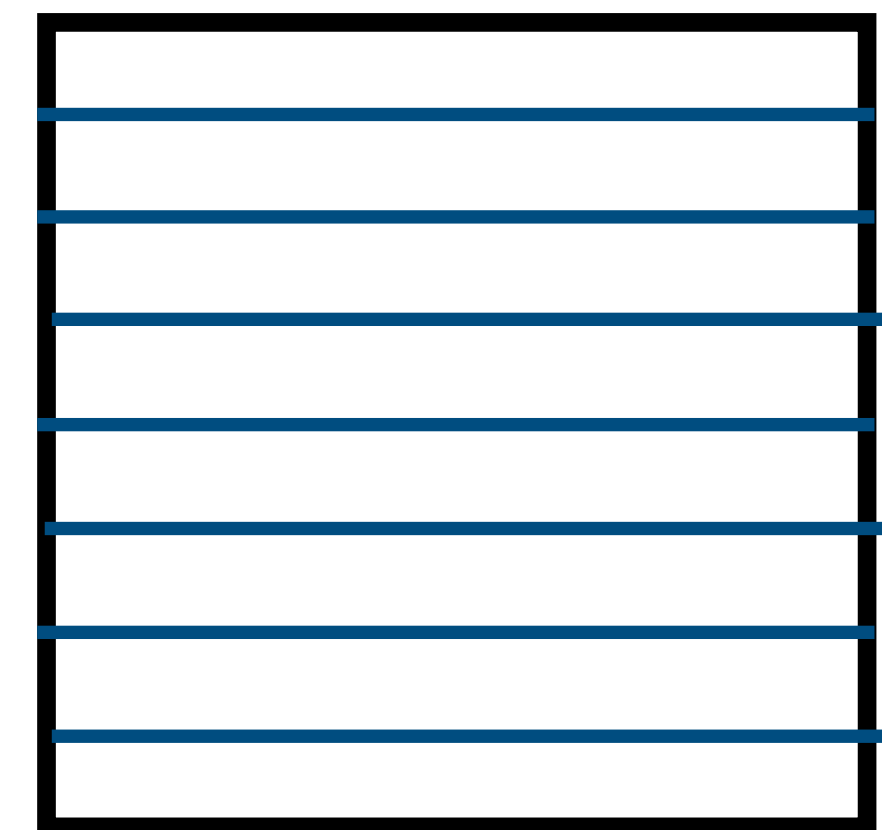
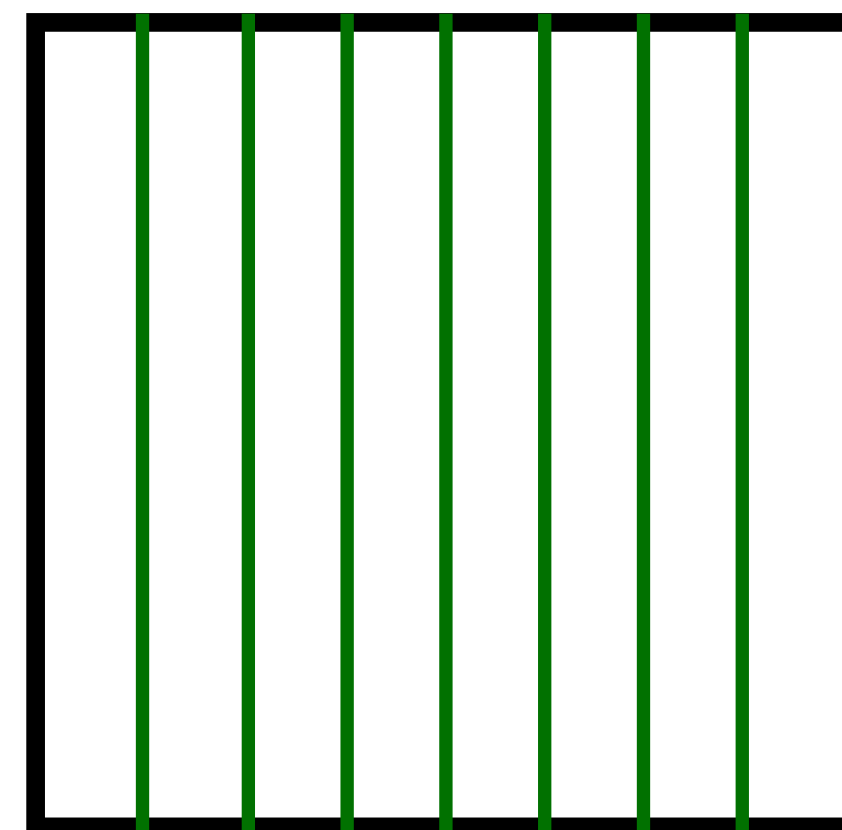
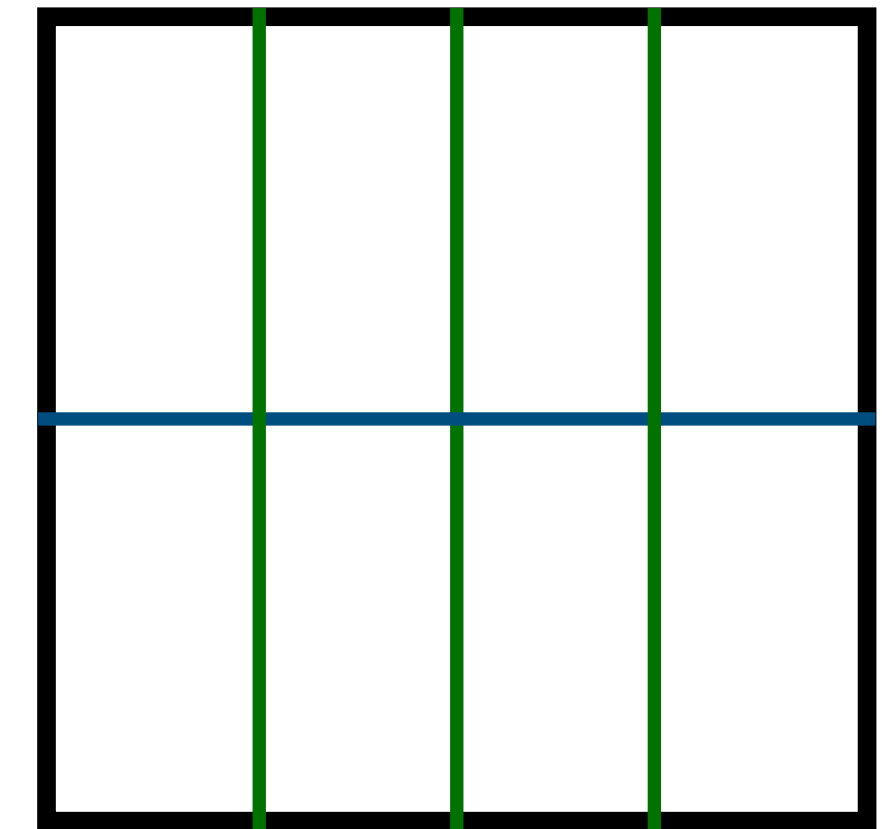
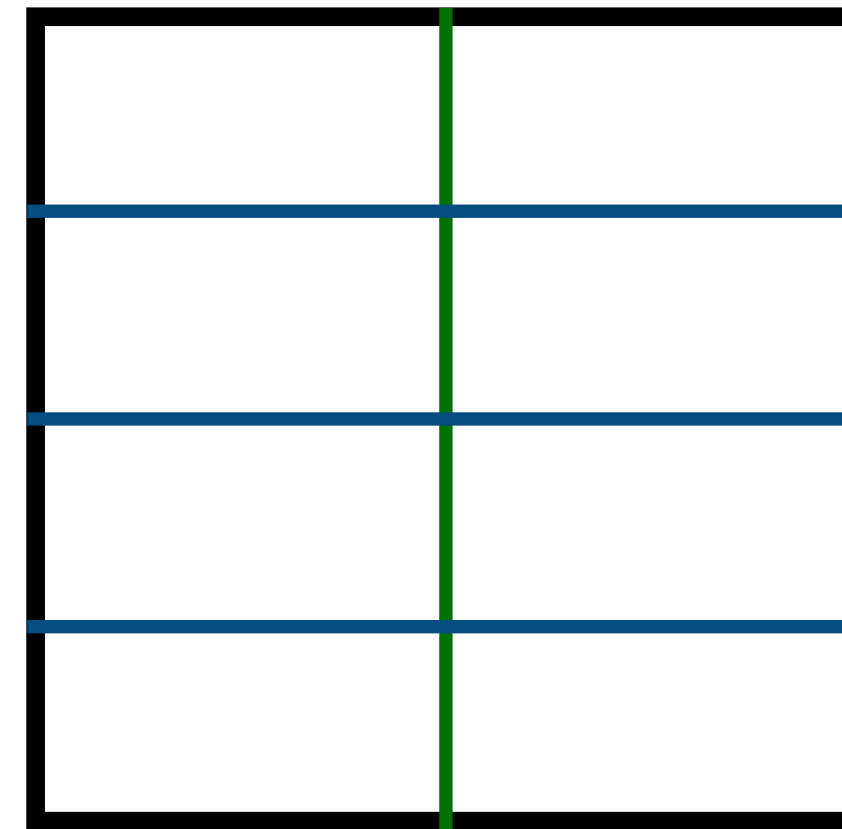
digital nets property = bijection between two vectors

bijection = the matrix being invertible!! (i.e. $\det \neq 0$)

11	110	111
10	100	101
01	010	011
00	000	001
	0	1

Designing generator matrices

enumerate all elementary intervals
(or even just subregions of the domain)



Designing generator matrices

enumerate all elementary intervals
(or even just subregions of the domain)

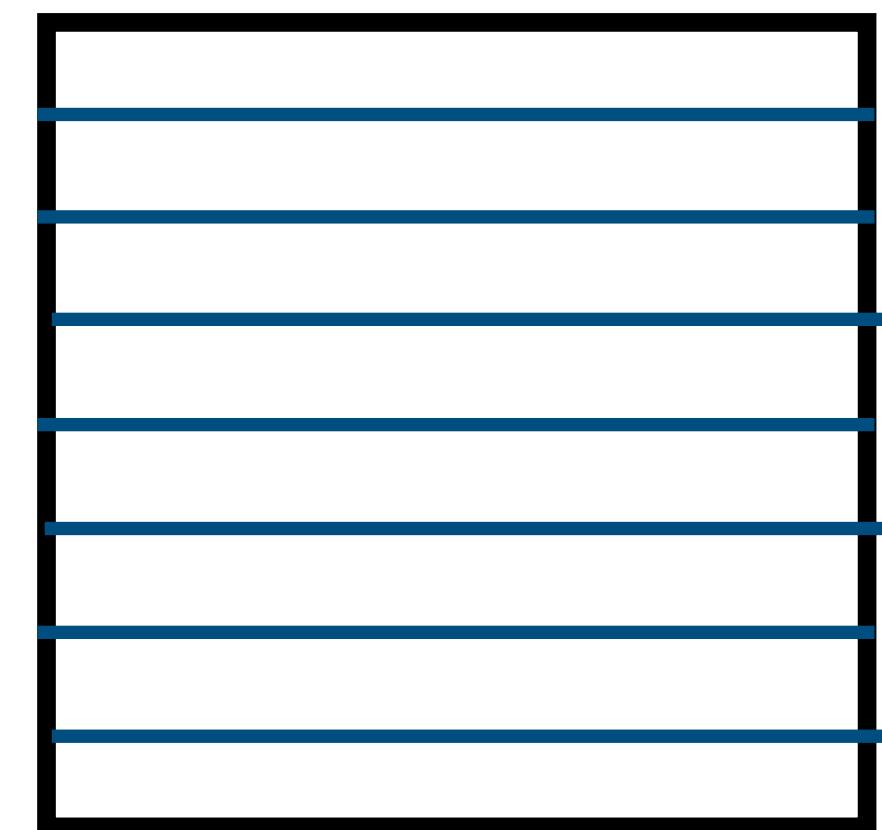
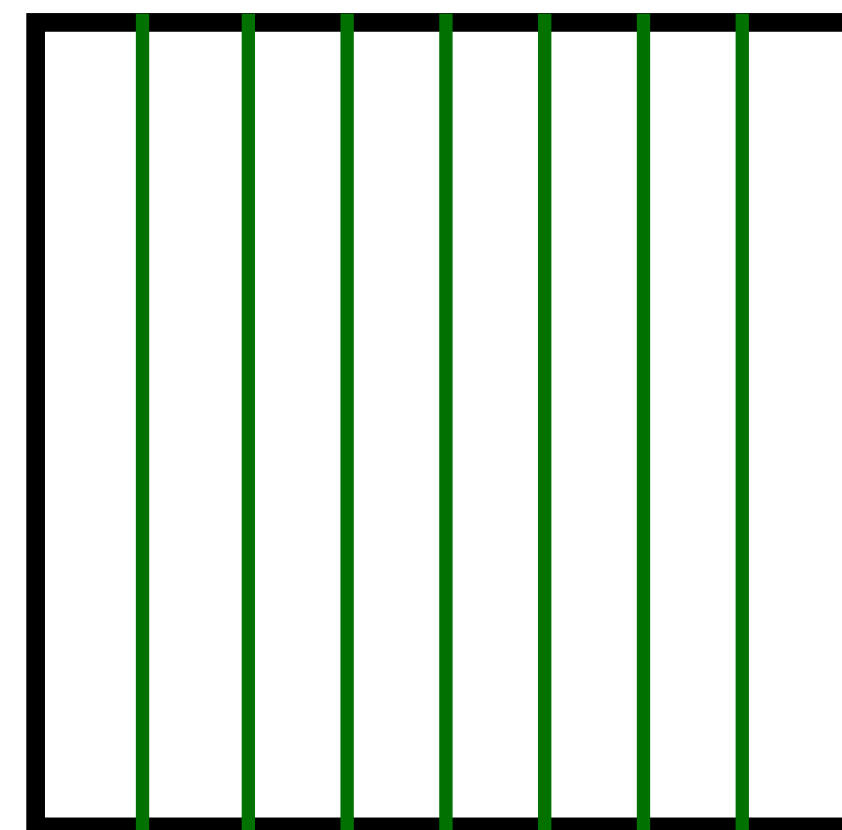
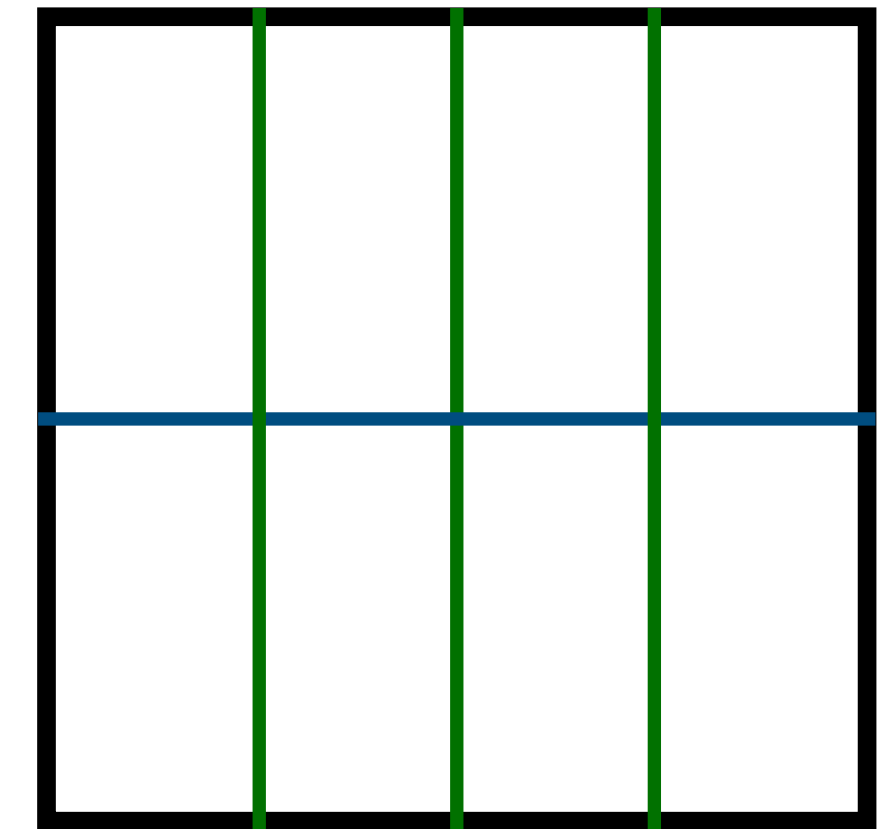
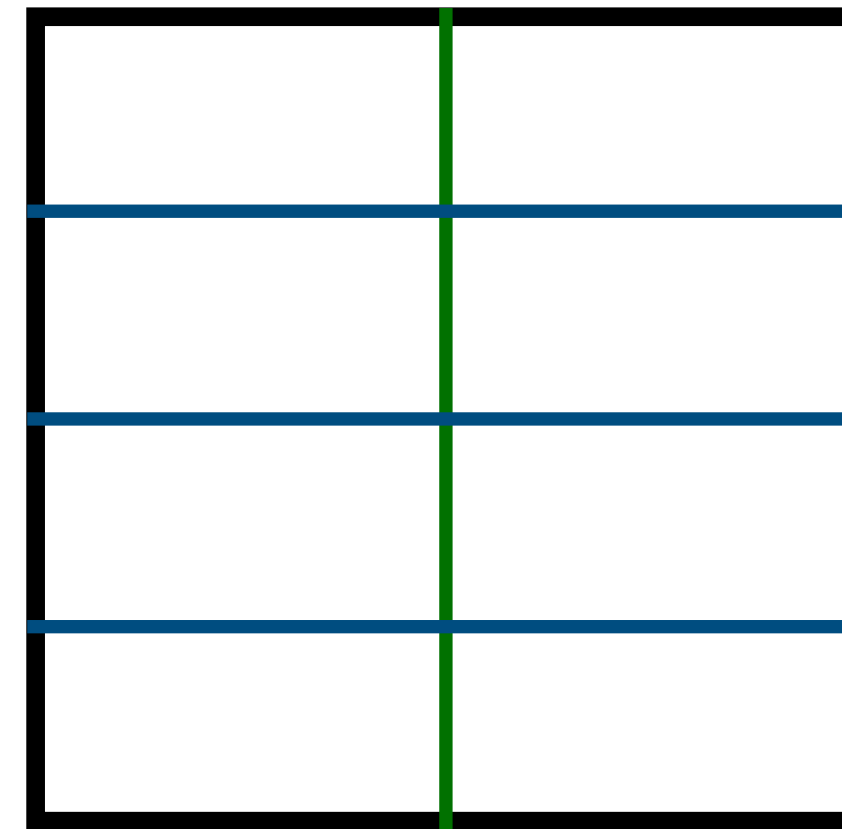
write down the constraints of different sub matrices

$$\det(A) \neq 0$$

$$\det(B) \neq 0$$

$$\det(C) \neq 0$$

$$\det(D) \neq 0$$



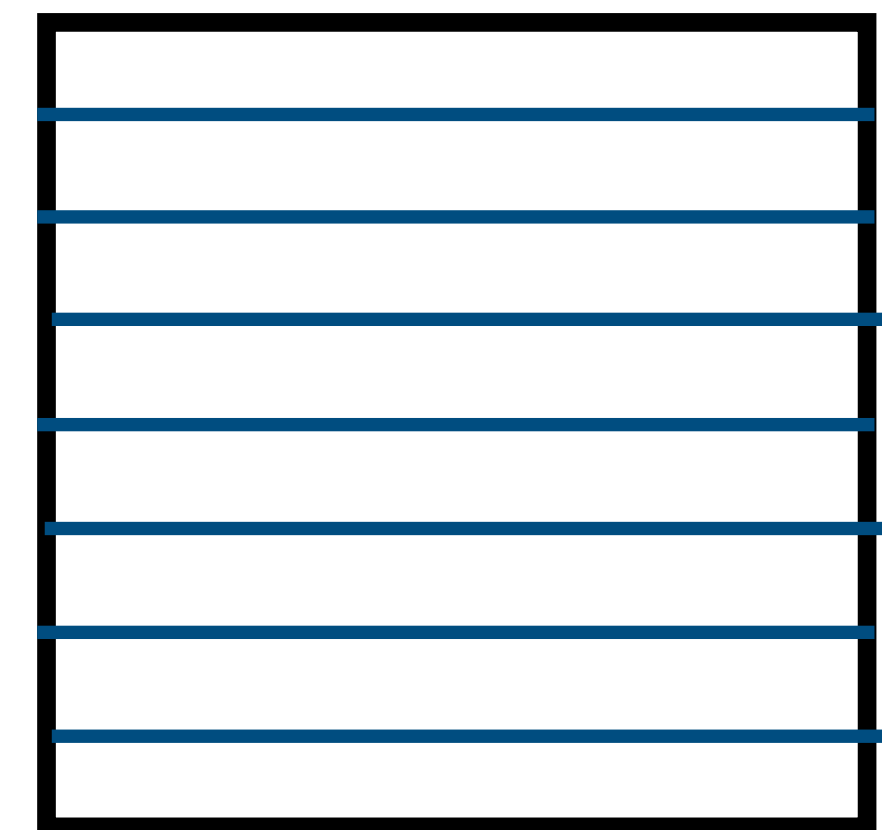
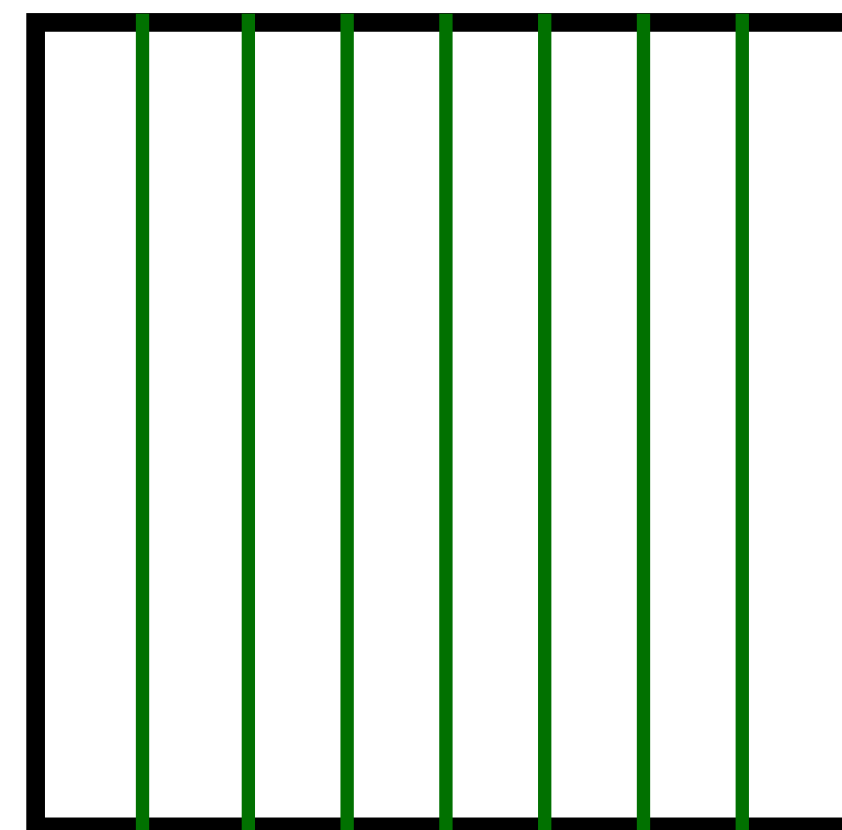
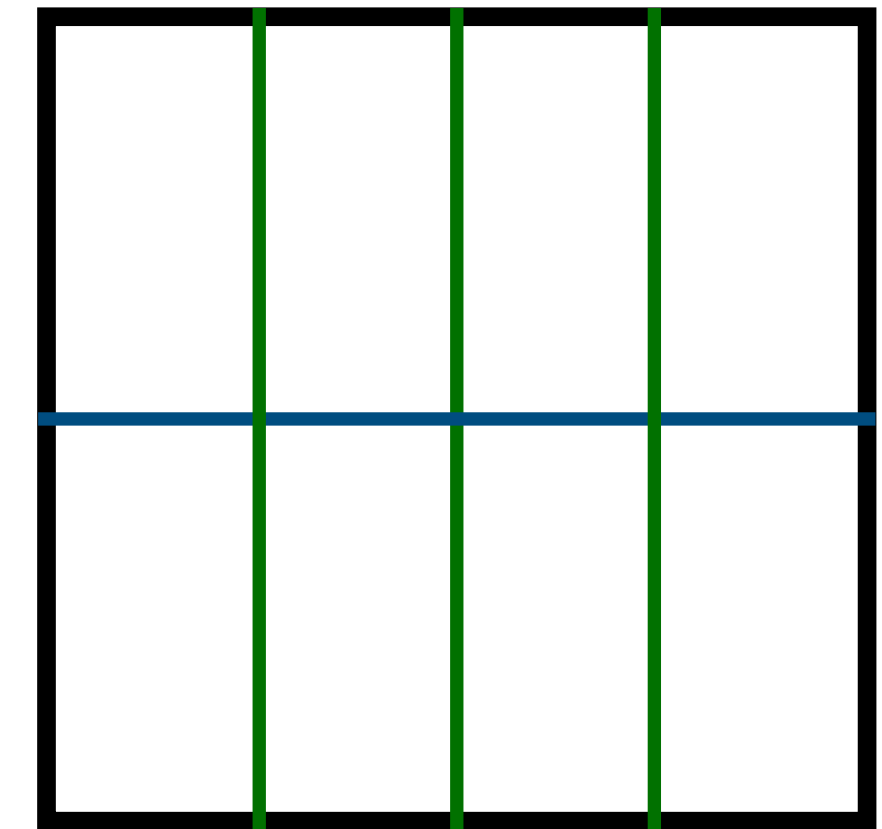
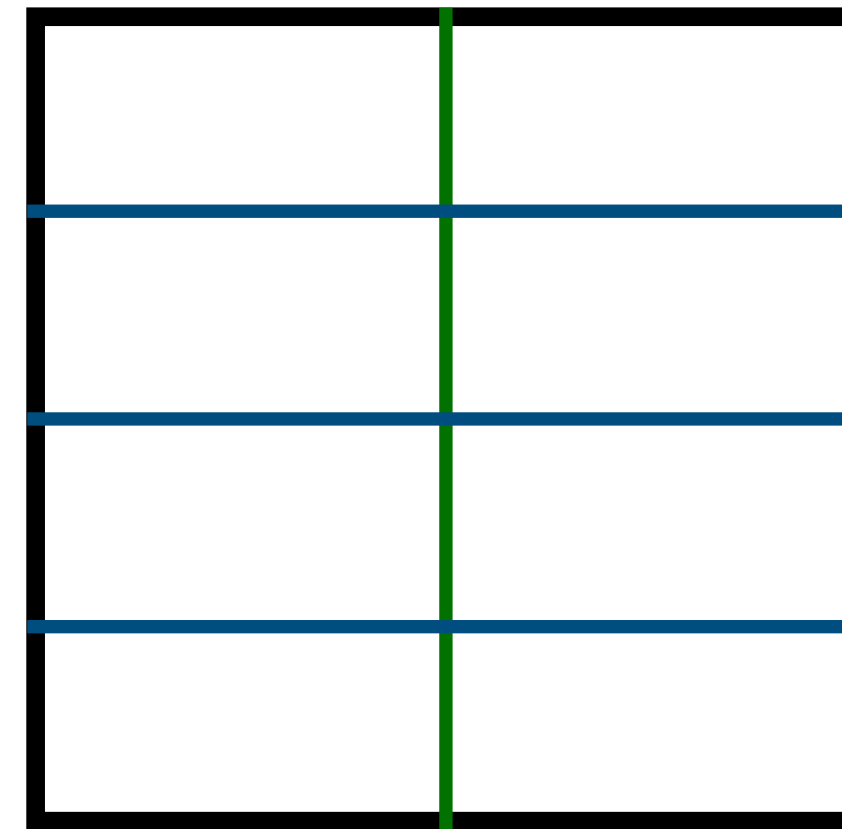
Designing generator matrices

enumerate all elementary intervals
(or even just subregions of the domain)

write down the constraints of different sub matrices

$\det(A) \neq 0$ $\det(B) \neq 0$ $\det(C) \neq 0$ $\det(D) \neq 0$

solve for the polynomial systems (in general NP hard,
but there are many known solutions in number theory,
and fast greedy approximation exists)



Example of generator matrices

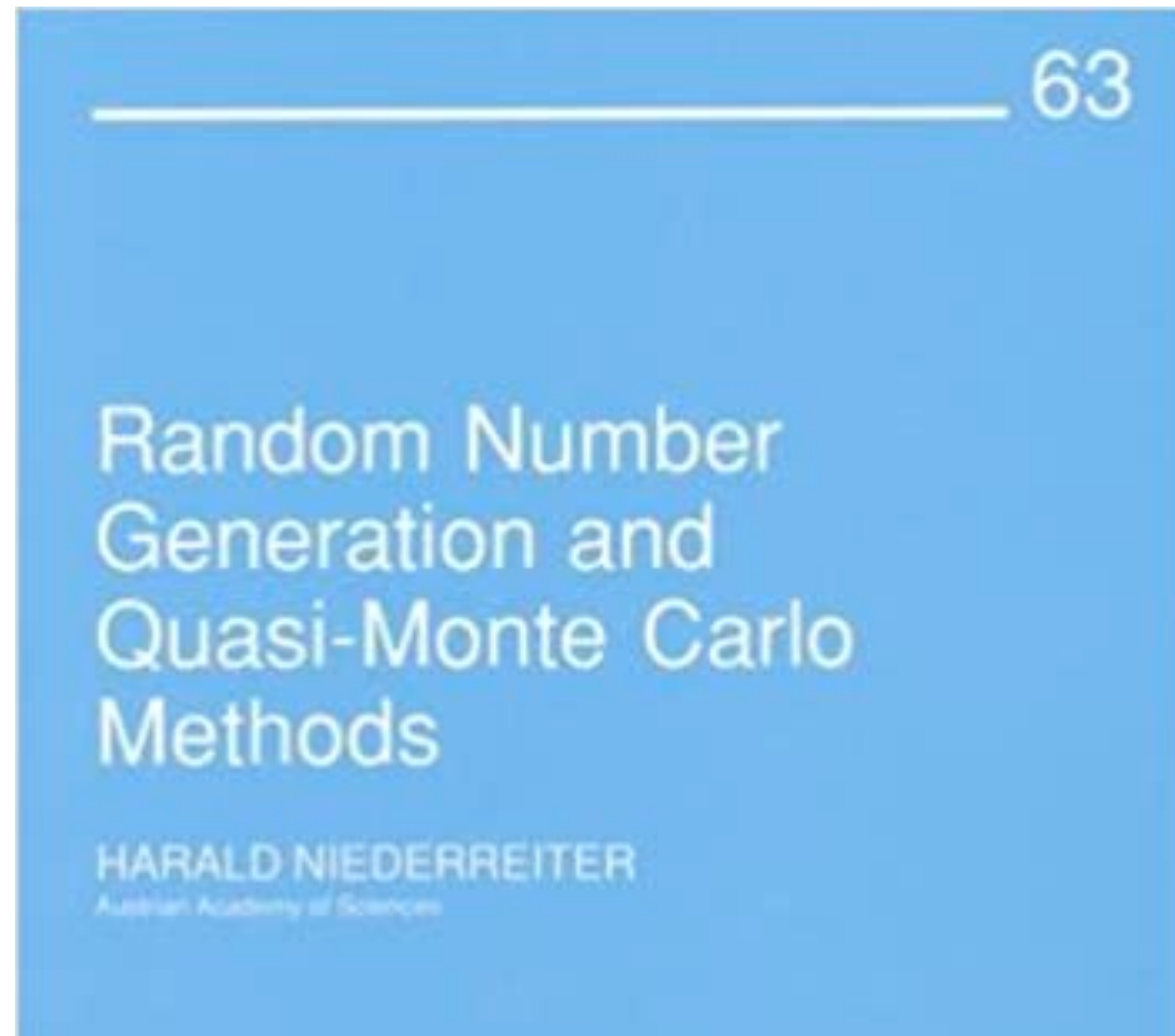
Sobol's algorithm produces a $(0,s)$ -sequence on base 2

base = 2, m = 6

$$C_1 = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$C_2 = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 & 1 & 1 \end{bmatrix}$$

Some good references



Efficient Multidimensional Sampling

Thomas Kollig and Alexander Keller

Department of Computer Science, Kaiserslautern University, Germany

MatBuilder: Mastering Sampling Uniformity Over Projections

LOÏS PAULIN, Univ Lyon, UCBL, CNRS, INSA Lyon, LIRIS, France

NICOLAS BONNEEL, Univ Lyon, CNRS, INSA Lyon, UCBL, LIRIS, France

DAVID COEURJOLLY, Univ Lyon, CNRS, INSA Lyon, UCBL, LIRIS, France

JEAN-CLAUDE IEHL, Univ Lyon, UCBL, CNRS, INSA Lyon, LIRIS, France

ALEXANDER KELLER, NVIDIA, Germany

VICTOR OSTROMOUKHOV, Univ Lyon, UCBL, CNRS, INSA Lyon, LIRIS, France

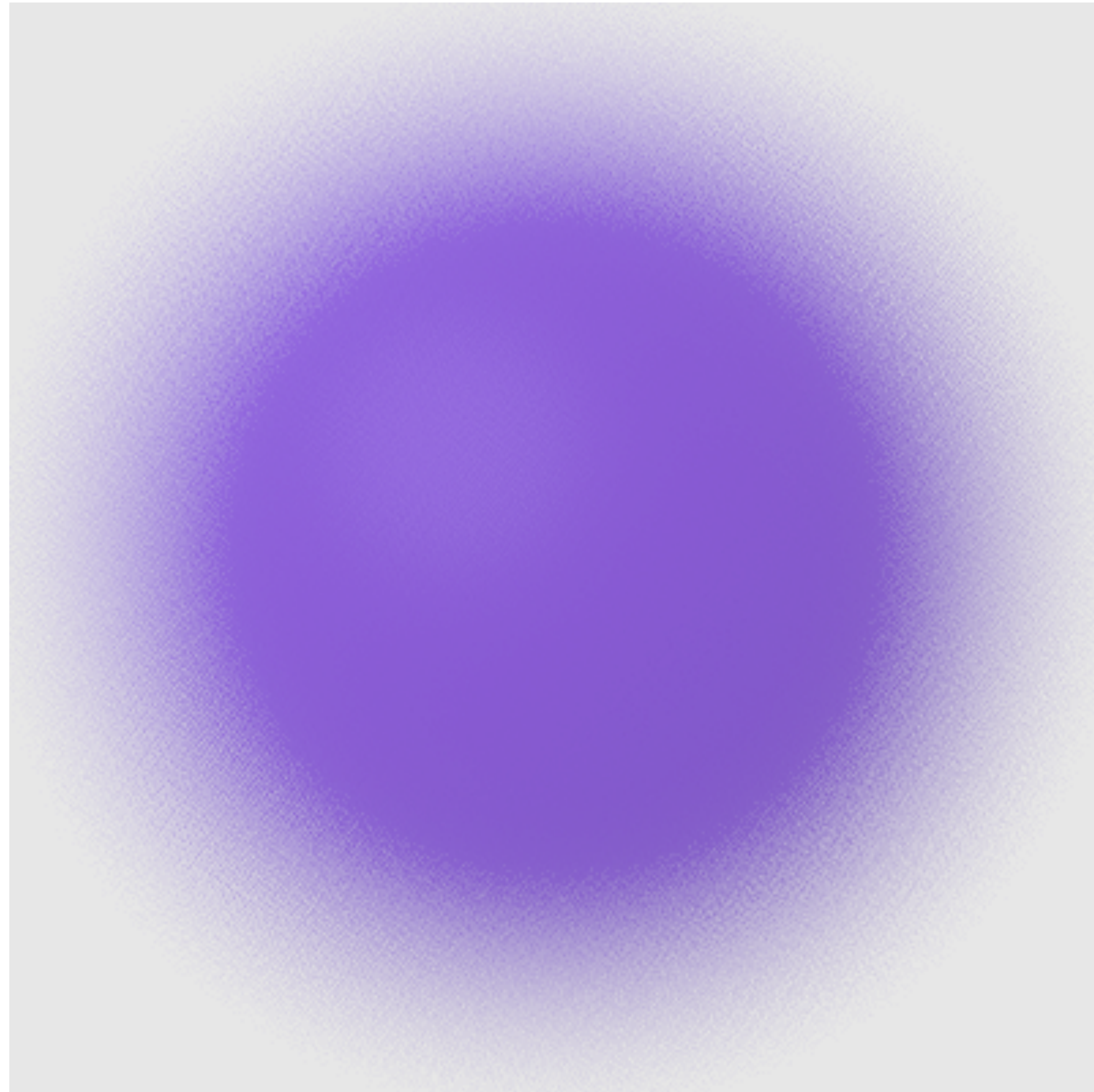
Optimizing Dyadic Nets

ABDALLA G. M. AHMED, KAUST, KSA

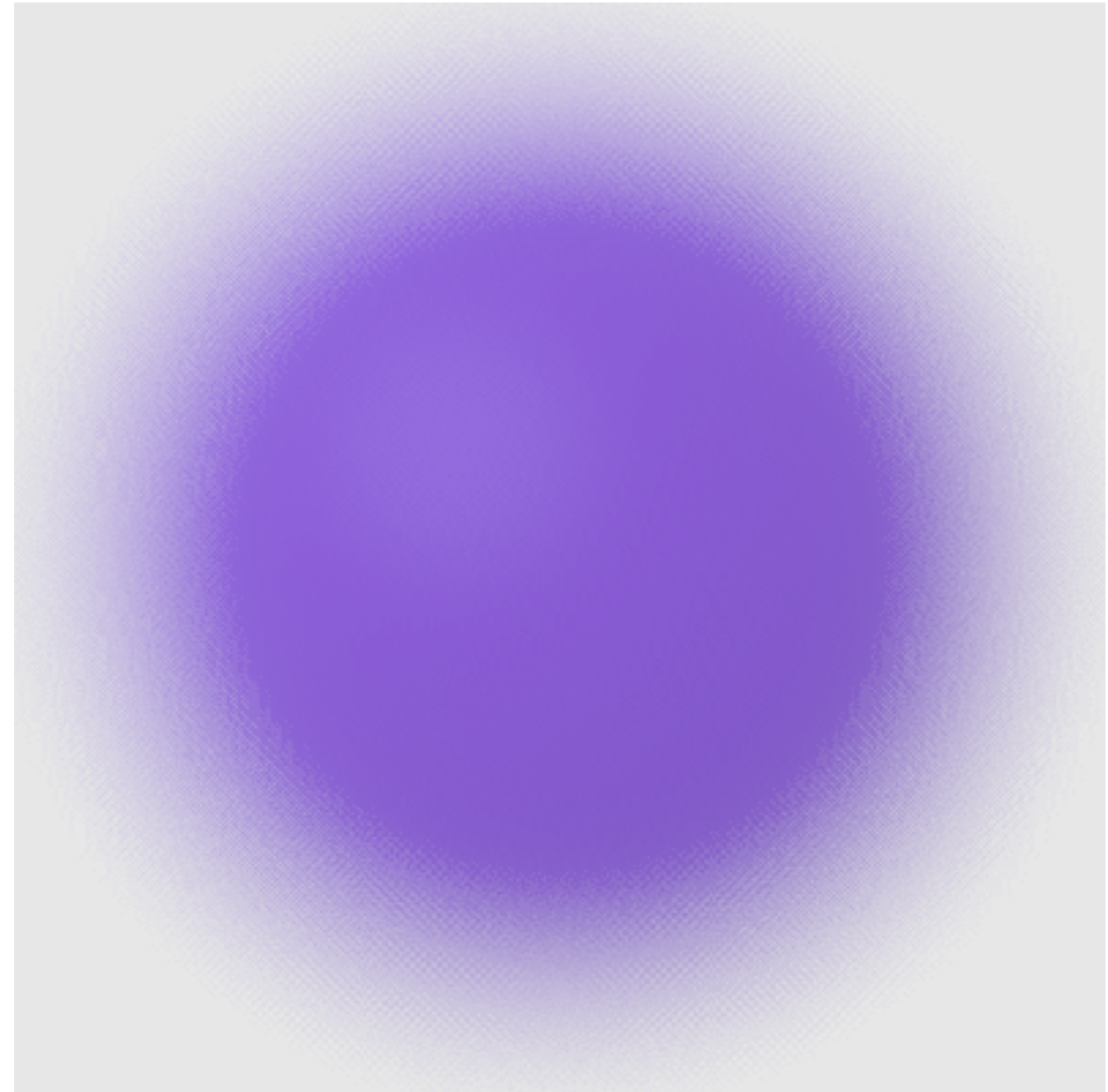
PETER WONKA, KAUST, KSA

Halton vs Sobol'

Sobol' converges faster than Halton/Hammersley (due to the digital nets property),
but introduces structural artifacts



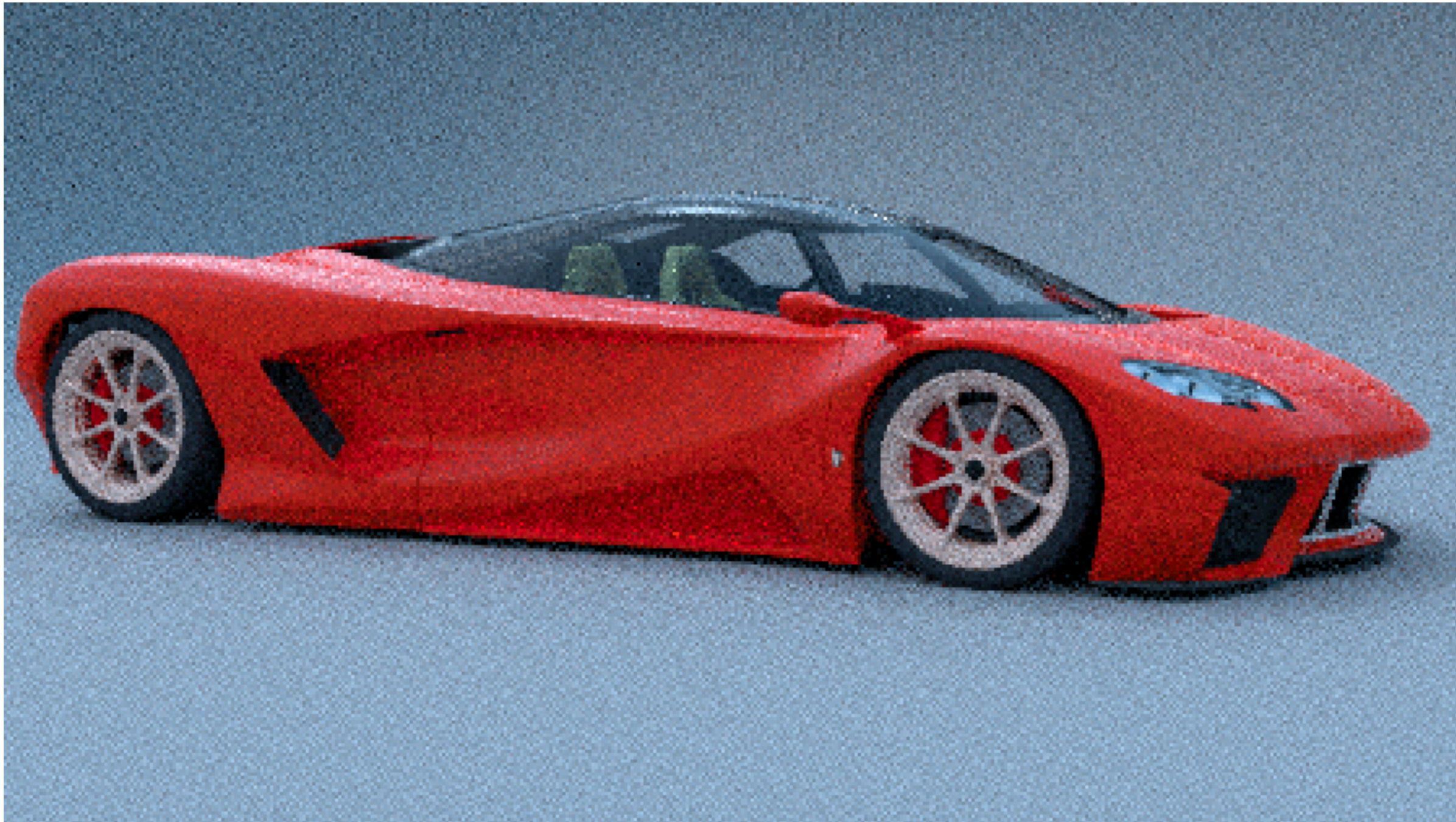
Halton



Sobol'

Halton vs Sobol'

Sobol' converges faster than Halton/Hammersley (due to the digital nets property),
but introduce structural artifacts



Halton



Sobol'

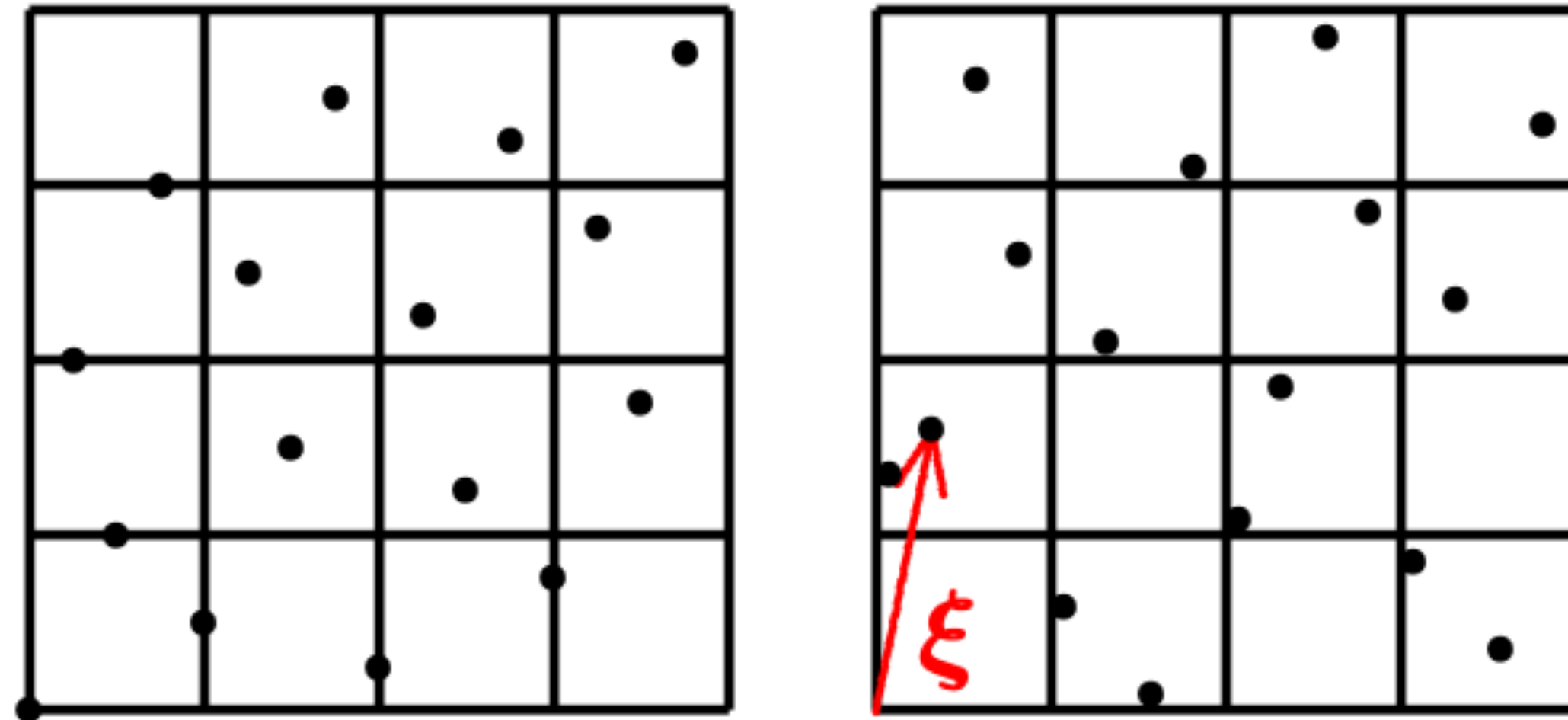
Avoiding structural artifacts in Sobol' sampling

- Cranley-Patterson rotation
- Owen scrambling

Avoiding structural artifacts in Sobol' sampling

- Cranley-Patterson rotation
- Owen scrambling

add a global random shift to all points in the sequence



can degrade uniformity a little bit

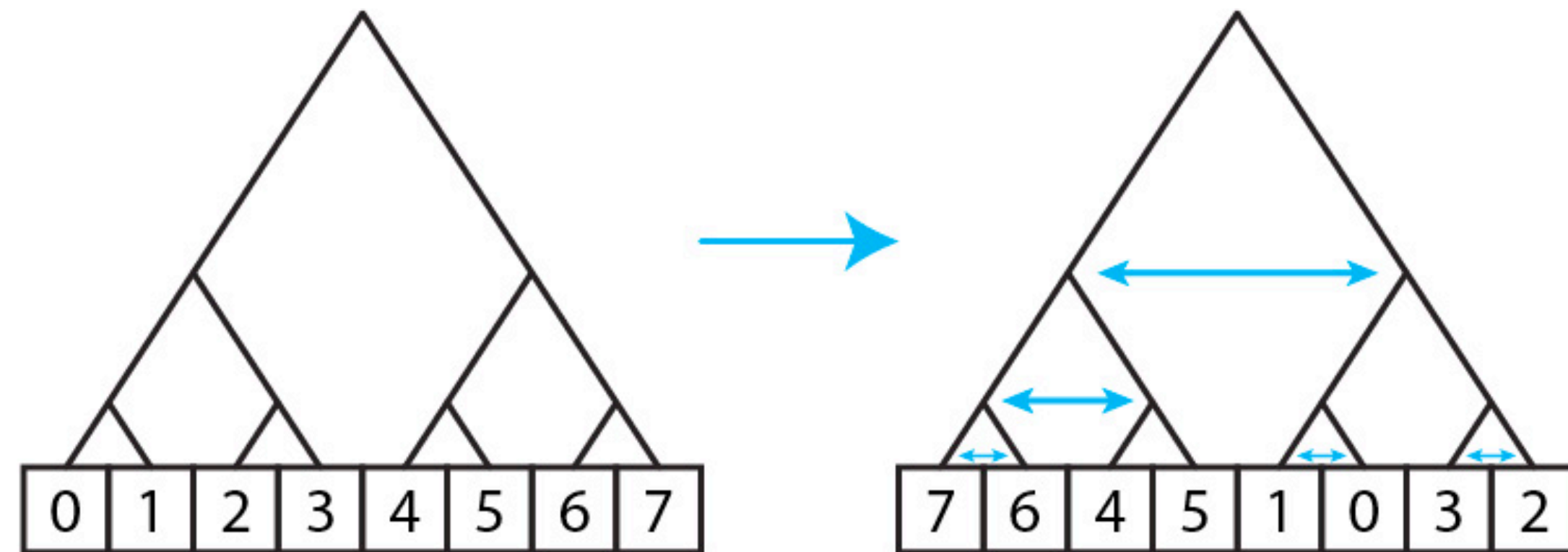
RANDOMIZATION OF NUMBER THEORETIC METHODS
FOR MULTIPLE INTEGRATION*

R. CRANLEY AND T. N. L. PATTERSON†

Avoiding structural artifacts in Sobol' sampling

- Cranley-Patterson rotation
- Owen scrambling

hierarchically and randomly scramble the elementary intervals
(similar to Faure's scrambling for Halton sequence)



provably preserves digital nets property and discrepancy!!

Blue noise + Sobol'

can be done by hacking Owen's scrambling or the generation matrices

Sequences with Low-Discrepancy Blue-Noise 2-D Projections

Hélène Perrier¹

David Coeurjolly¹

Feng Xie²

Matt Pharr³

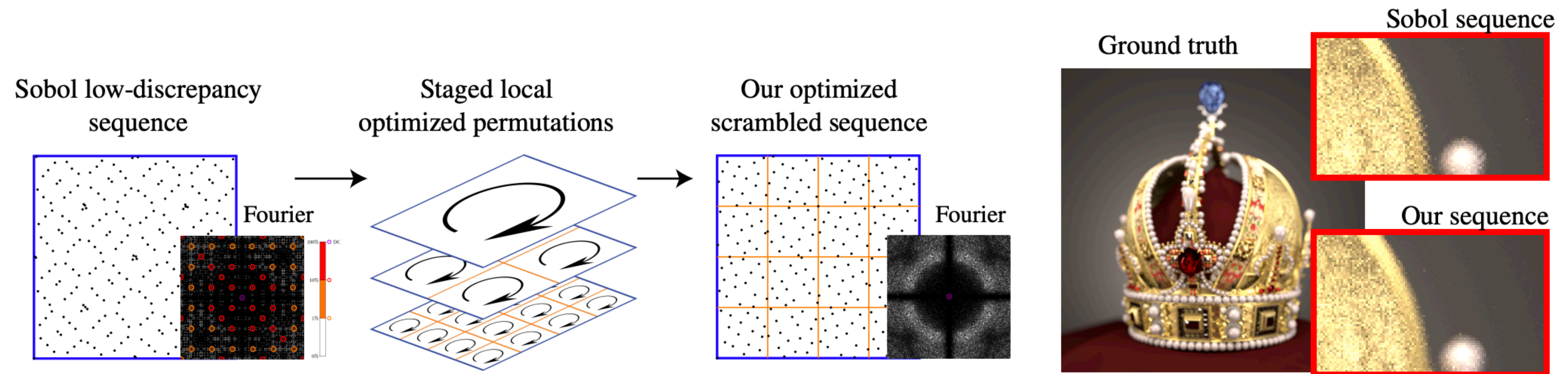
Pat Hanrahan²

Victor Ostromoukhov¹

¹Université de Lyon, CNRS, LIRIS, France

²Stanford, USA

³ Google, USA



Incorporation of blue noise in digital nets is still limiting

Low-Discrepancy Blue Noise Sampling

Abdalla G. M. Ahmed^{*1} H  l  ne Perrier² David Coeurjolly² Victor Ostromoukhov²
 Jianwei Guo³ Dong-Ming Yan³ Hui Huang^{4,5} Oliver Deussen^{1,5}
¹University of Konstanz ²Universit   de Lyon
³NLPR, Institute of Automation, CAS ⁴Shenzhen University ⁵SIAT

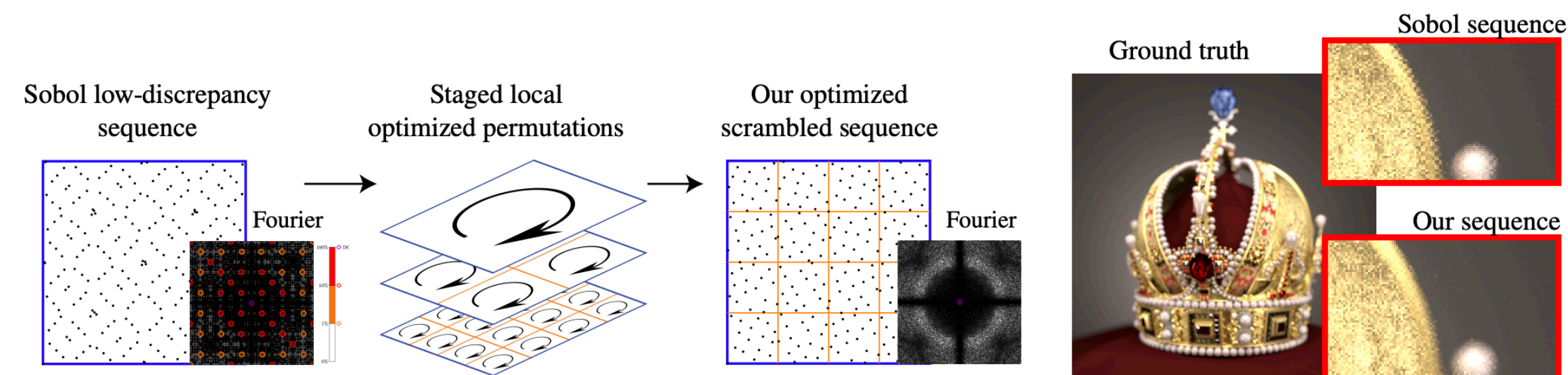
Optimizing Dyadic Nets

ABDALLA G. M. AHMED, KAUST, KSA
 PETER WONKA, KAUST, KSA

mostly applies to 2D

Sequences with Low-Discrepancy Blue-Noise 2-D Projections

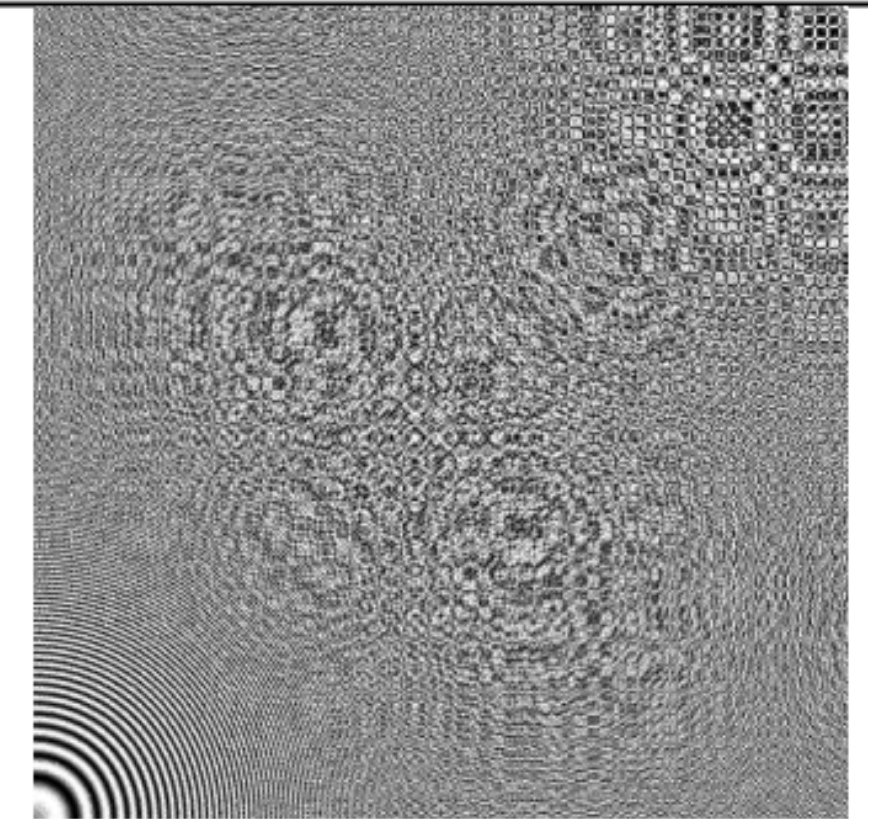
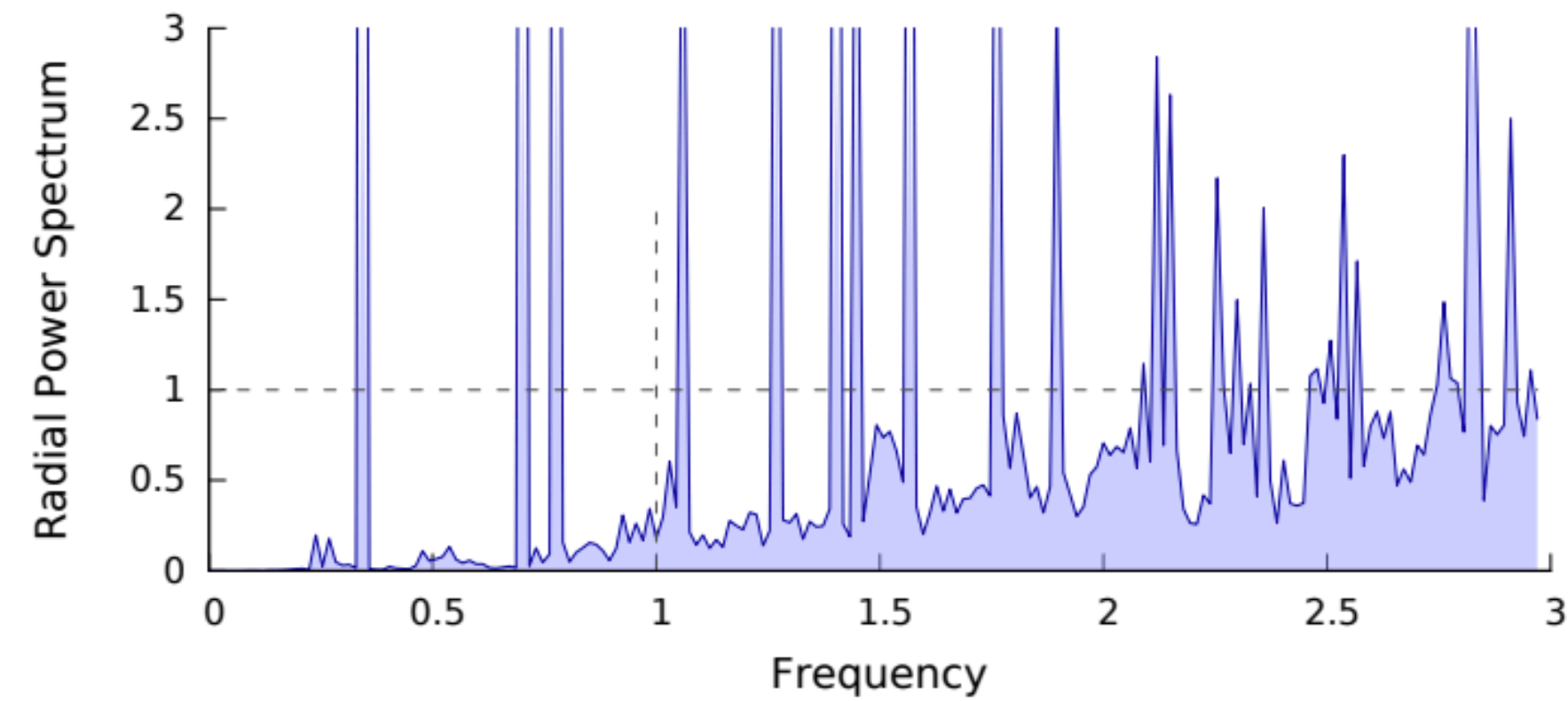
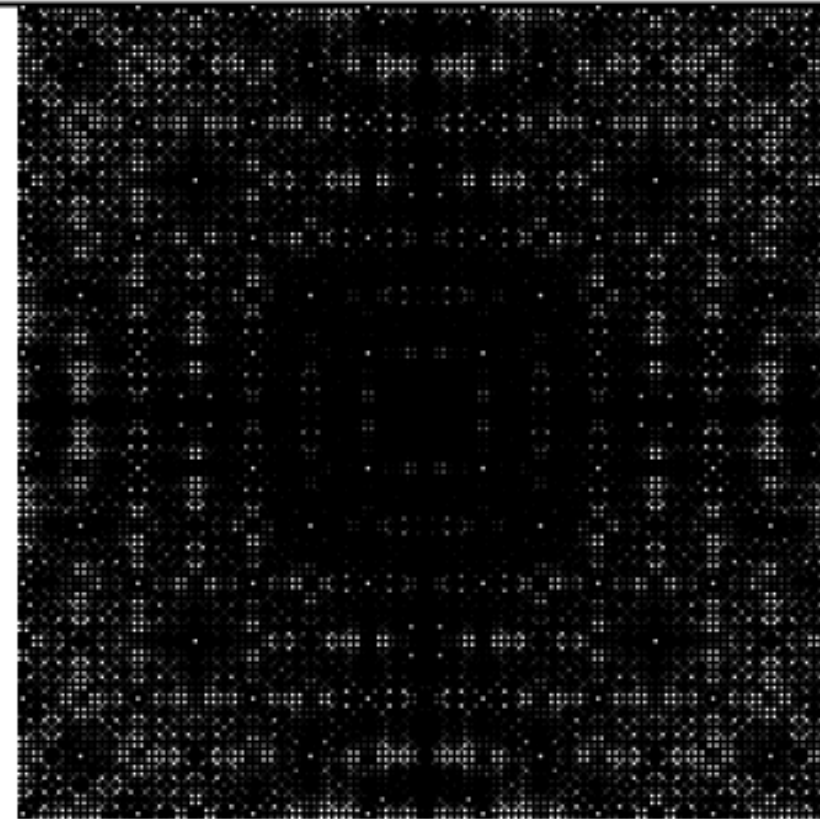
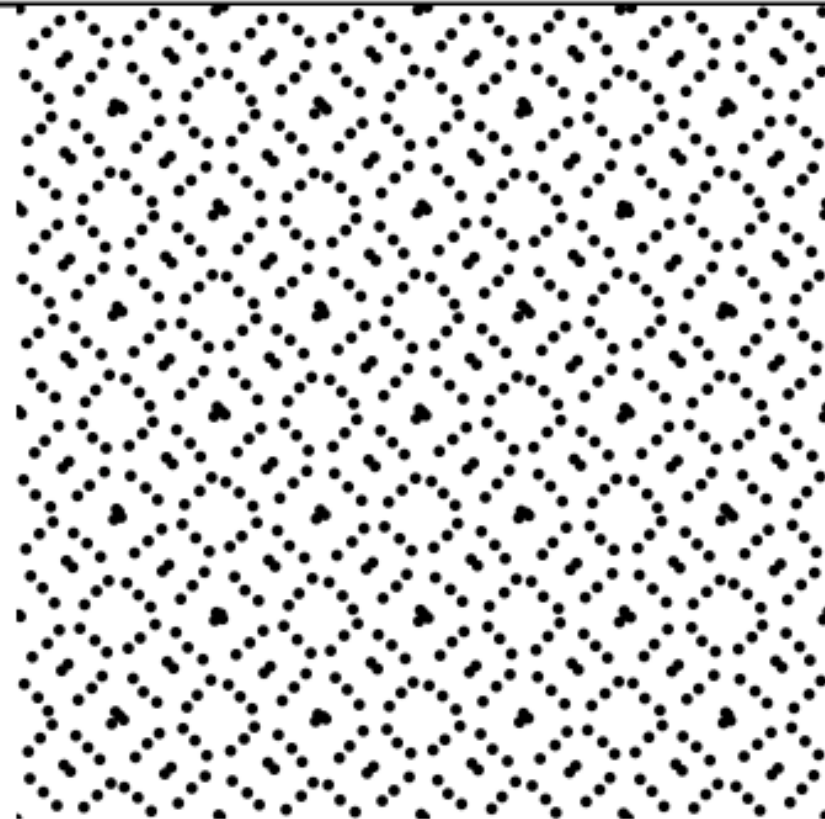
H  l  ne Perrier¹ David Coeurjolly¹ Feng Xie² Matt Pharr³ Pat Hanrahan² Victor Ostromoukhov¹
¹Universit   de Lyon, CNRS, LIRIS, France ²Stanford, USA ³Google, USA



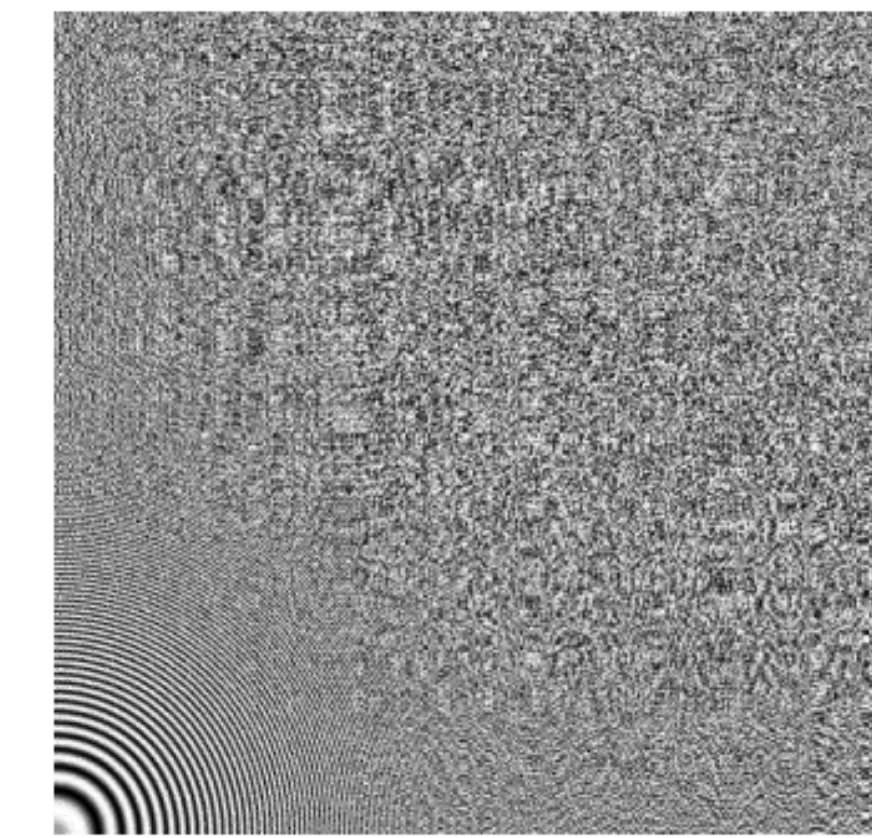
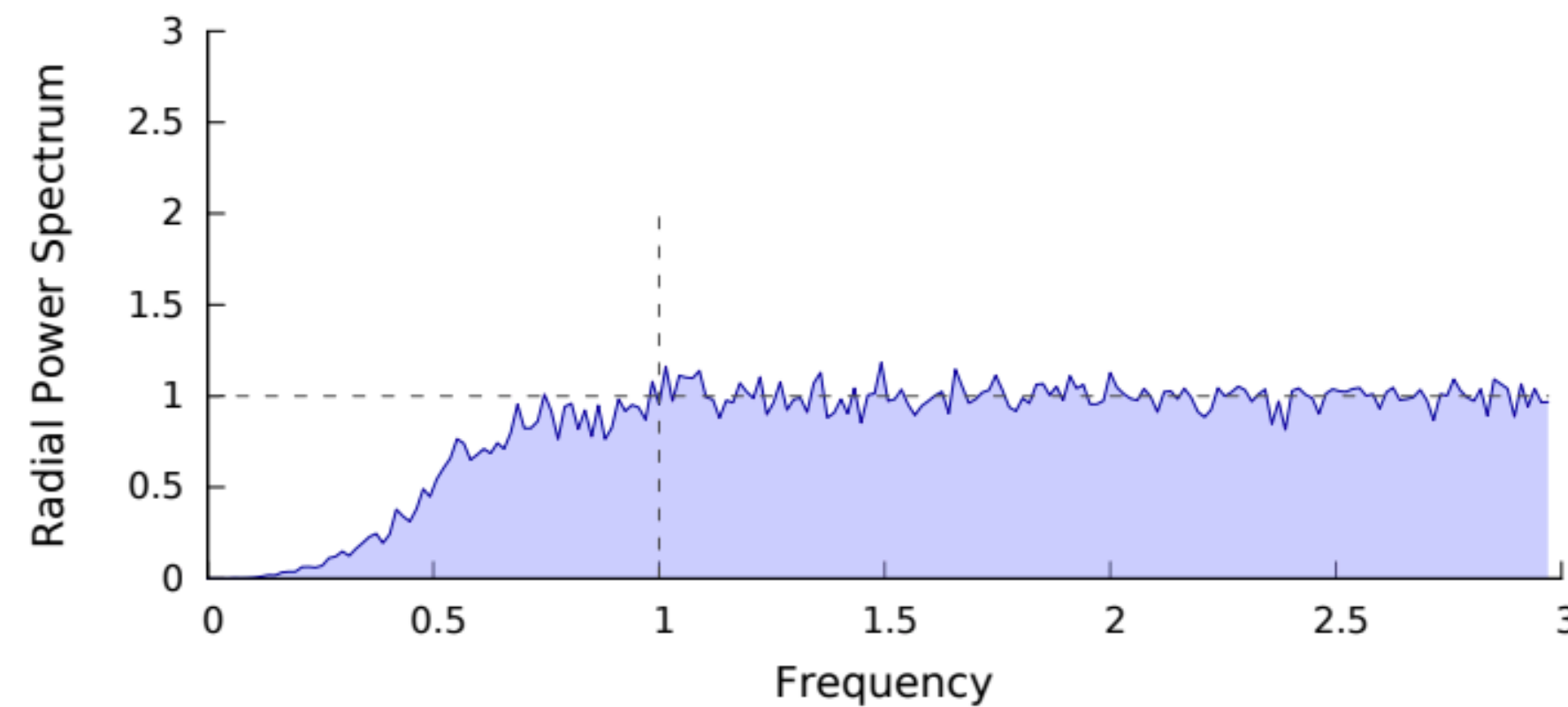
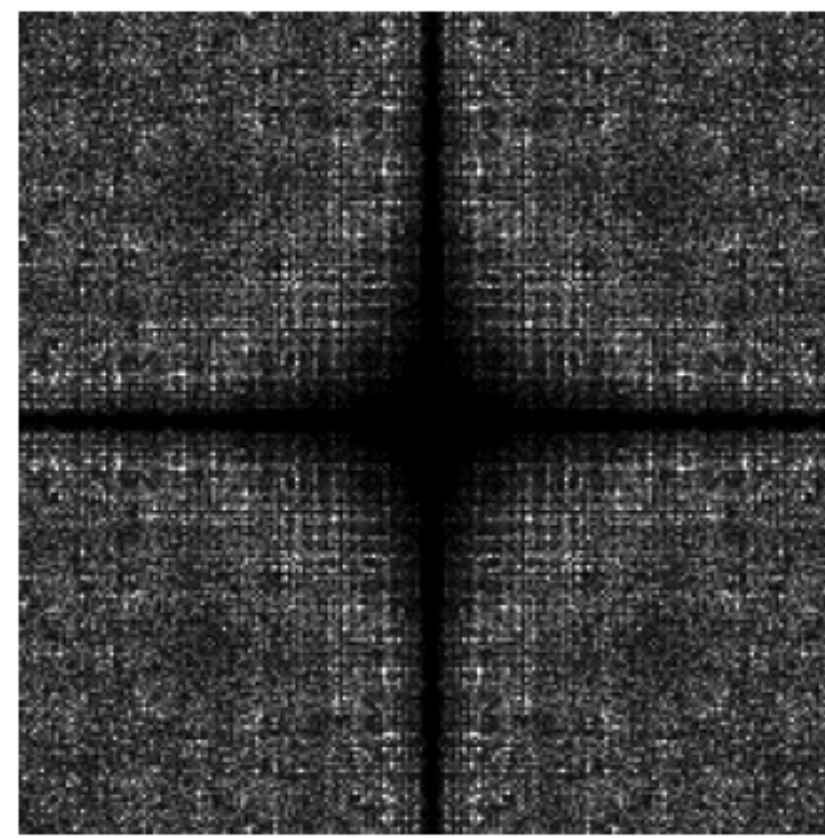
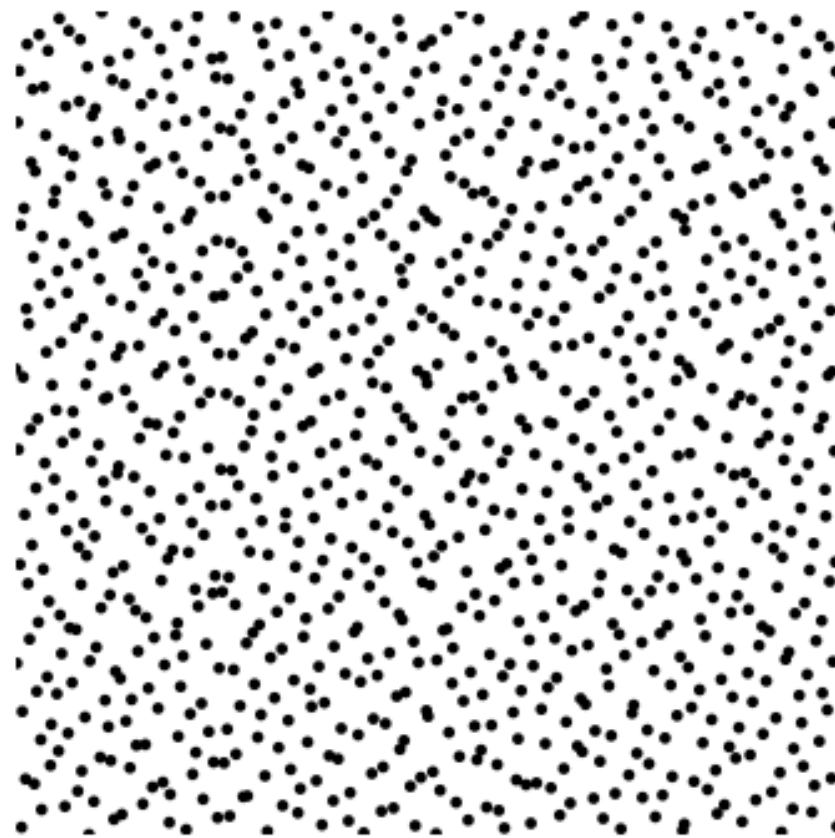
needs the # of samples to be power of 16

Power spectrum of Sobol' sampling

Sobol'
[Sob67]



Owen's scrambling
[Owe95]



Sequences with Low-Discrepancy Blue-Noise 2-D Projections

Hélène Perrier¹ David Coeurjolly¹ Feng Xie² Matt Pharr³ Pat Hanrahan² Victor Ostromoukhov¹

2019

¹Université de Lyon, CNRS, LIRIS, France

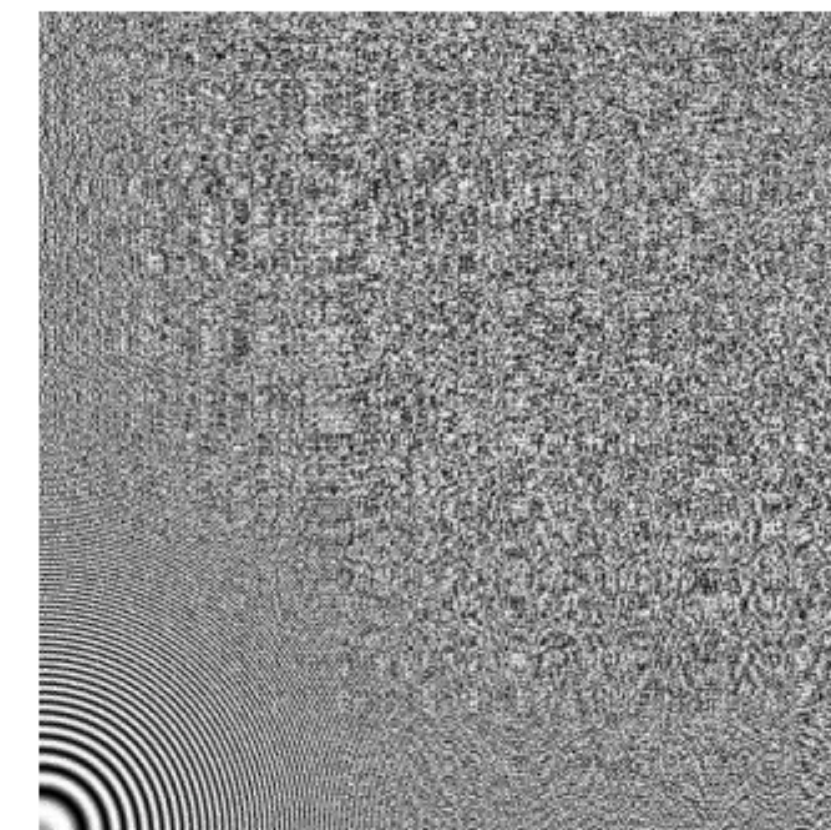
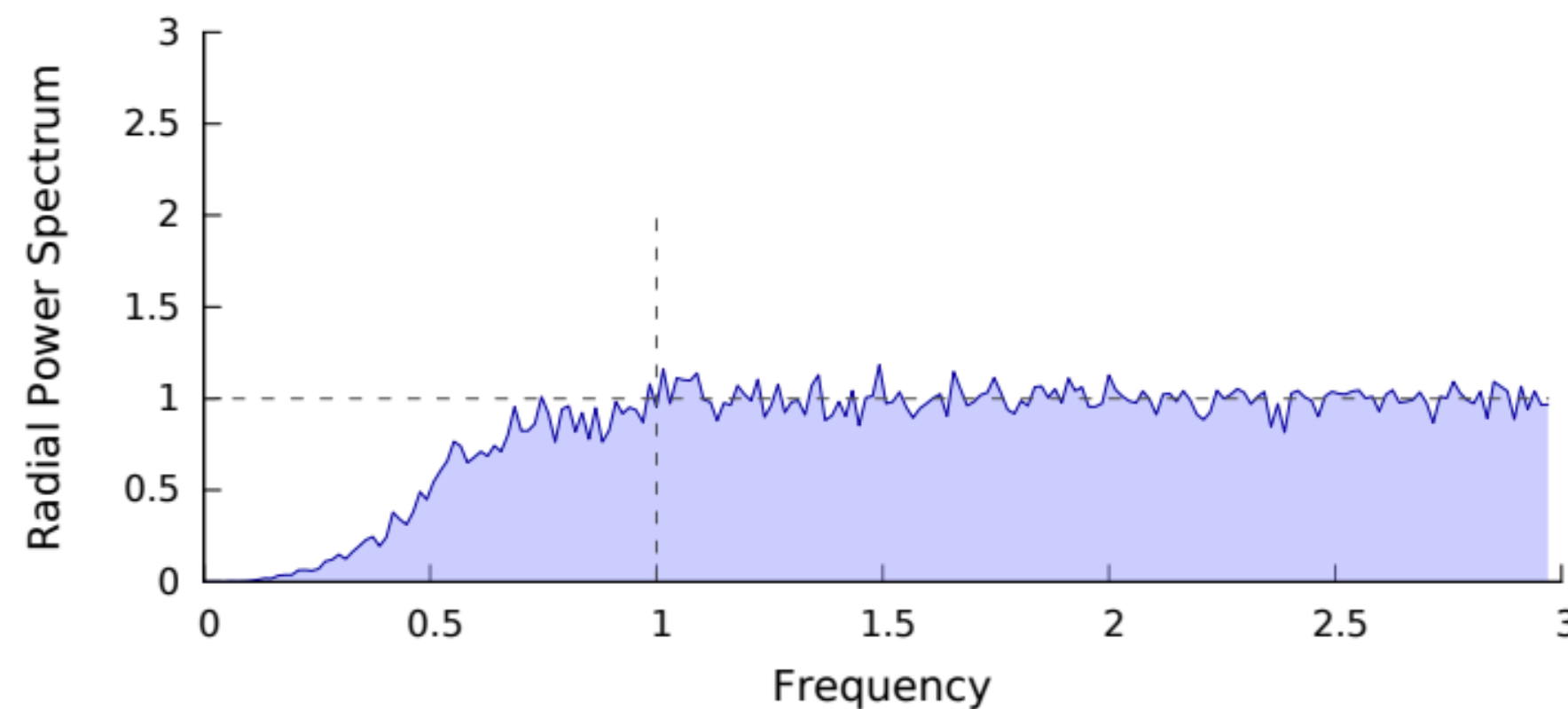
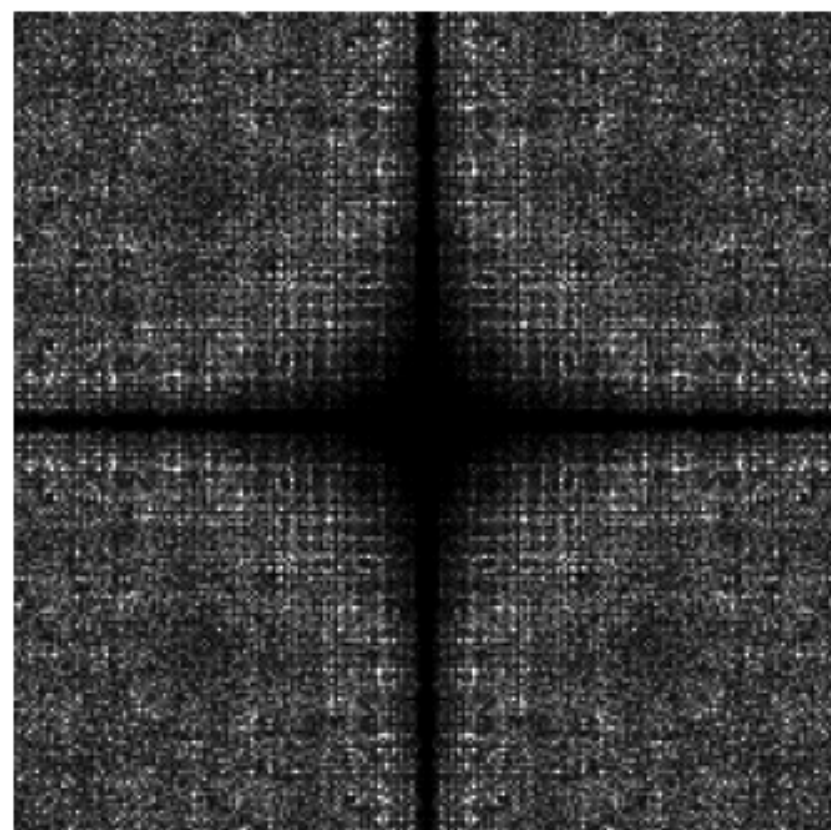
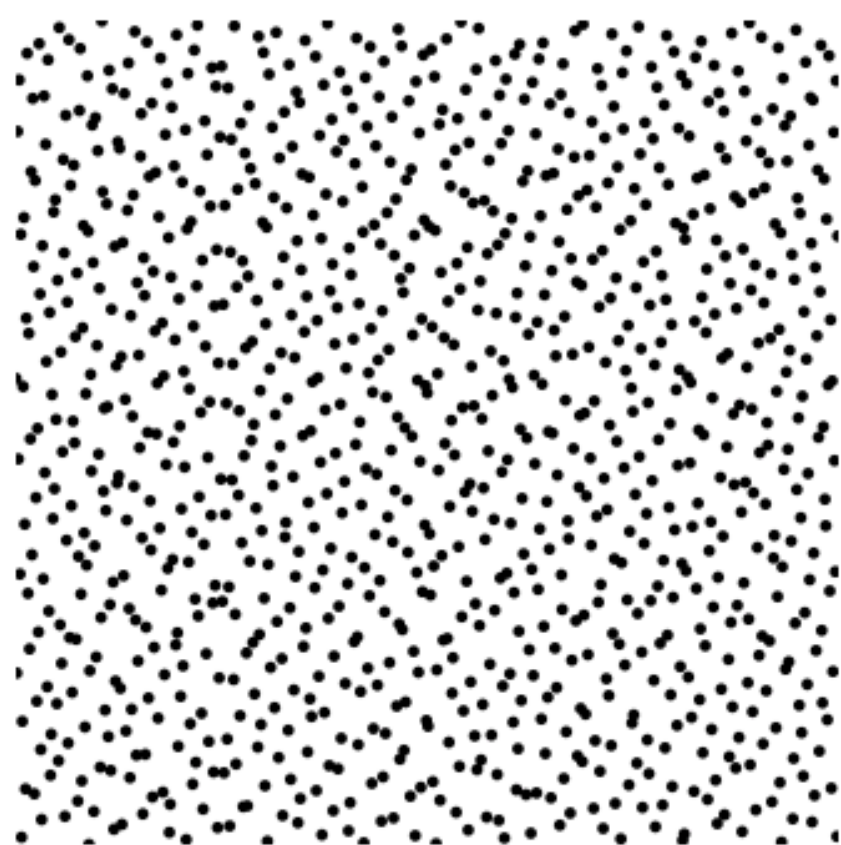
²Stanford, USA

³Google, USA

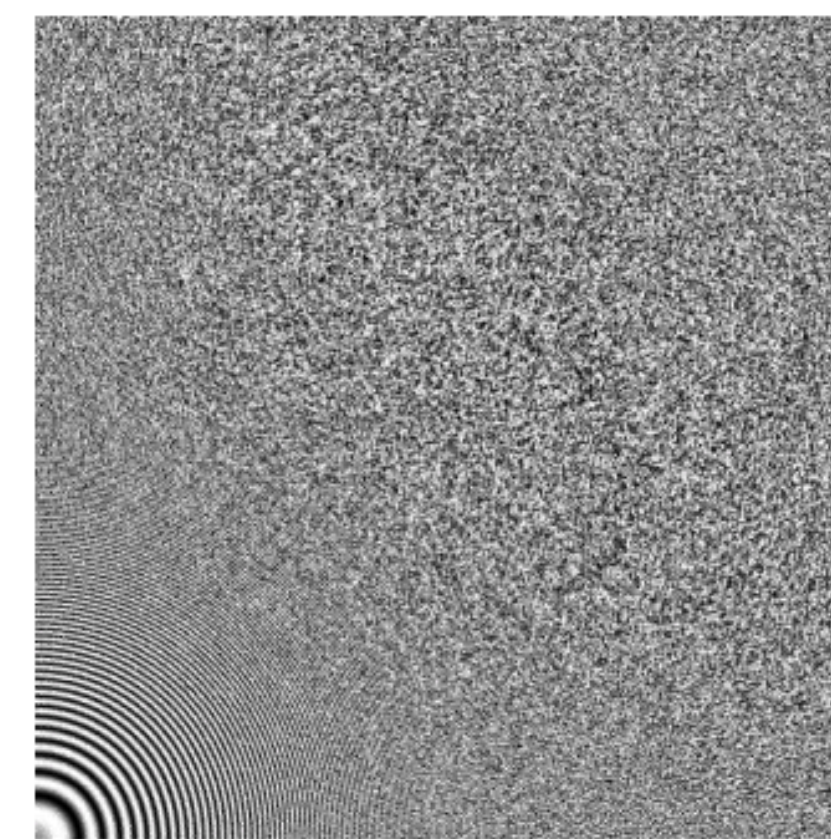
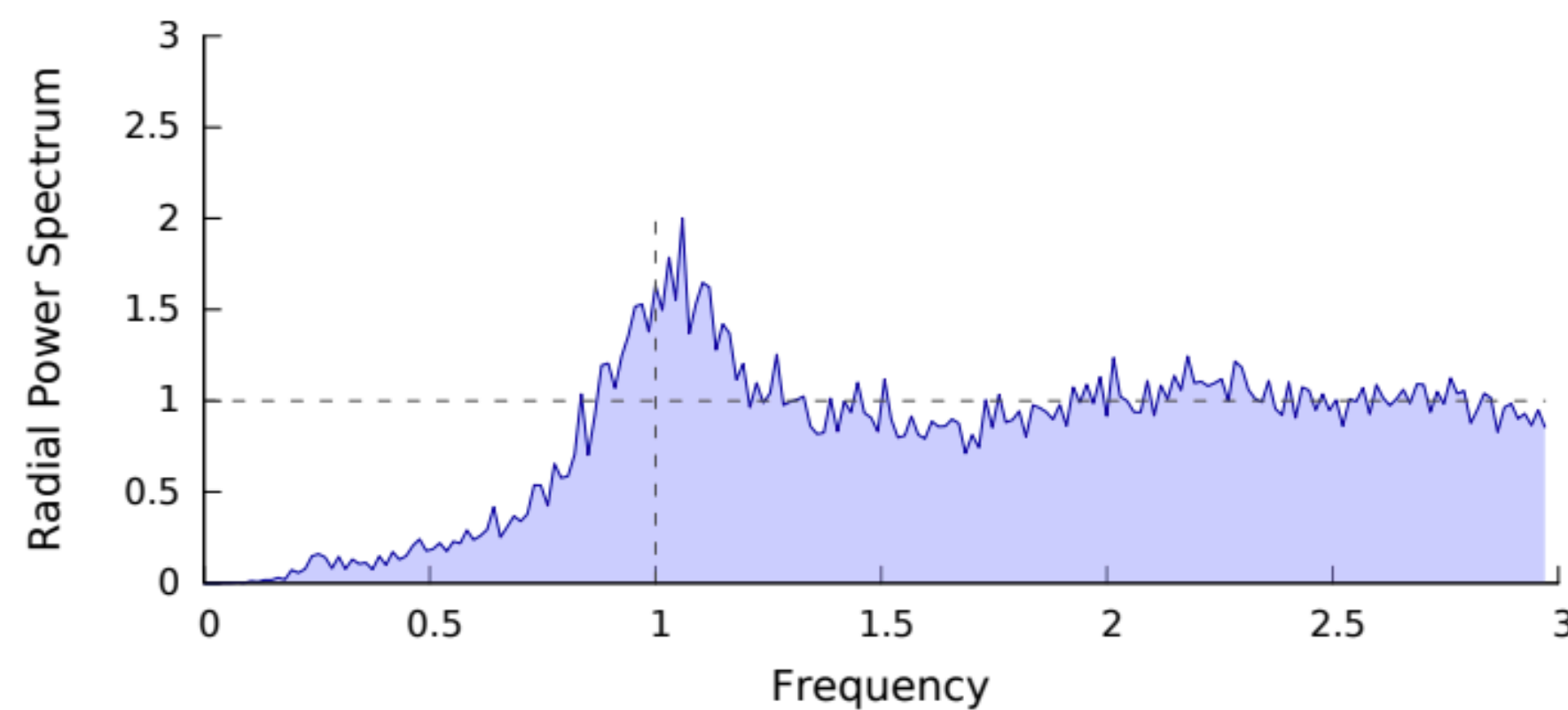
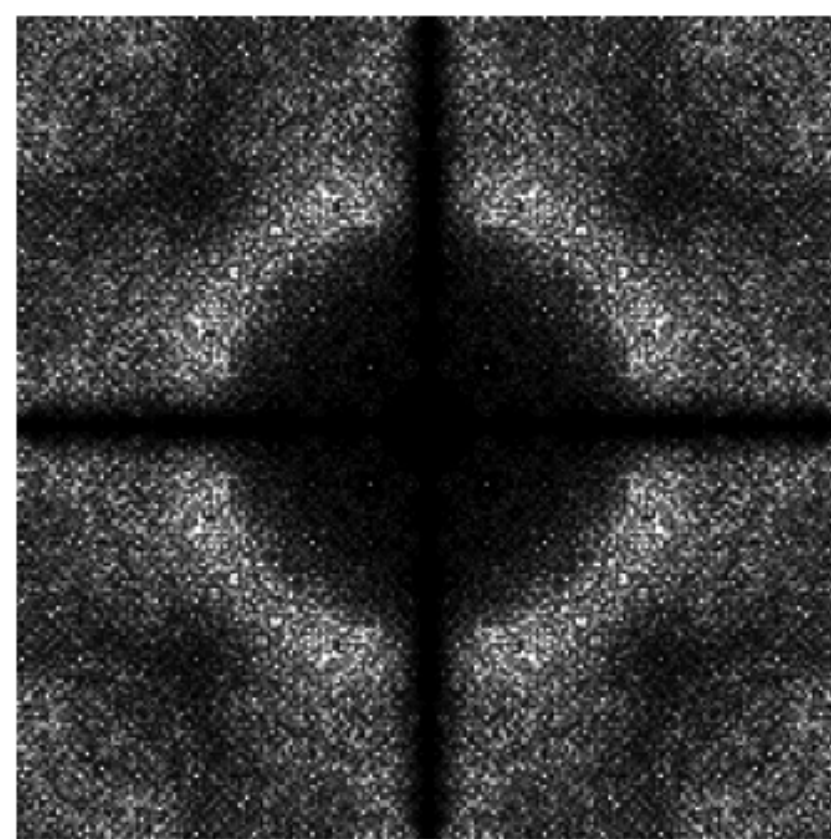
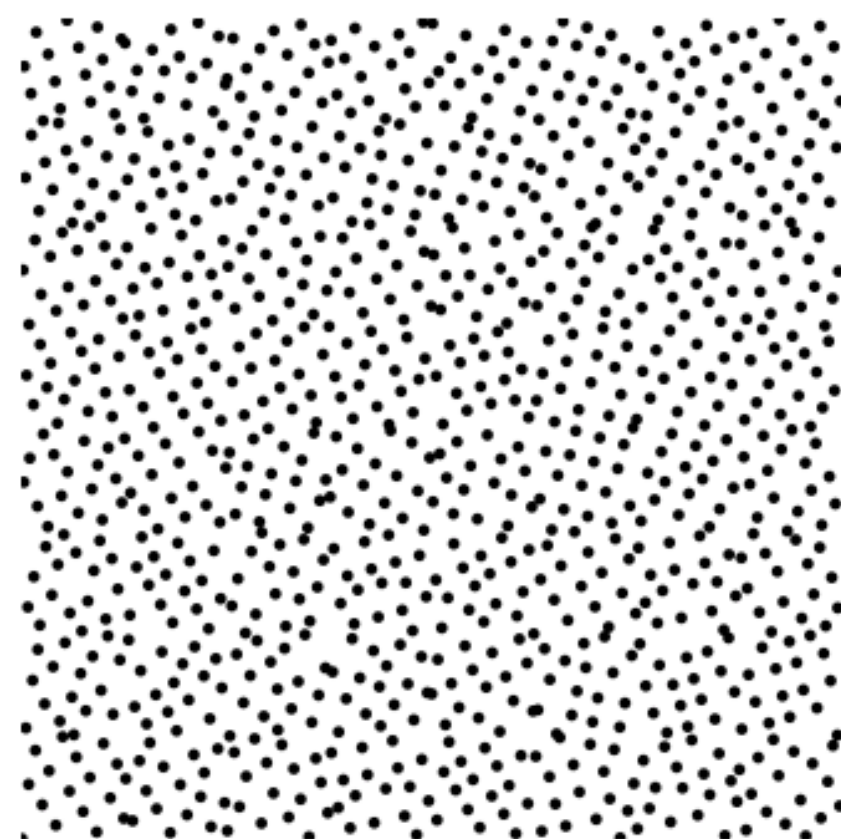
Blue-noise Low-Discrepancy Sequences

Owen's scrambling

[Owe95]



~~Ours~~, $K = 4$



Perrier et al.

Sequences with Low-Discrepancy Blue-Noise 2-D Projections

Hélène Perrier¹ David Coeurjolly¹ Feng Xie² Matt Pharr³ Pat Hanrahan² Victor Ostromoukhov¹

2019

¹Université de Lyon, CNRS, LIRIS, France

²Stanford, USA

³Google, USA

Connection to optimal transport/ Wasserstein distance

- Rubinstein-Kantorovich theorem

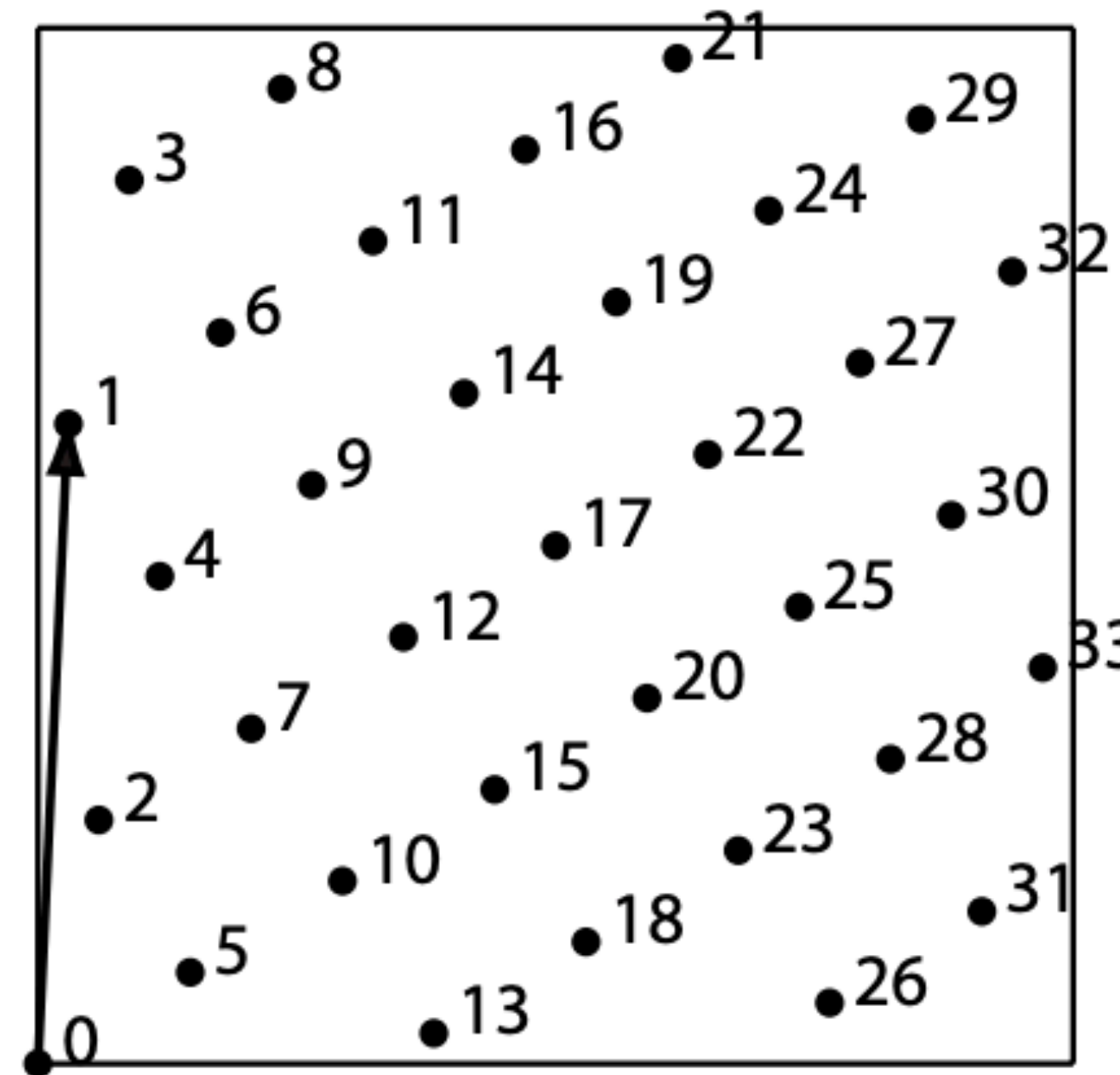
$$\left| \int f(x) dx - \frac{1}{n} \sum_{i=1}^n f(x^i) \right| \leq \text{Lip}(f) \cdot W_1(X, 1_\Omega),$$

instead of using discrepancies, measure the earth mover distance

Sliced Optimal Transport Sampling

LOIS PAULIN, Univ Lyon, CNRS
NICOLAS BONNEEL, Univ Lyon, CNRS
DAVID COEURJOLLY, Univ Lyon, CNRS
JEAN-CLAUDE IEHL, Univ Lyon, CNRS
ANTOINE WEBANCK, Univ Lyon, CNRS
MATHIEU DESBRUN, ShanghaiTech/Caltech
VICTOR OSTROMOUKHOV, Univ Lyon, CNRS

Rank-1 lattice



Rank-1 Lattices for Efficient Path Integral Estimation

Hongli Liu¹ and Honglei Han^{1 †} and Min Jiang²

¹State Key Laboratory of Media Convergence and Communication,
and School of Animation and Digital Arts, Communication University of China, China

²Framestore, United Kingdom

2021

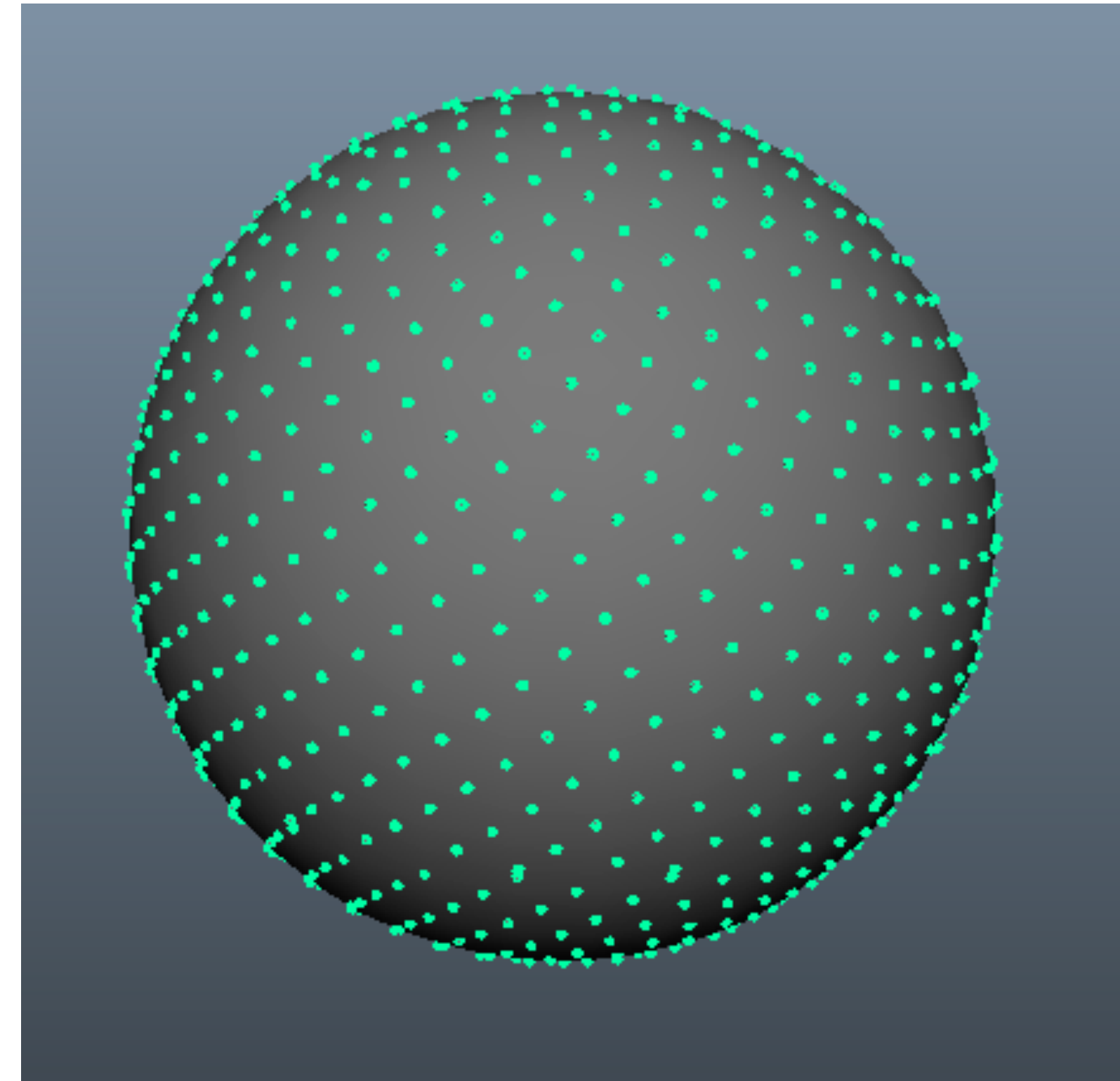
Image Synthesis by Rank-1 Lattices

S. Dammertz and A. Keller

Institute of Media Informatics, Ulm University, Germany

2006

Spherical Fibonacci lattice



Spherical Fibonacci Point Sets for Illumination Integrals

R. Marques¹, C. Bouville², M. Ribardière², L. P. Santos³ and K. Bouatouch²

¹INRIA Rennes, France

²IRISA Rennes, France

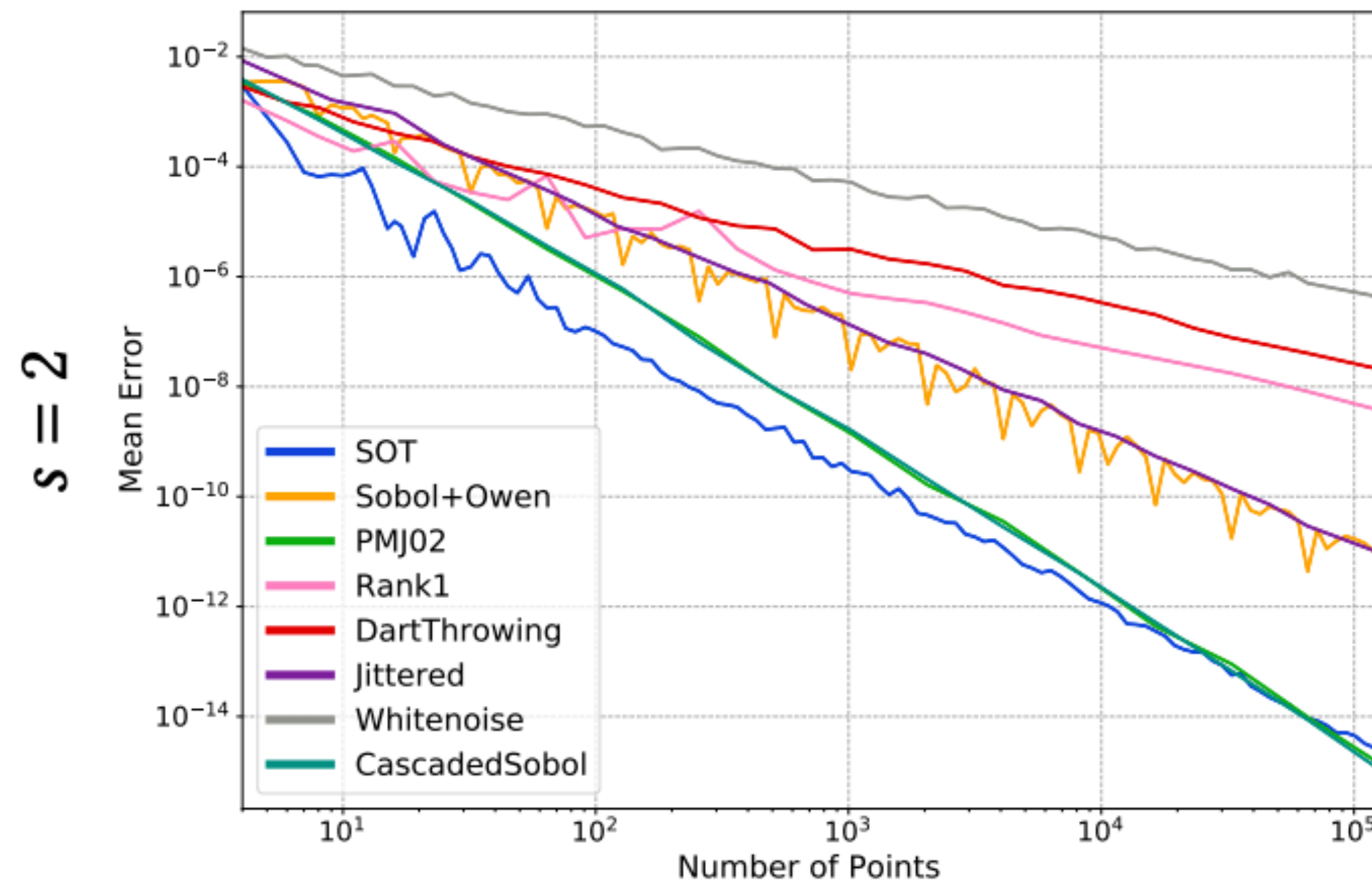
³Universidade do Minho, Braga, Portugal

<https://math.stackexchange.com/questions/3291489/can-the-fibonacci-lattice-be-extended-to-dimensions-higher-than-3>

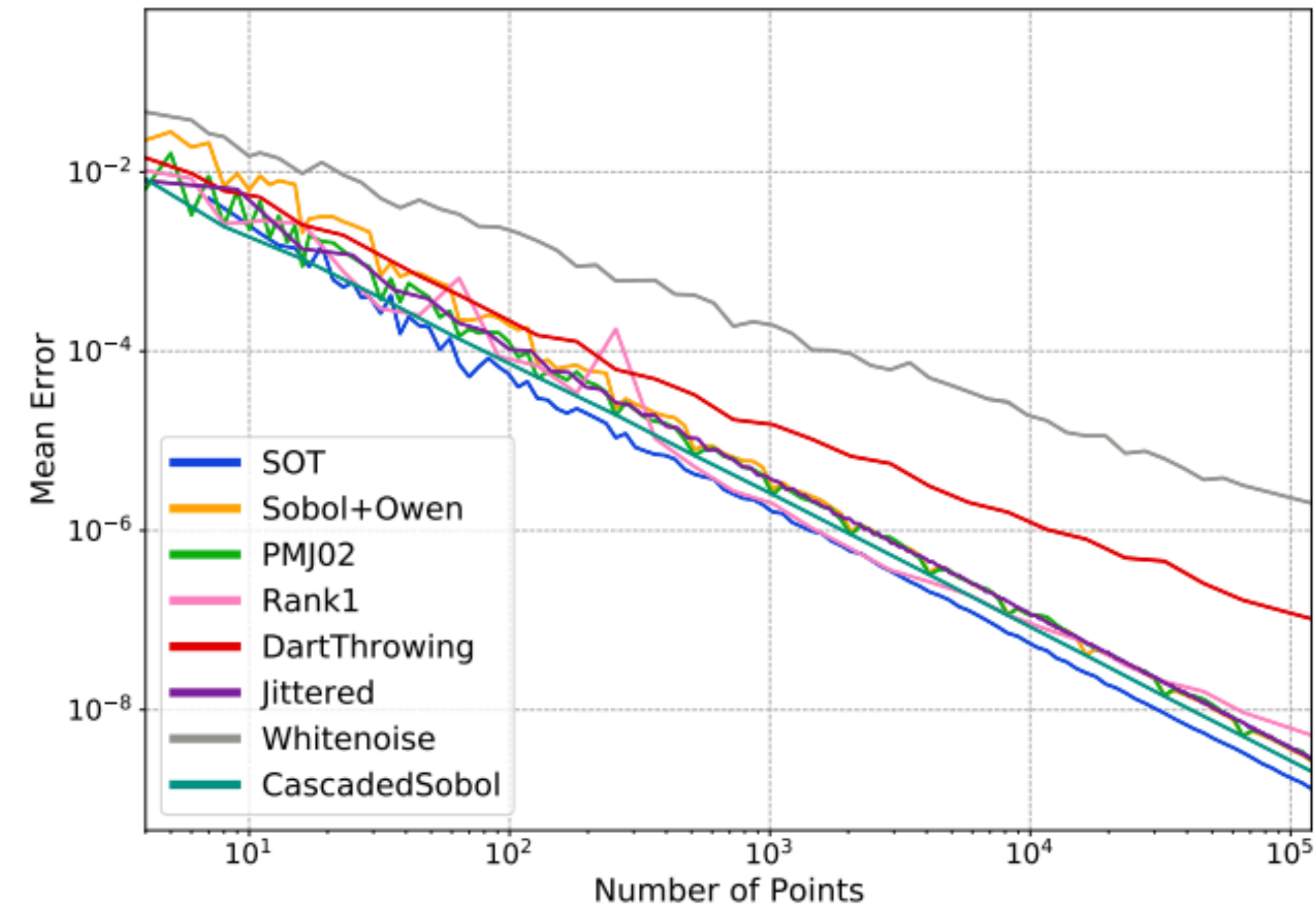
Comparison between low-discrepancy sequences and jittering

at low dimension, for smooth integrands, digital nets often outperform jittering
(but extensions of progressive multi-jittering, PMJ02, is as good at 2D)

Gaussian integrands

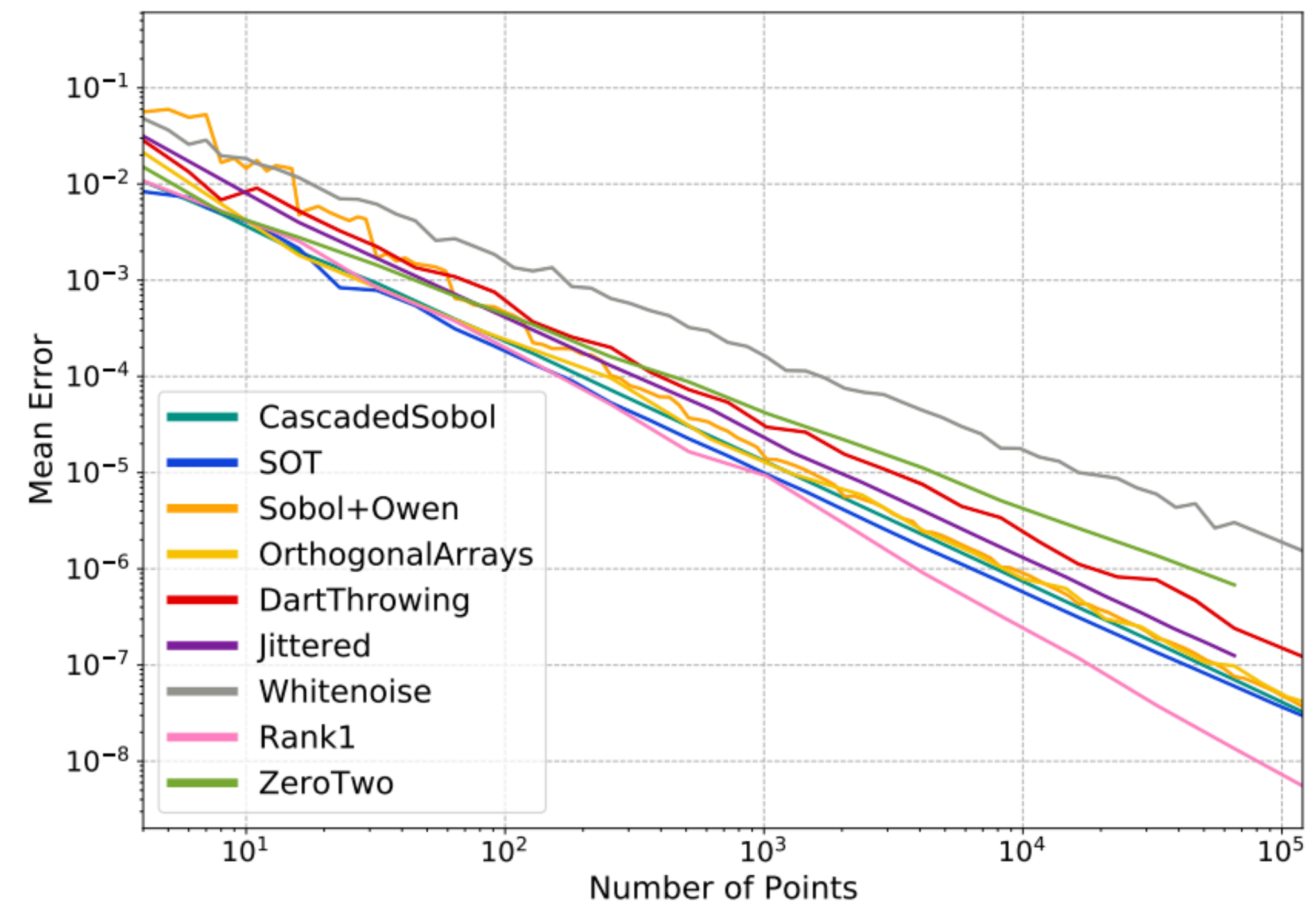
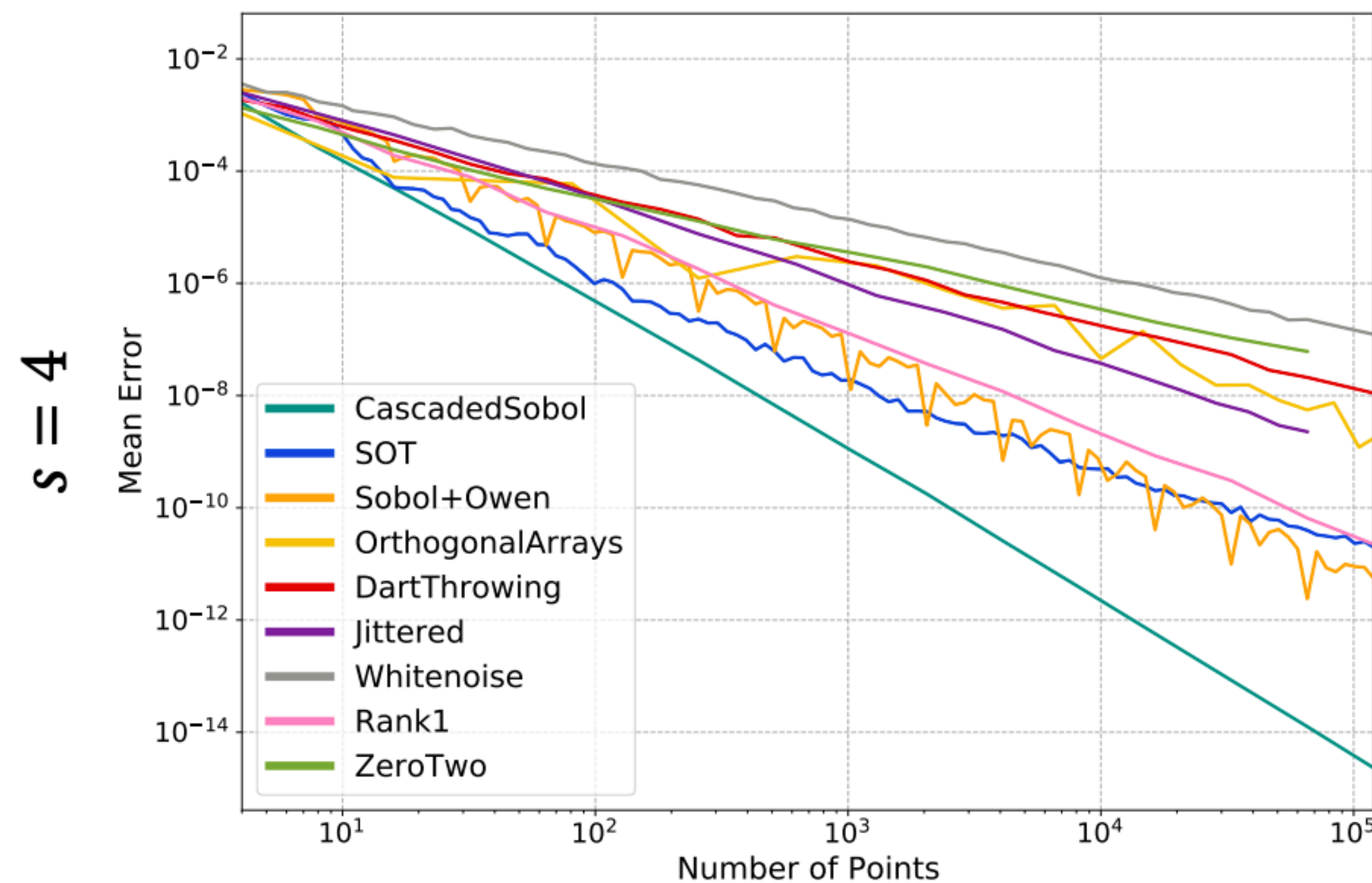


Heaviside integrands



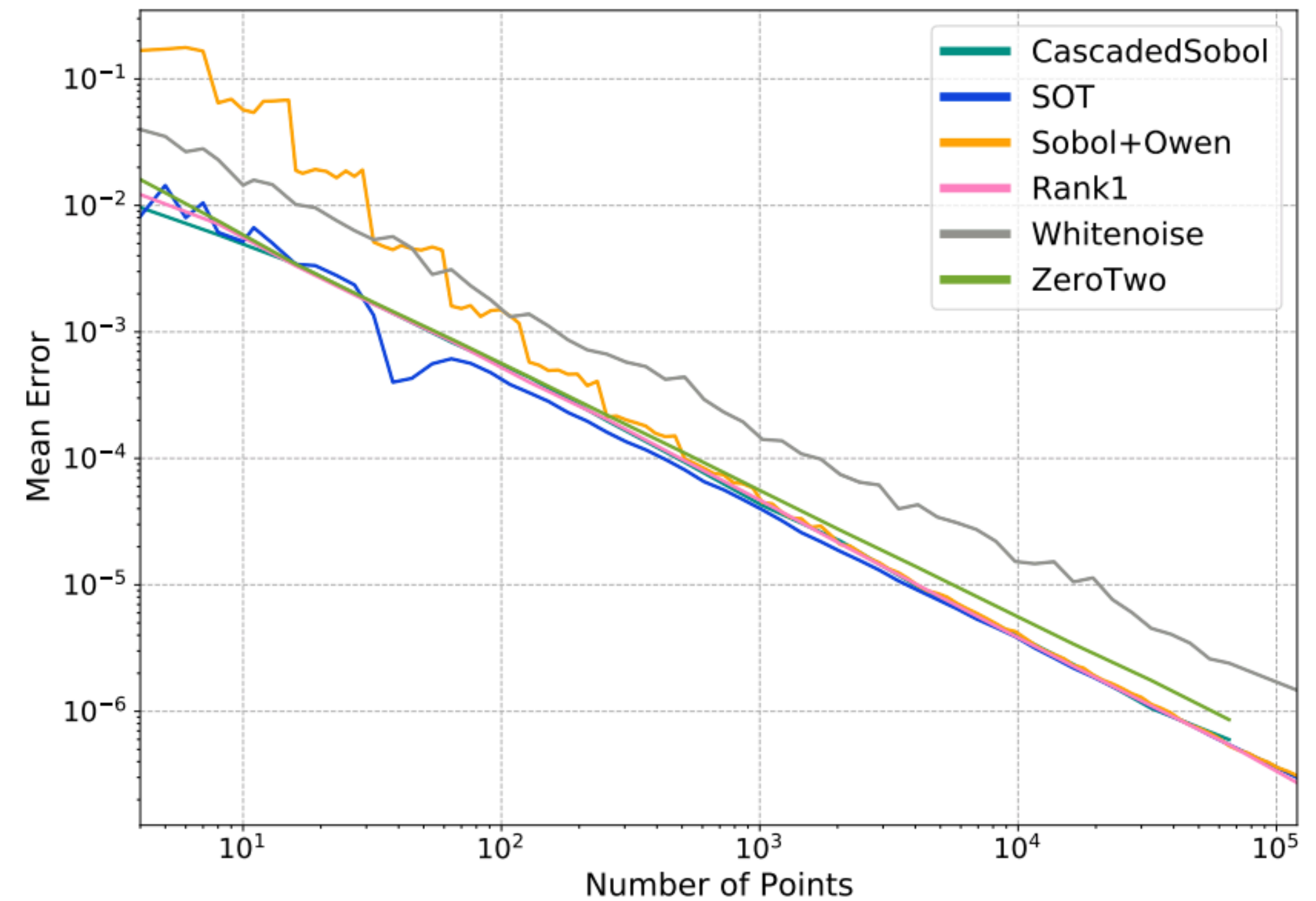
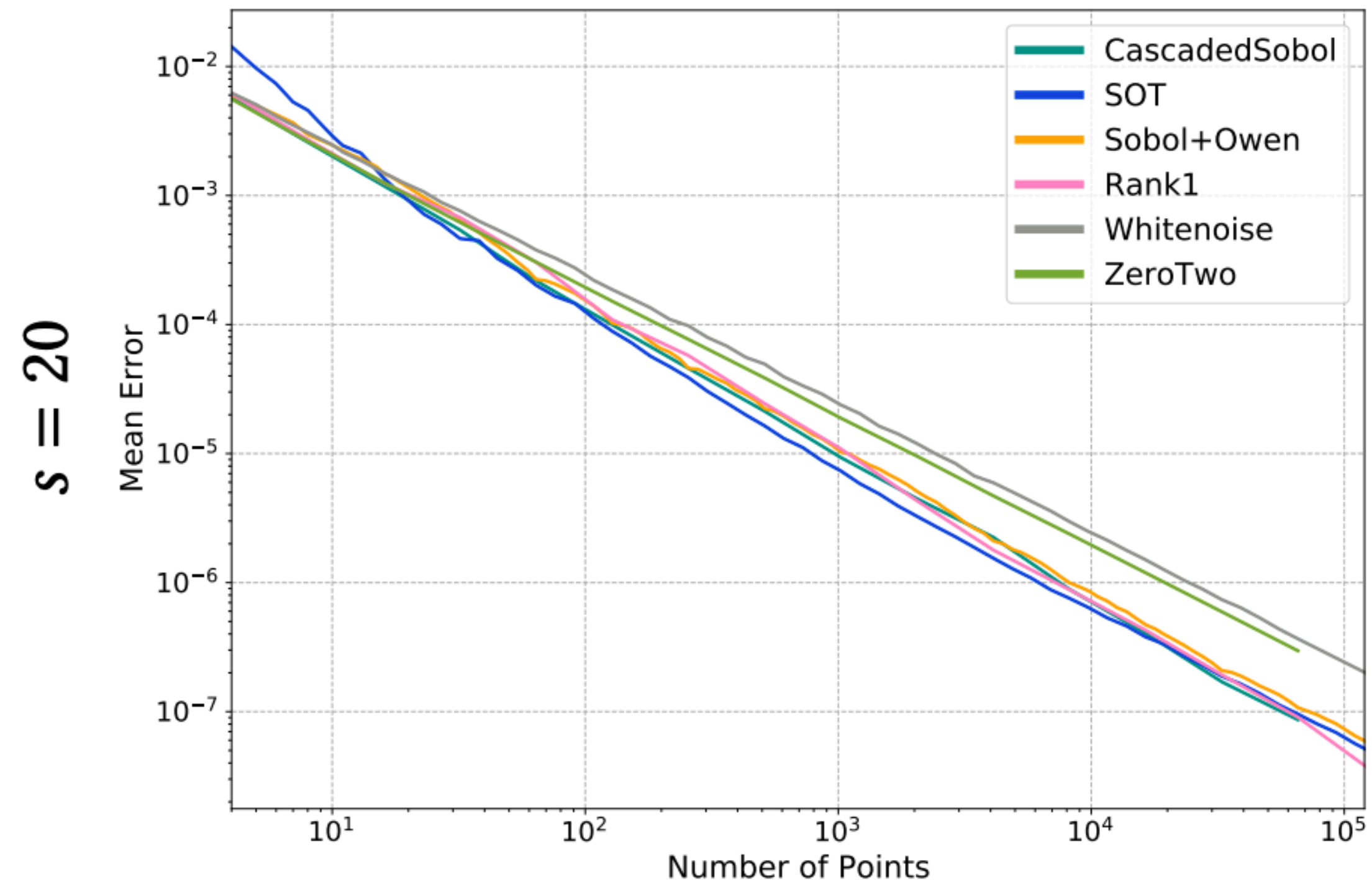
Comparison between low-discrepancy sequences and jittering

at mid dimension, for smooth integrals, digital nets still often outperform jittering
(PMJ02 requires uncorrelated jittering to work and is less effective)



Comparison between low-discrepancy sequences and jittering

at high dimension, all methods are similar, except independent white noise



So, which sample sequence should we use?

- PMJ is much easier to combine with blue noise, so it has better perceptual quality
- Digital nets can converge faster in mid dimensional smooth problems (e.g., 4-8D)
- For high-dimensional problems ($>10D$), you are good as long as you don't use white noise

Related topic: blue-noise dithered sampling

- focus on the reconstruction properties of sampling patterns, instead of integration

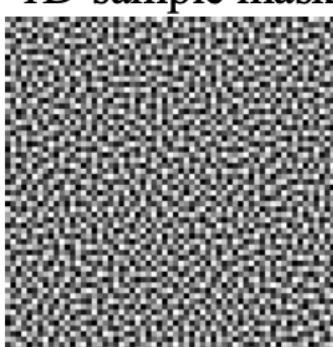
often by optimizing the Cranley-Patterson rotation offset in preprocessing

Blue-noise Dithered Sampling

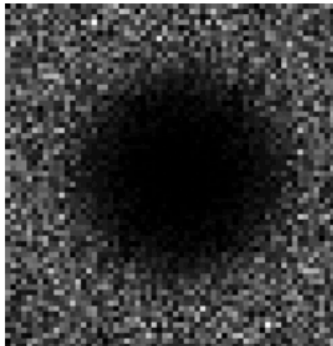
Iliyan Georgiev
Solid Angle

Marcos Fajardo
Solid Angle

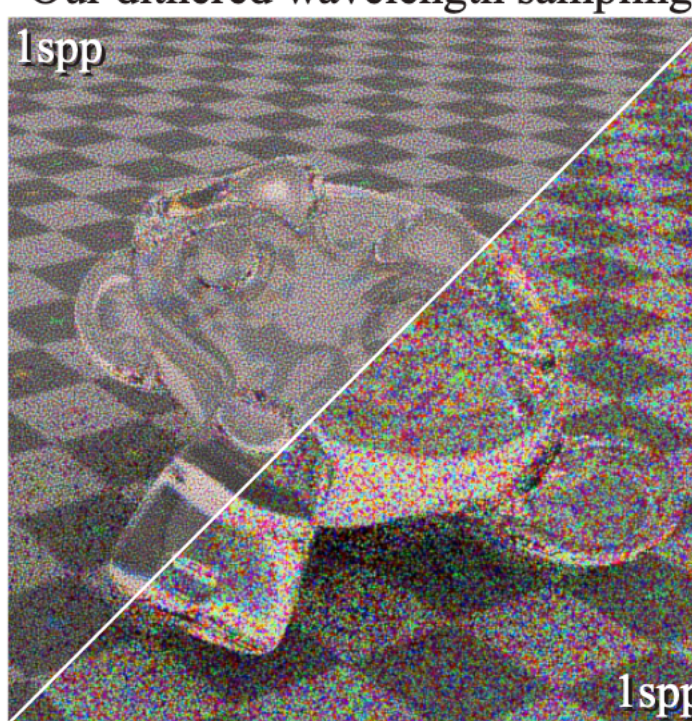
1D-sample mask



Fourier pow. spec.

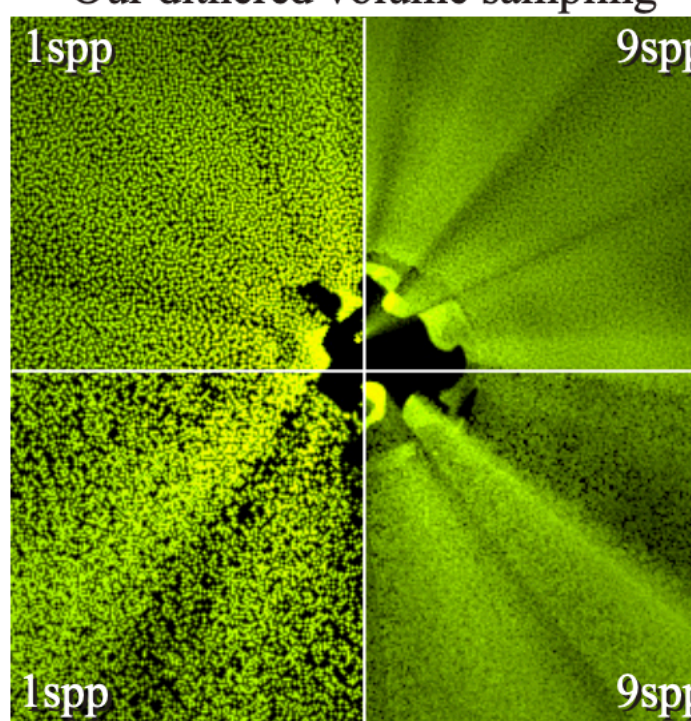


Our dithered wavelength sampling
1spp



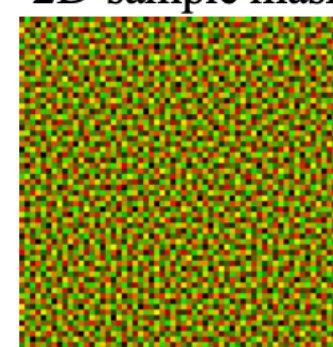
Random pixel decorrelation

Our dithered volume sampling
1spp



Random pixel decorrelation

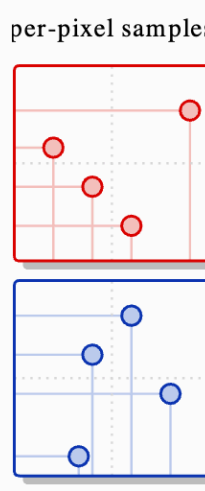
2D-sample mask

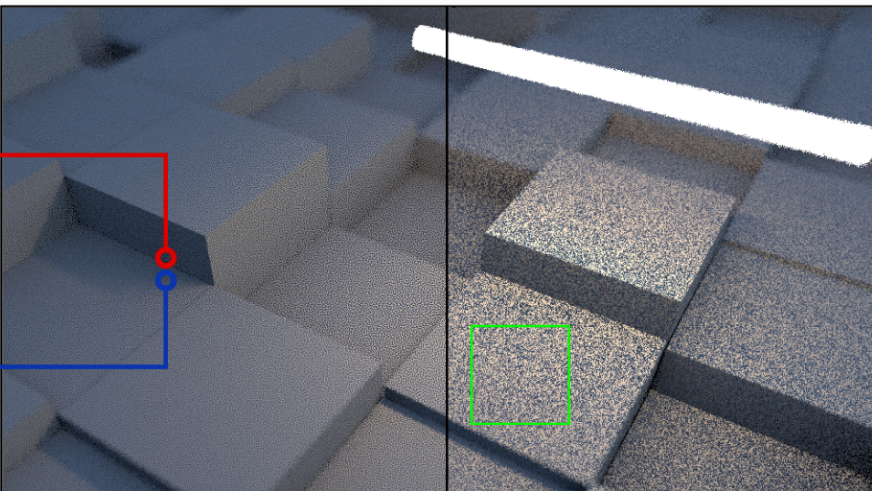


A Low-Discrepancy Sampler that Distributes Monte Carlo Errors as a Blue Noise in Screen Space
 Eric Heitz (Unity Technologies) - Laurent Belcour (Unity Technologies) - Victor Ostromoukhov - David Coeurjolly - Jean-Claude Iehl (LIRIS)
 Published in ACM SIGGRAPH Talk 2019

[paper](#) [bib](#) [supp. code](#) [supp. doc](#) [unity demo](#) [supp. html](#) [video](#) [slides](#)

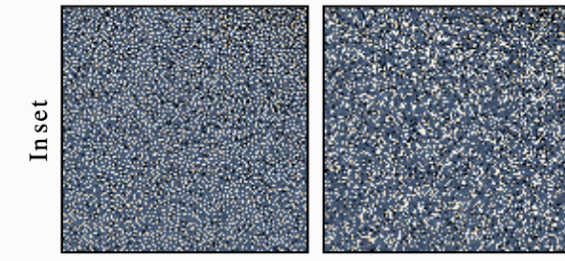
per-pixel samples



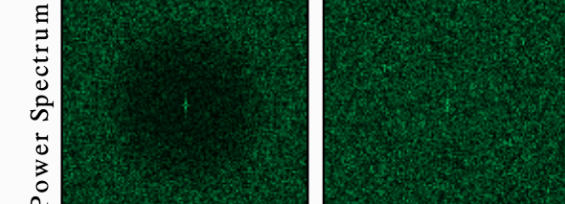


Ours Random LD sampler

1 spp



Inset



Power Spectrum

Ours Random LD sampler

Project Abstract

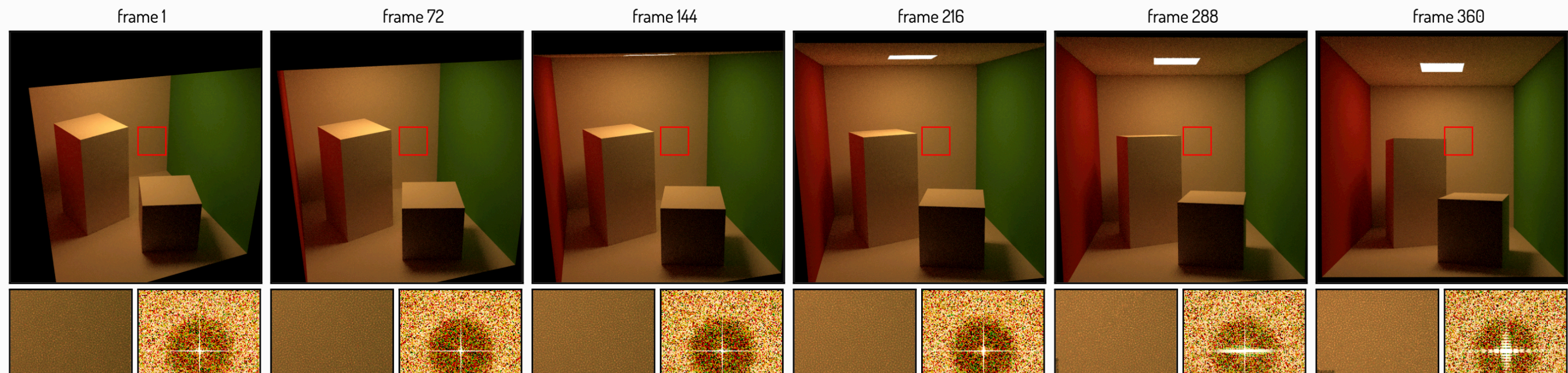
Distributing Monte Carlo Errors as a Blue Noise in Screen Space by Permuting Pixel Seeds Between Frames

Eric Heitz (Unity Technologies) - Laurent Belcour (Unity Technologies)
 Published in Eurographics Symposium on Rendering (EGSR) 2019

[paper](#) [supp. material](#) [demo](#) [slides](#)

Perceptual error optimization for Monte Carlo rendering

VASSILLEN CHIZHOV, MIA Group Saarland University, Max-Planck-Institut für Informatik, Germany
 ILIYAN GEORGIEV, Autodesk, United Kingdom
 KAROL MYSZKOWSKI, Max-Planck-Institut für Informatik, Germany
 GURPRIT SINGH, Max-Planck-Institut für Informatik, Germany



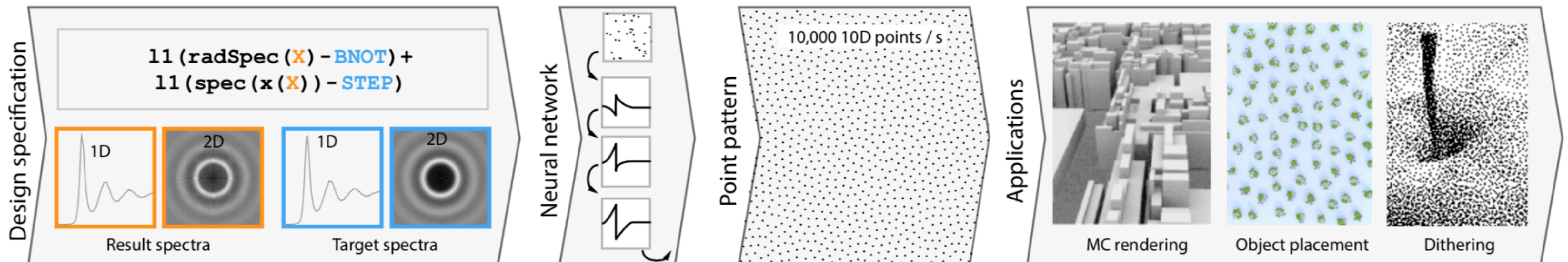
Neural nets for point sampling

Deep Point Correlation Design

Thomas Leimkühler¹, Gurprit Singh¹, Karol Myszkowski¹, Hans-Peter Seidel¹, Tobias Ritschel²

¹Max Planck Institute for Informatics, Saarbrücken, ²University College London, UK

In ACM Transactions on Graphics (Proceedings of SIGGRAPH Asia 2019, Volume 38 issue 6)



Next: path-space & Eric Veach

next Monday is holiday!

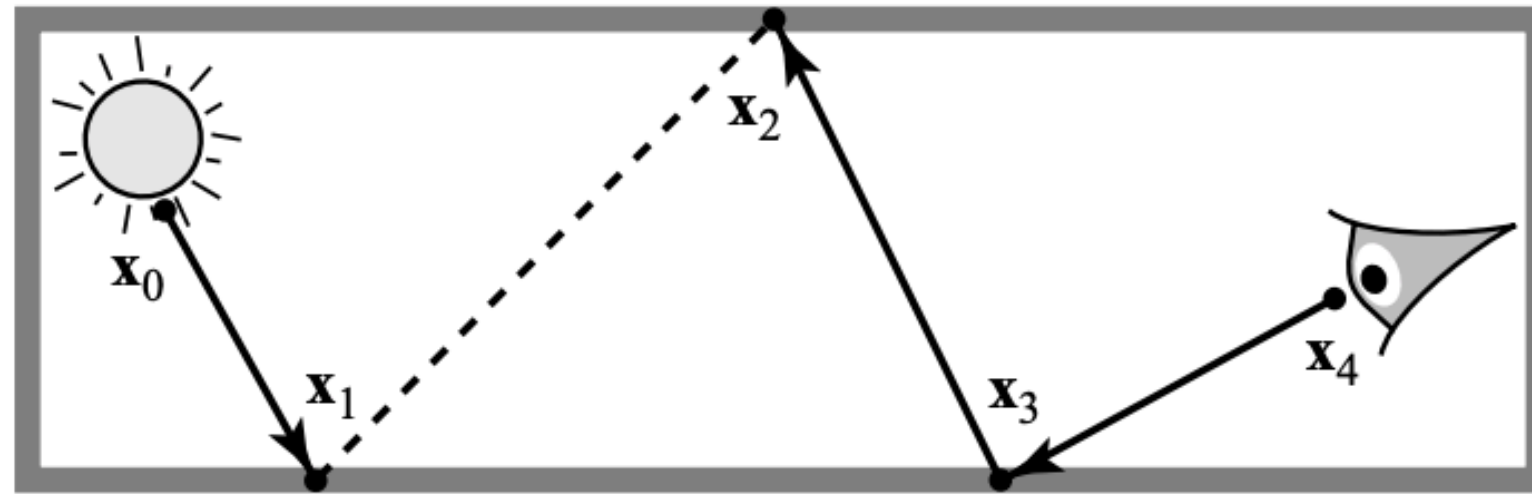
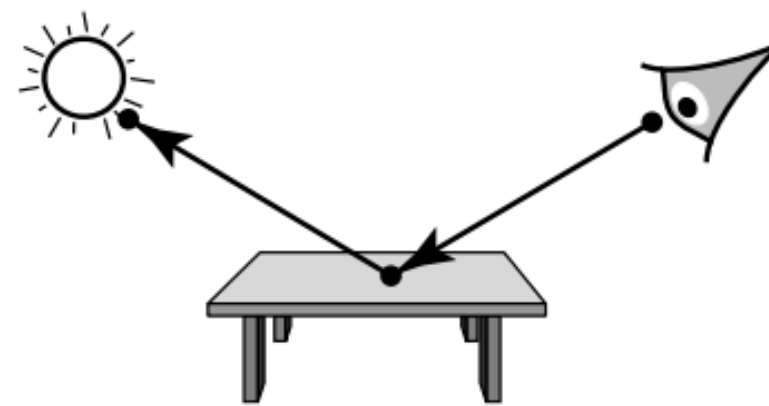


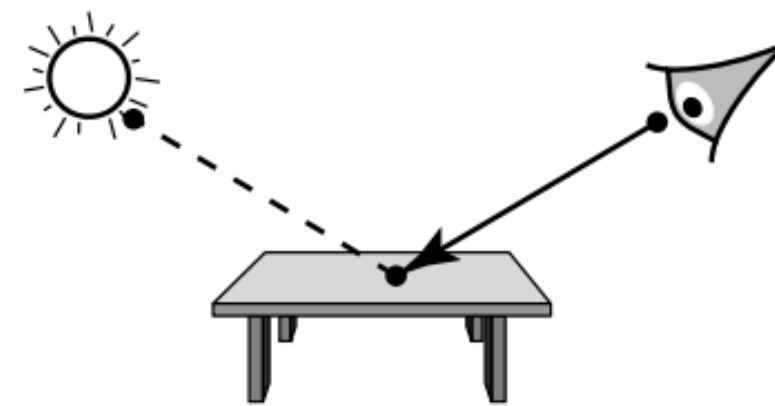
Figure 10.1: A transport path from a light source to the camera lens, created by concatenating two separately generated pieces.

ROBUST MONTE CARLO METHODS
FOR LIGHT TRANSPORT SIMULATION

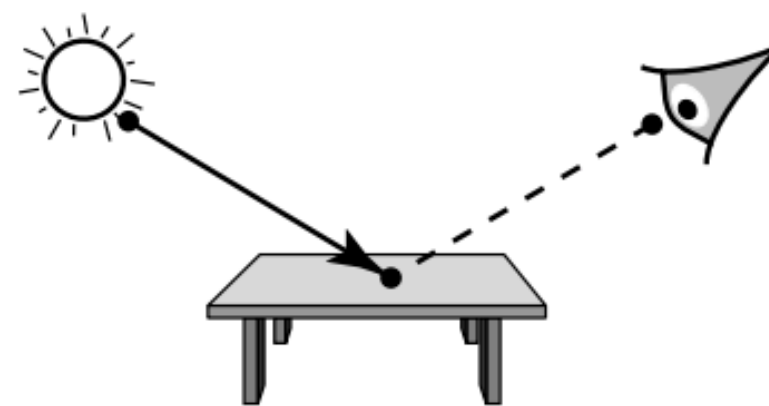
A DISSERTATION
SUBMITTED TO THE DEPARTMENT OF COMPUTER SCIENCE
AND THE COMMITTEE ON GRADUATE STUDIES
OF STANFORD UNIVERSITY
IN PARTIAL FULFILLMENT OF THE REQUIREMENTS
FOR THE DEGREE OF
DOCTOR OF PHILOSOPHY



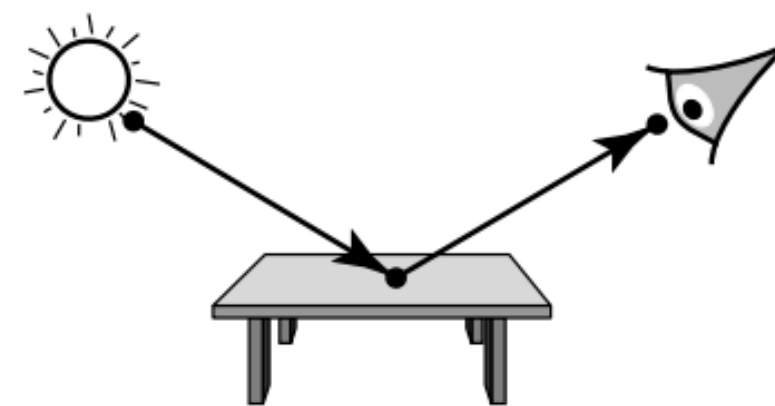
(a) $s = 0, t = 3$



(b) $s = 1, t = 2$



(c) $s = 2, t = 1$



(d) $s = 3, t = 0$

by
Eric Veach
December 1997