### Sachiko Matsumoto

Computer Science and Engineering University of California, San Diego

Website: https://cseweb.ucsd.edu/~smatsumo Email: smatsumo@ucsd.edu

**Research** Robotics, Human-Robot Interaction, Artificial Intelligence, Shared Control,

**Interests** Telepresence, Health Technology

**Education** University of California, San Diego

June 2024

Ph.D., Computer Science and Engineering

(Expected)

Advisor: Dr. Laurel D. Riek

Thesis: Telepresence Robots for Safety-Critical Environments: Contextualizing

Shared Control for Dynamic Spaces

University of California, Berkeley

May 2018

B.A., Computer Science; B.A., Physics

**Publications** Matsumoto, S. and Riek, L. D. (2024). Telepresence Robots for Dynamic,

Safety-Critical Environments. In Proceedings of the ACM/IEEE International

Conference on Human-Robot Interaction (HRI) Pioneers Workshop.

[Acceptance rate: 31%]

Matsumoto, S., Ghosh, P., Jamshad, R., and Riek, L. D. (2023). Robot,

Uninterrupted: Telemedical Robots to Mitigate Care Disruption. In *Proceedings of the ACM/IEEE International Conference on Human Robot Interaction (HRI)*.

[Acceptance rate: 25%]

**Matsumoto, S.**, Washburn, A., and Riek, L. D. (2022). A Framework to Explore Proximate Human-Robot Coordination. In *ACM Transactions on Human-Robot* 

Interaction (THRI).

**Matsumoto**, S. and Riek, L. D. (2022). Shared Control in Human Robot Teaming: Toward Context-Aware Communication. In *AAAI Spring Symposium on Closing the Assessment Loop: Communicating Proficiency and Intent in Human-Robot Teaming*.

**Matsumoto, S.**, Moharana, S., Devanagondi, N., Oyama, L. C., and Riek, L. D. (2021). Iris: A Low-Cost Telemedicine Robot to Support Healthcare Safety and Equity During a Pandemic. In *EAI PervasiveHealth*.

Taylor, A. M., **Matsumoto**, S., Xiao, W., Riek, L. D. (2021). Social Navigation for Mobile Robots in the Emergency Department. In *IEEE International Conference on Robotics and Automation (ICRA)*.

Taylor, A. M., **Matsumoto, S.**, Riek, L. D. (2020). Situating Robots in the Emergency Department. In *AAAI Spring Symposium on Applied AI in Healthcare: Safety, Community, and the Environment.* 

**Matsumoto, S.** and Riek, L. D. (2019). Fluent Coordination in Proximate Human Robot Teaming. In *AI and Its Alternatives for Shared Autonomy in Assistive and Collaborative Robotics, Workshop at Robotics: Science and Systems (RSS)*.

Washburn, A., **Matsumoto, S.**, and Riek, L. D. (2019). Trust-Aware Control in Proximate Human-Robot Teaming. In *Trust in Human-Robot Interaction: Research and Applications*. Elsevier.

# Awards and Honors

### **HRI Pioneers Workshop Travel Grant**

2024

Chosen to participate in a highly selective workshop seeking to foster creativity and collaboration across human-robot interaction

### NSF GRFP Honorable Mention

2020

One of 1,827 students, of approximately 12,000 who apply annually

### Inclusion@RSS Travel Grant

2019

Selected for workshop bringing together new robotics researchers to increase the participation of traditionally underrepresented groups in robotics

### **CRA-W Grad Cohort Workshop for Women Travel Grant**

2019

Selected for workshop bringing together women in computing to connect students with senior researchers and professionals

## Work **Experience**

### HRL Laboratories, Malibu, CA

2022

#### **Research Intern**

- Researched, developed, and deployed natural language and dialogue models
- Led work on recognition methods that were deployed on robots working in real-world environments

### Surface Optics Corporation, San Diego, CA Research and Development Intern

2016

### Research and Development Intern

- Led work on the bidirectional reflectance distribution function (BRDF) of different paints using the SOC-210 for the development of stealth vehicle coatings, computer generated imagery, and advanced lighting design
- Led technology transfer efforts through documentation for the SOC-210

|               | <ul> <li>Research Intern</li> <li>Led research exploring how to visualize connections between genes and diseases via a graph database with Implicitome and Semmed data in Neo4j</li> </ul> |            |
|---------------|--|------------|
| Teaching      | CSE 276D/176A: Healthcare Robotics, UC San Diego   |            |
| Experience    | Teaching Assistant   | 2020, 2022 |
|               | <ul> <li>Developed homework and lab questions, specified rubrics, wrote code samples,<br/>prepared lab hardware, provided constructive feedback on homework and labs</li> </ul>            |            |
| Invited Talks | Society of Women Engineers (SWE) San Diego AI Forum  | 2024       |
|               | Developing Robotic Systems to Support People in Safety-Critical Environments   |            |
|               | San Diego Robotics Forum   | 2023       |
|               | Telepresence Robots for Safety-Critical Environments   |            |
|               | ENGR 212: Introduction to Unix and Linux for Engineers, CSU San Francisco  | 2023       |
|               | Human-Robot Teaming to Support People in Dynamic Environments  |            |
|               | UCSD Pixel Cafe  | 2023       |
|               | Designing Telepresence Robots for Emergency Medicine   |            |
|               | UCSD CSE Open House  | 2022       |
|               | Human-Robot Coordination in Proximate Teaming and Acute Care Contexts  |            |
|               | Toyota HSR Community Meeting   | 2022       |
|               | Human-Robot Collaboration in Uncertain, Dynamic Environments   |            |
|               | Toyota HSR Community Meeting   | 2021       |
|               | Proximate Human-Robot Teaming in Uncertain Environments  |            |
|               | Workshop on AI and Its Alternatives for Shared Autonomy in Assistive and   | 2019       |
|               | Collaborative Robotics, RSS  |            |
|               | Fluent Coordination in Proximate Human-Robot Teaming   |            |
|               | UCSD CSE Open House  | 2019       |
|               | Coordinating Proximate Human-Robot Teaming in Dynamic Environments   |            |
|               | Contextual Robotics Institute Forum  | 2018       |
|               | Coordinating Proximate Human-Robot Teaming in Dynamic Environments   |            |

The Scripps Research Institute, La Jolla, CA

2015

| Professional     | UC San Diego Robotics Graduate Student Organization   | 2018-Present |
|------------------|---|--------------|
| Affiliations and | President (2021-2022), Vice President (2020-2021), Secretary (2019-2020)  |              |
| Leadership       | Mechanical and Aerospace Engineering Graduate Women's Mentorship Program Graduate mentor  | 2023-Present |
|                  | GradAMP Program   | 2022-2023    |
|                  | Mentored an undergraduate student applying to graduate school   |              |
|                  | My CS Ph.D.   | 2020-2021    |
|                  | Conducted interviews and wrote posts to provide better information about  |              |
|                  | Ph.D.s in computer science to undergraduates  | 2010 2020    |
|                  | Jacobs Undergraduate Mentoring Program  | 2019-2020    |
|                  | Graduate Mentor  Pay Area Scientists in Schools (PASIS)   | 2015 2019    |
|                  | Bay Area Scientists in Schools (BASIS)  | 2015-2018    |
|                  | Taught hands-on science lessons in underprivileged elementary schools   |              |
| Supervisees      | Vivek Gupte (M.S. Mechanical and Aerospace Engineering)   | 2023-Present |
|                  | Priyanshu Arora (M.S. Computer Science)   | 2023-Present |
|                  | James Olichney (B.S. Cognitive Science)   | 2023-Present |
|                  | Arthi Haripriyan (M.S. Computer Science)  | 2022-Present |
|                  | Alex Chow (B.S. Computer Science)   | 2022-2023    |
|                  | Vincent Santos (B.S. Computer Science)  | 2021-2022    |
|                  | Ashwin Rao (B.S. Computer Engineering)  | 2020-2021    |
|                  | Raechel Walker (B.S. Data Science)  | 2020-2021    |
|                  | Sharon Banh (B.S. Cognitive Science)  | 2020-2021    |
|                  | Nimisha Devanagondi (B.S. Cognitive Science)  | 2020-2021    |
| Academic         | Reviewer ACM/IEEE Conference on Human Robot Interaction (HRI)   | 2020-2024    |
| Service          | Reviewer ACM Transactions on Human-Robot Interaction (THRI)   | 2021-2024    |
|                  | Reviewer IEEE International Conference on Robotics and Automation (ICRA)  | 2021-2023    |
| Professional     | Programming Languages: Python including popular machine learning libraries  |              |
| Competencies     | such as sklearn   C++   C#   C   Java   SQL   Matlab  |              |
| competences      | such as skiedin   C   |              |
|                  | <b>Software Tools and Systems:</b> ROS (and robotics simulators such as Gazebo)   Latex   Github   Figma   Linux   Windows   MacOS                              |              |
|                  | <b>Hardware:</b> Arduino   Raspberry Pi   HoloLens   Various robot platforms (e.g., Turtlebot 2, Kuri, Toyota HSR, Stretch)                                     |              |
|                  | User-Centered Design and Research Methods: Ethnographic observation  <br>Interviews   Qualitative analysis   Rapid prototyping   Storyboarding  <br>Wireframing |              |