# NITHIN RAGHAVAN

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# EXPERIENCE

OCT 2019 -PRESENT

#### + VISUAL COMPUTING LAB, UC BERKELEY

NDERGRADUATE RESEARCHER

Co-authored NeurIPS spotlight publication (top 3% of papers) on Fourier Features, a new concept in neural network theory.
Researched volumetric octree compression on a voxel grid for the Neural Radiance Functions (NeRF) paper.

## JUN 2020 - + FORD GREENFIELD LABS

#### RESEARCH INTERN

• Worked on a neural network architecture to generate depth and segmentation maps from a single RGB image.

• Reduces cost to generate such maps to zero, compared to thousands of dollars currently required.

MAY 2019 -AUG 2019

#### + SAMSUNG ADVANCED COMPUTING LAB

#### RESEARCH INTERN

• Wrote neural networks to perform ambient occlusion and physically-based rendering style transfer for simple scenes.

• Researched the graphics pipeline and deep learning model optimization on Samsung's future compute architecture.

## PROJECTS

JUL 2019

#### + SOFTWARE RENDERER

 $\cdot$  Developed a software-based rasterizer and renderer with pixel and vertex shader support in C++.

• Capable of barycentric interpolation, backface culling and block-based rasterization.

DEC 2017 -PRESENT

### + RESOURCE-PROVISIONING GPU SERVER

• Developed a Python-based shell to automate on-demand request processing and resource provisioning in a GPU cluster.

• Uses Slurm for cluster management and deploys tasks in Docker containers.

JUL 2019

#### + WAVELET-BASED COMPRESSED SENSING

• Uses LASSO and the discrete wavelet transform to compress or denoise audio representations by any amount.

 $\cdot$  Can be used in an ML pipeline for signal preprocessing.

## EDUCATION

**UC BERKELEY** 2017 - 2021

COMPUTER SCIENCE APPLIED MATHEMATICS GPA: 3.73

### COURSEWORK

Data Structures Efficient Algorithms Optimization Models Numerical Analysis Partial Differential Equations Introduction to Robotics Introduction to Machine Learning

## SKILLS

#### LANGUAGES

Python C/C++ Java Matlab

## SOFTWARE

Numpy/Scipy Pytorch OpenCL Bash Docker Tensorflow