

Maximum Entropy Markov Models for Information Extraction and Segmentation

Andrew McCallum, Dayne Freitag, and Fernando Pereira

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Presentation by Gyozo Gidofalvi
Computer Science and Engineering Department
University of California, San Diego
gyozo@cs.ucsd.edu

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Outline

- Modeling sequential data with HMMs
- Problems with previous methods: motivation
- Maximum entropy Markov model (MEMM)
- Segmentation of FAQs: experiments and results
- Conclusions

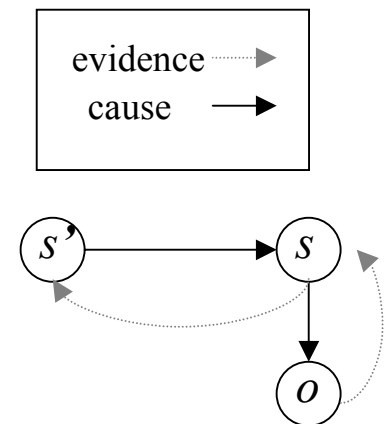
Background

- A large amount of text is available on the Internet
 - We need algorithms to process and analyze this text
- Hidden Markov models (HMMs), a “powerful tool for representing sequential data,” have been successfully applied to:
 - Part-of-speech tagging:
`<PRP>He</PRP> <VB>books</VB> <NNS>tickets</NNS>`
 - Text segmentation and event tracking:
tracking non-rigid motion in video sequences
 - Named entity recognition:
`<ORG>Mips</ORG> Vice President <PRS>John Hime</PRS>`
 - Information extraction:
`<TIME>After lunch</TIME> meet <LOC>under the oak tree</LOC>`

Brief overview of HMMs

- An HMM is a finite state automaton with stochastic state transitions and observations.
- Formally: An HMM is
 - a finite set of states \mathcal{S}
 - a finite set of observations \mathcal{O}
 - two conditional probability distributions:
 - for s given s' : $P(s|s')$
 - for o given s : $P(o|s)$
 - the initial state distribution $P_0(s)$

Dependency graph



The “three classical problems” of HMMs

- **Evaluation** problem: Given an HMM, determine the probability of a given observation sequence $\bar{o} = \langle o_1, \dots, o_T \rangle$:

$$P(\bar{o}) = \sum_{\bar{s}} P(\bar{o} | \bar{s})P(\bar{s})$$

- **Decoding** problem: Given a model and an observation sequence, determine the most likely states that led to the observation sequence

$$\bar{s} = \langle s_1, \dots, s_T \rangle : \quad \arg \max_{\bar{s}} P(\bar{o} | \bar{s})$$

- **Learning** problem: Suppose we are given the structure of a model $(\mathcal{S}, \mathcal{O})$ only. Given a set of observation sequences determine the best model parameters.

$$\arg \max_{\theta} P(\bar{o}, \theta) = \sum_{\bar{s}} P(\bar{o} | \bar{s}, \theta)P(\bar{s})$$

- Efficient dynamic programming (DP) algorithms that solve these problems are the Forward, Viterbi, and Baum-Welch algorithms respectively.

Assumptions made by HMMs

- **Markov assumption:** the next state depends only on the current state
- **Stationarity assumption:** state transition probabilities are independent of the actual time at which transitions take place
- **Output independence assumption:** the current output (observation) is independent of the previous outputs (observations) given the current state.

Difficulties with HMMs: Motivation

- We need a richer representation of observations:
 - Describe observations with overlapping features
 - When we cannot enumerate all possible observations (e.g. all possible lines of text) we want to represent observations by feature values.
 - Example features in text-related tasks:
 - capitalization
 - word ending
 - part-of-speech
 - formatting
 - position on the page
- Model $\underbrace{P(s_T|o_T)}$ rather than the joint probability $\underbrace{P(s_T, o_T)}$
Discriminative / Conditional Generative

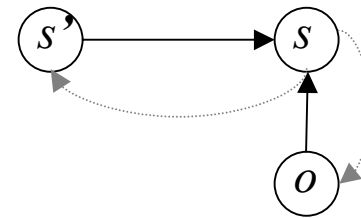
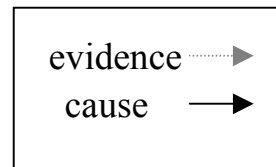
Example task:

Extract company names

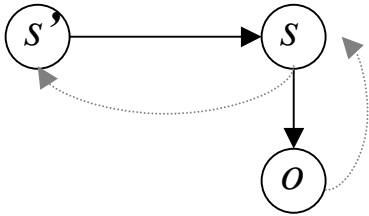
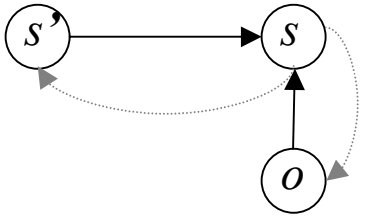
Definition of a MEMM

- Model the probability of reaching a state given an observation and the previous state

Dependency graph



- finite set of states \mathcal{S}
- set of possible observations \mathcal{O}
- State-observation transition probability for s given s' and the current observation o : $P(s|s',o)$
- initial state distribution: $P_0(s)$

Task	<p style="text-align: center;">Generative: HMM</p> 	<p style="text-align: center;">Discriminative / Conditional: MEMM</p> 
Evaluation	Find $P(o_T M)$	
Decoding = Prediction	Find s_T s.t. $P(o_T s_T, M)$ is maximized	Find s_T s.t. $P(s_T o_T, M)$ is maximized
Learning	Given o , find M s.t. $P(o M)$ is maximized (Need EM because S is unknown)	Given o and s , find M s.t. $P(s o, M)$ is maximized (Simpler Max likelihood problem)

DP to solve the “three classical problems”

- $\alpha_t(s)$ is the probability of being in state s at time t given the observation sequence up to time t :

$$\alpha_{t+1}(s) = \sum_{s' \in \mathcal{S}} \alpha_t(s') \cdot P(s | s', o_{t+1}) \quad (1)$$

- $\beta_t(s)$ is the probability of starting from state s at time t given the observation sequence after time t :

$$\beta_t(s') = \sum_{s \in \mathcal{S}} P(s | s', o_t) \beta_{t+1}(s) \quad (2)$$

Maximum Entropy Markov Models (MEMMs)

- For each s' separately conditional probabilities $P(s|s',o)$ are given by an exponential model
- Each exponential model is trained via maximum entropy

Note: $P(s|s',o)$ can be split into $|\mathbf{S}|$ separately trained transition functions $P_{s'}(s|o) = P(s|s',o)$.

Fitting exponential models by maximum entropy

- Basic idea:
 - The best model of the data satisfies certain constraints and makes the fewest possible assumptions.
 - “fewest possible assumptions” \equiv closest to the uniform distribution (i.e. has highest entropy)

- Allow non-independent observation features
- Constraints are counts for properties of training data:
 - “observation contains the word apple” and is labeled “header”
 - “observation contains a capitalized word” and is labeled “question”
- Properties (called features) can depend on observations and also their state label.
- Formally: A feature f_a is defined by $a = \langle b, r \rangle$, where
 - b is a binary feature of the current observation and
 - r is a state value:

$$f_{\langle b, r \rangle}(o_t, s_t) = \begin{cases} 1 & \text{if } b(o_t) \text{ is true and } s_t = r \\ 0 & \text{otherwise} \end{cases} \quad (3)$$

Constraints on the model

- For all s' the expected value E_a of each feature a in the learned distribution equals its average value F_a in training set:

$$E_a = \frac{1}{m_{s'}} \sum_{k=1}^{m_{s'}} \sum_{s \in S} P(s | s', o_k) f_a(o_k, s) = \frac{1}{m_{s'}} \sum_{k=1}^{m_{s'}} f_a(o_k, s_k) = F_a \quad (4)$$

- Theorem: The probability distribution with maximum entropy that satisfies the constraints is (a) unique, (b) the same as the ML solution, and (c) in exponential form. For a fixed s' :

$$P(s | s', o) = \frac{1}{Z(o, s')} \exp\left(\sum_a \lambda_a f_a(o, s)\right) \quad (5)$$

where λ_a are the parameters to be learned and

$$Z(o, s') = \frac{P(s | s', o)}{\sum_{s \in S} P(s | s', o)} \quad (6)$$

MEMM training algorithm

1. Split the training data into observation - destination state pairs $\langle o, s \rangle$ for each state s' .
2. Apply Generalized Iterative Scaling (GIS) for each s' using its $\langle o, s \rangle$ set to learn the maximum entropy solution for the transition function of s' .

This algorithm assumes that the state sequence for each training observation sequence is known.

GIS [Darroch & Ratcliff, 1972]

- Learn the transition function for one origin state s' by finding λ_a values that satisfy $E_a = F_a$ (Eq 4).
- Input for one origin state s' :
 - training examples with this origin s' numbered 1 to k
 - for each of these training examples
 - set of features f_a for $a = 1 \dots n$
 - values for features for each context $\langle o, s \rangle$ must sum to constant C
 - Use correction feature f_x if necessary: $f_x(o, s) = C - \sum_{a=1}^n f_a(o, s)$
- Outputs: set of λ_a values for $a = 1 \dots n$

For a fixed s' :

1. Let m_s be the number of training examples where the current state is s (and the previous state is s').
2. Calculate the relative frequency of each feature on the training data:

$$F_a = \frac{1}{m_s} \sum_{k=1}^{m_s} f_a(o_k, s_k) \quad (7)$$

3. Initialize λ_a to some arbitrary value, say 1.
4. Use current λ_a values in Eq 5 to estimate $P(s|s', o)$
5. Calculate the expectation of each feature “according to the model”:

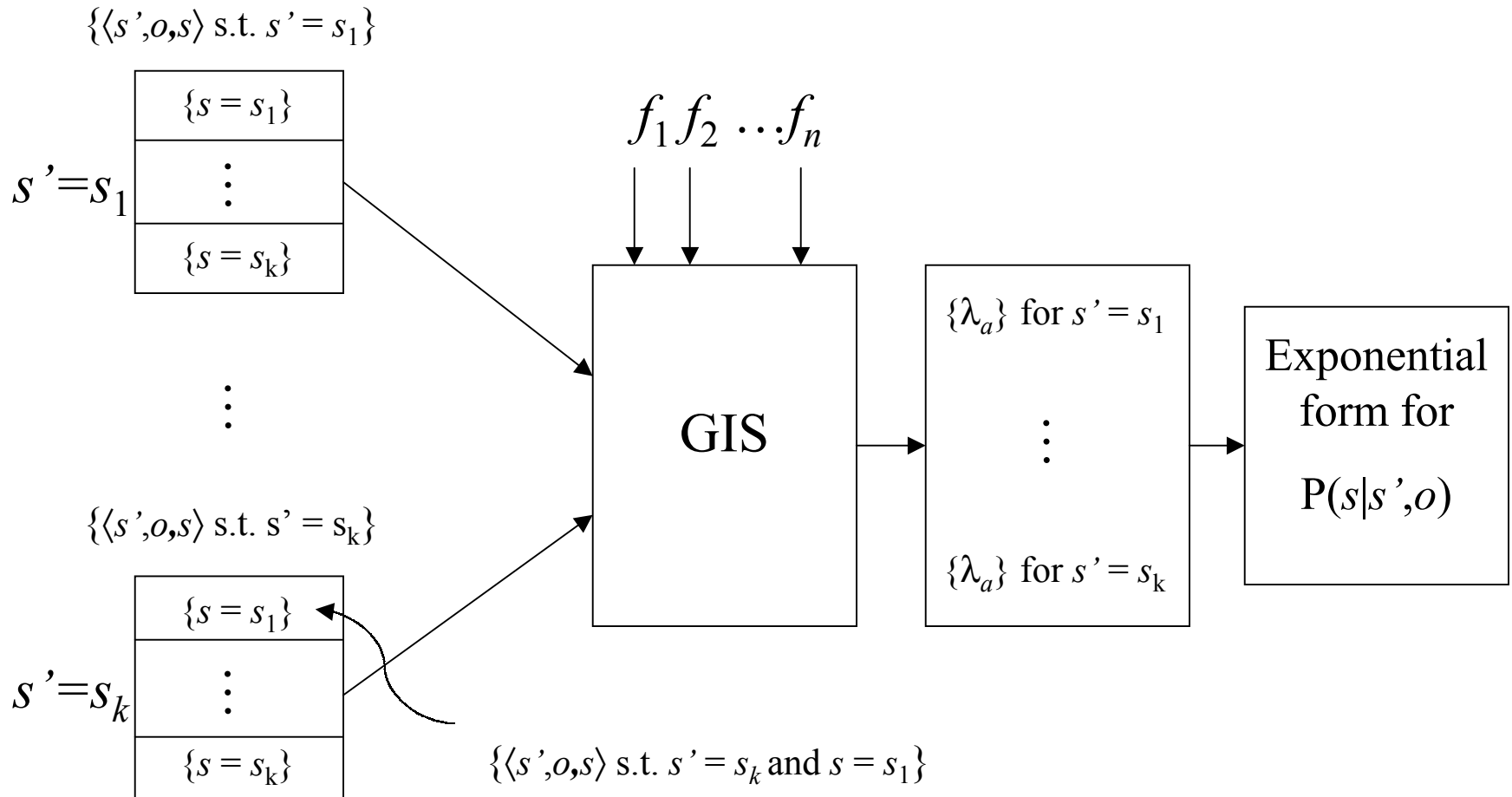
$$E_a = \frac{1}{m_s} \sum_{k=1}^{m_s} \sum_{s \in S} P(s | s', o_k) f_a(o_k, s) \quad (8)$$

6. Update each λ_a s.t. to make E_a be closer to the expectation of the training data:

$$\lambda_a := \lambda_a + \frac{1}{C} (\log F_a - \log E_a) \quad (9)$$

7. Repeat from step 4 until convergence.

Review of the MEMM model



Application: segmentation of FAQs

- 38 files belonging to 7 Usenet multi-part FAQs (set of files)
- Basic file structure:

header

text in Usenet header format

[preamble or table of content]

series of one or more question/answer pairs

tail

[copyright]

[acknowledgements]

[origin of document]

- Formatting regularities: indentation, numbered questions, types of paragraph breaks
- Consistent formatting within a single FAQ

- Lines in each file are hand-labeled into 4 categories: *head*, *questions*, *answers*, *tail*

```
<head>X-NNTP-Poster: NewsHound v1.33
<head>
<head>Archive-name: acorn/faq/part2
<head>Frequency: monthly
<head>
<question>2.6) What configuration of serial cable should I use
<answer>
<answer> Here follows a diagram of the necessary connections
<answer>programs to work properly. They are as far as I know t
<answer>agreed upon by commercial comms software developers fo
<answer>
<answer> Pins 1, 4, and 8 must be connected together inside
<answer>is to avoid the well known serial port chip bugs. The
```

Table 2: An excerpt from a labeled FAQ

- Prediction: Given a sequence of lines, a learner must return a sequence of labels.

Boolean features of lines

- The 24 line-based features used in the experiments are:

begins-with-number

begins-with-ordinal

begins-with-punctuation

begins-with-question-word

begins-with-subject

blank

contains-alphanum

contains-bracketed-number

contains-http

contains-non-space

contains-number

contains-pipe

contains-question-mark

contains-question-word

ends-with-question-mark

first-alpha-is-capitalized

indented

indented-1-to-4

indented-5-to-10

more-than-one-third-space

only-punctuation

prev-is-blank

prev-begins-with-ordinal

shorter-than-30

Experiment setup

- “Leave- n -minus-1-out” testing: For each file in a group (FAQ), train a learner and test it on the remaining files in the group.
- Scores are averaged over $n(n-1)$ results.

Evaluation metrics

- *Segment*: consecutive lines belonging to the same category
- *Co-occurrence agreement probability (COAP)*
 - Empirical probability that the actual and the predicted segmentation agree on the placement of two lines according to some distance distribution D between lines.

$$P_D(\text{actual}, \text{predicted}) = \sum_{i,j} D(i, j) \left[\begin{array}{c} \text{actual}(i) = \text{actual}(j) \\ = \\ \text{predicted}(i) = \text{predicted}(j) \end{array} \right]$$

- Measures whether segment boundaries are properly aligned by the learner
- *Segmentation precision (SP)*: $\frac{\text{\# of correctly identified segments}}{\text{\# of segments predicted}}$
- *Segmentation recall (SR)*: $\frac{\text{\# of correctly identified segments}}{\text{\# of actual segments}}$

Comparison of learners

- **ME-Stateless:** Maximum entropy classifier
 - documents is an unordered set of lines
 - lines are classified in isolation using the binary features, not using label of previous line
- **TokenHMM:** Fully connected HMM with hidden states for each of the four labels
 - no binary features
 - transitions between states only on line boundaries
- **FeatureHMM:** same as TokenHMM
 - lines are converted to sequences of features
- **MEMM**

Results

<i>Learner</i>	<i>COAP</i>	<i>SegPrec</i>	<i>SegRecall</i>
ME-Stateless	0.520	0.038	0.362
TokenHMM	0.865	0.276	0.140
FeatureHMM	0.941	0.413	0.529
MEMM	0.965	0.867	0.681

References

- McCallum, A., & Freitag, D., & Pereira, F., (2000). Maximum Entropy Markov Models for Information Extraction and Segmentation. Proc. 17th International Conf. on Machine Learning pp. 591-598.
- A Brief MAXENT tutorial:
<http://www-2.cs.cmu.edu/afs/cs/user/aberger/www/html/tutorial/tutorial.html>