Announcements

- Exam 1 grades out
 - B- cutoff ~ 55
 - A- cutoff ~ 85
- Exam 2 on Friday
 - In class
 - 3Qs in 45 min
 - Covers D&C and Greedy algorithms (through last week's lectures)
- No class on Monday

Last Time

- Greedy Algorithms
- Minimum Spanning Tree
- Tree Facts

Greedy Algorithms

General Algorithmic Technique:

- 1. Find decision criterion
- 2. Make best choice according to criterion
- 3. Repeat until done

Surprisingly, this sometimes works.

Trees

<u>Definition:</u> A <u>tree</u> is a connected graph, with no cycles.
A <u>spanning tree</u> in a graph G, is a subset of the edges of G that connect all vertices and have no cycles.
If G has weights, a <u>minimum spanning tree</u> is a spanning tree whose total weight is as small as possible.

Basic Facts about Trees

Lemma: For an undirected graph G, any two of the below imply the third:

- 1. |E| = |V| 1
- 2. G is connected
- 3. G has no cycles

<u>Corollary</u>: If G is a tree, then |E| = |V|-1.

Today

• Minimum Spanning Trees

Minimum Spanning Tree

Problem: Given a weighted, undirected graph G, find a spanning tree of G with the lowest possible weight.

Greedy Idea

How do you make an MST?

Greedy Idea

How do you make an MST?

• Try using the cheapest edges.

Greedy Idea

How do you make an MST?

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<u>**Proposition:</u>** In a graph G, let e be an edge of lightest weight. Then there exists an MST of G containing e. Furthermore, if e is the unique lightest edge, then *all* MSTs contain e.</u>

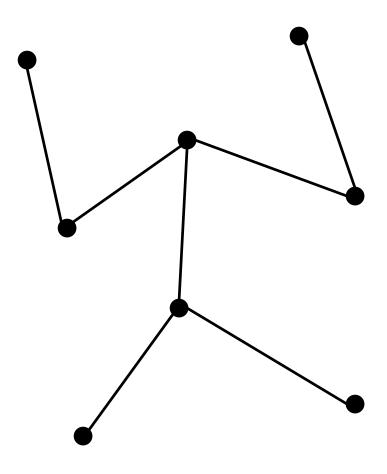
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- Modify T to get T' that does contain e and has wt(T') ≤ wt(T).

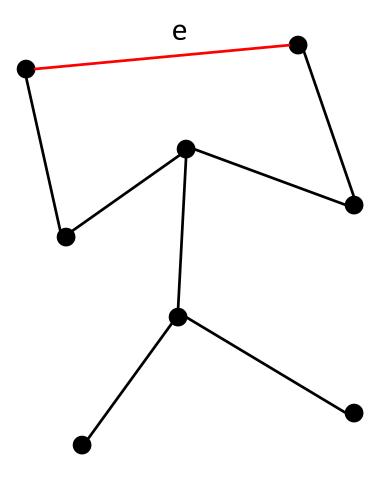
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- Furthermore if e is the unique lightest edge, wt(T') < wt(T), so T could not have been minimal.

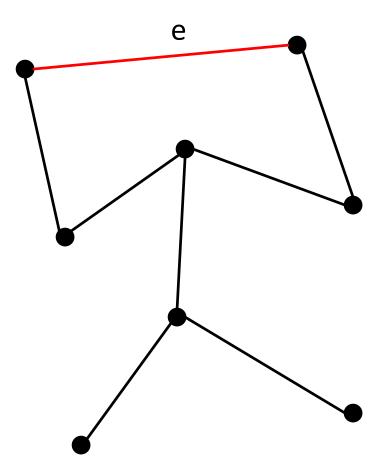
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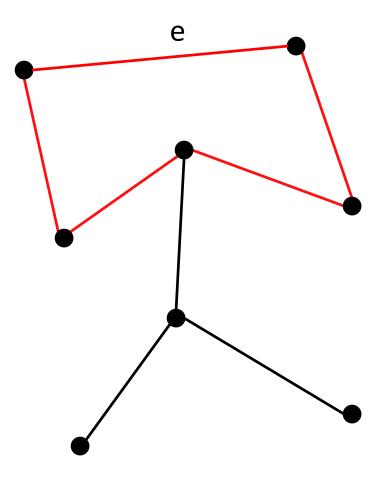
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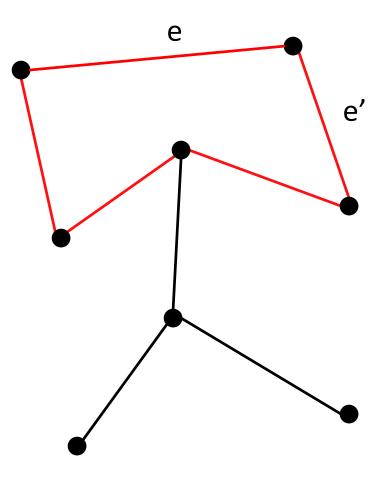
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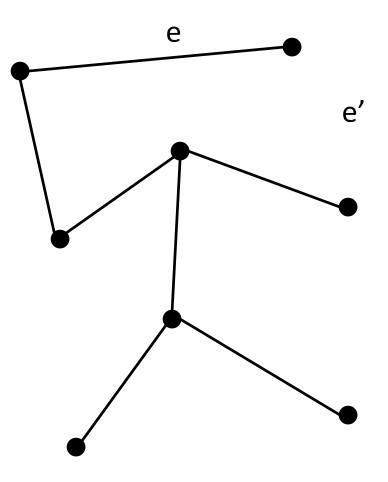
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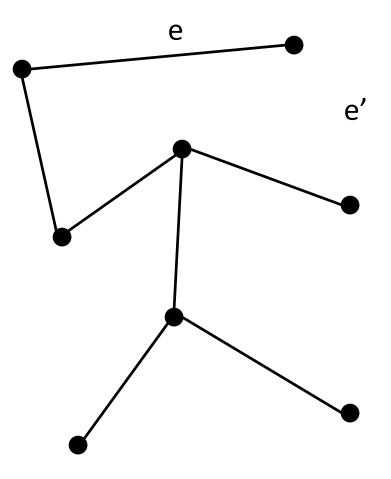
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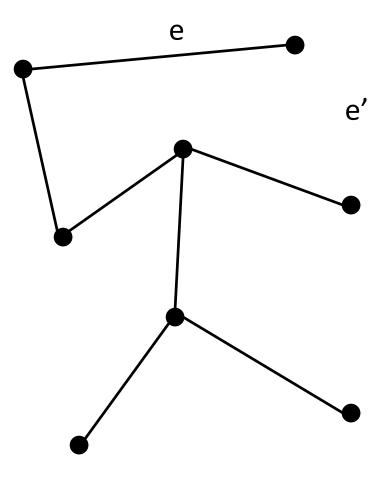


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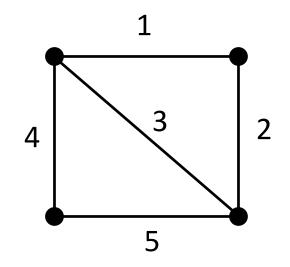


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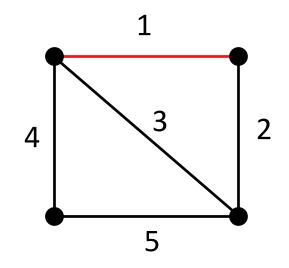
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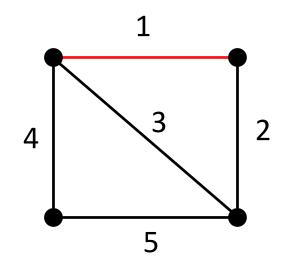
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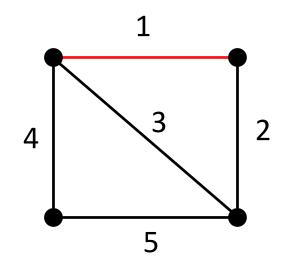
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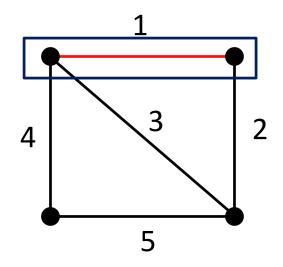
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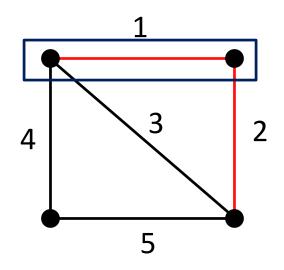
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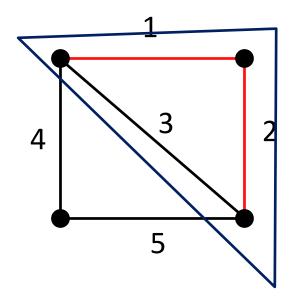
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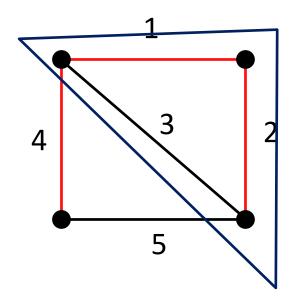
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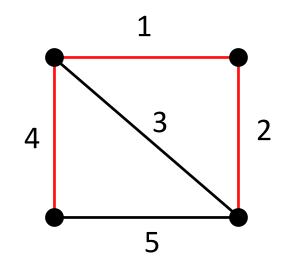
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• When more than one vertex, add lightest edge, and merge.

Repeat and then undo merges.

 Easier: An edge hasn't been merged away iff it does not create a cycle with already chosen edges.

```
Kruskal(G)
  \{ \} \rightarrow T
  While (|T| < |V|-1)
    Find lightest edge e that
     doesn't create cycle with T
    Add e to T
  Return T
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 $\{ \} \rightarrow \mathbb{T}$ O(|V|) Iterations While (|T| < |V|-1)Find lightest edge e that doesn't create cycle with T Add e to T O(|E|) edges Return T O(|V|+|E|) time to check for cycle

Algorithm

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 $T \leftarrow \{\}$ O(|V|) Iterations While (|T| < |V|-1)Find lightest edge e that doesn't create cycle with T Add e to T O(|E|) edges Return T O(|V|+|E|) time to **Runtime:** check for cycle $O(|V||E|^2)$

Optimizations

Two things are slow here:

- 1) Testing every edge every iteration.
- 2) Needing to test connectivity for every edge.

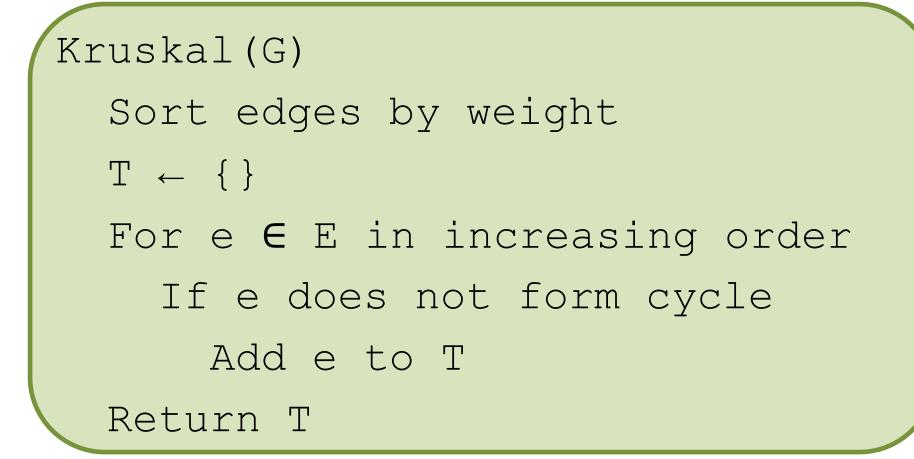
Optimizations

Two things are slow here:

- 1) Testing every edge every iteration.
- 2) Needing to test connectivity for every edge.

To improve (1), if an edge forms a cycle, it will never later become viable.

Sort edges once and use in order.



 $O(|E| \log |E|)$ Kruskal(G) Sort edges by weight $\{ \} \rightarrow \mathbb{T}$ For $e \in E$ in increasing order If e does not form cycle Add e to T Return T

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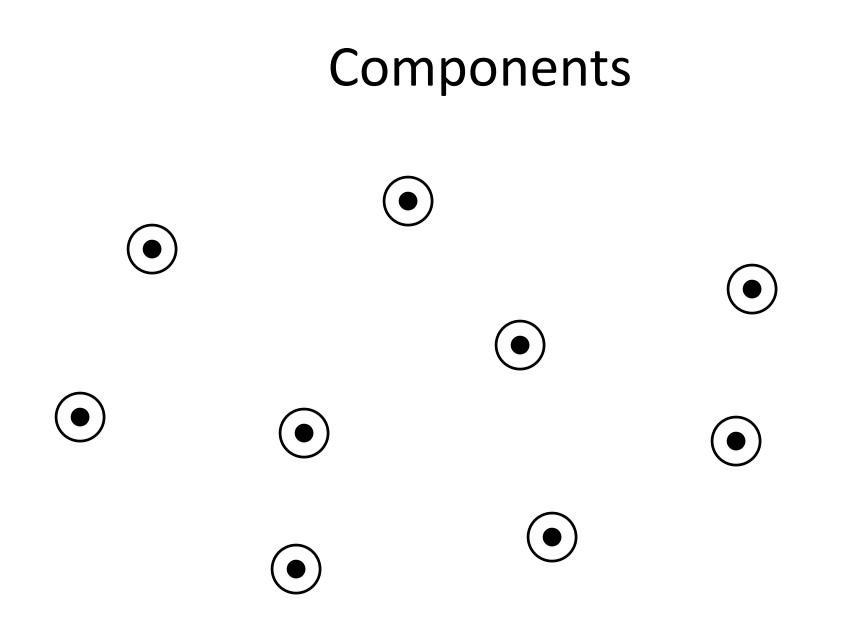
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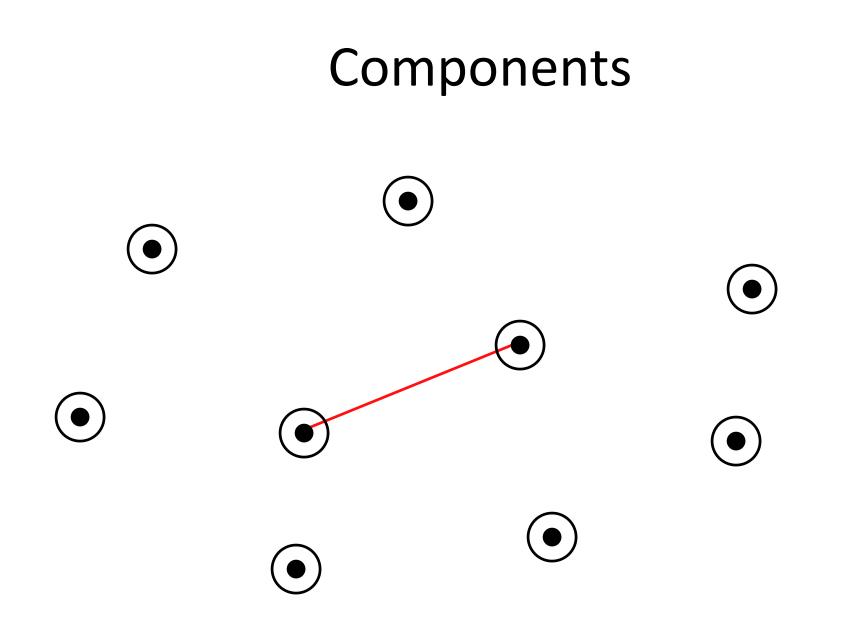
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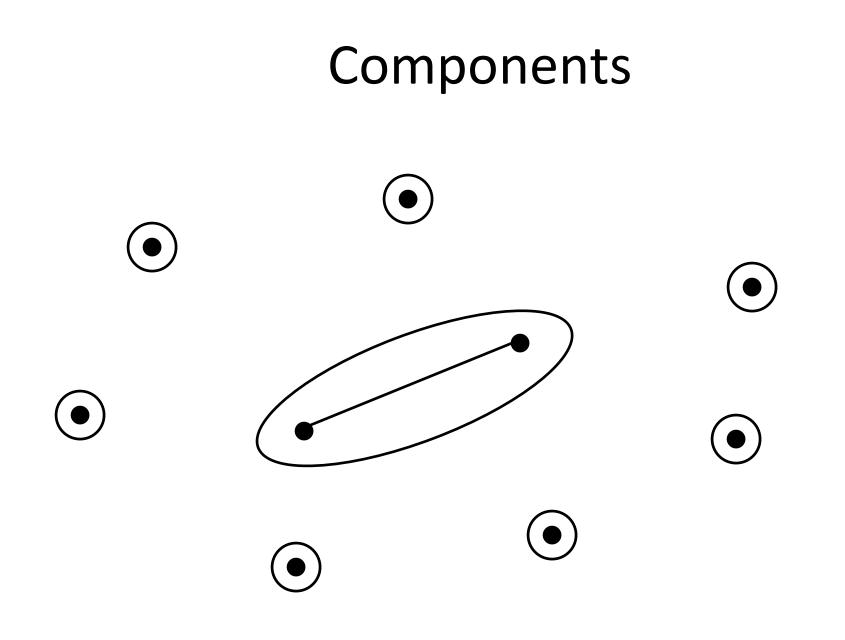
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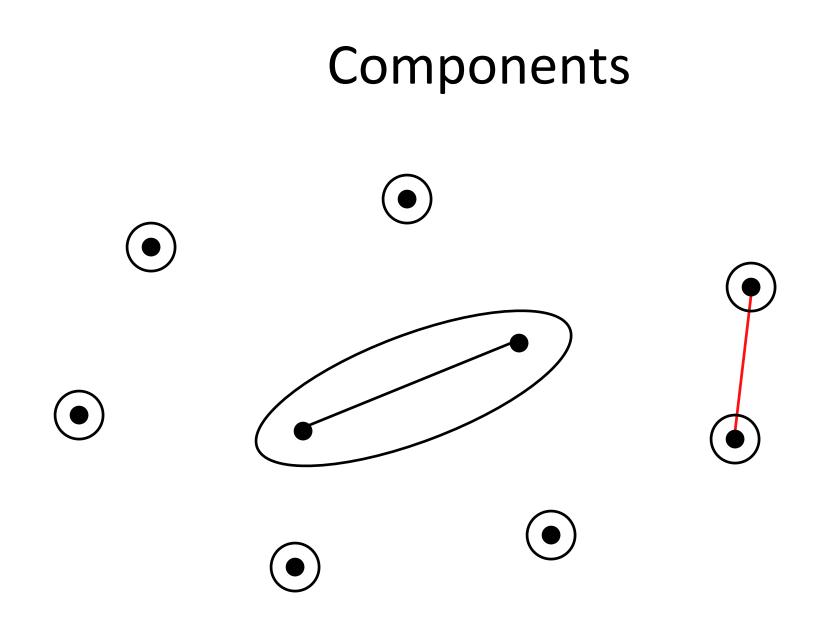
Need a data structure. That can:

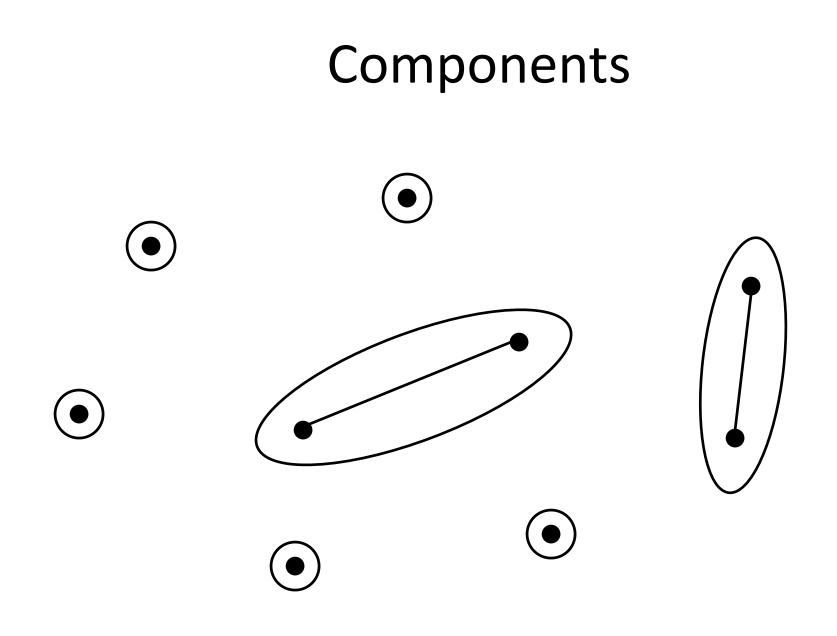
- Add edges to T.
- Test if two vertices in same CC.

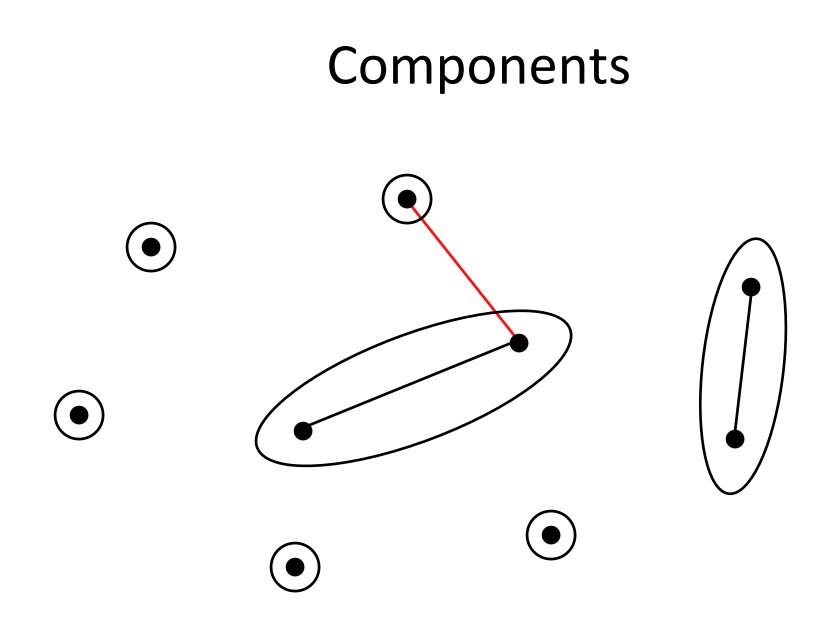


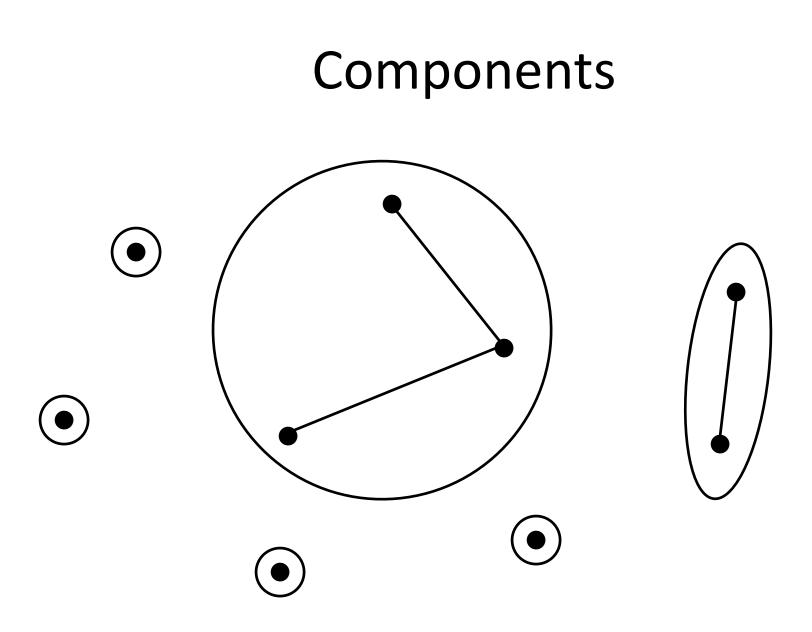


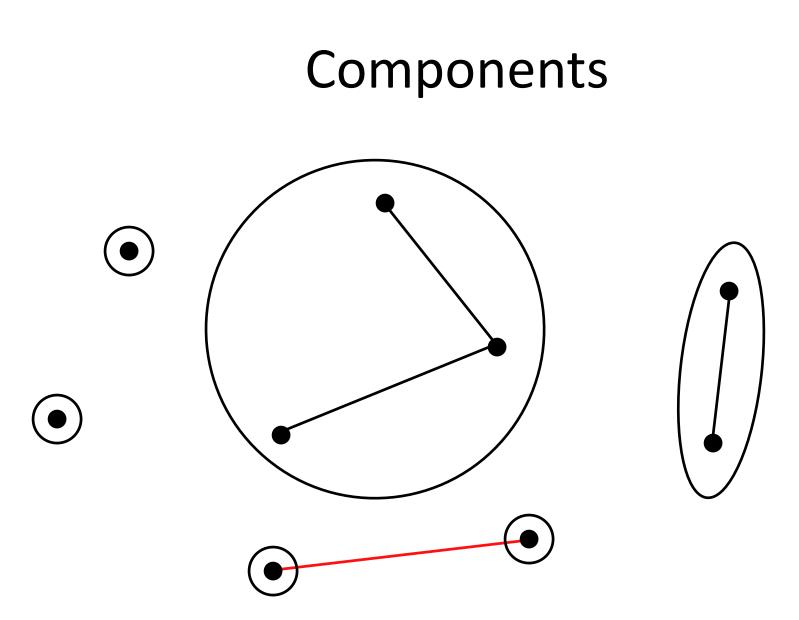


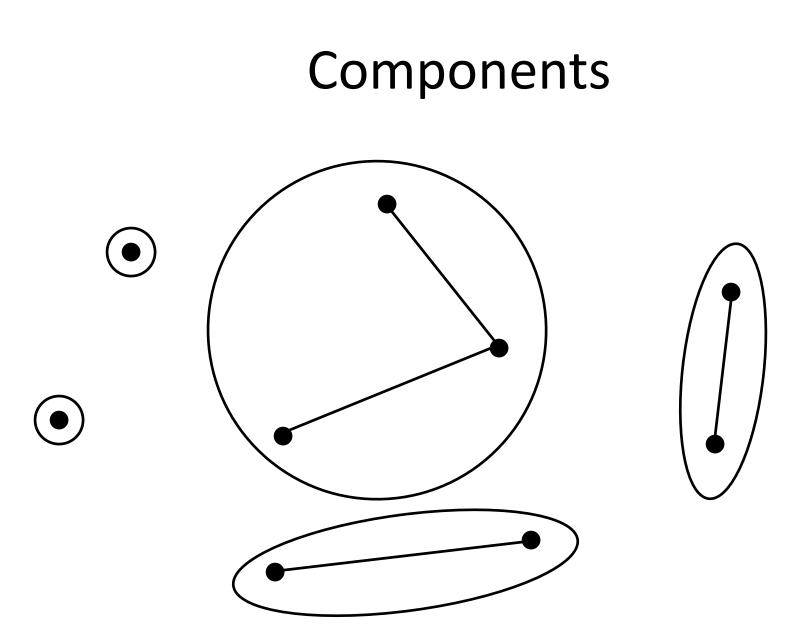


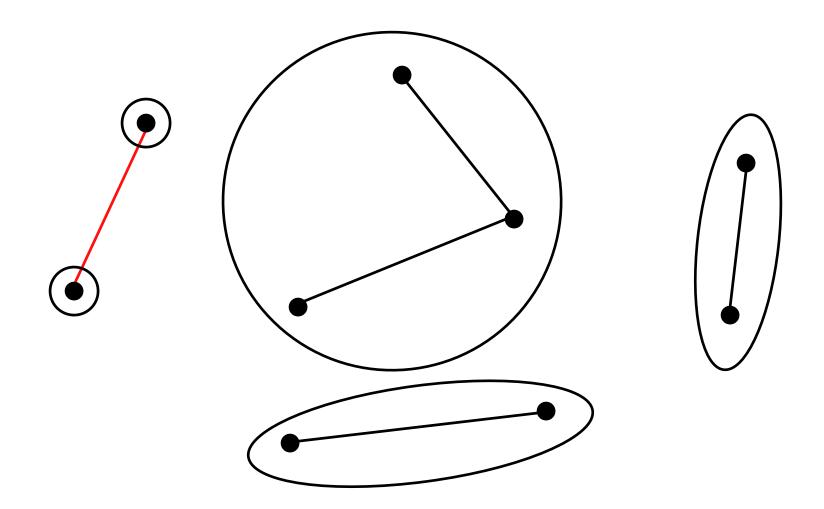


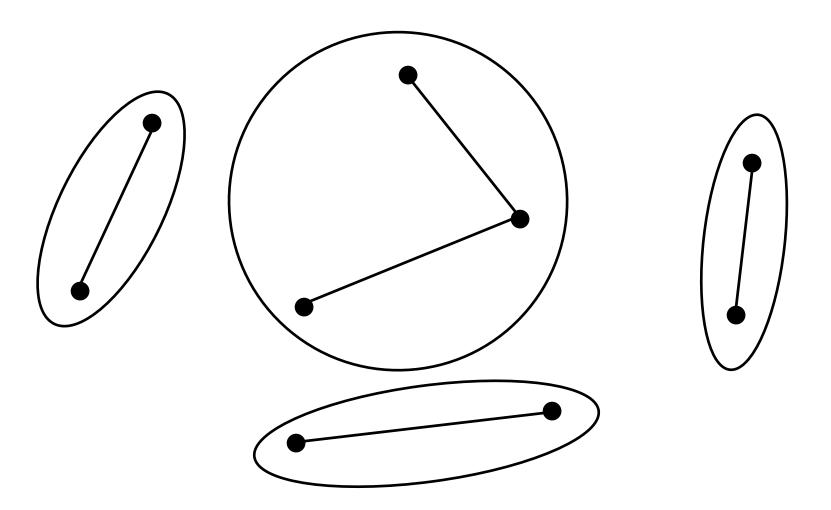


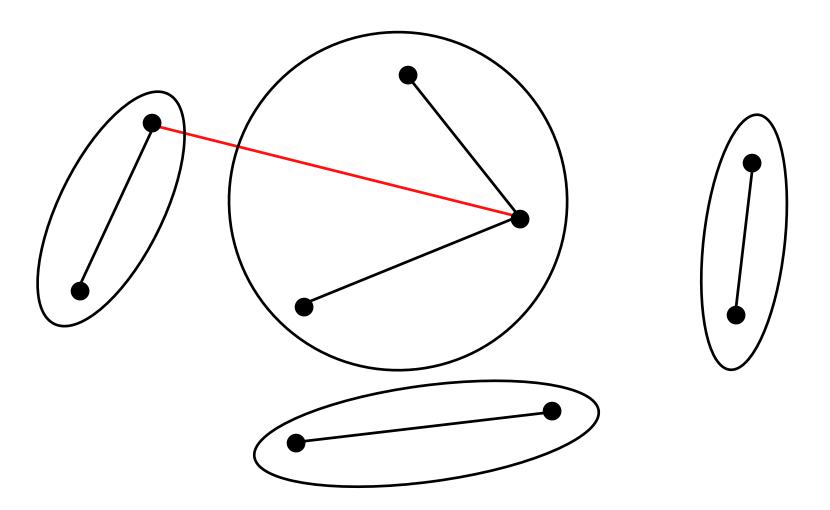


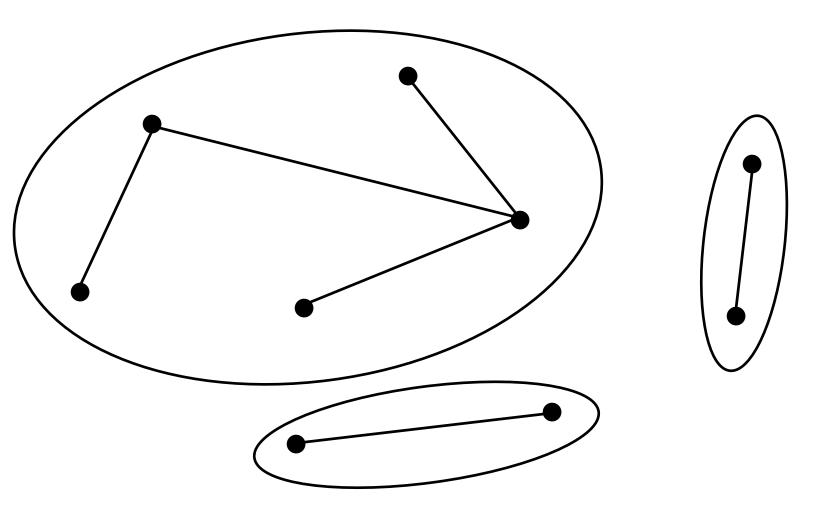


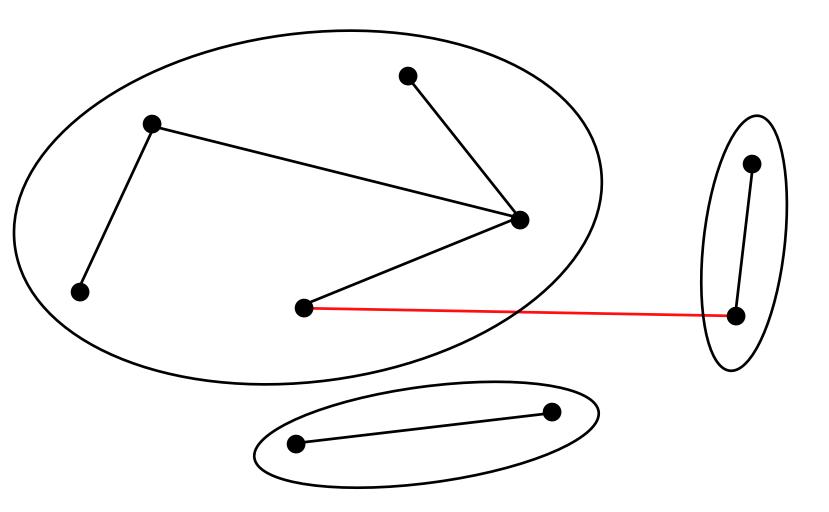


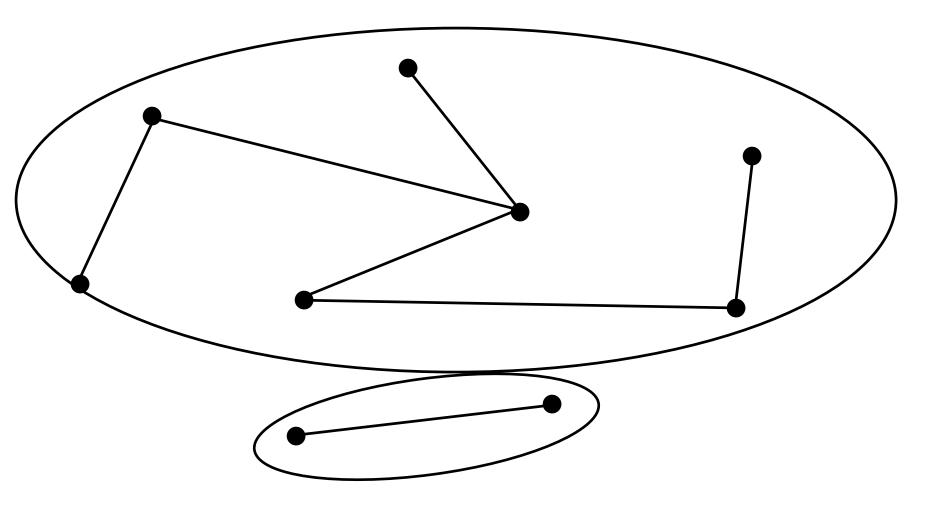


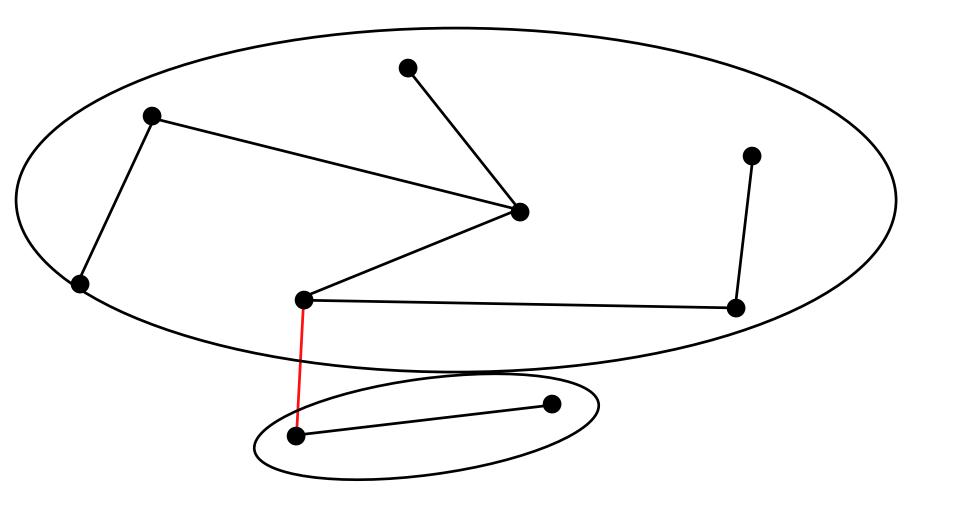


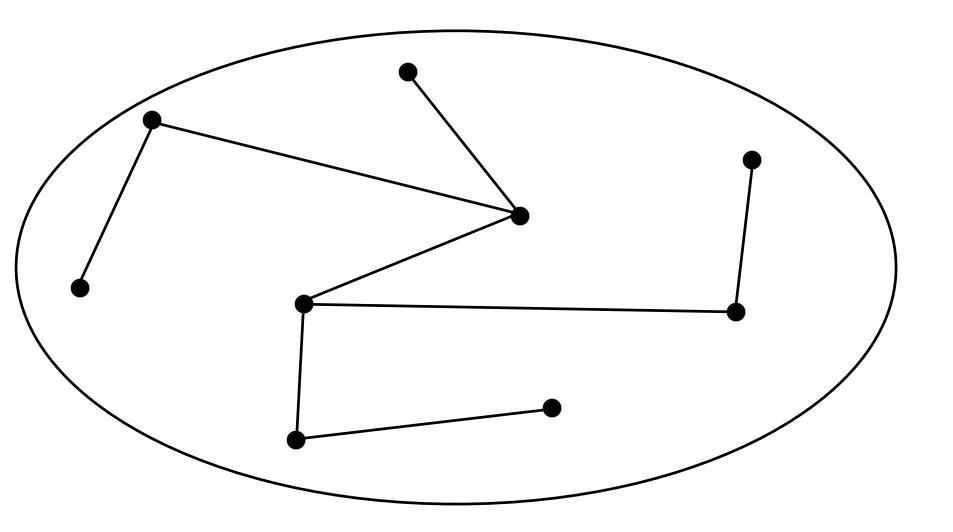












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<u>Note:</u> Check of v & w in same set by testing if Rep(v) = Rep(w).

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Kruskal(G)
  Sort edges by weight
  \{ \} \rightarrow \mathbb{T}
  Create Union Find
  For v \in V, New(v)
  For (v, w) \in E in increasing order
     If \operatorname{Rep}(v) \neq \operatorname{Rep}(w)
        Add (v,w) to T
        Join(v,w)
  Return T
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Kruskal(G)
  Sort edges by weight - O(|E| log |E|)
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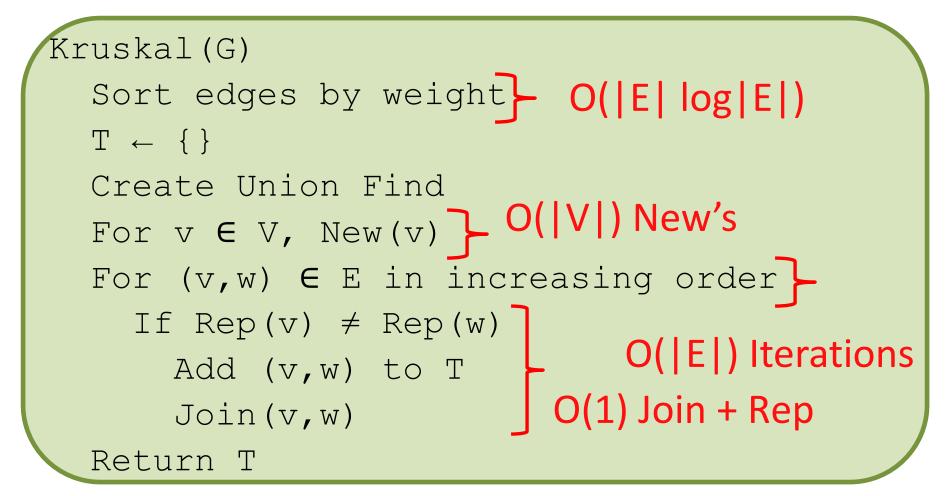
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                                 O(1) Join + Rep
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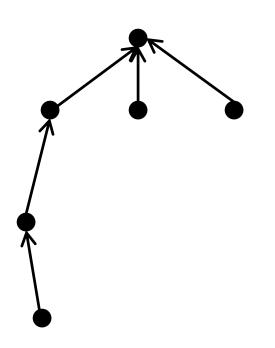
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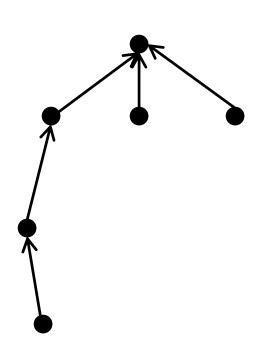
Runtime:O(|E|log|E|) +|E|(Union-Find Ops)

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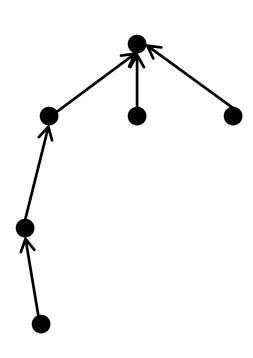


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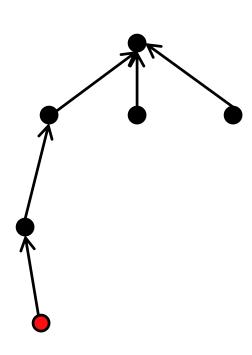


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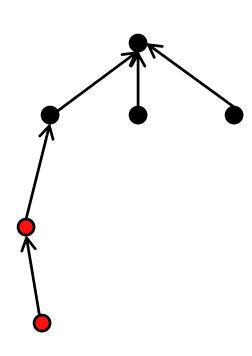
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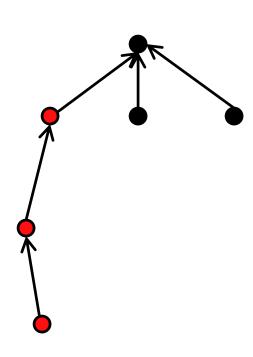
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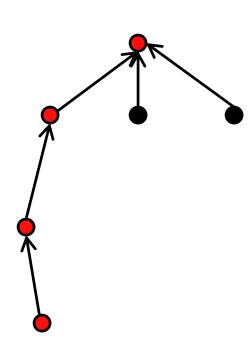
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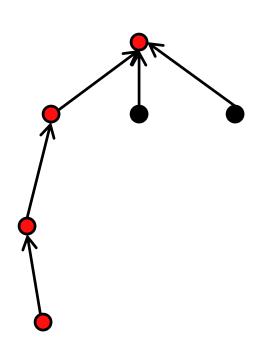
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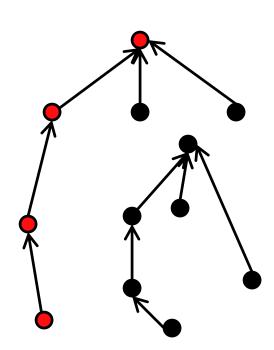
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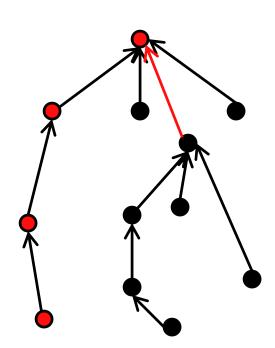
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Proof: Induction on n. n = 0, done.

To get a tree of depth n, need to join two trees of depth n-1. Total of at least $2^{n-1}+2^{n-1} = 2^n$ nodes.

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<u>Note</u>: Using path compressions, union-find actually runs in $\alpha(n)$ time per operation.

Other Algorithms

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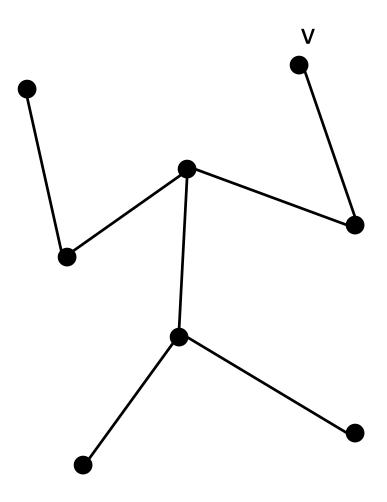
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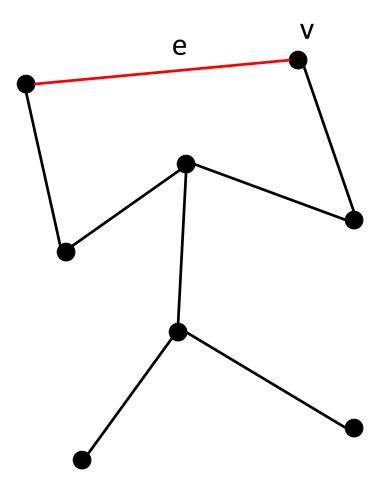
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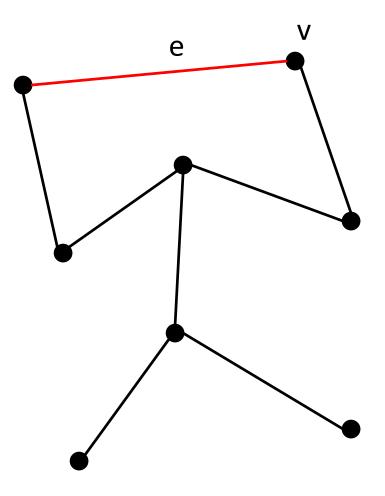
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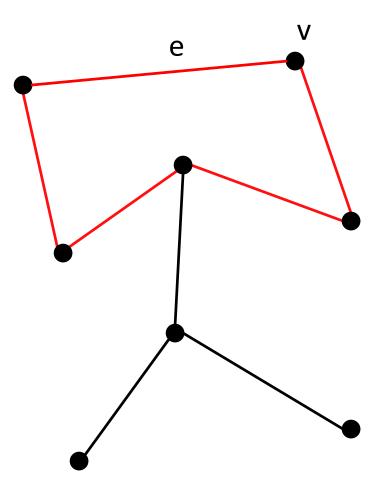
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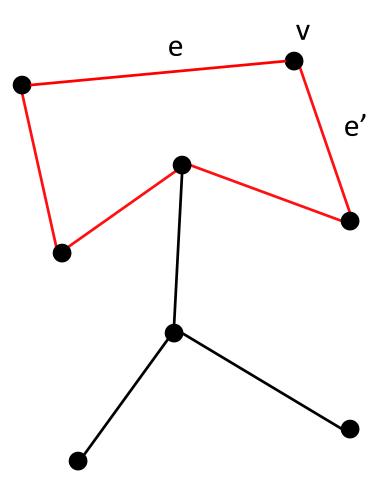
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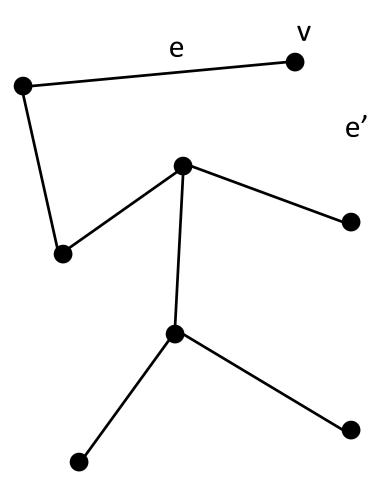
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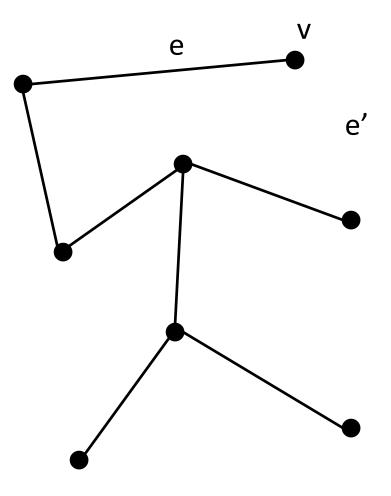
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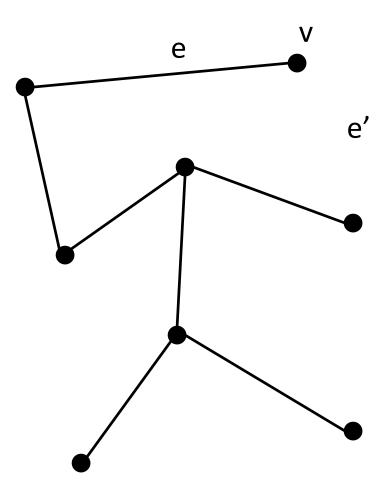
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- wt(T') = wt(T)+wt(e)-wt(e')
 ≤ wt(T)
 (because wt(e) is minimal).



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- So instead of checking *all* edges, you can just check edges from v.
- You can then contract edge and repeat.
- Prim's Algorithm: Add lightest edge that connects v to a new vertex.
- Implementation very similar to Dijkstra.

```
Prim(G,w)
  Pick vertex s
                                   \\ doesn't matter which
                            \\ lightest edge into v
  For v \in V, b(v) \leftarrow \infty
  T \leftarrow \{\}, b(s) \leftarrow 0
  Priority Queue Q, add all v with key=b(v)
  While (Q not empty)
    u \leftarrow \text{DeleteMin}(0)
    If u \neq s, add (u, Prev(u)) to T
    For (u, v) \in E
       If w(u, v) < b(v)
         b(v) \leftarrow w(u, v)
         Prev(v) \leftarrow u
         DecreaseKey(v)
  Return T
```

Prim's Algorithm

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Prim(G,w)
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 For v \in V, b(v) \leftarrow \infty
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    If u \neq s, add (u, Prev(u)) to T
    For (u, v) \in E
                                  Runtime:
       If w(u, v) < b(v)
                                  O(|V|\log|V| + |E|)
         b(v) \leftarrow w(u, v)
         Prev(v) \leftarrow u
                                  Slightly better than
         DecreaseKey(v)
                                  Kruskal
  Return T
```

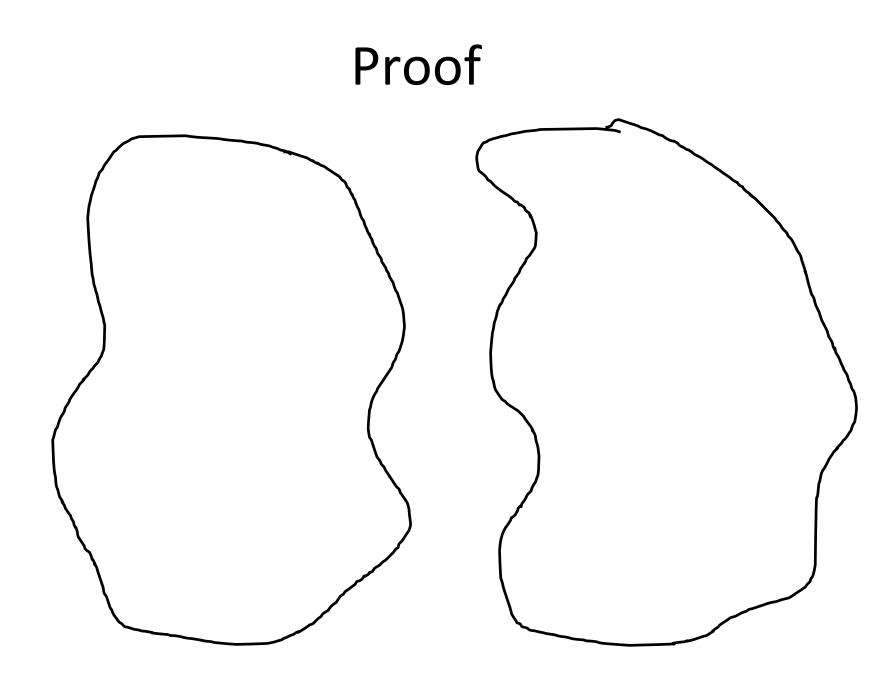
Analysis

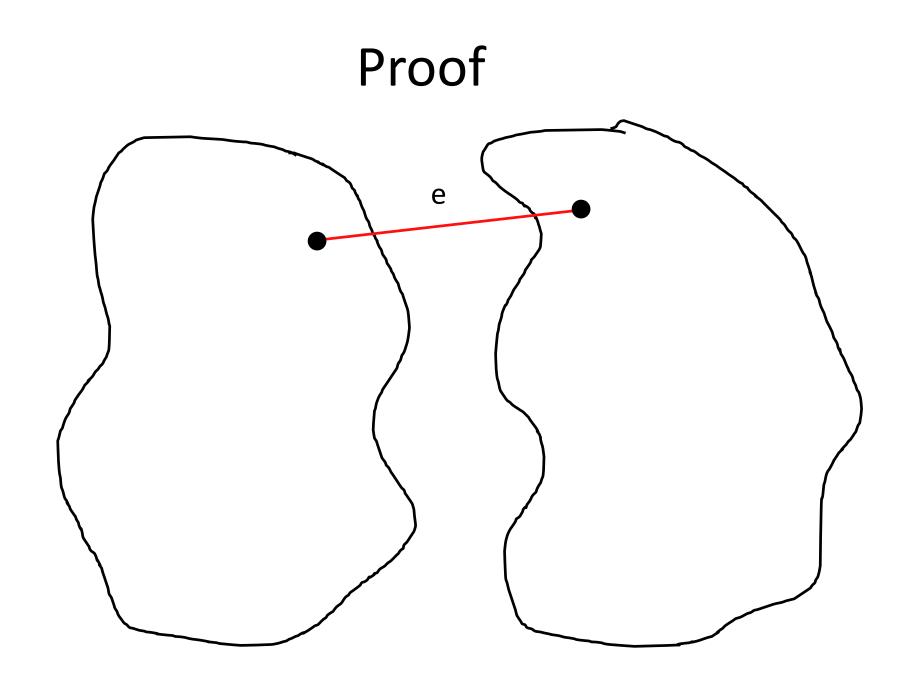
At any stage, have some set S of vertices connected to s. Find cheapest edge connecting S to S^C.

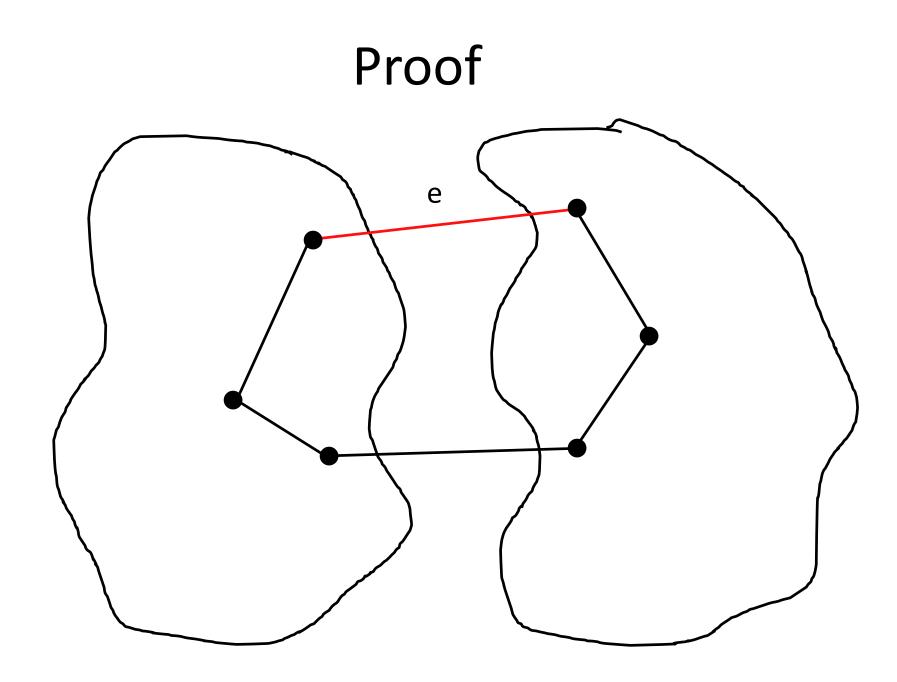
Analysis

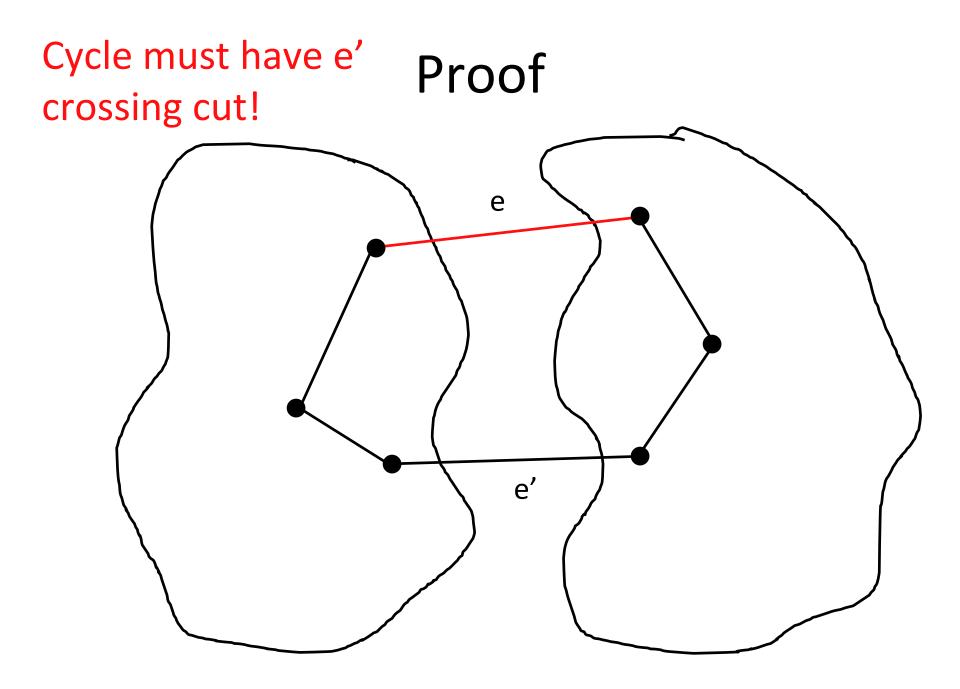
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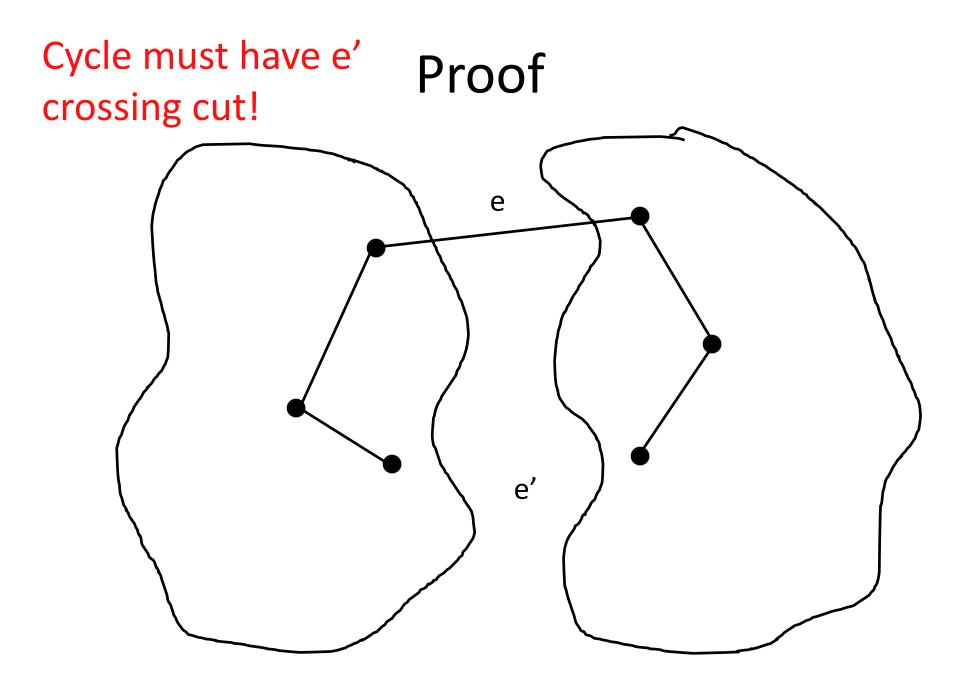
Proposition: In a graph G, with a <u>cut C</u>, let e be an edge of lightest weight <u>crossing C</u>. Then there exists an MST of G containing e. Furthermore, if e is the unique lightest edge, then *all* MSTs contain e.











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- Randomized O(|V|+|E|)
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- O(|E| α(|E|)) by Chazelle
- Best algorithm known (not known whether it is O(|V|+|E|))