

CSE203B Convex Optimization:

Chapter 9: Unconstrained Minimization

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Chapter 9 Unconstrained Minimization

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Introduction

Problem: $\min f(x)$ where $f: R^n \rightarrow R$
is convex and twice continuously differentiable

Theorem: Necessary and sufficient condition for a point x^* to be optimal is $\nabla f(x^*) = 0$.

Remark: keywords Taylor's expansion

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Taylor's Expansion & Bounds: Scalar case

$f(x) = f(x_0) + \nabla f(x_0)^T(x - x_0) + \frac{1}{2}(x - x_0)^T \nabla^2 f(z)(x - x_0)$
for some z on the segment $[x, x_0]$

(1) Scalar case: $f(x) = f(x_0) + f'(x_0)(x - x_0) + \frac{1}{2}f''(z)(x - x_0)^2$

We simplify the notations $f(x) = \frac{m}{2}(x - x_0)^2 + a(x - x_0) + b$

For fixed $m, a,$ and b , the optimal solution can be derived as:

$$\nabla f(x) = 0 \Rightarrow m(x - x_0) + a = 0 \Rightarrow x - x_0 = -\frac{a}{m}$$

Thus, we have

$$f(x) = \frac{m}{2} \frac{a^2}{m^2} + a \frac{(-a)}{m} + b = \frac{a^2}{2m} - \frac{a^2}{m} + b = \frac{-a^2}{2m} + b$$

Or $f(x) - f(x_0) = -\frac{a^2}{2m}$

a. How far from opt. x^ ? $x^* - x_0 = -\frac{a}{m}$*

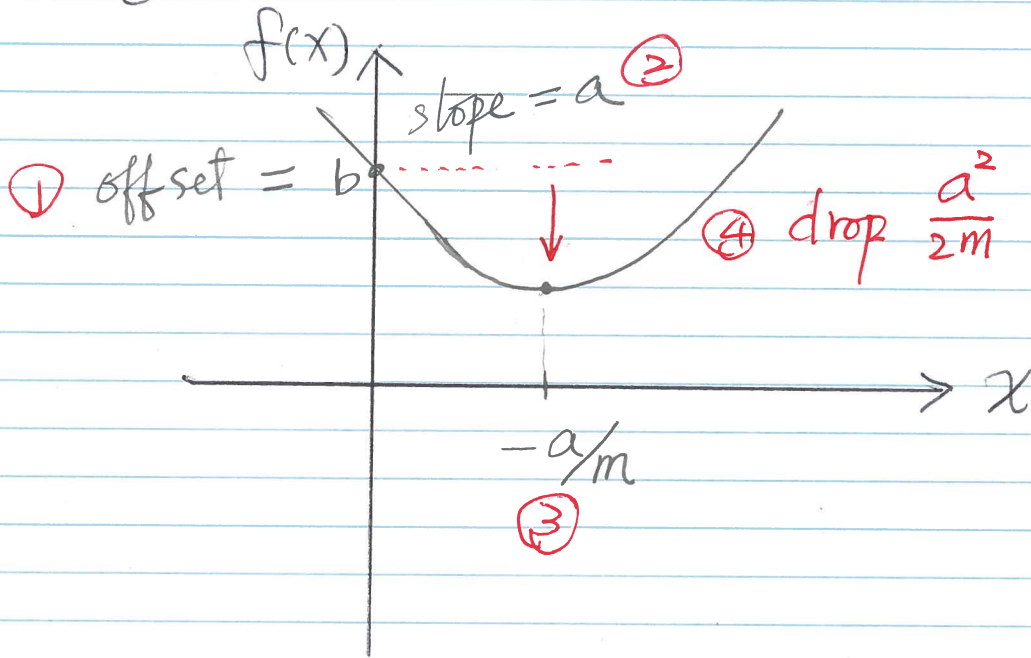
b. How much difference from opt. $f(x^)$? $f(x_0) - f(x^*) = \frac{a^2}{2m}$*

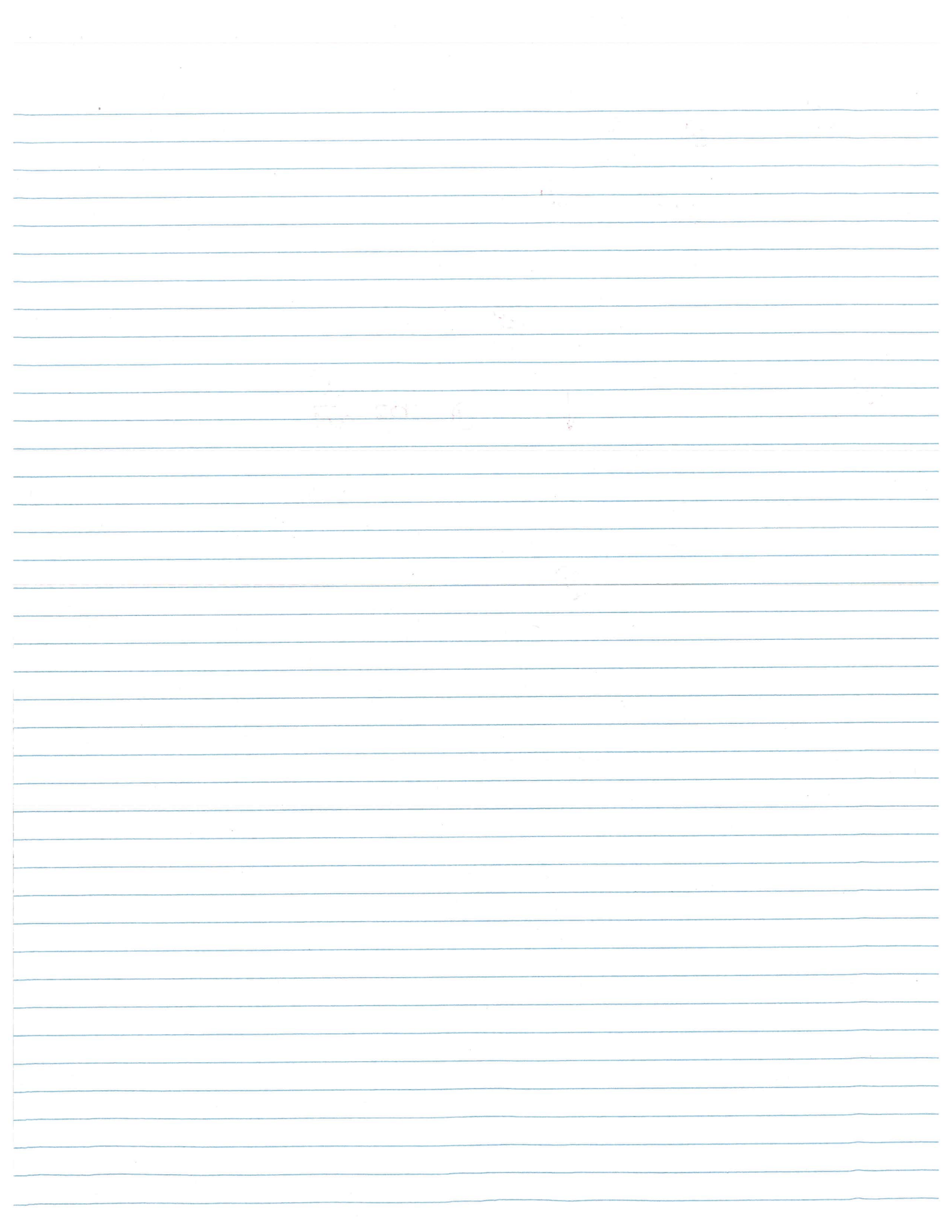
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m is positive

$$f(x) = \frac{m}{2}x^2 + ax + b$$

$$= \frac{m}{2}\left(x + \frac{a}{m}\right)^2 - \frac{a^2}{2m} + b$$





Taylor's Expansion & Bounds: Example

$$f(x) = x^2 + 4x + 1$$

For the format

$$f(x) = \frac{m}{2}x^2 + ax + b, \quad m = 2, a = 4, b = 1.$$

Let $x_0 = 0$, we have the answer.

a. *How far?* $x^* - x_0 = -\frac{a}{m} = -2$

b. *How much?* $f(x_0) - f(x^*) = \frac{a^2}{2m} = 4$

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Taylor's Expansion & Bounds: Bounds

(2) Vector case:

Assumption A: $\nabla^2 f(x)$ is bounded, i.e. $mI \preceq \nabla^2 f(x) \preceq MI$

Theorem A: We have the following bounds

$$\frac{1}{M} \|\nabla f(x_0)\|_2 \stackrel{\textcircled{4}}{\leq} \|x_0 - x^*\|_2 \stackrel{\textcircled{1}}{\leq} \frac{2}{m} \|\nabla f(x_0)\|_2$$
$$\frac{1}{2M} \|\nabla f(x_0)\|_2^2 \stackrel{\textcircled{3}}{\leq} f(x_0) - p^* \stackrel{\textcircled{2}}{\leq} \frac{1}{2m} \|\nabla f(x_0)\|_2^2$$

$$MI - \nabla^2 f(x) \succeq 0$$

Proof: $\textcircled{1}$

$$f(x) + \nabla f(x)^T (y - x) + \frac{m}{2} \|y - x\|_2^2 \leq f(y)$$
$$\leq f(x) + \nabla f(x)^T (y - x) + \frac{M}{2} \|y - x\|_2^2$$

(Taylor's Expansion + Assumption A)

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Taylor's Expansion & Bounds: Bounds

Proof ①: $\|x - x^*\|_2 \leq \frac{2}{m} \|\nabla f(x)\|_2$

$p^* = f(x^*) \geq f(x) + \nabla f(x)^T(x^* - x) + \frac{m}{2} \|x^* - x\|_2^2$ (Taylor's exp + Assumption A.)

$$\geq f(x) - \|\nabla f(x)\|_2 \|x^* - x\|_2 + \frac{m}{2} \|x^* - x\|_2^2$$

We shift $f(x)$ to the left hand side.

$$0 \geq p^* - f(x) \geq -\|\nabla f(x)\|_2 \|x^* - x\|_2 + \frac{m}{2} \|x^* - x\|_2^2$$

Shift $-\|\nabla f(x)\|_2 \|x^* - x\|_2$ to the left,

$$\|\nabla f(x)\|_2 \|x^* - x\|_2 \geq \frac{m}{2} \|x^* - x\|_2^2$$

Therefore we have

1. $\|\nabla f(x)\|_2 \geq \frac{m}{2} \|x^* - x\|_2$

2. $\|x^* - x\|_2 \leq \frac{2}{m} \|\nabla f(x)\|_2$

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Taylor's Expansion & Bounds: Bounds

Proof ②: $f(y) \geq f(x) + \nabla f(x)^T(y - x) + \frac{m}{2} \|y - x\|_2^2$

(Taylor's exp + assumption A.)

$$\geq f(x) - \frac{1}{2m} \|\nabla f(x)\|_2^2 \text{ (Minimization with } y)$$

Thus, we have

$$f(x) - f(y) \leq \frac{1}{2m} \|\nabla f(x)\|_2^2, \quad \forall y$$

Therefore

$$f(x) - f(x^*) \leq \frac{1}{2m} \|\nabla f(x)\|_2^2$$

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Taylor's Expansion & Bounds

Remark:

(1) If $\|\nabla f(x)\|_2 \leq (2m\epsilon)^{\frac{1}{2}}$

We have $\|x - x^*\|_2 \leq \frac{2}{m} (2m\epsilon)^{\frac{1}{2}}$

$$f(x) - f(x^*) \leq \frac{\|\nabla f(x)\|_2^2}{2m} = \epsilon$$

(2) The bounds can be used to design algorithms.

prove the convergence.

(3) If $M \gg m$ (e.g. 10^{10})

Impact on the bounds become very loose

→ Efficiency of gradient descent approaches.

(4) Quadratic obj. with sparse matrix (A)

$$\frac{1}{2} x^T A x + b^T x + c$$

is a preferred formulation in terms of algorithm efficiency.

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II. Descent Methods

Given convex function, twice continuously differentiable $f(x)$
and an initial point $x_0 \in \text{dom } f$.

Repeat

1. Determine a descent direction Δx ($\nabla f(x)^T \Delta x < 0$)

2. Line Search, choose a step size $t > 0$.

3. Update $x = x + t\Delta x$

Until stopping criterion is met.

Line Search : $t = \arg \min_{t>0} f(x + t\Delta x)$

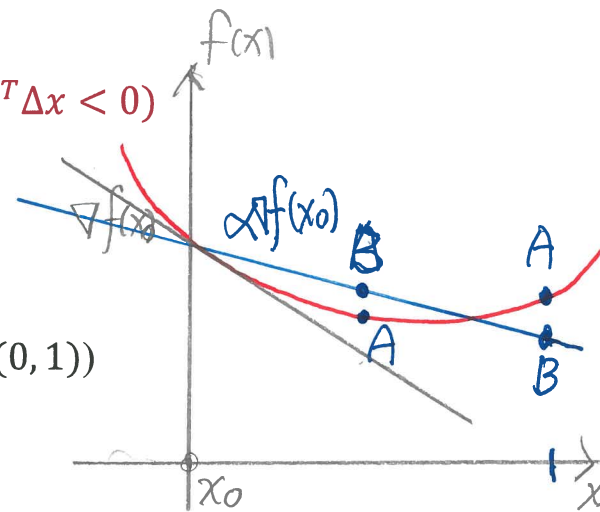
Backtracking line search ($\alpha \in (0, 1/2), \beta \in (0, 1)$)

Start at $t = 1$, repeat $t := \beta t$

until $f(x + t\Delta x) < f(x) + \alpha t \nabla f(x)^T \Delta x$

A

B



Stopping criterion $\|\nabla f(x)\|_2 \leq \eta$ $\eta = (2m\epsilon)^{\frac{1}{2}}$ (Theorem A (2))

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Taylor's Expansion & Bounds: Bounds

$$\text{Proof } \textcircled{3}: f(y) \geq f(x) + \nabla f(x)^T (y - x) + \frac{m}{2} \|y - x\|_2^2$$

(Taylor's exp + assumption A.)

$$\geq f(x) - \frac{1}{2m} \|\nabla f(x)\|_2^2 \text{ (Minimization with } y)$$

Let $y = x - \frac{1}{M} \nabla f(x)$, we have

$$\begin{aligned} f\left(x - \frac{1}{M} \nabla f(x)\right) &\leq f(x) + \nabla f(x)^T \frac{-1}{M} \nabla f(x) + \frac{M}{2} \left\| \frac{1}{M} \nabla f(x) \right\|_2^2 \\ &= f(x) - \frac{1}{2M} \|\nabla f(x)\|_2^2 \end{aligned}$$

Shift the terms on the left and right, we have

$$\begin{aligned} \frac{1}{2M} \|\nabla f(x)\|_2^2 &\leq f(x) - f\left(x - \frac{1}{M} \nabla f(x)\right) \\ &\leq f(x) - f(x^*) \end{aligned}$$

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Taylor's Expansion & Bounds: Bounds

$$(4) \text{ Proof: } f(y) \leq f(x) + \nabla f(x)^T (y - x) + \frac{M}{2} \|y - x\|_2^2$$

(Taylor's exp. + assumption A)

(i) Let $x = x^*$, we have $\nabla f(x^*) = 0$,
thus, we can write the above eq.

$$f(y) \leq f(x^*) + \frac{M}{2} \|y - x^*\|_2^2$$

$$\text{or } f(y) - p^* \leq \frac{M}{2} \|y - x^*\|_2^2$$

(ii) From (3), we have

$$\frac{1}{2M} \|\nabla f(x_o)\|_2^2 \leq f(x_o) - p^*$$

(iii) From (i)&(ii), we have

$$\frac{1}{2M} \|\nabla f(x_o)\|_2^2 \leq \frac{M}{2} \|x_o - x^*\|_2^2$$

Therefore, we have

$$\frac{1}{M} \|\nabla f(x_o)\|_2 \leq \|x_o - x^*\|_2$$

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