

CSE203B Convex Optimization:

Chapter 9: Unconstrained Minimization

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Chapter 9 Unconstrained Minimization

- Introduction
- Taylor's Expansion & Bounds
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Introduction

Problem: $\min f(x)$ where $f: R^n \rightarrow R$
is convex and twice continuously
differentiable

Theorem: Necessary and sufficient condition for a
point x^* to be optimal is $\nabla f(x^*) = 0$.

$$\nabla^2 f(x^*) \geq 0$$

Remark: keywords Taylor's expansion

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Taylor's Expansion & Bounds: Scalar case

$$f(x) = f(x_0) + \nabla f(x_0)^T(x - x_0) + \frac{1}{2}(x - x_0)^T \nabla^2 f(z)(x - x_0)$$

for some z on the segment $[x, x_0]$

$$(1) \text{Scalar case: } f(x) = f(x_0) + f'(x_0)(x - x_0) + \frac{1}{2}f''(z)(x - x_0)^2$$

$$\text{We simplify the notations } f(x) = \frac{m}{2}(x - x_0)^2 + a(x - x_0) + b$$

For fixed m, a , and b , the optimal solution can be derived as:

$$\nabla f(x) = 0 \Rightarrow m(x - x_0) + a = 0 \Rightarrow x - x_0 = -\frac{a}{m}$$

Thus, we have

$$f(x) = \frac{m}{2} \frac{a^2}{m^2} + a \frac{(-a)}{m} + b = \frac{a^2}{2m} - \frac{a^2}{m} + b = \frac{-a^2}{2m} + b$$

$$\text{Or } f(x) - f(x_0) = -\frac{a^2}{2m}$$

$$a. \text{ How far from opt. } x^*? x^* - x_0 = -\frac{a}{m}$$

$$b. \text{ How much difference from opt. } f(x^*)? f(x_0) - f(x^*) = \frac{a^2}{2m}$$

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Taylor's Expansion & Bounds: Example

$$f(x) = x^2 + 4x + 1$$

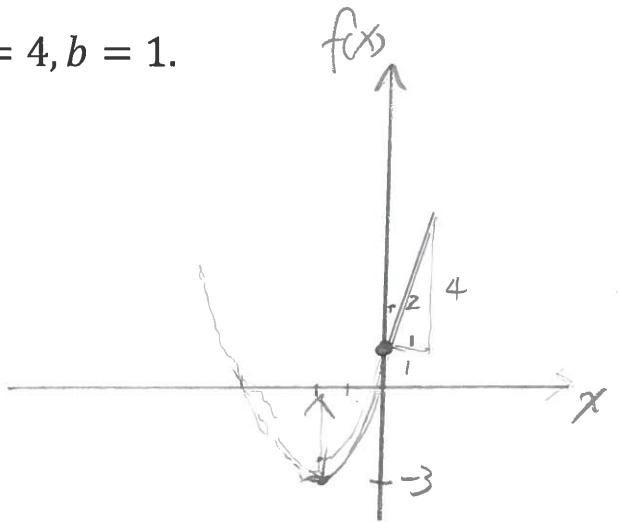
For the format

$$f(x) = \frac{m}{2}x^2 + ax + b, \quad m = 2, a = 4, b = 1.$$

Let $x_0 = 0$, we have the answer.

a. **How far?** $x^* - x_0 = -\frac{a}{m} = -2$

b. **How much?** $f(x_0) - f(x^*) = \frac{a^2}{2m} = 4$



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Taylor's Expansion & Bounds: Bounds

(2) Vector case:

Assumption A: $\nabla^2 f(x)$ is bounded, i.e. $mI \leq \nabla^2 f(x) \leq MI$

Theorem A: We have the following bounds

$$\frac{1}{M} \|\nabla f(x_0)\|_2 \stackrel{(4)}{\leq} \|x_0 - x^*\|_2 \stackrel{(1)}{\leq} \frac{2}{m} \|\nabla f(x_0)\|_2$$

$$\frac{1}{2M} \|\nabla f(x_0)\|_2^2 \stackrel{(3)}{\leq} f(x_0) - p^* \stackrel{(2)}{\leq} \frac{1}{2m} \|\nabla f(x_0)\|_2^2$$

Proof: ①

$$f(x) + \nabla f(x)^T(y - x) + \frac{m}{2} \|y - x\|_2^2 \leq f(y)$$

$$\leq f(x) + \nabla f(x)^T(y - x) + \frac{M}{2} \|y - x\|_2^2$$

(Taylor's Expansion + Assumption A)

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Taylor's Expansion & Bounds: Bounds

$$\text{Proof ①: } \|x - x^*\|_2 \leq \frac{2}{m} \|\nabla f(x)\|_2$$

$p^* = f(x^*) \geq f(x) + \nabla f(x)^T (x^* - x) + \frac{m}{2} \|x^* - x\|_2^2$ (Taylor's exp + Assumption A.)

$$\geq f(x) - \|\nabla f(x)\|_2 \|x^* - x\|_2 + \frac{m}{2} \|x^* - x\|_2^2$$

We shift $f(x)$ to the left hand side.

$$0 \geq p^* - f(x) \geq -\|\nabla f(x)\|_2 \|x^* - x\|_2 + \frac{m}{2} \|x^* - x\|_2^2$$

Shift $-\|\nabla f(x)\|_2 \|x^* - x\|_2$ to the left,

$$\|\nabla f(x)\|_2 \|x^* - x\|_2 \geq \frac{m}{2} \|x^* - x\|_2^2$$

Therefore we have

$$1. \|\nabla f(x)\|_2 \geq \frac{m}{2} \|x^* - x\|_2$$

$$2. \|x^* - x\|_2 \leq \frac{2}{m} \|\nabla f(x)\|_2$$

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Taylor's Expansion & Bounds: Bounds

$$\text{Proof ②: } f(y) \geq f(x) + \nabla f(x)^T (y - x) + \frac{m}{2} \|y - x\|_2^2$$

(Taylor's exp + assumption A.)

$$\geq f(x) - \frac{1}{2m} \|\nabla f(x)\|_2^2 \text{ (Minimization with } y)$$

Thus, we have

$$f(x) - f(y) \leq \frac{1}{2m} \|\nabla f(x)\|_2^2, \quad \forall y$$

Therefore

$$f(x) - f(x^*) \leq \frac{1}{2m} \|\nabla f(x)\|_2^2$$

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Taylor's Expansion & Bounds: Bounds

$$\begin{aligned}
 \text{Proof ③: } f(y) &\geq f(x) + \nabla f(x)^T (y - x) + \frac{m}{2} \|y - x\|_2^2 \\
 &\quad (\text{Taylor's exp + assumption A.}) \\
 &\geq f(x) - \frac{1}{2m} \|\nabla f(x)\|_2^2 \quad (\text{Minimization with } y)
 \end{aligned}$$

Let $y = x - \frac{1}{M} \nabla f(x)$, we have

$$\begin{aligned}
 f\left(x - \frac{1}{M} \nabla f(x)\right) &\leq f(x) + \nabla f(x)^T \frac{-1}{M} \nabla f(x) + \frac{M}{2} \left\| \frac{1}{M} \nabla f(x) \right\|_2^2 \\
 &= f(x) - \frac{1}{2M} \|\nabla f(x)\|_2^2
 \end{aligned}$$

Shift the terms on the left and right, we have

$$\begin{aligned}
 \frac{1}{2M} \|\nabla f(x)\|_2^2 &\leq f(x) - f\left(x - \frac{1}{M} \nabla f(x)\right) \\
 &\leq f(x) - f(x^*)
 \end{aligned}$$

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Taylor's Expansion & Bounds: Bounds

$$\begin{aligned}
 (4) \text{ Proof: } f(y) &\leq f(x) + \nabla f(x)^T (y - x) + \frac{M}{2} \|y - x\|_2^2 \\
 &\quad (\text{Taylor's exp. + assumption A})
 \end{aligned}$$

- (i) Let $x = x^*$, we have $\nabla f(x^*) = 0$,
- thus, we can write the above eq.

$$\begin{aligned}
 f(y) &\leq f(x^*) + \frac{M}{2} \|y - x^*\|_2^2 \\
 \text{or } f(y) - p^* &\leq \frac{M}{2} \|y - x^*\|_2^2
 \end{aligned}$$

- (ii) From (3), we have

$$\frac{1}{2M} \|\nabla f(x_o)\|_2^2 \leq f(x_o) - p^*$$

- (iii) From (i)&(ii), we have

$$\frac{1}{2M} \|\nabla f(x_o)\|_2^2 \leq \frac{M}{2} \|x_o - x^*\|_2^2$$

Therefore, we have

$$\frac{1}{M} \|\nabla f(x_o)\|_2 \leq \|x_o - x^*\|_2$$

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Taylor's Expansion & Bounds

Remark:

(1) If $\|\nabla f(x)\|_2 \leq (2m\epsilon)^{\frac{1}{2}}$

We have $\|x - x^*\|_2 \leq \frac{2}{m} (2m\epsilon)^{\frac{1}{2}}$

$$f(x) - f(x^*) \leq \frac{\|\nabla f(x)\|_2^2}{2m} = \epsilon$$

(2) The bounds can be used to design algorithms.

prove the convergence.

(3) If $M \gg m$ (e.g. 10^{10})

Impact on the bounds become very loose

→ Efficiency of gradient descent approaches.

(4) Quadratic obj. with sparse matrix (A)

$$\frac{1}{2} x^T A x + b^T x + c$$

is a preferred formulation in terms of algorithm efficiency.

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II. Descent Methods

Given convex function, twice continuously differentiable $f(x)$
and an initial point $x_0 \in \text{dom } f$.

Repeat

1. Determine a descent direction Δx ($\nabla f(x)^T \Delta x < 0$)

2. Line Search, choose a step size $t > 0$.

3. Update $x = x + t\Delta x$

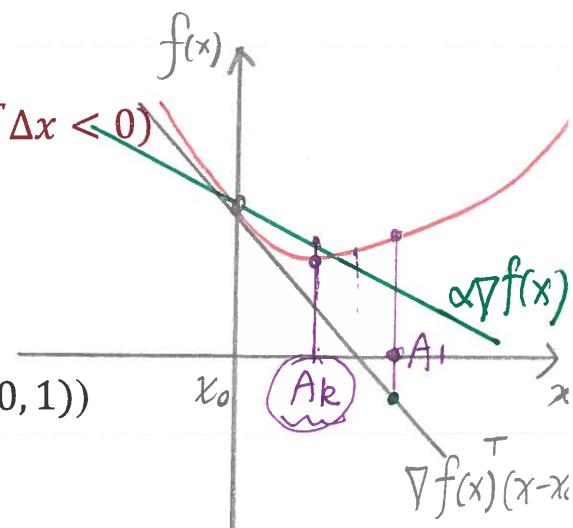
Until stopping criterion is met.

Line Search : $t = \arg \min_{t>0} f(x + t\Delta x)$

Backtracking line search ($\alpha \in (0, 1/2), \beta \in (0, 1)$)

Start at $t = 1$, repeat $t := \beta t$

until $f(x + t\Delta x) < f(x) + \alpha t \nabla f(x)^T \Delta x$



Stopping criterion $\|\nabla f(x)\|_2 \leq \eta$ $\eta = (2m\epsilon)^{\frac{1}{2}}$ (Theorem A (2))

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II. Descent Methods: Example

Problem: $\min f(x) = \frac{1}{2}(x_1^2 + \gamma x_2^2)$ $\gamma > 0$

$$x^o = (\gamma, 1), f(x^o) = \frac{\gamma(\gamma+1)}{2}, \nabla f(x^o) = (\gamma, \gamma)$$

Thus, $x^1 = (\gamma, 1) - t(\gamma, \gamma) = (\gamma(1-t), 1-t\gamma)$

and $\nabla f(x^1) = (\gamma(1-t), \gamma(1-t\gamma))$

1. To opt $f(x^1)$ with respect to variable t ,

we have $f(x^1) = \frac{1}{2}(\gamma^2(1-t)^2 + \gamma(1-t\gamma)^2)$

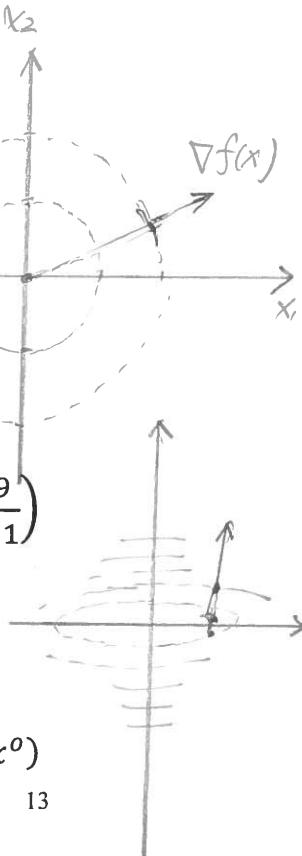
$$\frac{\partial f(x^1)}{\partial t} = \gamma^2(1-t) + \gamma(1-t\gamma)\gamma = 0$$

Thus, $t = \frac{2\gamma^2}{\gamma^2+\gamma^3} = \frac{2}{1+\gamma}$, and $x^1 = \left(\frac{\gamma(\gamma-1)}{1+\gamma}, \frac{1-\gamma}{1+\gamma}\right) = \left(\frac{10 \times 9}{11}, -\frac{9}{11}\right)$

2. We repeat the process to step k , $x^k = (\gamma \left(\frac{\gamma-1}{\gamma+1}\right)^k, \left(\frac{1-\gamma}{1+\gamma}\right)^k)$

3. Equal potential plot

$$f(x^k) = \frac{\gamma(\gamma+1)}{2} \left(\frac{\gamma-1}{\gamma+1}\right)^{2k} = \left(\frac{\gamma-1}{\gamma+1}\right)^{2k} f(x^o) = \left(\frac{1-m/M}{1+m/M}\right)^{2k} f(x^o)$$



II. Descent Methods: Descent for various norms

1. Problem: Min $f(x)$

2. For each iteration, we try the steepest descent in terms of a given norm.

$$\begin{aligned} \text{Min } & \nabla f(x)^T \Delta x \\ \text{s.t. } & \|\Delta x\| \leq 1 \end{aligned}$$

3. We show the step of

i. Quadratic norm

ii. L1 norm

II. Descent Methods: Descent for quadratic norm

1. Problem: Min $f(x)$

2. For each iteration, we try the steepest descent in terms of a given norm.

$$\begin{aligned} \text{Min}_{\Delta x} \quad & \nabla f(x)^T \Delta x \\ \text{s.t. } & \|\Delta x\|_P \leq 1 \end{aligned}$$

$$\|\Delta x\|_P = (\Delta x^T P \Delta x)^{1/2}, P \in S_{++}^n$$

$$\text{Lagrangian } L(\Delta x, \lambda) = \nabla f(x)^T \Delta x + \lambda (\|\Delta x\|_P - 1), \lambda \geq 0$$

$$\text{We can derive: } \Delta x_{nsd} = -(\underbrace{\nabla f(x)^T P^{-1} \nabla f(x)}_{\text{Lagrangian term}})^{-1/2} P^{-1} \nabla f(x)$$

$$\text{Or } \Delta x_{sd} = -P^{-1} \nabla f(x)$$

$$\begin{aligned} \nabla L(\Delta x, \lambda) &= \nabla f(x) + \lambda P \Delta x = 0 \\ \Delta x &= \frac{-1}{\lambda} P^{-1} \nabla f(x) \end{aligned}$$

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II. Descent Methods: Descent for quadratic norm

The coordinate change has effects on the descent direction.

$$\text{Example: } \min f(x) = \frac{1}{2} x^T P x + q^T x, P \in S_{++}^n$$

$$\text{Affine transform: } \bar{x} = P^{1/2} x \quad ((P^{1/2})^2 = P)$$

No transform.

$$\nabla_x f(x) = P x + q = 0 \Rightarrow x = -P^{-1} q$$

$$\begin{aligned} \text{Transform} \\ x &= P^{-1/2} \bar{x} \end{aligned}$$

$$f(\bar{x}) = \frac{1}{2} \bar{x}^T \bar{x} + q^T P^{-1/2} \bar{x}$$

$$\nabla_{\bar{x}} f(\bar{x}) = \bar{x} + P^{-1/2} q = 0 \Rightarrow \bar{x} = -P^{-1/2} q$$

$$\Rightarrow P^{1/2} x = -P^{-1/2} q$$

$$\Rightarrow x = -P^{-1} q$$

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II. Descent Methods: Descent for L1 norm

1. Problem: Min $f(x)$

2. For each iteration, we try the steepest descent in terms of a given norm.

$$\text{Min } \nabla f(x)^T \Delta x < 0$$

$$\text{s.t. } \|\Delta x\|_1 \leq 1$$

Lagrangian $L(\Delta x, \lambda) = \nabla f(x)^T \Delta x + \lambda (\|\Delta x\|_1 - 1)$, $\lambda \geq 0$

We can derive: $\Delta x_{nsd} = -\text{sign}\left(\frac{\partial f(x)}{\partial x_i}\right) e_i$,

where i is the index for which $\|\nabla f(x)\|_\infty = |\nabla f(x)_i|$

Or $\Delta x_{sd} = -\frac{\partial f(x)}{\partial x_i} e_i$

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Gradient descent method: Convergence analysis

$$\tilde{f}(t) \equiv f(x - t\nabla f(x)) \leq f(x) - t\|\nabla f(x)\|_2^2 + \frac{Mt^2}{2}\|\nabla f(x)\|_2^2$$

$$\tilde{f}(t_{exact}) \leq \tilde{f}\left(t = \frac{1}{M}\right) \leq f(x) - \frac{1}{2M}\|\nabla f(x)\|_2^2 \quad (\min_t \tilde{f}(t) \nabla f(x))$$

$$A. \tilde{f}(t_{exact}) - p^* \leq f(x) - p^* - \frac{1}{2M}\|\nabla f(x)\|_2^2$$

$$B. \frac{1}{2M}\|\nabla f(x)\|_2^2 \geq \frac{m}{M}(f(x) - p^*) \text{ since } \frac{\|\nabla f(x)\|_2^2}{2m} \geq f(x) - p^*$$

C. From B, we have

$$\begin{aligned} f(x) - p^* - \frac{1}{2M}\|\nabla f(x)\|_2^2 &\leq f(x) - p^* - \frac{m}{M}(f(x) - p^*) \\ &= (f(x) - p^*)(1 - \frac{m}{M}) \end{aligned}$$

D. We can conclude from A & C

$$f(x^{k+1}) - p^* \leq \left(1 - \frac{m}{M}\right)(f(x^k) - p^*) \leq \left(1 - \frac{m}{M}\right)^k (f(x^0) - p^*)$$

To achieve $f(x^*) - p^* \leq \epsilon$,

we need $\frac{\log((f(x^0) - p^*)/\epsilon)}{\log(1/c)}$ steps, where $c = 1 - \frac{m}{M} < 1$,

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Gradient descent method : Convergence analysis

$$\log(1/c) = -\log(1 - m/M) \approx m/M \text{ for large } M/m$$

Remark: when $M/m > 100$

the method can be very slow.

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Newton Step

Use the approximation of 2nd order Taylor's Exp.

$$f(x + v) \approx f(x) + \nabla f(x)^T v + \frac{1}{2} v^T \nabla^2 f(x) v$$

We would like to derive

$$\nabla_v f(x + v) = 0 \rightarrow \nabla f(x) + \nabla^2 f(x) v = 0$$

$$\text{Thus, we have } v = -\nabla^2 f(x)^{-1} \nabla f(x)$$

$$\begin{aligned} f(x + v) &= f(x) + (-1) \nabla f(x)^T \nabla^2 f(x)^{-1} \nabla f(x) + \\ &\quad \frac{1}{2} \nabla f(x)^T \nabla^2 f(x)^{-1} \nabla f(x) \\ &= f(x) - \frac{1}{2} \nabla f(x)^T \nabla^2 f(x)^{-1} \nabla f(x) \end{aligned}$$

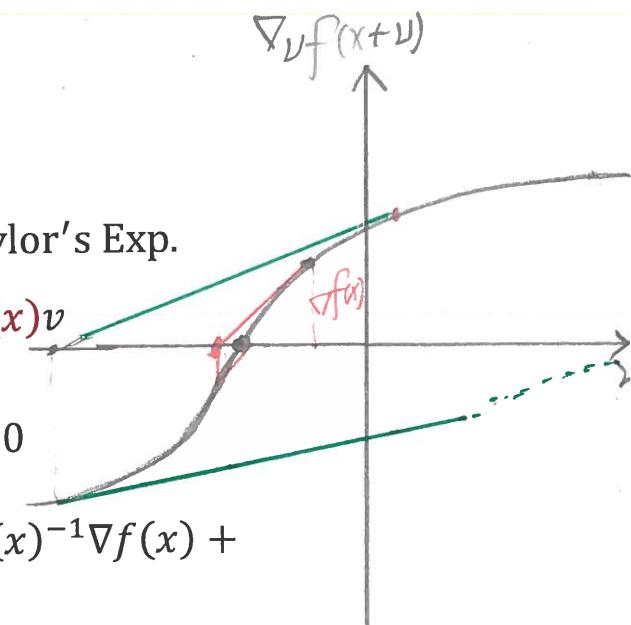
Input $x \in \text{dom } f$, $\epsilon > 0$

Repeat: 1. $\Delta x_{nt} := -\nabla^2 f(x)^{-1} \nabla f(x)$, $\lambda^2(x) = \nabla f(x)^T \nabla^2 f(x)^{-1} \nabla f(x)$

2. *Quit if $\lambda^2/2 \leq \epsilon$*

3. *Line Search t*

4. $x := x + t \Delta x_{nt}$



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