## CSE 203B W22 Homework 1

Due Time : 11:50pm, Wednesday Jan. 12, 2022 Submit to Gradescope Gradescope: https://gradescope.com/

In this homework, we work on the basic concepts of convex optimization and linear algebra.
All the problems are graded by content.

## 1. Convex Optimization (12 pts)

1.1. Given a function $f_{0}(x)=x^{4}-4 x^{3}+6 x^{2}-4 x+1$, where $x \in \mathbb{R}$. Solve $\min _{x} f_{0}(x)$ using Kuhn-Tucker conditions. Show your derivation. (2 pts)
1.2. Given two functions $f_{0}(x)=x^{2}-3 x+1$, and $f_{1}(x)=3 x+1$, where $x \in \mathbb{R}$. Solve $\min _{x} f_{0}(x)$ subject to $f_{1}(x) \leq 0$ using the primal dual transform with Lagrange multipliers. Show your derivation. (10 pts)

## 2. Matrix Properties (14 pts)

2.1. Linear System (2pts)

Consider the following system of linear equations

$$
\begin{array}{r}
x_{1}+x_{2}+3 x_{3}=1 \\
2 x_{1}-x_{2}+2 x_{3}=-2 \\
3 x_{1}+5 x_{3}=-1 .
\end{array}
$$

Write the equations in a matrix form.
2.2. For the matrix in problem 2.1, derive its range. What's the rank of this matrix? (2pts)
2.3. Derive the nullspace of the matrix in problem 2.1. What's the relation between the range and nullspace of a matrix? (2pts)
2.4. Derive the trace and determinant of the matrix in problem 2.1. Write the eigenvalues and eigenvectors. (2pts)
2.5. Prove the following properties. ( 3 pts )

- For $A \in \mathbb{R}^{m \times n}, B \in \mathbb{R}^{n \times m}, \operatorname{tr} A B=\operatorname{tr} B A$.
- For $A, B \in \mathbb{R}^{n \times n}, \operatorname{det} A B=\operatorname{det} A \operatorname{det} B$.
- For $A \in \mathbb{R}^{n \times n}, \operatorname{det} A=\prod_{i=1}^{n} \lambda_{i}$, and $\operatorname{tr} A=\sum_{i=1}^{n} \lambda_{i}$, where $\lambda_{i}, i=1, \ldots, n$ are the eigenvalues of $A$.
2.6. Suppose that you are a tutor. Devise a simple but meaningful numerical example to illustrate the three equations in problem 2.5. (3 pts)

3. Matrix Operations ( 14 pts )

Gradient: consider a function $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ that takes a vector $x \in \mathbb{R}^{n}$ and returns a real value. Then the gradient of $f$ (w.r.t. $x$ ) is the vector of partial derivatives, defined as

$$
\nabla_{x} f(x)=\left[\begin{array}{c}
\frac{\partial f(x)}{\partial x_{1}} \\
\frac{\partial f(x)}{\partial x_{2}} \\
\vdots \\
\frac{\partial f(x)}{\partial x_{n}}
\end{array}\right]
$$

Hessian: consider a function $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$ that takes a vector $x \in \mathbb{R}^{n}$ and returns a real value. Then the Hessian matrix of $f$ (w.r.t. $x$ ) is the $n \times n$ matrix of partial derivatives, defined as

$$
\nabla_{x}^{2} f(x)=\left[\begin{array}{cccc}
\frac{\partial^{2} f(x)}{\partial x_{1}^{2}} & \frac{\partial^{2} f(x)}{\partial x_{1} \partial x_{2}} & \cdots & \frac{\partial^{2} f(x)}{\partial x_{1} \partial x_{n}} \\
\frac{\partial^{2} f(x)}{\partial x_{1} \partial x_{2}} & \frac{\partial^{2} f(x)}{\partial x_{2}^{2}} & \ldots & \frac{\partial^{2} f(x)}{\partial x_{2} \partial x_{n}} \\
\vdots & \vdots & \ddots & \vdots \\
\frac{\partial^{2} f(x)}{\partial x_{n} \partial x_{1}} & \frac{\partial^{2} f(x)}{\partial x_{n} \partial x_{2}} & \ldots & \frac{\partial^{2} f(x)}{\partial x_{n}^{2}}
\end{array}\right]
$$

3.1. Write the gradient and Hessian matrix for the linear function

$$
f(x)=2 b^{T} x
$$

where $x \in \mathbb{R}^{n}$ and vector $b \in \mathbb{R}^{n} .(2 \mathrm{pts})$
3.2. Write the gradient and Hessian matrix of the quadratic function

$$
f(x)=x^{T} A x+b^{T} x+c,
$$

where $x \in \mathbb{R}^{n}$, matrix $A \in \mathbb{R}^{n \times n}$, vector $b \in \mathbb{R}^{n}$, and $c \in \mathbb{R}$. (2 pts)
3.3. Write the gradient and Hessian matrix of the quadratic function

$$
f(x)=x^{T}\left(A+A^{T}\right) x+b^{T} x+c
$$

where $x \in \mathbb{R}^{n}$, matrix $A \in \mathbb{R}^{n \times n}$, vector $b \in \mathbb{R}^{n}$, and $c \in \mathbb{R}$. (2 pts)
3.4. Given matrix $A \in \mathbb{R}^{m \times n}$ where $m<n$ and $\operatorname{rank}(A)=m$, and vector $b \in \mathbb{R}^{m}$, find a solution $x \in \mathbb{R}^{n}$ such that $A x=b$. $(3 \mathrm{pts})$
3.5. Given a nonsingular matrix

$$
A=\left[\begin{array}{lll}
a & b & c \\
d & e & f \\
g & h & i
\end{array}\right]
$$

write the analytic solution of $A^{-1}$. (2 pts)
3.6. Given a nonsingular matrix

$$
M=\left[\begin{array}{ll}
A & B \\
C & D
\end{array}\right],
$$

where elements $A, B, C, D \in \mathbb{R}^{2 \times 2}$, write an analytic solution of $M^{-1}$. Hint: For matrices, the multiplication does not commute, e.g. we cannot claim that $A B=B A$ ( 3 pts )

