

COLOR

Introduction to Computer Vision
CSE 152
Lecture 17

CSE 152, Spring 2017

Introduction to Computer Vision

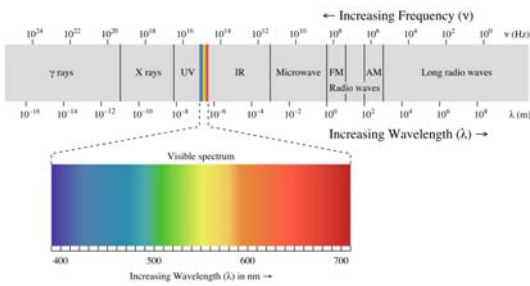
Announcements

- Homework 5 is due Sat, Jun 10, 11:59 PM
- Reading:
 - Chapter 3: Color

CSE 152, Spring 2017

Introduction to Computer Vision

Electromagnetic Spectrum



CSE 152, Spring 2017

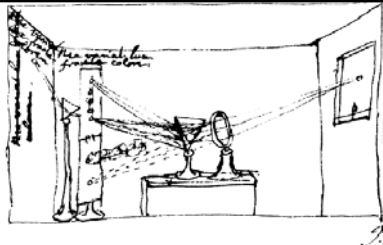
Introduction to Computer Vision

The appearance of colors

- Color appearance is strongly affected by (at least):
 - spectrum of lighting striking the retina
 - other nearby colors (space)
 - adaptation to previous views (time)
 - “state of mind”

CSE 152, Spring 2017

Introduction to Computer Vision



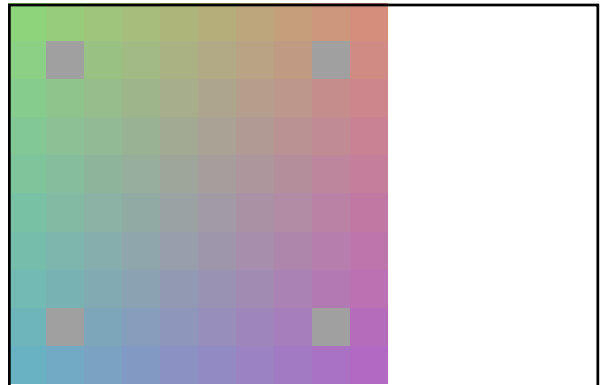
4.1. NEWTON'S SUMMARY DRAWING of his experiments with light. Using a point source of light and a prism, Newton separated sunlight into its fundamental components. By reconverging the rays, he also showed that the decomposition is reversible.

From Foundations of Vision, Brian Wandell, 1995, via B. Freeman slides



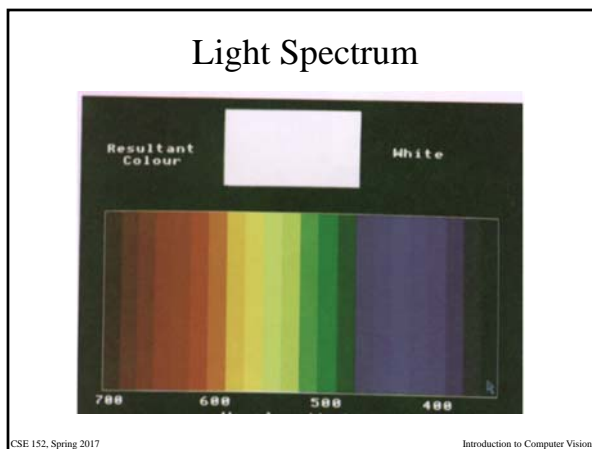
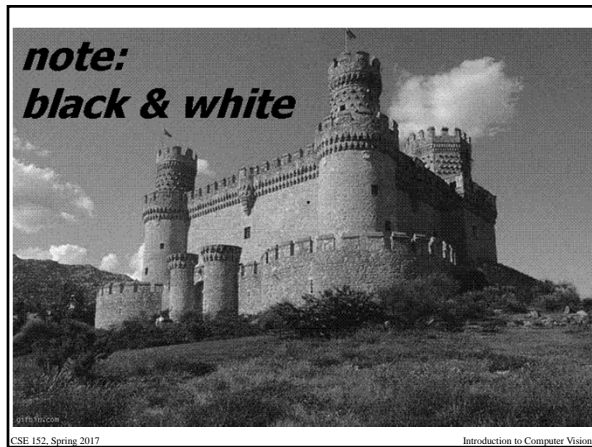
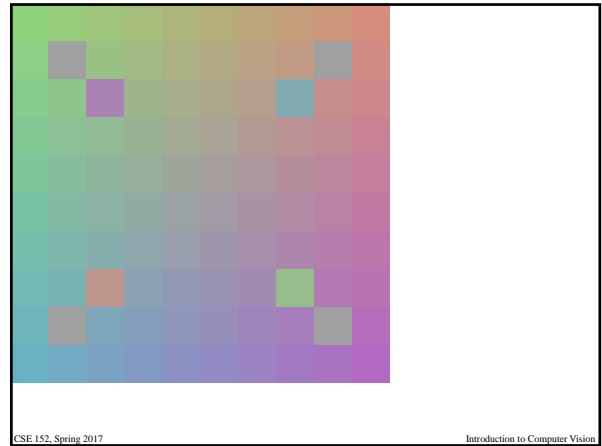
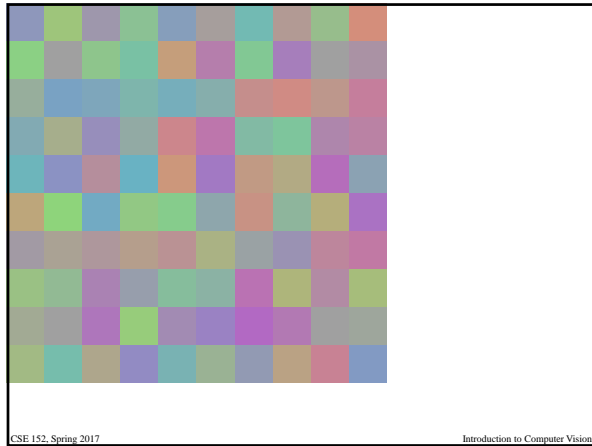
CSE 152, Spring 2017

Introduction to Computer Vision



CSE 152, Spring 2017

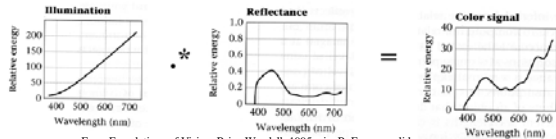
Introduction to Computer Vision



- ### Talking about colors
1. Spectrum –
 - A positive function over interval 400nm-700nm
 - “Infinite” number of values needed.
 2. Names
 - red, harvest gold, cyan, aquamarine, auburn, chestnut
 - A large, discrete set of color names
 3. R,G,B values
 - Just 3 numbers
- CSE 152, Spring 2017 Introduction to Computer Vision

Color Reflectance

Measured color spectrum is a function of the spectrum of the illumination and reflectance

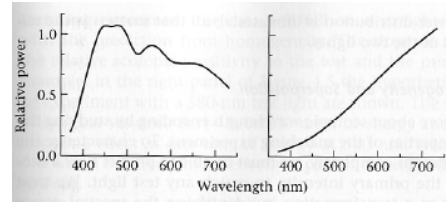


CSE 152, Spring 2017

Introduction to Computer Vision

Illumination Spectra

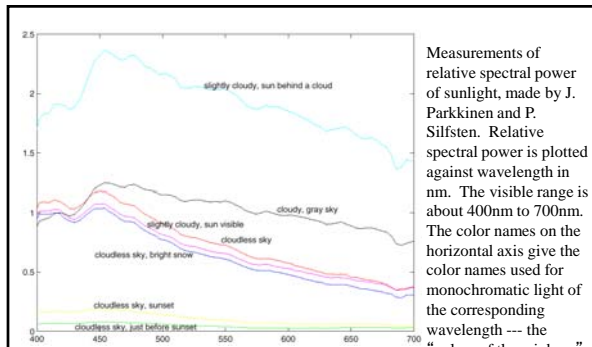
Blue skylight Tungsten bulb



From Foundations of Vision, Brian Wandell, 1995, via B. Freeman slides

CSE 152, Spring 2017

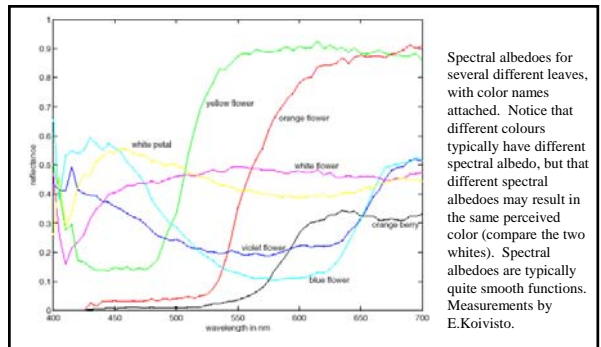
Introduction to Computer Vision



Measurements of relative spectral power of sunlight, made by J. Parkkinen and P. Silfsten. Relative spectral power is plotted against wavelength in nm. The visible range is about 400nm to 700nm. The color names on the horizontal axis give the color names used for monochromatic light of the corresponding wavelength --- the "colors of the rainbow". Mnemonic is "Richard of York got blisters in Venice".

CSE 152, Spring 2017

Introduction to Computer Vision

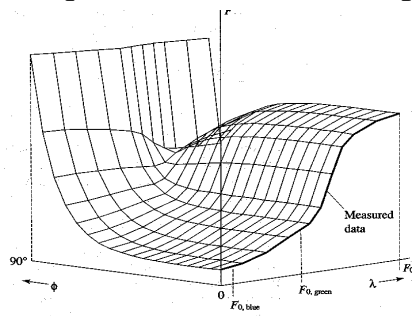


Spectral albedoes for several different leaves, with color names attached. Notice that different colours typically have different spectral albedo, but that different spectral albedoes may result in the same perceived color (compare the two whites). Spectral albedoes are typically quite smooth functions. Measurements by E.Koivisto.

CSE 152, Spring 2017

Introduction to Computer Vision

Fresnel Equation for Polished Copper



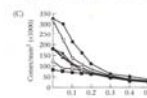
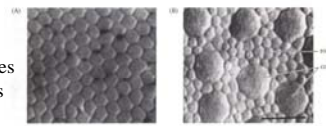
CSE 152, Spring 2017

Introduction to Computer Vision

RGB Color Model

- Based on human perception of color

Red cones
Green cones
Blue cones

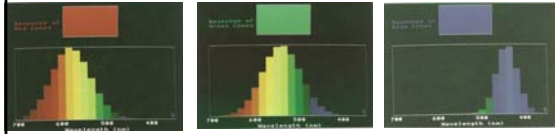


3.4 THE SPATIAL MOSAIC OF THE HUMAN CONES. Cross sections of the human retina at the level of the inner segment showing (A) cones in the fovea, and (B) cones in the periphery. Note the size difference (scale bar = 10 micrometers), and that, as the separation between cones grows, the red receptors are in the periphery. (C) Cone density plotted as a function of distance from the center of the fovea for cones in human retina; cone density decreases with distance from the fovea. Source: Curcio et al., 1990.

CSE 152, Spring 2017

Introduction to Computer Vision

Color receptors



“Red” cone

“Green” cone

“Blue” cone

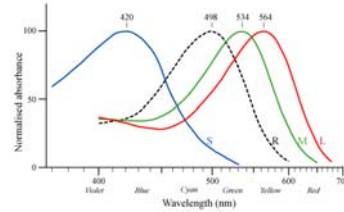
$$\text{Response of } k\text{th cone} = \int \rho_k(\lambda)E(\lambda)d\lambda$$

CSE 152, Spring 2017

Introduction to Computer Vision

Three types of cones: R,G,B

$$\text{Response of } k\text{th cone} = \int \rho_k(\lambda)E(\lambda)d\lambda$$



There are three types of cones

S: Short wave lengths (Blue)

M: Mid wave lengths (Green)

L: Long wave lengths (Red)



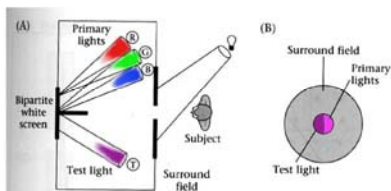
• Three attributes to a color

• Three numbers to describe a color

CSE 152, Spring 2017

Introduction to Computer Vision

Color matching experiment



4.10 THE COLOR-MATCHING EXPERIMENT. The observer views a bipartite field and adjusts the intensities of the three primary lights to match the appearance of the test light. (A) A top view of the experimental apparatus. (B) The appearance of the stimuli to the observer. After Judd and Wyszecki, 1975.

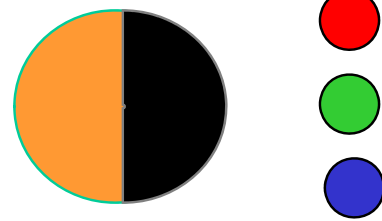
Foundations of Vision, by Brian Wandell, Sinauer Assoc., 1995

Not on a computer Screen

CSE 152, Spring 2017

Inside from T. Darrel

Color Matching

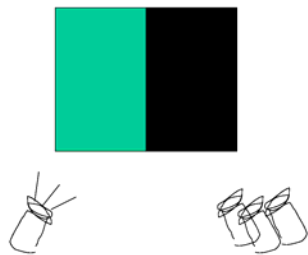


Not on a computer Screen

CSE 152, Spring 2017

Introduction to Computer Vision

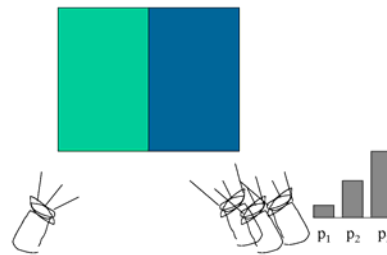
Color matching experiment 1



CSE 152, Spring 2017

Inside from T. Darrel

Color matching experiment 1



CSE 152, Spring 2017

Inside from T. Darrel

Color matching experiment 1

A diagram showing a cyan color on the left and its match on the right. The match is composed of three primary colors: P1 (a small amount), P2 (a medium amount), and P3 (a large amount). Below the colors are illustrations of test color and primary color containers.

CSE 152, Spring 2017 inside.from.T.Darrel

Color matching experiment 1

The same diagram as above, but with a blue arrow pointing to the primary color amounts. The annotation reads: "The primary color amounts needed for a match".

CSE 152, Spring 2017 inside.from.T.Darrel

Color matching experiment 2

A diagram showing a black color on the left and its match on the right. The match is composed of three primary colors: P1 (a small amount), P2 (a very small amount), and P3 (a small amount). Below the colors are illustrations of test color and primary color containers.

CSE 152, Spring 2017 inside.from.T.Darrel

Color matching experiment 2

A diagram showing a magenta color on the left and its match on the right. The match is composed of three primary colors: P1 (a large amount), P2 (a very small amount), and P3 (a small amount). Below the colors are illustrations of test color and primary color containers.

CSE 152, Spring 2017 inside.from.T.Darrel

Color matching experiment 2

A diagram showing a red color on the left and its match on the right. The match is composed of three primary colors: P1 (a large amount), P2 (a very small amount), and P3 (a small amount). Below the colors are illustrations of test color and primary color containers.

CSE 152, Spring 2017 inside.from.T.Darrel

Color matching experiment 2

The same diagram as above, but with two blue annotations. The first annotation on the left says: "We say a 'negative' amount of p_2 was needed to make the match, because we added it to the test color's side." The second annotation on the right says: "The primary color amounts needed for a match:". Below the match, the primary color amounts are shown as P1 (large), P2 (small, with a minus sign), and P3 (small).

CSE 152, Spring 2017 inside.from.T.Darrel

The principle of trichromacy

- Experimental facts:
 - Three primaries will work for most people if we allow subtractive matching
 - Exceptional people can match with two or only one primary.
 - This could be caused by a variety of deficiencies.
 - Most people make the same matches.
 - There are some anomalous trichromats, who use three primaries but make different combinations to match.

CSE 152, Spring 2017

Introduction to Computer Vision

Color matching functions

- Choose primaries, say $P_1(\lambda)$, $P_2(\lambda)$, $P_3(\lambda)$
- For monochromatic (single wavelength) energy function, what amounts of primaries will match it?
- i.e., For each wavelength λ , determine how much of A, of B, and of C is needed to match light of that wavelength alone.

$$a(\lambda)$$

$$b(\lambda)$$

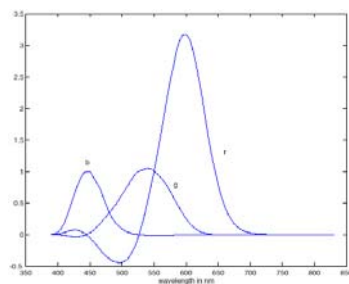
$$c(\lambda)$$

- These are color matching functions

CSE 152, Spring 2017

Introduction to Computer Vision

RGB

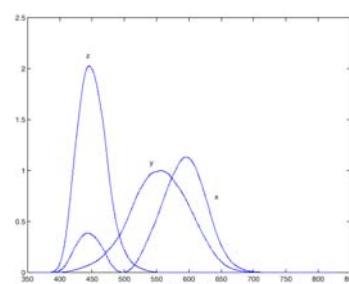


RGB: primaries are monochromatic, energies are 645.2nm, 526.3nm, 444.4nm. Color matching functions have negative parts -> some colors can be matched only subtractively.

CSE 152, Spring 2017

Introduction to Computer Vision

CIEXYZ



CIEXYZ: Color matching functions are positive everywhere, but primaries are imaginary (i.e., not visible colors).

CSE 152, Spring 2017

Introduction to Computer Vision

Color spaces

- Linear color spaces describe colors as linear combinations of primaries
- Choice of primaries = choice of color matching functions = choice of color space
- Color matching functions, hence color descriptions, are all within linear transformations
- RGB: primaries are monochromatic, energies are 645.2nm, 526.3nm, 444.4nm. Color matching functions have negative parts -> some colors can be matched only subtractively
- CIE XYZ: Color matching functions are positive everywhere, but primaries are imaginary (i.e., not visible colors).

CSE 152, Spring 2017

Introduction to Computer Vision

Color Spaces

There are many different color spaces, with each describing a color using three numbers:

- | | |
|-----------|---------------|
| 1. RGB | 6. YIQ (NTSC) |
| 2. XYZ | 7. YUV (PAL) |
| 3. CIEXyz | 8. YCbCr |
| 4. LMS | 9. SUV |
| 5. CMY | |

In general a color represented in one color space (say XYZ) can be converted and represented in a second color space (say RGB)

CSE 152, Spring 2017

Introduction to Computer Vision

Example: RGB to YIQ

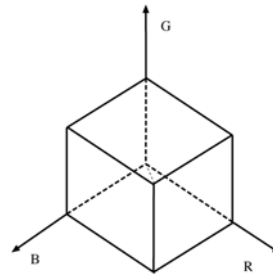
$$\begin{bmatrix} Y \\ I \\ Q \end{bmatrix} = \begin{bmatrix} 0.299 & 0.587 & 0.114 \\ 0.596 & -0.275 & -0.321 \\ 0.212 & -0.532 & 0.311 \end{bmatrix} \begin{bmatrix} R \\ G \\ B \end{bmatrix}$$

- Used by NTSC TV standard
- Separates Hue & Saturation (I,Q) from Luminance (Y)

CSE 152, Spring 2017

Introduction to Computer Vision

RGB Color Cube



- Block of colors for (r, g, b) in the range (0-1).
- Convenient to have an upper bound on coefficient of each primary.
- In practice:
 - primaries given by monitor phosphors (phosphors are the materials on the face of the monitor screen that glow when struck by electrons)

CSE 152, Spring 2017

Introduction to Computer Vision

CIELAB

- Also referred to as CIE L*a*b*
- Designed to approximate human vision
 - Nonlinear response
- Includes 100% of visible colors
- L is lightness
- A and B are color-opponent dimensions
- Nonlinear conversion to/from CIE XYZ colorspace
- Human perceptual difference between two colors is the Euclidean distance between the two 3D points in CIELAB space

CSE 152, Spring 2017

Introduction to Computer Vision

XYZ Color Space

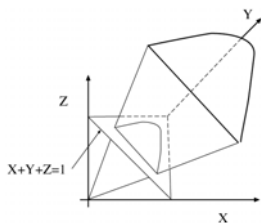
- Encompasses all color sensations the average person can experience
- Standard reference
 - Many other color space definitions are based on XYZ
- Y is luminance
- Z is quasi-equal to blue stimulation
- X is a linear combination of cone response curves chosen to be nonnegative
- The plane parallel to the XZ plane and that Y lies on contains all possible chromaticities at that luminance

$$\begin{aligned} x &= \frac{X}{X+Y+Z} & X &= \frac{y}{x} \\ y &= \frac{Y}{X+Y+Z} & Z &= \frac{y}{x}(1-x-y) \\ z &= \frac{Z}{X+Y+Z} = 1-x-y \end{aligned}$$

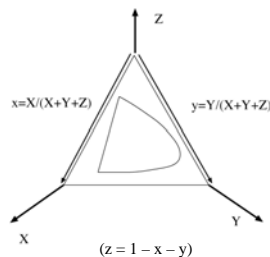
CSE 152, Spring 2017

Introduction to Computer Vision

CIE XYZ and CIE xy



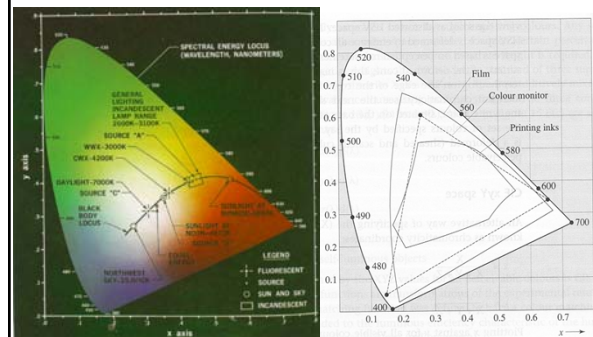
Usually draw x, y, where
 $x = X/(X+Y+Z)$ and
 $y = Y/(X+Y+Z)$



CSE 152, Spring 2017

Introduction to Computer Vision

CIE xyY (Chromaticity Space)

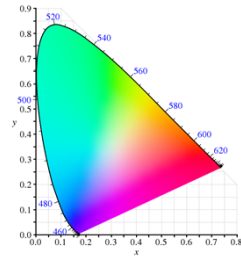


CSE 152, Spring 2017

Introduction to Computer Vision

Color Specification: Chromaticity

- Chromaticity coordinates
 - (x, y, z) where $x + y + z = 1$
 - Usually specified by (x, y) where $z = 1 - x - y$



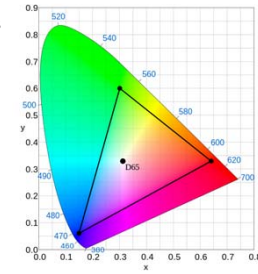
The CIE 1931 color space chromaticity diagram

CSE 152, Spring 2017

Introduction to Computer Vision

Chromaticities

- Set of chromaticities
 - Red
 - Green
 - Blue
 - White (point)



CSE 152, Spring 2017

Introduction to Computer Vision

Standard Illuminants

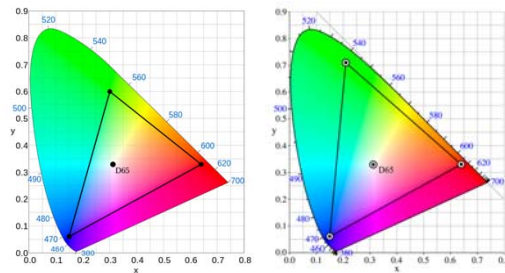
Name	CIE 1931 Z ⁺		CIE 1964 2° ⁺		CCT (K)	Hue	Note
	x ₂	y ₂	x ₁₀	y ₁₀			
A	0.44787	0.40735	0.45117	0.40594	2856	Orange	Incandescent / Tungsten
B	0.34842	0.35161	0.34990	0.35270	4874	Blue	[obsolete] Direct sunlight at noon
C	0.31006	0.31616	0.31039	0.31905	6774	Blue	[obsolete] Average / North sky Daylight
D50	0.34567	0.35850	0.34773	0.35952	5003	Blue	Horizon Light, ICC profile PCS
D55	0.33242	0.34743	0.33411	0.34877	5503	Blue	Mid-morning / Mid-afternoon Daylight
D65	0.31271	0.32902	0.31382	0.33100	6504	Blue	Noon Daylight, Television, sRGB color space
D75	0.29902	0.31485	0.29968	0.31740	7504	Blue	North sky Daylight
E	1/3	1/3	1/3	1/3	5454	White	Equal energy
F1	0.31310	0.33727	0.31811	0.33559	6430	Blue	Daylight Fluorescent
F2	0.37208	0.37529	0.37925	0.36738	4230	Blue	Cool White Fluorescent
F3	0.40910	0.39430	0.41761	0.38324	3450	Blue	White Fluorescent
F4	0.44018	0.40329	0.44920	0.39074	2940	Blue	Warm White Fluorescent
F5	0.31379	0.34531	0.31975	0.34246	6350	Blue	Daylight Fluorescent
F6	0.37790	0.38835	0.38660	0.37847	4150	Blue	Lite White Fluorescent
F7	0.31292	0.32933	0.31569	0.32960	6500	Blue	D50 simulator, Daylight simulator
F8	0.34588	0.35875	0.34902	0.35939	5000	Blue	D50 simulator, Sylvania F40 Design 50
F9	0.37417	0.37281	0.37829	0.37045	4150	Blue	Cool White Deluxe Fluorescent
F10	0.34609	0.35986	0.35090	0.35444	5000	Blue	Philips TL85, Ultralume 50
F11	0.38052	0.37713	0.38541	0.37123	4000	Blue	Philips TL84, Ultralume 40
F12	0.43695	0.40441	0.44256	0.39717	3000	Blue	Philips TL83, Ultralume 30

Hue of each white point, calculated with luminance $Y = 0.54$

CSE 152, Spring 2017

Introduction to Computer Vision

Chromaticity Diagrams



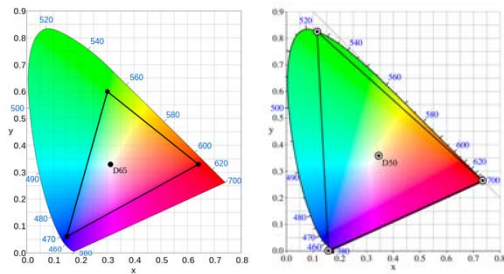
Rec. 709 and sRGB
35.9% of visible colors

Adobe RGB
52.1% of visible colors

CSE 152, Spring 2017

Introduction to Computer Vision

Chromaticity Diagrams



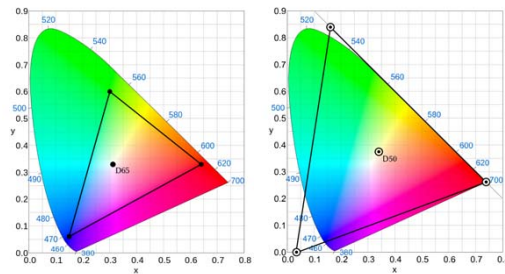
Rec. 709 and sRGB
35.9% of visible colors

Wide gamut RGB
77.6% of visible colors

CSE 152, Spring 2017

Introduction to Computer Vision

Chromaticity Diagrams



Rec. 709 and sRGB
35.9% of visible colors

ProPhoto RGB
90% of visible colors

CSE 152, Spring 2017

Introduction to Computer Vision

Academy Color Encoding Specification (ACES)

Color	CIE x	CIE y	CIE z
Red	0.73470	0.26530	0.00000
Green	0.00000	1.00000	0.00000
Blue	0.00010	-0.07700	1.07690
White	0.32168	0.33767	0.34065

Approximately D60

CIE 2 Degree Chromaticity Diagram

100% of visible colors

CSE 152, Spring 2017 Introduction to Computer Vision

Incorrect Image Conversion

Same pixel values stored in files,
but with different sets of chromaticities

CSE 152, Spring 2017 Introduction to Computer Vision

Chromatic Adaptation

- Estimating the appearance of a sample under a different illuminant
 - Convert between different white points
- LMS color space
 - Response of the three types of cones in the human eye
 - Long, medium, and short wavelengths
- XYZ to LMS
 - Bradford transformation matrix
- Chromatic adaptation
 - Adaptation matrix

$$\begin{bmatrix} L \\ M \\ S \end{bmatrix} = \begin{bmatrix} 0.8951 & 0.2664 & -0.1614 \\ -0.7502 & 1.7135 & 0.0367 \\ 0.0389 & -0.0685 & 1.0296 \end{bmatrix} \begin{bmatrix} X \\ Y \\ Z \end{bmatrix}$$

$$D = D_1^{-1} D_2 = \begin{bmatrix} L_2/L_1 & 0 & 0 \\ 0 & M_2/M_1 & 0 \\ 0 & 0 & S_2/S_1 \end{bmatrix}$$

CSE 152, Spring 2017 Introduction to Computer Vision

Application: Color Transfer

- RGB to XYZ with white point of standard illuminant E (use chromatic adaptation)
- XYZ to Lab
- Map source pixels such that the $L^*a^*b^*$ mean and standard deviations match those of the target image

CSE 152, Spring 2017 Introduction to Computer Vision

Nonlinear Encoding

- All of these standards use nonlinear encoding (gamma encoding)
 - Video
 - Recommendation ITU-R BT.601 (standard-definition television (SDTV))
 - SMPTE standard 240M (precursor to Rec. 709)
 - Recommendation ITU-R BT.709 (high-definition television (HDTV))
 - Image
 - sRGB
 - Adobe RGB
 - Wide gamut RGB (or Adobe Wide Gamut RGB)
 - ProPhoto RGB (or reference output medium metric (ROMM) RGB)
- Must convert to linear colorspace first for most color processing

CSE 152, Spring 2017 Introduction to Computer Vision

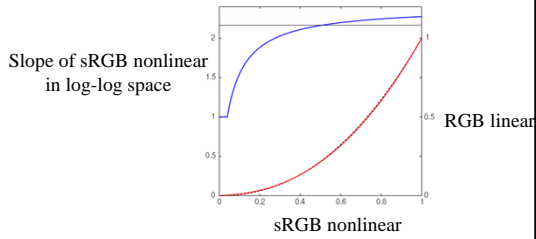
Nonlinear Encoding and Conversion to Linear

- Typical CRT monitors have a transfer function of $\gamma = 2.2$
- Image and video standards were designed to be directly displayed on CRTs
 - Pixel values are encoded to approximate $\gamma = 2.2$
- Nonlinear to linear (floating-point) using a lookup table
- Linear to nonlinear calculation

CSE 152, Spring 2017 Introduction to Computer Vision

Nonlinear R'G'B' Color Space and Linear RGB Color Space

- Example: sRGB



CSE 152, Spring 2017

Introduction to Computer Vision

Luminance Y and Luma Y'

- Luminance is calculated from linear RGB
 - Y coordinate of XYZ
- Luma is calculated from nonlinear R'G'B'
- Luminance is different than Luma
- Example: sRGB

$$Y = 0.21263903 * R + 0.71516871 * G + 0.072192319 * B$$

$$Y' = 0.21263903 * R' + 0.71516871 * G' + 0.072192319 * B'$$

CSE 152, Spring 2017

Introduction to Computer Vision

Next Lecture

- Human visual system
- Reading:
 - Section 1.1.4: The Human Eye

CSE 152, Spring 2017

Introduction to Computer Vision