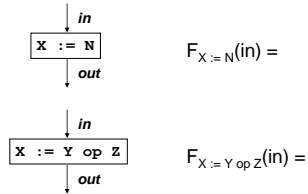


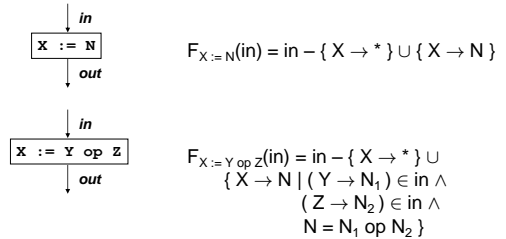
### Another example: constant prop

- Set  $D =$

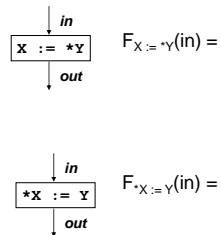


### Another example: constant prop

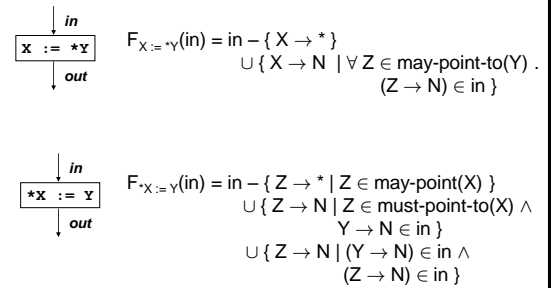
- Set  $D = 2 \{x \rightarrow N \mid x \in \text{Vars} \wedge N \in Z\}$



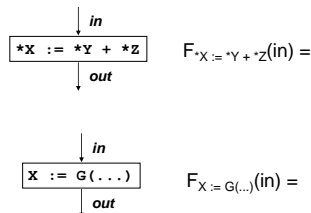
### Another example: constant prop



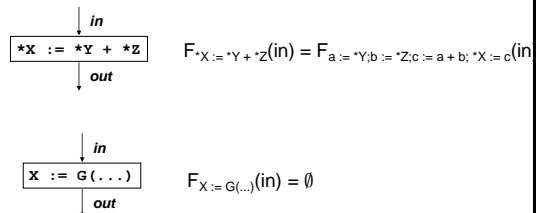
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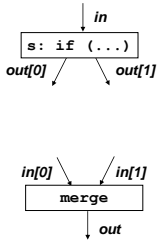
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## Another example: constant prop



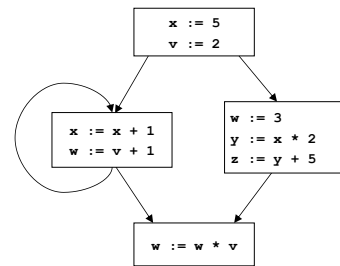
## Lattice

- $(D, \sqsubseteq, \perp, \top, \sqcup, \sqcap) =$

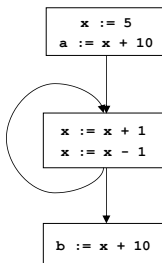
## Lattice

- $(D, \sqsubseteq, \perp, \top, \sqcup, \sqcap) =$   
 $(2^A, \supseteq, A, \emptyset, \cap, \cup)$   
where  $A = \{x \rightarrow N \mid x \in \text{Vars} \wedge N \in \mathbb{Z}\}$

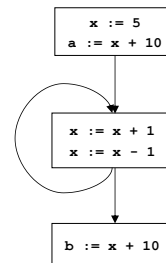
## Example



## Another Example



## Another Example starting at top



## Back to lattice

- $(D, \sqsubseteq, \perp, \top, \sqcup, \sqcap) =$   
 $(2^A, \supseteq, A, \emptyset, \cap, \cup)$   
 where  $A = \{x \rightarrow N \mid x \in \text{Vars} \wedge N \in \mathbb{Z}\}$
- What's the problem with this lattice?

## Back to lattice

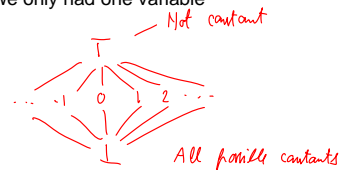
- $(D, \sqsubseteq, \perp, \top, \sqcup, \sqcap) =$   
 $(2^A, \supseteq, A, \emptyset, \cap, \cup)$   
 where  $A = \{x \rightarrow N \mid x \in \text{Vars} \wedge N \in \mathbb{Z}\}$
- What's the problem with this lattice?
- Lattice is infinitely high, which means we can't guarantee termination

## Better lattice

- Suppose we only had one variable

## Better lattice

- Suppose we only had one variable



- $D = \{\perp, \top\} \cup \mathbb{Z}$
- $\forall i \in \mathbb{Z}. \perp \sqsubseteq i \wedge i \sqsubseteq \top$
- height = 3

## For all variables

- Two possibilities
- Option 1: Tuple of lattices
- Given lattices  $(D_1, \sqsubseteq_1, \perp_1, \top_1, \sqcup_1, \sqcap_1) \dots (D_n, \sqsubseteq_n, \perp_n, \top_n, \sqcup_n, \sqcap_n)$  create:

tuple lattice  $D^n =$

## For all variables

- Two possibilities
- Option 1: Tuple of lattices
- Given lattices  $(D_1, \sqsubseteq_1, \perp_1, \top_1, \sqcup_1, \sqcap_1) \dots (D_n, \sqsubseteq_n, \perp_n, \top_n, \sqcup_n, \sqcap_n)$  create:

tuple lattice  $D^n = ((D_1 \times \dots \times D_n), \sqsubseteq, \perp, \top, \sqcup, \sqcap)$  where  
 $\perp = (\perp_1, \dots, \perp_n)$   
 $\top = (\top_1, \dots, \top_n)$   
 $(a_1, \dots, a_n) \sqcup (b_1, \dots, b_n) = (a_1 \sqcup_1 b_1, \dots, a_n \sqcup_n b_n)$   
 $(a_1, \dots, a_n) \sqcap (b_1, \dots, b_n) = (a_1 \sqcap_1 b_1, \dots, a_n \sqcap_n b_n)$   
 height = height( $D_1$ ) + ... + height( $D_n$ )

## For all variables

- Option 2: Map from variables to single lattice
- Given lattice  $(D, \sqsubseteq, \perp, \top, \sqcup, \sqcap)$  and a set  $V$ , create:

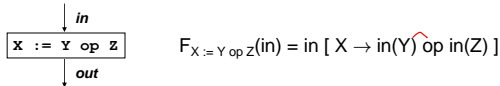
map lattice  $V \rightarrow D = (V \rightarrow D, \sqsubseteq, \perp, \top, \sqcup, \sqcap)$

$$\perp = \lambda v \rightarrow \perp_1$$

## Back to example



## Back to example



where  $a \hat{op} b =$

$$\begin{array}{cccc} \hat{op} & \perp & d_1 & \top \\ \perp & \perp & \perp & \top \\ d_2 & \perp & d_1 d_2 & \top \\ \top & \top & \top & \top \end{array}$$

## General approach to domain design

- Simple lattices:
  - boolean logic lattice
  - powerset lattice
  - incomparable set: set of incomparable values, plus top and bottom (eg const prop lattice)
  - two point lattice: just top and bottom
- Use combinators to create more complicated lattices
  - tuple lattice constructor
  - map lattice constructor

## May vs Must

- Has to do with definition of computed info
- Set of  $x \rightarrow y$  must-point-to pairs
  - if we compute  $x \rightarrow y$ , then, then during program execution,  $x$  must point to  $y$
- Set of  $x \rightarrow y$  may-point-to pairs
  - if during program execution, it is possible for  $x$  to point to  $y$ , then we must compute  $x \rightarrow y$

## May vs must

	May	Must
most optimistic (bottom)		
most conservative (top)		
safe		
merge		

## May vs must

	May	Must
most optimistic (bottom)	empty set	full set
most conservative (top)	full set	empty set
safe	overly big	overly small
merge	$\cup$	$\cap$

## Common Sub-expression Elim

- Want to compute when an expression is available in a var
- Domain:

## Common Sub-expression Elim

- Want to compute when an expression is available in a var
- Domain:

$$S = \{X \rightarrow E \mid X \in \text{Var}, E \in E_{\text{op}}\}$$

$$\begin{aligned} \emptyset &= Z^S \\ f &= S \\ T &= \emptyset \\ U &= \Lambda \end{aligned}$$

## Flow functions

$$\begin{array}{c} \downarrow \text{in} \\ \boxed{X := Y \text{ op } Z} \\ \downarrow \text{out} \end{array} \quad F_{X := Y \text{ op } Z}(\text{in}) =$$

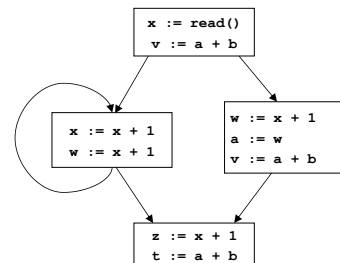
$$\begin{array}{c} \downarrow \text{in} \\ \boxed{X := Y} \\ \downarrow \text{out} \end{array} \quad F_{X := Y}(\text{in}) =$$

## Flow functions

$$\begin{array}{c} \downarrow \text{in} \\ \boxed{X := Y \text{ op } Z} \\ \downarrow \text{out} \end{array} \quad F_{X := Y \text{ op } Z}(\text{in}) = \text{in} - \{X \rightarrow *\} \\ \quad \quad \quad - \{ * \rightarrow \dots X \dots \} \cup \\ \quad \quad \quad \{X \rightarrow Y \text{ op } Z \mid X \neq Y \wedge X \neq Z\}$$

$$\begin{array}{c} \downarrow \text{in} \\ \boxed{X := Y} \\ \downarrow \text{out} \end{array} \quad F_{X := Y}(\text{in}) = \text{in} - \{X \rightarrow *\} \\ \quad \quad \quad - \{ * \rightarrow \dots X \dots \} \cup \\ \quad \quad \quad \{X \rightarrow E \mid Y \rightarrow E \in \text{in}\}$$

## Example



## Direction of analysis

- Although constraints are not directional, flow functions are
- All flow functions we have seen so far are in the forward direction
- In some cases, the constraints are of the form  $in = F(out)$
- These are called backward problems.
- Example: live variables
  - compute the set of variables that may be live

## Live Variables

- A variable is live at a program point if it will be used before being redefined
- A variable is dead at a program point if it is redefined before being used

## Example: live variables

- Set  $D =$
- Lattice:  $(D, \sqsubseteq, \perp, \top, \sqcup, \sqcap) =$

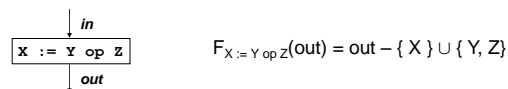
## Example: live variables

- Set  $D = 2^{Vars}$
- Lattice:  $(D, \sqsubseteq, \perp, \top, \sqcup, \sqcap) = (2^{Vars}, \subseteq, \emptyset, Vars, \cup, \cap)$

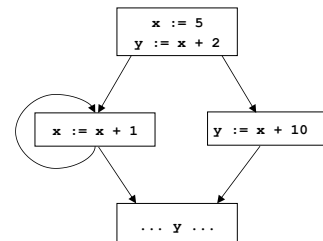


## Example: live variables

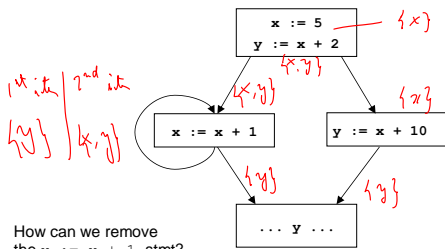
- Set  $D = 2^{Vars}$
- Lattice:  $(D, \sqsubseteq, \perp, \top, \sqcup, \sqcap) = (2^{Vars}, \subseteq, \emptyset, Vars, \cup, \cap)$



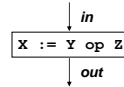
## Example: live variables



## Example: live variables

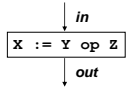


## Revisiting assignment



$$F_{X := Y \text{ op } Z}(\text{out}) = \text{out} - \{X\} \cup \{Y, Z\}$$

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$$F_{X := Y \text{ op } Z}(\text{out}) = \text{out} - \{X\} \cup \{Y, Z\}$$

$$\text{out} - \{x\} \cup$$

$$x \notin \text{out? } \emptyset : \{y, z\}$$

## Theory of backward analyses

- Can formalize backward analyses in two ways
- Option 1: reverse flow graph, and then run forward problem
- Option 2: re-develop the theory, but in the backward direction

## Precision

- Going back to constant prop, in what cases would we lose precision?

## Precision

- Going back to constant prop, in what cases would we lose precision?

```

x := 5
if (<expr>) {
  x := 6
}
... x ...

where <expr> is
equiv to false

if (p) {
  x := 5;
} else {
  x := 4;
}
...
if (p) {
  y := x + 1
} else {
  y := x + 2
}
... y ...

if (...) {
  x := -1;
} else {
  x := 1;
}
... y := x * x;
... Y ...

```

## Precision

- The first problem: Unreachable code
  - solution: run unreachable code removal before
  - the unreachable code removal analysis will do its best, but may not remove all unreachable code
- The other two problems are path-sensitivity issues
  - Branch correlations: some paths are infeasible
  - Path merging: can lead to loss of precision

## MOP: meet over all paths

- Information computed at a given point is the meet of the information computed by each path to the program point

```

if (...) {
  x := -1;
} else
  x := 1;
}
y := x * x;
... y ...
    
```

## MOP

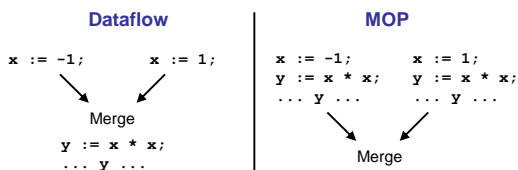
- For a path  $p$ , which is a sequence of statements  $[s_1, \dots, s_n]$ , define:  $F_p(\text{in}) = F_{s_n}(\dots F_{s_1}(\text{in}) \dots)$
- In other words:  $F_p = F_{s_1} \circ \dots \circ F_{s_n}$
- Given an edge  $e$ , let  $\text{paths-to}(e)$  be the (possibly infinite) set of paths that lead to  $e$
- Given an edge  $e$ ,  $\text{MOP}(e) = \bigsqcup_{p \in \text{paths-to}(e)} F_p(\perp)$
- For us, should be called JOP (ie: join, not meet)

## MOP vs. dataflow

- MOP is the “best” possible answer, given a fixed set of flow functions
  - This means that  $\text{MOP} \sqsubseteq \text{dataflow}$  at edge in the CFG
- In general, MOP is not computable (because there can be infinitely many paths)
  - vs dataflow which is generally computable (if flow fns are monotonic and height of lattice is finite)
- And we saw in our example, in general,  $\text{MOP} \neq \text{dataflow}$

## MOP vs. dataflow

- However, it would be great if by imposing some restrictions on the flow functions, we could guarantee that dataflow is the same as MOP. What would this restriction be?



## MOP vs. dataflow

- However, it would be great if by imposing some restrictions on the flow functions, we could guarantee that dataflow is the same as MOP. What would this restriction be?
- Distributive problems. A problem is distributive if:
  - $\forall a, b. F(a \sqcup b) = F(a) \sqcup F(b)$
- If flow function is distributive, then  $\text{MOP} = \text{dataflow}$



## Summary of precision

---

- Dataflow is the basic algorithm
- To basic dataflow, we can add path-separation
  - Get MOP, which is same as dataflow for distributive problems
  - Variety of research efforts to get closer to MOP for non-distributive problems
- To basic dataflow, we can add path-pruning
  - Get branch correlation
- To basic dataflow, can add both:
  - meet over all feasible paths