

CSE 120

Principles of Operating Systems

Fall 2024

Lecture 4: Threads

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Processes

- Recall that a process includes many things
 - ◆ An address space (defining all the code and data pages)
 - ◆ OS resources (e.g., open files) and accounting information
 - ◆ Execution state (PC, SP, regs, etc.)
- **Creating a new process is costly** because of the data structures that must be allocated and initialized
 - ◆ Recall `struct proc` in Solaris
- **Communicating between processes is also costly** because most communication goes through the OS
 - ◆ Overhead of system calls and copying data

Concurrent Programs

- Recall our Web server example that forks off copies of itself to handle multiple simultaneous requests
 - ◆ Or any parallel program that executes on a multiprocessor
- To execute these programs we need to
 - ◆ Create several processes that execute in parallel
 - ◆ Cause each to map to the same address space to share data
 - » They are all part of the same computation
 - ◆ Schedule these processes in parallel (logically or physically)
- This situation is **very inefficient**
 - ◆ **Space**: PCB, page tables, etc.
 - ◆ **Time**: create data structures, fork and copy addr space, etc.

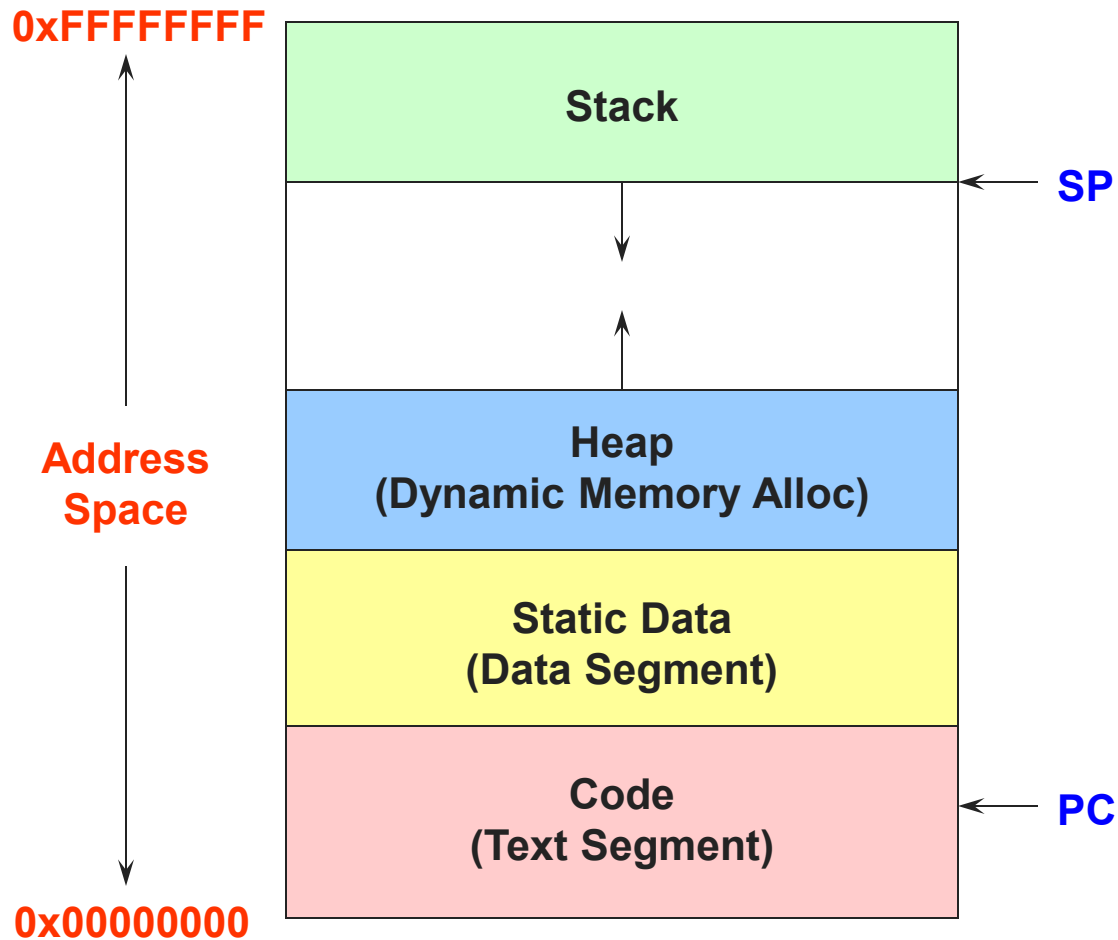
Rethinking Processes

- What is similar in these cooperating processes?
 - ◆ They all share the same code and data (address space)
 - ◆ They all share the same privileges (user ID)
 - ◆ They all share the same resources (files, sockets, etc.)
- What don't they share?
 - ◆ Each has its own execution state: PC, SP, and registers
- **Key idea:** Why don't we separate the concept of a process from its execution state?
 - ◆ **Process:** address space, privileges, resources, etc.
 - ◆ **Execution state:** PC, SP, registers
- Exec state also called **thread of control**, or **thread**

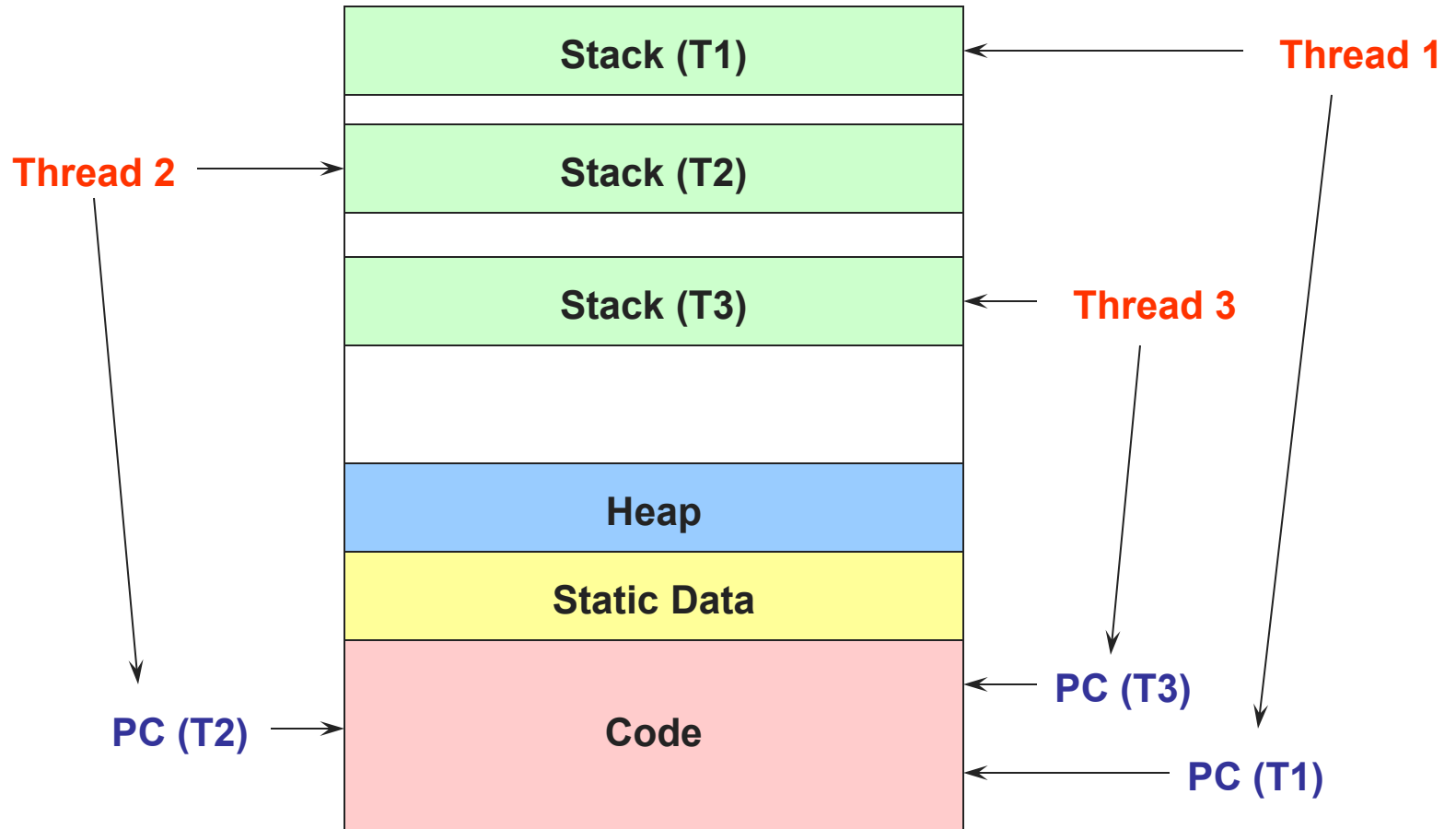
Threads

- Modern OSes (Windows, Unix, OS X) separate the concepts of processes and threads
 - ◆ The **thread** defines a sequential execution stream within a process (PC, SP, registers)
 - ◆ The **process** defines the address space and general process attributes (everything but threads of execution)
- A thread is bound to a single process
 - ◆ Processes, however, can have multiple threads
- Threads become the basic unit of scheduling
 - ◆ Processes are now the **containers** in which threads execute
 - ◆ Processes become static, threads are the dynamic entities

Basic Process Address Space



Threads in a Process



Process/Thread Separation

- Separating threads and processes makes it easier to support multithreaded applications
 - ◆ Concurrency does not require creating new processes
- Concurrency (multithreading) can be very useful
 - ◆ Improving program structure
 - ◆ Handling concurrent events (e.g., Web requests)
 - ◆ Writing parallel programs
- So multithreading is even useful on a uniprocessor
 - ◆ Although today even cell phones are multicore

Process: Concurrent Servers

- Using `fork()` to create new processes to handle requests in parallel is often overkill
- Recall our forking Web server:

```
while (1) {  
    int sock = accept();  
    if ((child_pid = fork()) == 0) {  
        Handle client request  
        Close socket and exit  
    } else {  
        Close socket  
    }  
}
```

Threads: Concurrent Servers

Instead, we can create a new thread for each request:

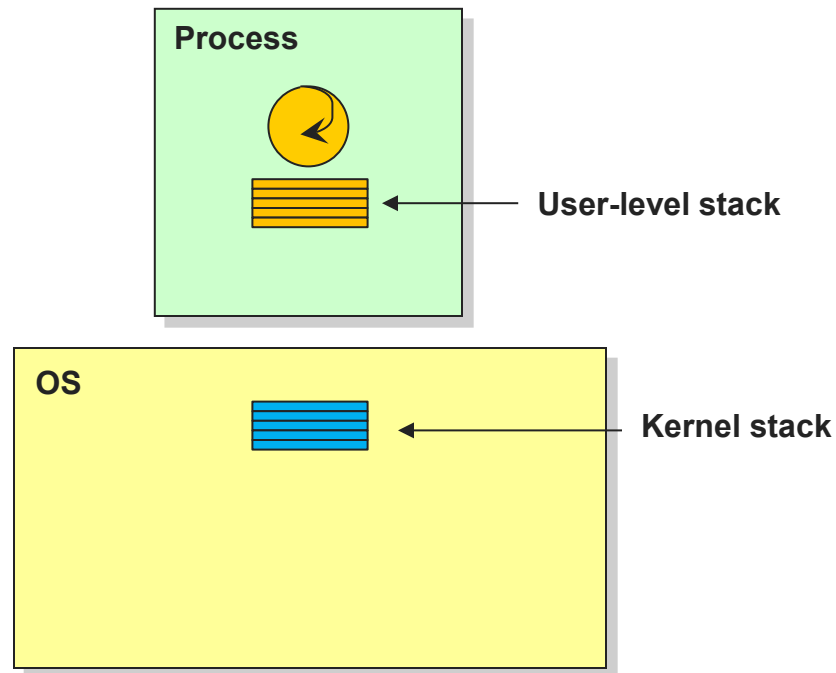
```
web_server() {  
    while (1) {  
        int sock = accept();  
        thread_fork(handle_request, sock);  
    }  
}
```

```
handle_request(int sock) {  
    Process request  
    close(sock);  
}
```

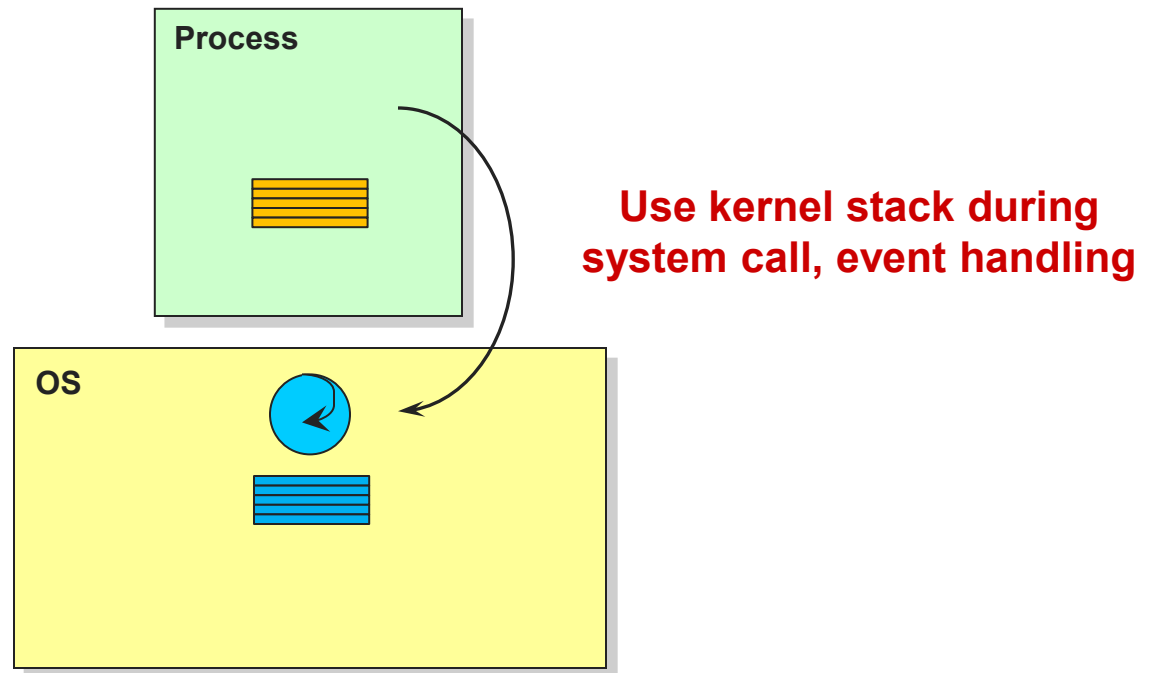
Kernel-Level Threads

- We have taken the execution aspect of a process and separated it out into threads
 - ◆ To make concurrency cheaper
- As such, the OS now manages threads *and* processes
 - ◆ All thread operations are implemented in the kernel
 - ◆ OS schedules the threads it implements
- OS-managed threads are called **kernel-level threads** or **lightweight processes**
 - ◆ Linux (pthreads), Windows (threads), Solaris (lightweight processes (LWPs)), ...

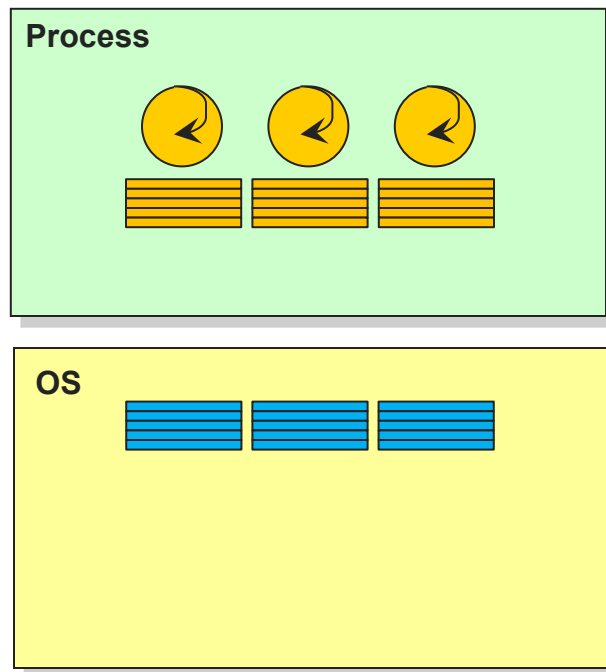
User and Kernel Stacks



System Calls / Events



Kernel Threads



- Multiple kernel threads (OS manages, schedules)
- Physical parallelism (run on multiple cores)
- Multiple, separate system calls / events

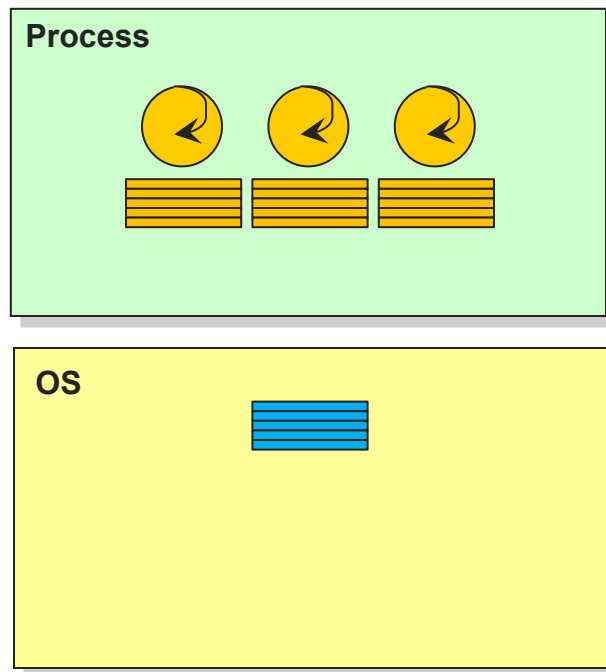
Kernel Thread Limitations

- Kernel-level threads make concurrency much cheaper than processes
 - ◆ Much less state to allocate and initialize
- However, for fine-grained concurrency, kernel-level threads still suffer from overhead
 - ◆ Thread operations still require system calls
 - » Ideally, want thread operations to be **as fast as a procedure call**
 - ◆ Kernel-level threads have to be general to support the needs of all programmers, languages, runtimes, etc.
- For such fine-grained concurrency, need even “cheaper” threads

User-Level Threads

- To make threads cheap and fast, they need to be implemented at user level
 - ◆ **Kernel-level threads** are managed by the OS
 - ◆ **User-level threads** are managed entirely by the run-time system (user-level library)
- User-level threads are small and fast
 - ◆ A thread is simply represented by a PC, registers, stack, and small thread control block (TCB)
 - ◆ Creating a new thread, switching between threads, and synchronizing threads are done via **procedure call**
 - » User-level thread operations **100x faster** than kernel threads
 - ◆ Early JVMs (Thread), Go (goroutines)

User Threads



- Multiple user threads (app manages, schedules)
- Multiplexed on one “kernel” thread (no OS support needed)
- Only one system call / event at a time, no physical parallelism

U/L Thread Limitations

- But, user-level threads are not a perfect solution
 - ◆ As with everything else, they are a tradeoff
- User-level threads are **invisible** to the OS
 - ◆ They are not well integrated with the OS
- As a result, the OS can make poor decisions
 - ◆ Scheduling a process with idle threads
 - ◆ Blocking a process whose thread initiated an I/O, even though the process has other threads that can execute
 - ◆ Unscheduling a process with a thread holding a lock

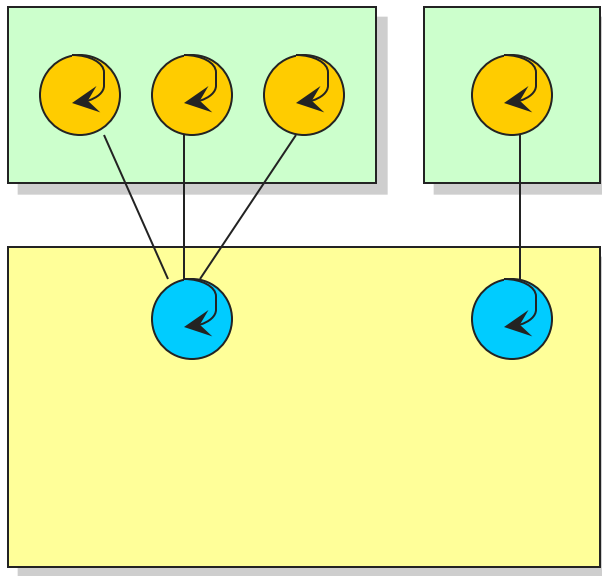
Kernel vs. User Threads

- Kernel-level threads
 - ◆ Integrated with OS (informed scheduling)
 - ◆ Slower to create, manipulate, synchronize
- User-level threads
 - ◆ Faster to create, manipulate, synchronize
 - ◆ Not integrated with OS (uninformed scheduling)

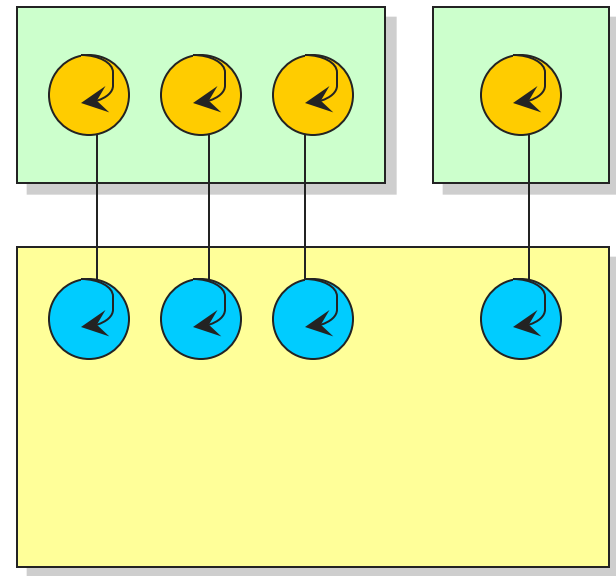
Kernel and User Threads

- Or use **both** kernel and user-level threads
 - ◆ Can associate a user-level thread with a kernel-level thread
 - ◆ Or, multiplex user-level threads on top of kernel-level threads
- Java Virtual Machine (JVM) (also C#, others)
 - ◆ On older Unix, only one “kernel thread” per process
 - » Multiplex all Java threads on this one kernel thread (M:1)
 - ◆ On modern OSes
 - » Each Java thread uses a separate kernel thread (1:1)
 - » Can have more Java threads than kernel threads (M:N)

User and Kernel Threads



**Multiplexing user-level threads
on a single kernel thread for
each process**



**Multiplexing user-level threads
on multiple kernel threads for
each process**

Implementing Threads

- Implementing threads has several aspects
 - ◆ Interface
 - ◆ Context switch
 - ◆ Preemptive vs. non-preemptive scheduling
 - ◆ Synchronization (next lecture)

Nachos Thread API

- **KThread.fork**
 - ◆ Run a new thread (also “create” in other thread packages)
- **KThread.sleep**
 - ◆ Block the calling thread (also “stop”, “suspend”)
- **KThread.ready**
 - ◆ Start the given thread (also “start”, “resume”)
- **KThread.yield**
 - ◆ Voluntarily give up the processor
- **KThread.join**
 - ◆ Block until another thread finishes (Project 1)
- **KThread.finish**
 - ◆ Terminate the calling thread (also “exit”, “destroy”)

Thread Scheduling

- The thread scheduler determines when a thread runs
- It uses queues to keep track of what threads are doing
- Run queue: Threads currently running
 - ♦ Just one with Nachos
- Ready queue: Threads ready to run
- Wait queues: Threads blocked (asleep) waiting
 - ♦ Synchronization, Alarm

Non-Preemptive Scheduling

- Threads voluntarily give up the CPU with yield

Ping Thread

```
while (1) {  
    printf("ping\n");  
    yield();  
}
```

Pong Thread

```
while (1) {  
    printf("pong\n");  
    yield();  
}
```

- What is the output of running these two threads?

yield

- Wait a second. How does `yield()` work?
- The semantics of `yield` are that it gives up the CPU to another thread
 - ◆ In other words, it **context switches** to another thread
- So what does it mean for `yield` to return?
 - ◆ It means that *another thread* called `yield`!
- Execution trace of ping/pong
 - ◆ `printf("ping\n");`
 - ◆ `yield();`
 - ◆ `printf("pong\n");`
 - ◆ `yield();`
 - ◆ ...

Implementing yield

```
yield() {  
    thread_t old_thread = current_thread;  
    current_thread = get_next_thread();  
    append_to_queue(ready_queue, old_thread);  
    context_switch(old_thread, current_thread);  
    return;  
}
```

As old thread

As new thread

- The magic step is invoking `context_switch()`
- Why do we need to call `append_to_queue()`?

Thread Context Switch

- The context switch routine does all of the magic
 - ◆ Saves context of the currently running thread (`old_thread`)
 - » Push all machine state onto its stack
 - ◆ Restores context of the next thread
 - » Pop all machine state from the next thread's stack
 - ◆ The next thread becomes the current thread
 - ◆ Return to caller as new thread
- This is all done in assembly language
 - ◆ It works at the level of the procedure calling convention, so it cannot be implemented using procedure calls

Example Implementation

```
#
# a0 -- old stack_pointer_t*
# a1 -- new stack_pointer_t*
#
LEAF(minithread_switch)
    subu    sp, MACHINE_STATE_SIZE
    sw      s0, S0(sp)
    sw      s1, S1(sp)
    sw      s2, S2(sp)
    sw      s3, S3(sp)
    sw      s4, S4(sp)
    sw      s5, S5(sp)
    sw      s6, S6(sp)
    sw      s7, S7(sp)
    sw      fp, FP(sp)
    sw      ra, PC(sp)          # save return address
    sw      sp, 0(a0)          # save new stack pointer

    lw      sp, 0(a1)          # t0 contains new sp
    lw      s0, S0(sp)
    lw      s1, S1(sp)
    lw      s2, S2(sp)
    lw      s3, S3(sp)
    lw      s4, S4(sp)
    lw      s5, S5(sp)
    lw      s6, S6(sp)
    lw      s7, S7(sp)
    lw      fp, FP(sp)
    lw      ra, PC(sp)          # save return address
    addu    sp, MACHINE_STATE_SIZE
    j       ra
END(minithread_switch)
```

Preemptive Scheduling

- Non-preemptive threads must voluntarily give up CPU
 - ◆ A long-running thread will take over the machine
 - ◆ Only voluntary calls to yield, sleep, or finish cause a context switch
- **Preemptive scheduling** uses **involuntary** context switches
 - ◆ Need to regain control of processor asynchronously
 - ◆ Use timer interrupt
 - ◆ Timer interrupt handler forces current thread to “call” yield
 - » See `Alarm.timerInterrupt` in Nachos

Threads Summary

- The operating system as a large multithreaded program
 - ◆ Each process executes as a thread within the OS
- Multithreading is also very useful for applications
 - ◆ Efficient multithreading requires fast primitives
 - ◆ Processes are too heavyweight
- Solution is to separate threads from processes
 - ◆ Kernel-level threads much better, but still significant overhead
 - ◆ User-level threads even better, but not well integrated with OS
- Now, how do we get our threads to correctly cooperate with each other?
 - ◆ Synchronization...

Next time...

- Read Chapters 28, 29
- Start reading through Project 1