Lecture 8: Scheduling and Deadlock
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• Friday
  ♦ Project #1 due at 11:59pm

• Saturday
  ♦ Homework #2 due at 9pm

• Wednesday
  ♦ Q&A review session

• Thursday
  ♦ Midterm
Scheduling Overview

• In discussing process management and synchronization, we talked about context switching among processes/threads on the ready queue
• But we have glossed over the details of exactly which thread is chosen from the ready queue
• Making this decision is called scheduling
• In this lecture, we’ll look at:
  ♦ Goals of scheduling
  ♦ Various well-known scheduling algorithms
  ♦ Standard Unix scheduling algorithm
  ♦ Deadlock
Multiprogramming

- In a multiprogramming system, we try to increase CPU utilization and job throughput by overlapping I/O and CPU activities
  - Doing this requires a combination of mechanisms and policy
- We have covered the **mechanisms**
  - Context switching, how and when it happens
  - Process queues and process states
- Now we’ll look at the **policies**
  - Which process (thread) to run, for how long, etc.
- We’ll refer to schedulable entities as **jobs** (standard usage) – could be processes, threads, people, etc.
Scheduling Goals

• Scheduling works at two levels in an operating system
  ♦ To determine the multiprogramming level, the number of jobs loaded into memory
    » Moving jobs to/from memory is called swapping
  ♦ To decide what job to run next to guarantee “good service”
    » Good service could be one of many different criteria

• These decisions are known as long-term and short-term scheduling decisions, respectively
  ♦ Long-term scheduling happens relatively infrequently
    » Significant overhead in swapping a process out to disk
  ♦ Short-term scheduling happens relatively frequently
    » Want to minimize the overhead of scheduling
      ▪ Fast context switches, fast queue manipulation
Scheduling

• The scheduler (aka dispatcher) is the module that manipulates the queues, moving jobs to and fro
• The scheduling algorithm determines which jobs are chosen to run next and what queues they wait on
• In general, the scheduler runs:
  ♦ When a job switches from running to waiting
  ♦ When an interrupt occurs (e.g., I/O completes)
  ♦ When a job is created or terminated
• We’ll discuss scheduling algorithms in two contexts
  ♦ In preemptive systems the scheduler can interrupt a running job (involuntary context switch)
  ♦ In non-preemptive systems, the scheduler waits for a running job to explicitly block (voluntary context switch)
Scheduling Metrics

- Scheduling algorithms can have many different goals:
  - CPU utilization ($%CPU$)
  - Job throughput (# jobs/time)
  - Turnaround time ($T_{finish} - T_{start}$)
  - Waiting time ($\text{Avg}(T_{wait})$: avg time spent on wait queues)
  - Response time ($\text{Avg}(T_{ready})$: avg time spent on ready queue)

- Batch systems
  - Strive for job throughput, turnaround time (supercomputers)

- Interactive systems
  - Strive to minimize response time for interactive jobs (PC)
Starvation

Starvation is a scheduling “non-goal”:

• **Starvation** is a situation where a process is prevented from making progress because some other process has the resource it requires
  ♦ Resource could be the CPU, or a lock (recall readers/writers)

• **Starvation usually a side effect of the sched. algorithm**
  ♦ A high priority process always prevents a low priority process from running on the CPU
  ♦ One thread always beats another when acquiring a lock

• **Starvation can be a side effect of synchronization**
  ♦ Constant supply of readers always blocks out writers
First-come first-served (FCFS), first-in first-out (FIFO)
- Jobs are scheduled in order of arrival to ready Q
- "Real-world" scheduling of people in lines (e.g., supermarket)
- Typically non-preemptive (no context switching at market)
- Jobs treated equally, no starvation

Problem
- Average waiting time can be large if small jobs wait behind long ones (high turnaround time)
  » You have a basket, but you’re stuck behind someone with a cart
Shortest Job First (SJF)

- Shortest Job First (SJF)
  - Choose the job with the smallest expected CPU burst
    » Person with smallest number of items to buy
  - Provably optimal minimum average waiting time (AWT)

\[
\text{AWT} = \frac{8 + (8+4)+(8+4+2)}{3} = 11.33
\]

\[
\text{AWT} = \frac{4 + (4+8)+(4+8+2)}{3} = 10
\]

\[
\text{AWT} = \frac{4+ (4+2)+(4+2+8)}{3} = 8
\]

\[
\text{AWT} = \frac{2 + (2+4)+(2+4+8)}{3} = 7.33
\]
Shortest Job First (SJF)

- **Problems**
  - Impossible to know size of CPU burst
    - Like choosing person in line without looking inside basket/cart
  - How can you make a reasonable guess?
  - Can potentially starve

- **Flavors**
  - Can be either preemptive or non-preemptive
  - Preemptive SJF is called shortest remaining time first (SRTF)
Priority Scheduling

• Priority Scheduling
  ♦ Choose next job based on priority
    » Airline boarding for first class passengers
  ♦ Can implement SJF, priority = 1/(expected CPU burst)
  ♦ Also can be either preemptive or non-preemptive

• Problem
  ♦ Starvation – low priority jobs can wait indefinitely

• Solution
  ♦ “Age” processes
    » Increase priority as a function of waiting time
    » Decrease priority as a function of CPU consumption
Round Robin (RR)

- Round Robin
  - Excellent for timesharing
  - Ready queue is treated as a circular queue (FIFO)
  - Each job is given a time slice called a quantum
  - A job executes for the duration of the quantum, or until it blocks or is interrupted
  - No starvation

- Problem
  - Context switches are frequent and need to be very fast
Combining Algorithms

- Scheduling algorithms can be combined
  - Have multiple queues
  - Use a different algorithm for each queue
  - Move processes among queues

- Example: Multiple-level feedback queues (MLFQ)
  - Multiple queues representing different job types
    » Interactive, CPU-bound, batch, system, etc.
  - Queues have priorities, jobs on same queue scheduled RR
  - Jobs can move among queues based upon execution history
    » Feedback: Switch from interactive to CPU-bound behavior
Unix Scheduler

• The canonical Unix scheduler uses a MLFQ
  ♦ 3-4 classes spanning ~170 priority levels
    » Timesharing: first 60 priorities
    » System: next 40 priorities
    » Real-time: next 60 priorities
    » Interrupt: next 10 (Solaris)

• Priority scheduling across queues, RR within a queue
  ♦ The process with the highest priority always runs
  ♦ Processes with the same priority are scheduled RR

• Processes dynamically change priority
  ♦ Increases over time if process blocks before end of quantum
  ♦ Decreases over time if process uses entire quantum
Motivation of Unix Scheduler

- The idea behind the Unix scheduler is to reward interactive processes over CPU hogs.
- Interactive processes (shell, editor, etc.) typically run using short CPU bursts.
  - They do not finish quantum before waiting for more input.
- Want to minimize response time.
  - Time from keystroke (putting process on ready queue) to executing keystroke handler (process running).
  - Don’t want editor to wait until CPU hog finishes quantum.
- This policy delays execution of CPU-bound jobs.
  - But that’s ok.
Scheduling Overhead

• Operating systems aim to minimize overhead
  ♦ Context switching takes non-zero time, so it is pure overhead
  ♦ Overhead includes context switch + choosing next process

• Modern time-sharing OSes (Unix, Windows, …) time-slice processes in ready list
  ♦ A process runs for its quantum, OS context switches to another, next process runs, etc.
  ♦ A CPU-bound process will use its entire quantum (e.g., 10ms)
  ♦ An IO-bound process will use part (e.g., 1ms), then issue IO
  ♦ The IO-bound process goes on a wait queue, the OS switches to the next process to run, the IO-bound process goes back on the ready list when the IO completes
Utilization

• CPU utilization is the fraction of time the system is doing useful work (e.g., not context switching)

• If the system has
  ♦ Quantum of 10ms + context-switch overhead of 0.1ms
  ♦ 3 CPU-bound processes + round-robin scheduling

• In steady-state, time is spent as follows:
  ♦ 10ms + 0.1ms + 10ms + 0.1ms + 10ms + 0.1ms
  ♦ CPU utilization = time doing useful work / total time
  ♦ CPU utilization = (3*10ms) / (3*10ms + 3*0.1ms) = 30/30.3

• If one process is IO-bound, it will not use full quantum
  ♦ 10ms + 0.1ms + 10ms + 0.1ms + 1ms + 0.1ms
  ♦ CPU util = (2*10 + 1) / (2*10 + 1 + 3*0.1) = 21/21.3
Scheduling Summary

- Scheduler (dispatcher) is the module that gets invoked when a context switch needs to happen
- Scheduling algorithm determines which process runs, where processes are placed on queues
- Many potential goals of scheduling algorithms
  - Utilization, throughput, wait time, response time, etc.
- Various algorithms to meet these goals
  - FCFS/FIFO, SJF, Priority, RR
- Can combine algorithms
  - Multiple-level feedback queues
  - Unix example
Deadlock

- Synchronization is a live gun – we can easily shoot ourselves in the foot
  - Incorrect use of synchronization can block all processes
  - You have likely been intuitively avoiding this situation already
- More generally, processes that allocate multiple resources generate dependencies on those resources
  - Locks, semaphores, monitors, etc., just represent the resources that they protect
- If one process tries to allocate a resource that a second process holds, and vice-versa, they can never make progress
- We call this situation **deadlock**, and we’ll look at:
  - Definition and conditions necessary for deadlock
  - Representation of deadlock conditions
  - Approaches to dealing with deadlock
Deadlock Definition

- Deadlock is a problem that can arise:
  - When processes compete for access to limited resources
  - When processes are incorrectly synchronized

- Definition:
  - Deadlock exists among a set of processes if every process is waiting for an event that can be caused only by another process in the set.

```java
Process 1
lockA.acquire();
...
lockB.acquire();

Process 2
lockB.acquire();
...
lockA.acquire();
```
Deadlock with Join

Thread A

...  B.join();  ...

Thread B

...  A.join();  ...

Thread A  Thread B
Conditions for Deadlock

• Deadlock can exist if and only if the following four conditions hold simultaneously:
  1. Mutual exclusion – At least one resource must be held in a non-sharable mode
  2. Hold and wait – There must be one process holding one resource and waiting for another resource
  3. No preemption – Resources cannot be preempted (critical sections cannot be aborted externally)
  4. Circular wait – There must exist a set of processes \([P_1, P_2, P_3, \ldots, P_n]\) such that \(P_1\) is waiting for \(P_2\), \(P_2\) for \(P_3\), etc.
Resource Allocation Graph

- Deadlock can be described using a resource allocation graph (RAG)
- The RAG consists of a set of vertices \( P = \{P_1, P_2, \ldots, P_n\} \) of processes and \( R = \{R_1, R_2, \ldots, R_m\} \) of resources
  - A directed edge from a process to a resource, \( P_i \rightarrow R_j \), means that \( P_i \) has requested \( R_j \)
  - A directed edge from a resource to a process, \( R_i \rightarrow P_i \), means that \( R_j \) has been allocated by \( P_i \)
  - Each resource has a fixed number of units

- If the graph has no cycles, deadlock cannot exist
- If the graph has a cycle, deadlock may exist
RAG Example

A cycle...and deadlock!

Same cycle...but no deadlock. Why?
A Simpler Case

- If all resources are single unit and all processes make single requests, then we can represent the resource state with a simpler waits-for graph (WFG)
  - Useful for tracking locks
- The WFG consists of a set of vertices \( P = \{P_1, P_2, \ldots, P_n\} \) of processes
  - A directed edge \( P_i \rightarrow P_j \) means that \( P_i \) has requested a resource that \( P_j \) currently holds
- If the graph has no cycles, deadlock cannot exist
- If the graph has a cycle, deadlock exists
Dealing With Deadlock

- There are four approaches for dealing with deadlock:
  - Ignore it – how lucky do you feel?
  - Prevention – make it impossible for deadlock to happen
  - Avoidance – control allocation of resources
  - Detection and Recovery – look for a cycle in dependencies
Deadlock Prevention

- Prevention – Ensure that at least one of the necessary conditions cannot happen
  - Mutual exclusion
    - Make resources sharable (not generally practical)
  - Hold and wait
    - Process cannot hold one resource when requesting another
    - Process requests, releases all needed resources at once
  - Preemption
    - OS can preempt resource (costly)
  - Circular wait
    - Impose an ordering (numbering) on the resources and request them in order
    - Popular OS implementation technique when using multiple locks
Deadlock Avoidance

• Avoidance
  ♦ Provide information in advance about what resources will be needed by processes to guarantee that deadlock will not happen
  ♦ System only grants resource requests if it knows that the process can obtain all resources it needs in future requests
  ♦ Avoids circularities (wait dependencies)

• Tough
  ♦ Hard to determine all resources needed in advance
  ♦ Good theoretical problem, not as practical to use
Detection and Recovery

• Detection and recovery
  ♦ If we don’t have deadlock prevention or avoidance, then deadlock may occur
  ♦ In this case, we need to detect deadlock and recover from it

• To do this, we need two algorithms
  ♦ One to determine whether a deadlock has occurred
  ♦ Another to recover from the deadlock

• Possible, but expensive (time consuming)
  ♦ Implemented in VMS
  ♦ Run detection algorithm when resource request times out
Deadlock Detection

- Detection
  - Traverse the resource graph looking for cycles
  - If a cycle is found, preempt resource (force a process to release)
- Expensive
  - Many processes and resources to traverse
- Only invoke detection algorithm depending on
  - How often or likely deadlock is
  - How many processes are likely to be affected when it occurs
Deadlock Recovery

Once a deadlock is detected, we have two options…

1. Abort processes
   - Abort all deadlocked processes
     » Processes need to start over again
   - Abort one process at a time until cycle is eliminated
     » System needs to rerun detection after each abort

2. Preempt resources (force their release)
   - Need to select process and resource to preempt
   - Need to rollback process to previous state
   - Need to prevent starvation
Deadlock Summary

• Deadlock occurs when processes are waiting on each other and cannot make progress
  ♦ Cycles in Resource Allocation Graph (RAG)

• Deadlock requires four conditions
  ♦ Mutual exclusion, hold and wait, no resource preemption, circular wait

• Four approaches to dealing with deadlock:
  ♦ Ignore it – Living life on the edge
  ♦ Prevention – Make one of the four conditions impossible
  ♦ Avoidance – Banker’s Algorithm (control allocation)
  ♦ Detection and Recovery – Look for a cycle, preempt or abort