

Matrix-Based Transforms and The Wavelet Transform

Image Processing

CSE 166

Lecture 13

Reading

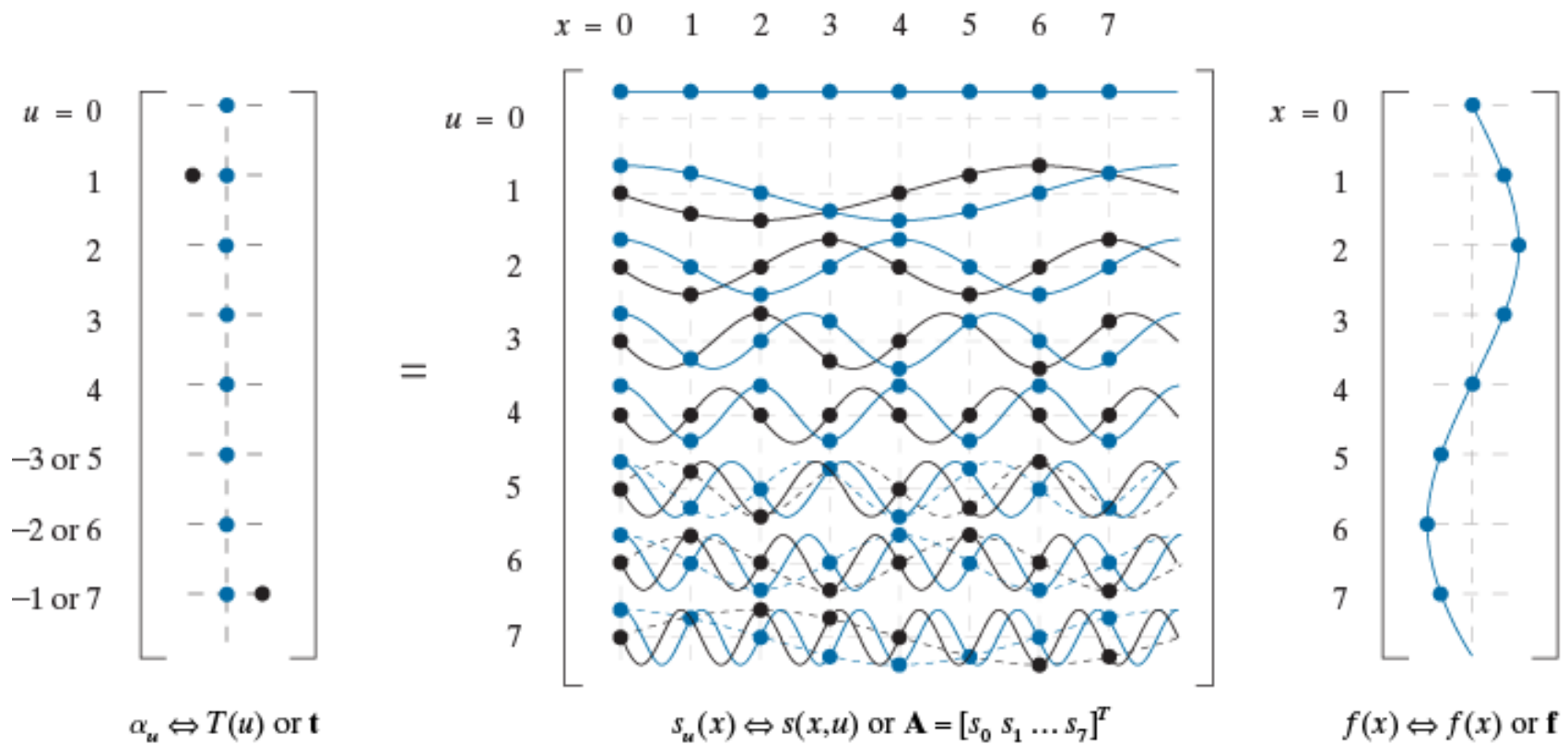
- Digital Image Processing, 4th edition
 - Chapter 6: Wavelet and Other Image Transforms
 - Sections 6.2—6.10

Matrix-based transforms

- Discrete Fourier transform (DFT)
- Discrete Hartley transform (DHT)
- Discrete cosine transform (DCT)
- Discrete sine transform (DST)
- Walsh-Hadamard (WHT)
- Slant (SLT)
- Haar (HAAR)
- Daubechies (DB4)
- Biorthogonal B-spline (BIOR3.1)

Basis vectors of matrix-based 1D transforms

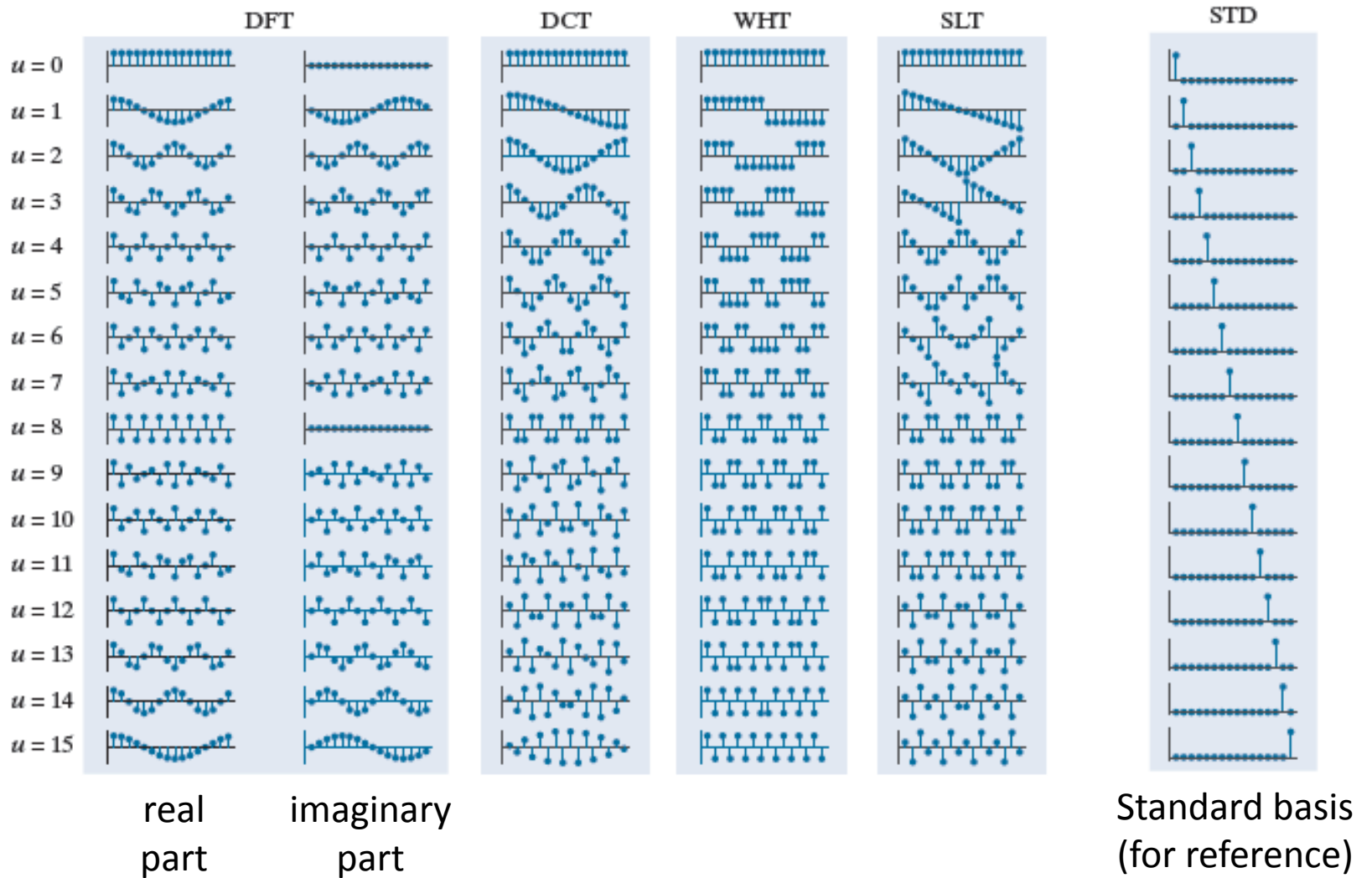
Example: DFT of $f(x) = \sin(2\pi x)$, $N = 8$



real part + imaginary part

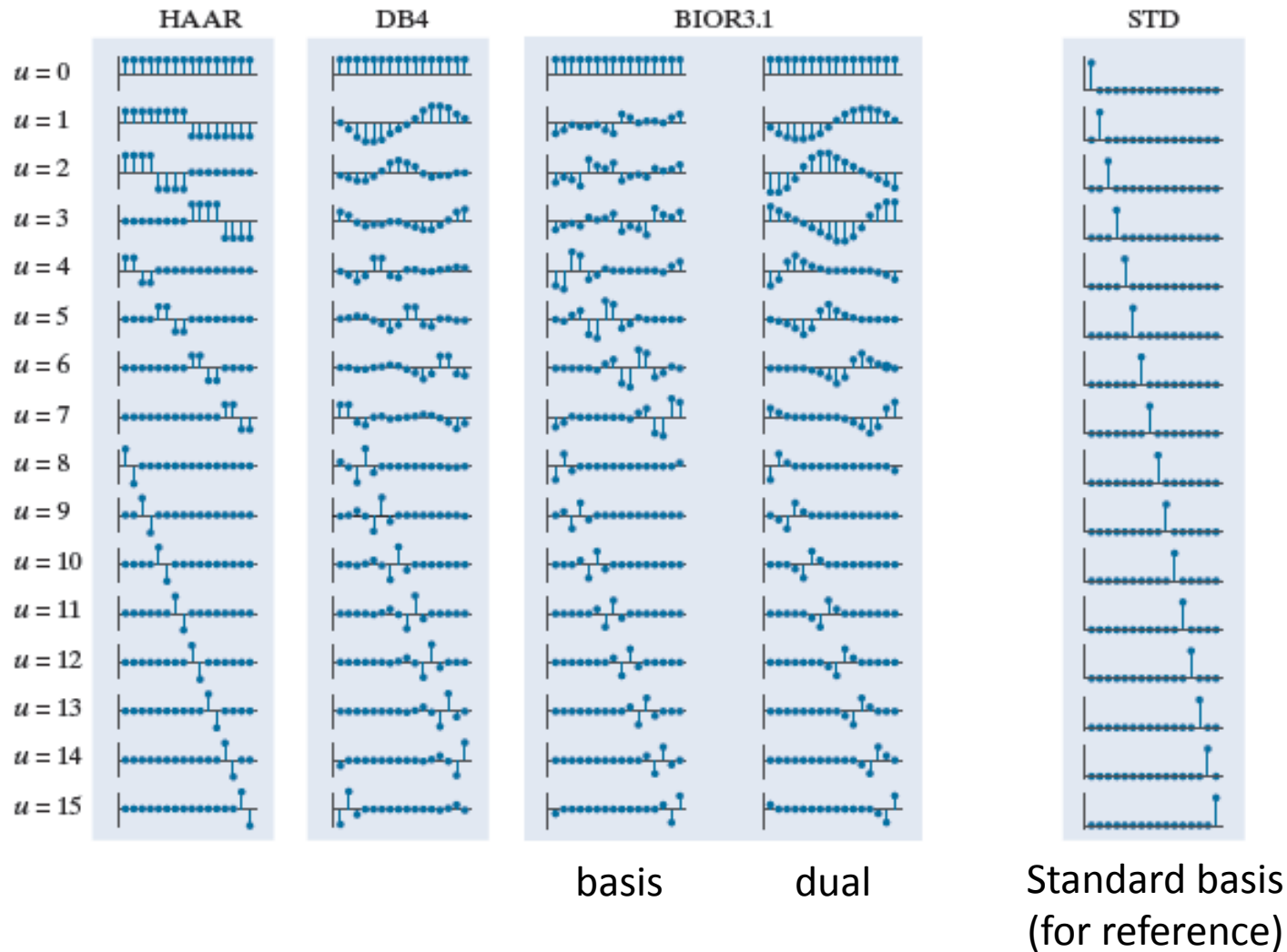
Basis vectors of matrix-based 1D transforms

$N = 16$



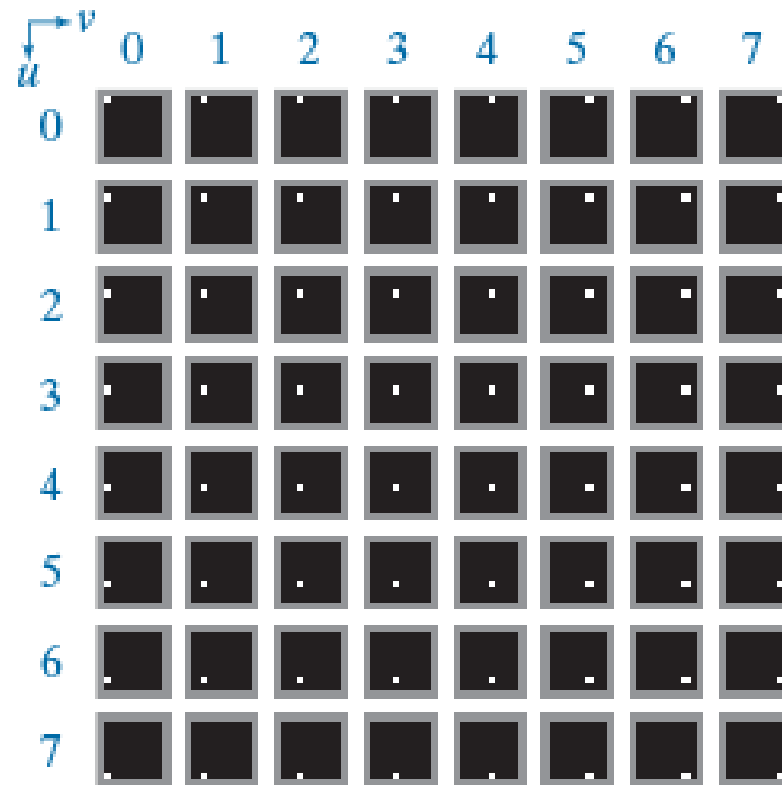
Basis vectors of matrix-based 1D transforms

$N = 16$



Basis images of matrix-based 2D transforms

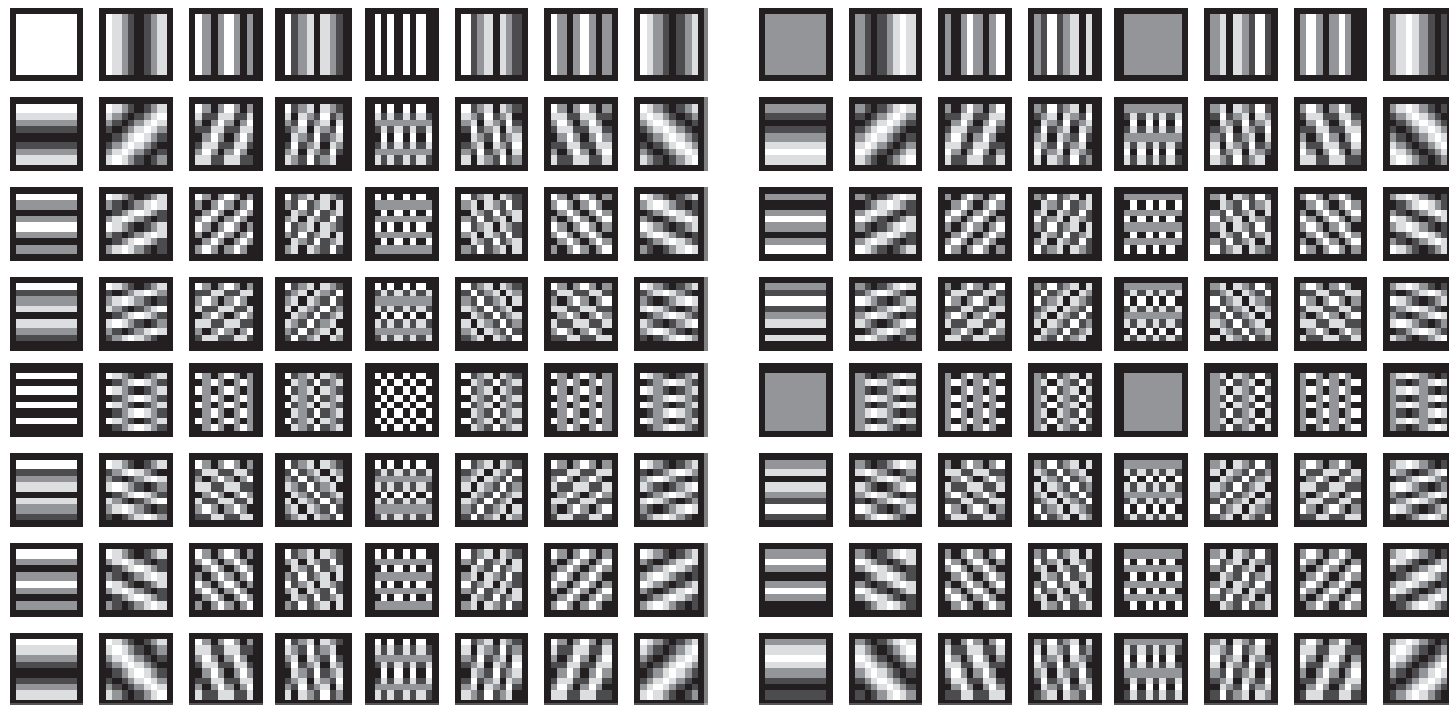
Standard basis images (for reference)



8-by-8
array of
8-by-8
basis images

Basis images of matrix-based 2D transforms

Discrete Fourier transform (DFT) basis images

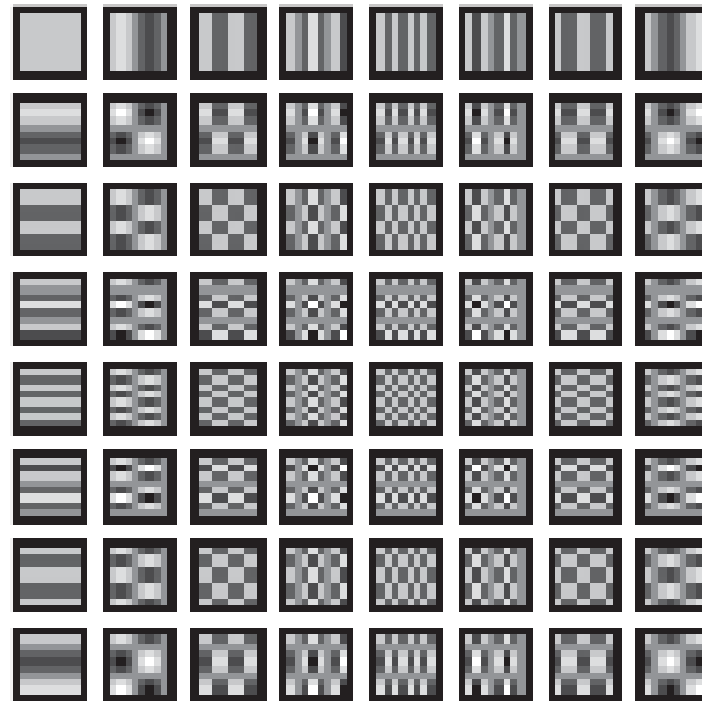


real part

imaginary part

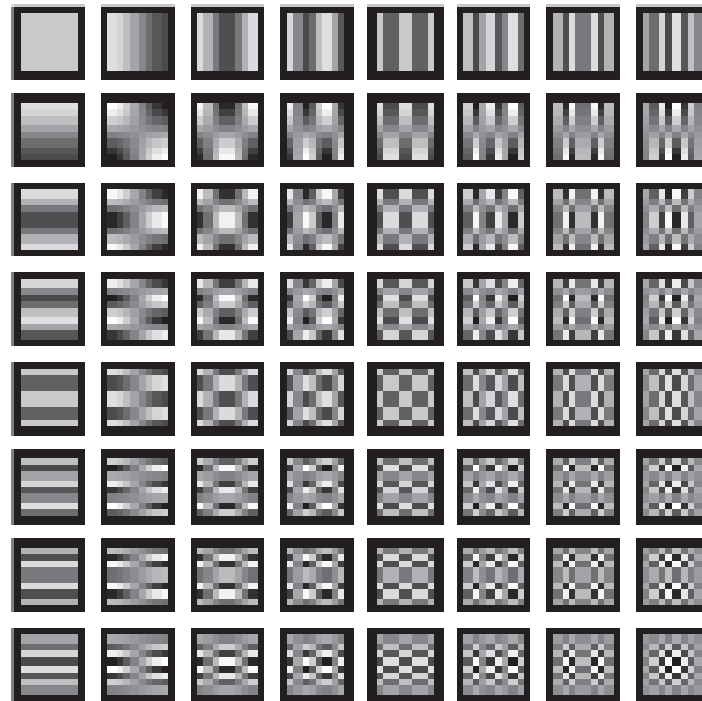
Basis images of matrix-based 2D transforms

Discrete Hartley transform (DHT) basis images



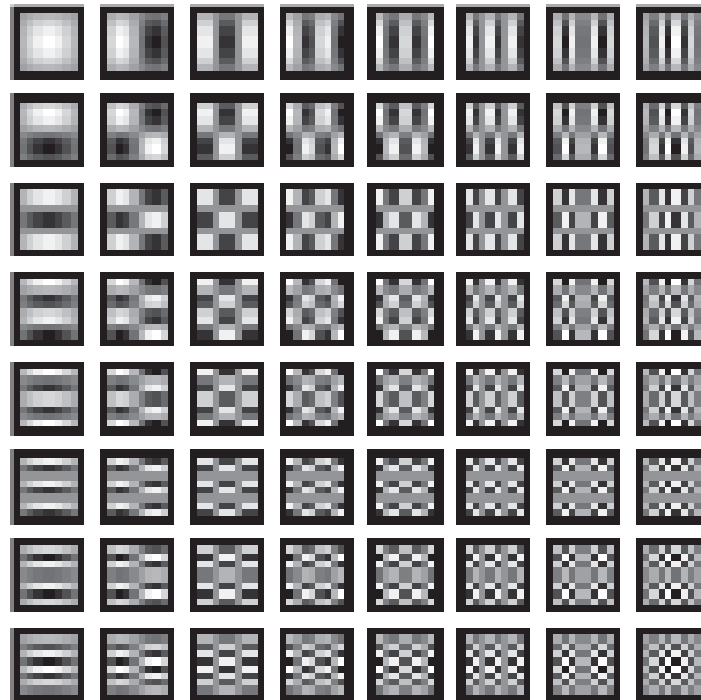
Basis images of matrix-based 2D transforms

Discrete cosine transform (DCT) basis images



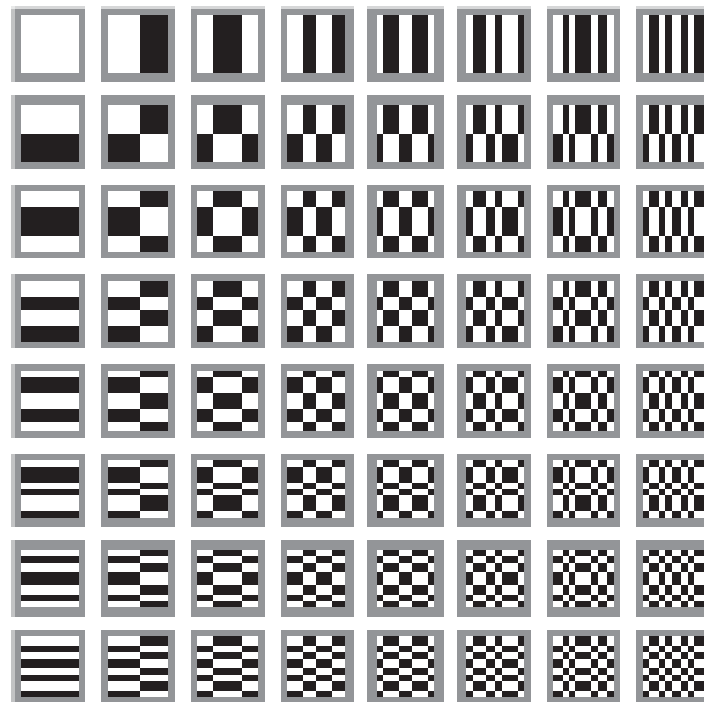
Basis images of matrix-based 2D transforms

Discrete sine transform (DST) basis images



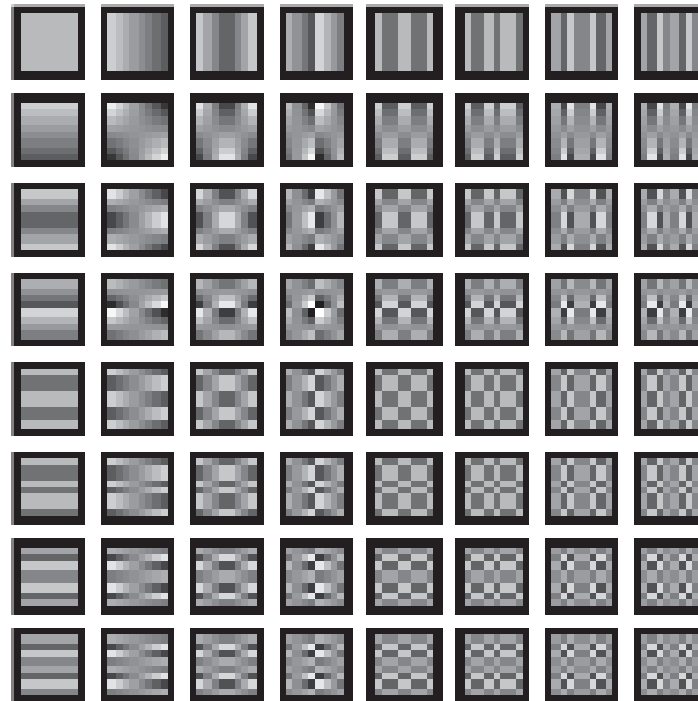
Basis images of matrix-based 2D transforms

Walsh-Hadamard transform (WHT) basis images



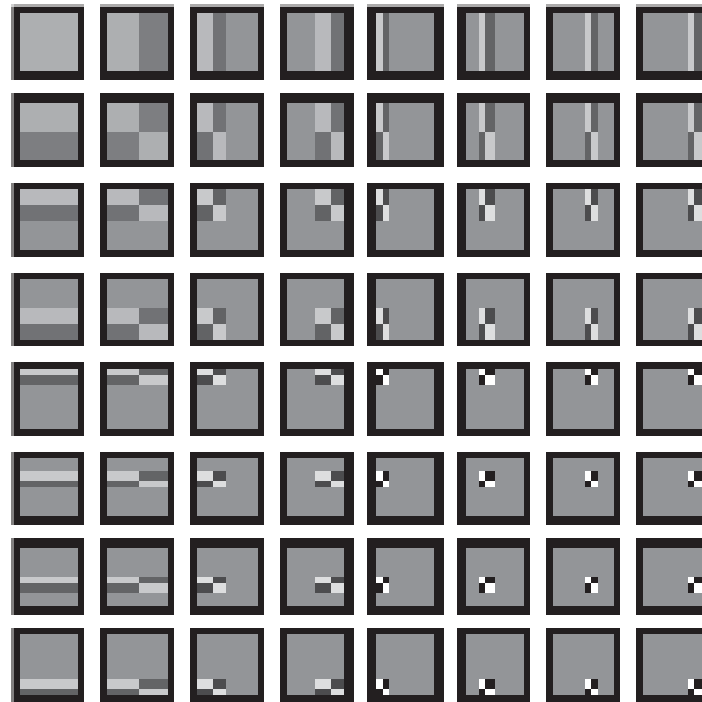
Basis images of matrix-based 2D transforms

Slant transform (SLT) basis images



Basis images of matrix-based 2D transforms

Haar transform (HAAR) basis images



Wavelet transforms

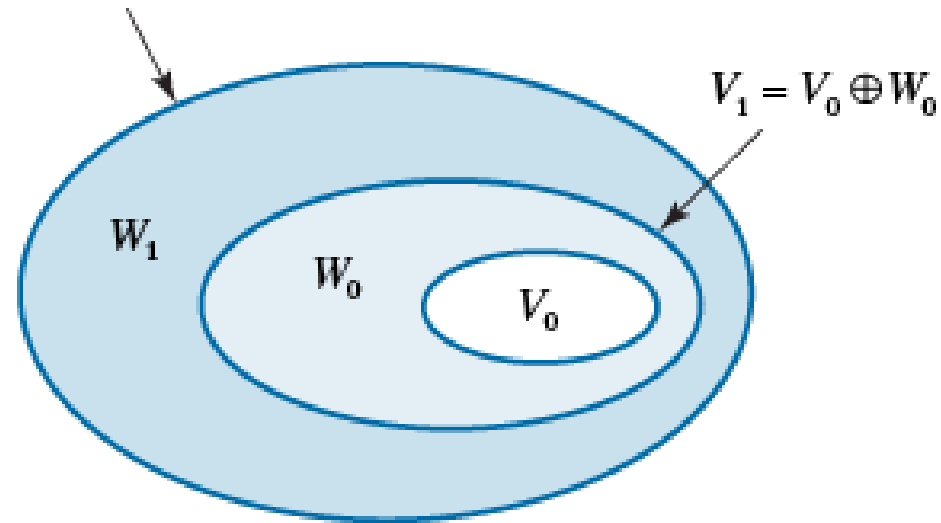
- A scaling function is used to create a series of approximations of a function or image, each differing by a factor of 2 in resolution from its nearest neighboring approximations.
- Wavelet functions (wavelets) are then used to encode the differences between adjacent approximations.
- The discrete wavelet transform (DWT) uses those wavelets, together with a single scaling function, to represent a function or image as a linear combination of the wavelets and scaling function.

Scaling function, multiresolution analysis

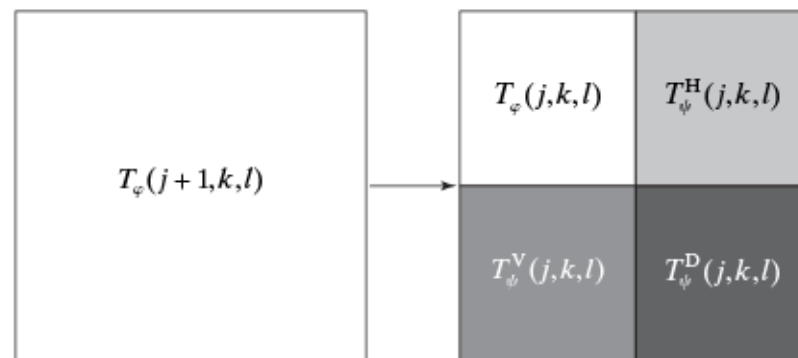
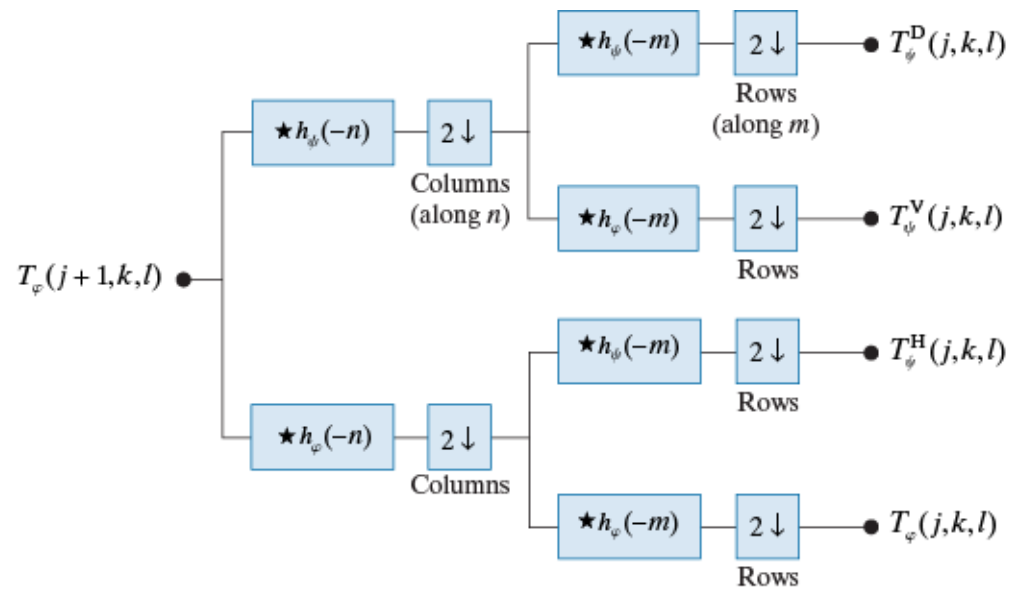
1. The scaling function is orthogonal to its integer translates.
2. The function spaces spanned by the scaling function at low scales are nested within those spanned at higher scales.
$$V_{-\infty} \subset \dots \subset V_{-1} \subset V_0 \subset V_1 \subset \dots \subset V_{\infty}$$
3. The only function representable at every scale (all V_j) is $f(x) = 0$.
4. All measurable, square-integrable functions can be represented as $j \rightarrow \infty$

Relationship between scaling and wavelet function spaces

$$V_2 = V_1 \oplus W_1 = V_0 \oplus W_0 \oplus W_1$$



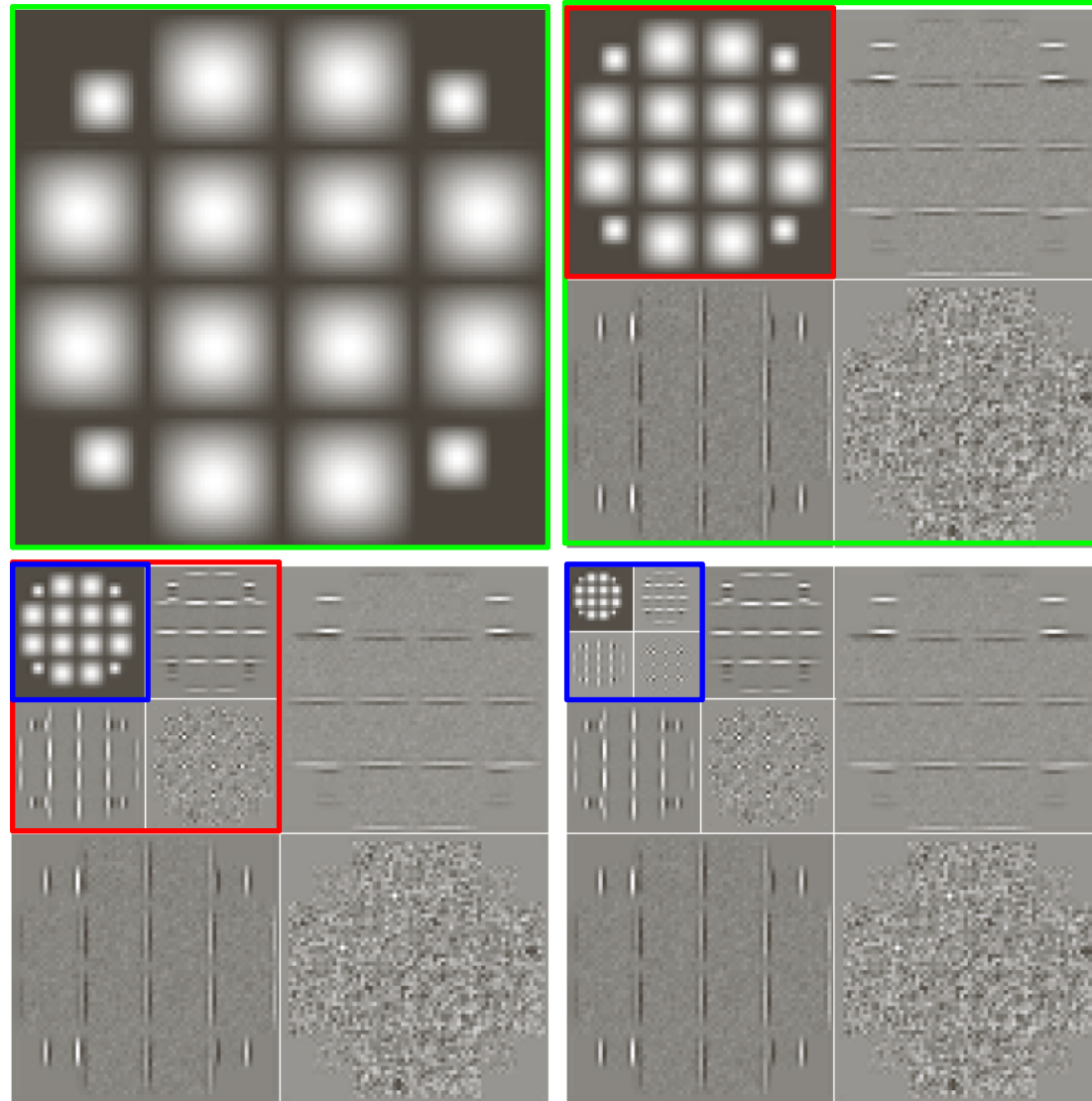
2D discrete wavelet transform



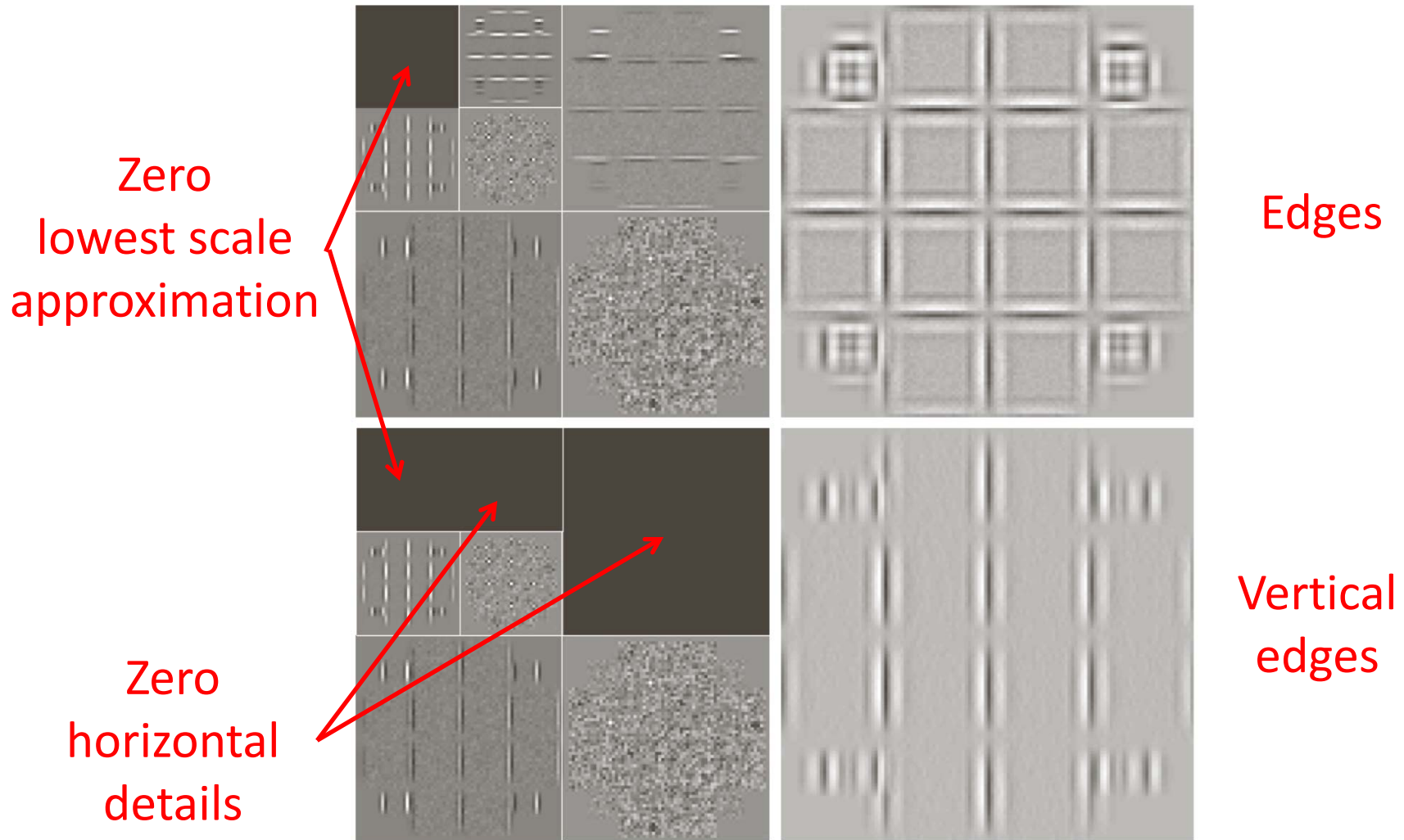
Decomposition

2D discrete wavelet transform

3-level
wavelet
decomposition



Wavelet-based edge detection

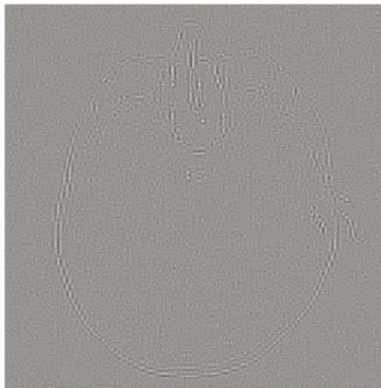


Wavelet-based noise removal

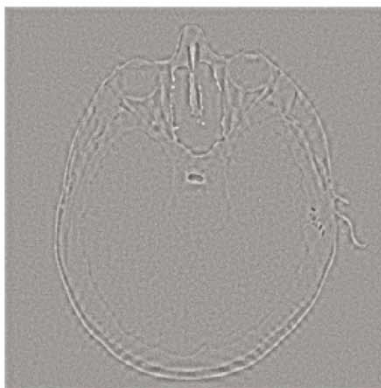
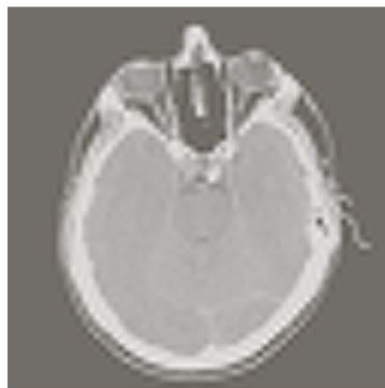
Noisy image



Zero
highest
resolution
details



Zero details
for all levels



Threshold
details

a	b
c	d
e	f

FIGURE 7.28

Modifying a DWT for noise removal: (a) a noisy CT of a human head; (b), (c) and (e) various reconstructions after thresholding the detail coefficients; (d) and (f) the information removed during the reconstruction of (c) and (e). (Original image courtesy Vanderbilt University Medical Center.)