

**CSE166 – Image Processing – Final**

Instructor: Prof. Serge Belongie

<http://www-cse.ucsd.edu/classes/fa06/cse166>

11:30am-2:30pm Tue. Dec. 5, 2006.

On this exam you are allowed to use a calculator and two 8.5" by 11" sheets of notes. The total number of points possible is 58. Good luck!

Part I: Fill in the Blank (1 pt. each, 20 pts. total).

1. The Fourier transform of a Gaussian is a(n) \_\_\_\_\_ .
2. If a function is narrow in the spatial domain, then it is \_\_\_\_\_ in the frequency domain.
3.  $\nabla I(x, y)$  is computed in Matlab using the function \_\_\_\_\_ .
4. Given a function  $f(x)$ , the  $M$ -point DFT  $F(u)$  evaluated at  $u = (M/2) + 1$  is also known as the \_\_\_\_\_ -component.
5. The binomial function is the discrete approximation to a \_\_\_\_\_ function.
6. A neighborhood of an image where half the gradient vectors equal  $(\pm 1, 0)$  and the other half equal  $(0, \pm 1)$  is an example of a rank-\_\_\_\_\_ neighborhood.
7. The values  $u$  and  $v$  satisfying the equation  $I_x u + I_y v + I_t = 0$  in a small window represent the \_\_\_\_\_ .
8. The convolution of an  $M \times M$  image with an  $N \times N$  kernel is of size \_\_\_\_\_ .
9. The image enhancement operation that makes the probability density function of pixel brightnesses approximately uniform is called \_\_\_\_\_ .
10. \_\_\_\_\_ is an example of a lossless image compression method.
11. The lower bound in lossless image compression is set by the \_\_\_\_\_ of the source.
12. When computing the \_\_\_\_\_ transform, each pixel in the  $(x, y)$  domain produces a sinusoid in the  $(\rho, \theta)$  domain.
13. We compute  $I(x, y, t) - I(x, y, t - 1)$  as an approximation of \_\_\_\_\_ .
14. The ambiguity of motion viewed in a small window is known as the \_\_\_\_\_ problem.
15. True or False: JPEG is recommended for compressing images of natural scenes. \_\_\_\_\_
16. An image with an approximately flat histogram has \_\_\_\_\_ entropy than an image with a highly peaked histogram .
17. Given an RGB image, the \_\_\_\_\_ channel representation is given by the three images  $R - G$ ,  $B - (R + G)/2$  and  $(R + G + B)/3$ .
18. The morphological operation that fattens pixels around object boundaries is called \_\_\_\_\_ .
19. In the HSI color space, the length of the vector extending from the axis of the cone represents the \_\_\_\_\_ and the angle represents the \_\_\_\_\_ .
20. If you fixate on an image of an American flag for 60 seconds and subsequently view a blank white screen, you will see the following three colors in place of red, white and blue: \_\_\_\_\_ , \_\_\_\_\_ , and \_\_\_\_\_ , respectively.

Part II: Written problems.

- (6 pts.) Write down the steps of  $k$ -means clustering, including the initialization, the basic iteration, and the stopping criterion. Illustrate your answer with a 2D pointset example with two clumps. Set  $k = 2$  and show iterations 0, 1 and 2. Assume the initialized cluster centers both fall within one of the clumps.
- (13 pts) This problem makes use of the binary image displayed in Figure 1, in which black=1 and white=0. Note: in calculating the various quantities in this problem, round your answers to 2 significant figures.

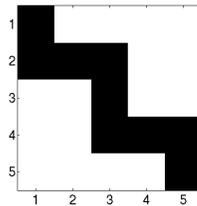


Figure 1:  $5 \times 5$  binary image.

- Compute the coordinates of the centroid  $\mathbf{m}$ .
- Compute the scatter matrix  $C$ .
- Find the eigenvalues  $\lambda_1$  and  $\lambda_2$  of  $C$  and use them to compute the aspect ratio.
- Find the angle  $\phi$  of the principal eigenvector of  $C$ . Also write down the angle of the 2nd eigenvector. Express each answer in units of degrees.
- Letting  $\mathbf{x}_k$  denote the original coordinates of the nonzero pixels, find the values of the rotation matrix  $R$  and translation vector  $\mathbf{t}$  in the expression

$$\mathbf{x}'_k = R(\mathbf{x}_k + \mathbf{t}), \quad k = 1, 2, \dots, 9$$

such that the set of transformed coordinates  $\mathbf{x}'_k$  for  $k = 1, 2, \dots, 9$  is centered at the origin and has its principal axis aligned with the  $y$  axis.

- (5 pts.) Define  $h(x)$  to be the centered first difference kernel. Now define the function

$$H(u) = \sum_{x=-\infty}^{\infty} h(x)e^{-j2\pi ux}$$

In this problem,  $x$  is discrete and  $u$  is continuous.

- What does  $H(u)$  represent?
  - Plug in the values of  $h(x)$  to solve for  $H(u)$ , and write it in its simplest form.
  - Sketch  $H(u)$ .
  - Based on the shape of  $H(u)$ , what type of filter is  $h(x)$ ?
- (4 pts.) Prove that the eigenvalues of a covariance matrix are non-negative. What is this property called?