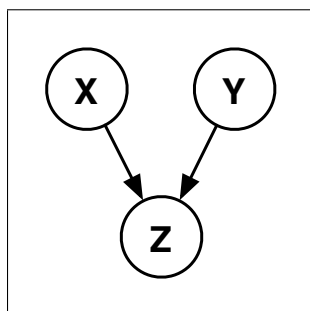


Out: Tue Aug 12

Due: Fri Aug 15

3.1 Noisy-OR



Nodes: $X \in \{0, 1\}, Y \in \{0, 1\}, Z \in \{0, 1\}$

Noisy-OR CPT: $P(Z = 1|X, Y) = 1 - (1 - p_x)^X (1 - p_y)^Y$

Parameters: $p_x \in [0, 1], p_y \in [0, 1], p_y > p_x$

Suppose that the nodes in this network represent binary random variables and that the CPT for $P(Z|X, Y)$ is parameterized by a noisy-OR model, as shown above. Suppose also that

$$0 < P(X=1) < 1,$$

$$0 < P(Y=1) < 1,$$

while the parameters of the noisy-OR model satisfy:

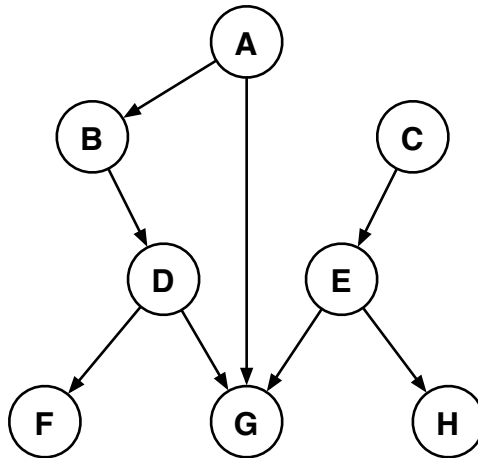
$$0 < p_x < p_y < 1.$$

Consider the following pairs of probabilities. In each case, indicate whether the probability on the left is equal (=), greater than (>), or less than (<) the probability on the right.

- | | | | |
|-----|--------------------|--------------------------|------------------------|
| (a) | $P(Z=1 X=0, Y=0)$ | <input type="checkbox"/> | $P(Z=1 X=0, Y=1)$ |
| (b) | $P(Z=1 X=0, Y=1)$ | <input type="checkbox"/> | $P(Z=1 X=1, Y=0)$ |
| (c) | $P(Z=1 X=1, Y=0)$ | <input type="checkbox"/> | $P(Z=1 X=1, Y=1)$ |
| (d) | $P(X=1)$ | <input type="checkbox"/> | $P(X=1 Y=1)$ |
| (e) | $P(X=1)$ | <input type="checkbox"/> | $P(X=1 Z=1)$ |
| (f) | $P(X=1 Y=1, Z=1)$ | <input type="checkbox"/> | $P(X=1 Z=1)$ |
| (g) | $P(X=1, Y=1, Z=1)$ | <input type="checkbox"/> | $P(X=1) P(Y=1) P(Z=1)$ |

3.2 Conditional independence

For the belief network shown below, indicate whether the following statements of conditional independence are **true (T)** or **false (F)**.



$$P(B|G, C) = P(B|G)$$

$$P(F, G|D) = P(F|D) P(G|D)$$

$$P(D|B, F, G) = P(D|B, F, G, A)$$

$$P(A, C) = P(A) P(C)$$

$$P(F, H) = P(F) P(H)$$

$$P(F, C|G) = P(F|G) P(C|G)$$

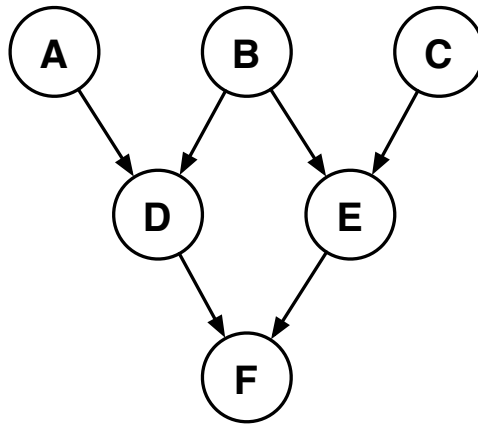
$$P(D, E|F, H) = P(D|F) P(E|H)$$

$$P(D, E, G) = P(D) P(E) P(G|D, E)$$

$$P(H|C) = P(H|A, B, C, D, F)$$

$$P(H|A, C) = P(H|A, C, G)$$

3.3 Subsets



For the belief network shown above, consider the following statements of conditional independence. Indicate the largest subset of nodes $\mathcal{S} \subset \{A, B, C, D, E, F\}$ for which each statement is true. Note that one possible answer is the empty set $\mathcal{S} = \emptyset$ or $\mathcal{S} = \{\}$ (whichever notation you prefer). The first one is done as an example.

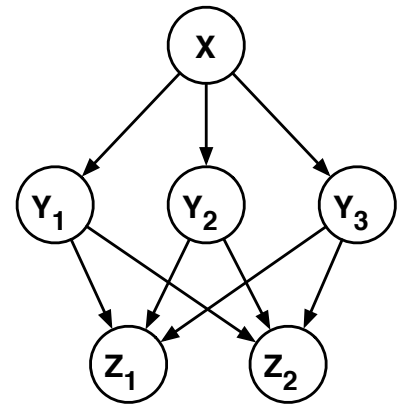
- | | |
|--------------------------------|-----------------------------|
| $P(A) = P(A \mathcal{S})$ | $\mathcal{S} = \{B, C, E\}$ |
| $P(A D) = P(A \mathcal{S})$ | _____ |
| $P(A B, D) = P(A \mathcal{S})$ | _____ |
| $P(B D, E) = P(B \mathcal{S})$ | _____ |
| $P(D) = P(D \mathcal{S})$ | _____ |
| $P(D F) = P(D \mathcal{S})$ | _____ |
| $P(D E, F) = P(D \mathcal{S})$ | _____ |
| $P(D A, B) = P(D \mathcal{S})$ | _____ |
| $P(F) = P(F \mathcal{S})$ | _____ |
| $P(F D) = P(F \mathcal{S})$ | _____ |
| $P(F D, E) = P(F \mathcal{S})$ | _____ |

3.4 Node clustering

Consider the belief network shown below over binary variables $X, Y_1, Y_2, Y_3, Z_1,$ and Z_2 . The network can be transformed into a polytree by clustering the nodes $Y_1, Y_2,$ and Y_3 into a single node Y . From the CPTs in the original belief network, fill in the missing elements of the CPTs for the polytree.

X	$P(Y_1 = 1 X)$	$P(Y_2 = 1 X)$	$P(Y_3 = 1 X)$
0	0.9	0.8	0.3
1	0.5	0.6	0.7

Y_1	Y_2	Y_3	$P(Z_1 = 1 Y_1, Y_2, Y_3)$	$P(Z_2 = 1 Y_1, Y_2, Y_3)$
0	0	0	0.1	0.8
1	0	0	0.2	0.7
0	1	0	0.3	0.6
0	0	1	0.4	0.5
1	1	0	0.5	0.4
1	0	1	0.6	0.3
0	1	1	0.7	0.2
1	1	1	0.8	0.1



Y_1	Y_2	Y_3	Y	$P(Y X=0)$	$P(Y X=1)$	$P(Z_1=1 Y)$	$P(Z_2=1 Y)$
0	0	0	1				
1	0	0	2				
0	1	0	3				
0	0	1	4				
1	1	0	5				
1	0	1	6				
0	1	1	7				
1	1	1	8				

