

Lecture 1: Upper bound on learning unstructured distribution

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Abstract

This lecture introduces the basic set up of distribution learning and proves an upper bound on the number of samples required for learning an unstructured distribution.

1 Setup

Say there is an unknown probability distribution p (perhaps known to satisfy extra properties). We take independent samples from p and would like to determine some information about p .

The main parameters of this algorithm that we need to keep track of are:

- **How many samples ?** We want almost information theoretically optimal (within constant factors)
- **How efficient is the algorithm ?** Ideally we want near linear in the number of samples, but we also accept polynomial time algorithms.
- **What is the probability of failure ?** We usually require only a $\frac{2}{3}$ probability of success, but this doesn't matter very much. We can usually amplify the probability of success to $1 - \delta$ with $O(\log(1/\delta))$ independent repetitions of the same algorithm.

Let us begin with the following example:

2 Learning Unstructured distribution

Let p be an arbitrary distribution on $[n] = \{1, 2, \dots, n\}$.

Objective: Learn p Note that this cannot be done exactly because there are infinitely many such distributions but we are only given access to a finite number of samples. So we revise our objective as follows.

Revise: Return another distribution q such that

$$d_{TV}(p, q) = \frac{1}{2} \|p - q\|_1 = \frac{1}{2} \sum_{i=1}^n |p_i - q_i| < \epsilon$$

Intuition: A nice way to think of Total Variation distance is the by the following coupling inequality

Lemma 2.1. *Let μ, ν be two probability measures. For any rvs X, Y whose marginals are μ, ν we have*

$$\|\mu - \nu\|_{TV} \leq \Pr[X \neq Y]$$

In fact X, Y can be constructed so that this is an equality.

3 Algorithm:

The algorithm is very simple. Take N independent samples and we take the empirical distribution.

$$q_i = \frac{\text{No of samples in the } i\text{th bin}}{N}$$

4 Analysis:

Let X_i denote the number of samples from bin i . Then $q_i = \frac{X_i}{N}$.

The total variation distance is $d_{TV}(p, q) = \frac{1}{2} \sum_{i=1}^n |p_i - \frac{X_i}{N}|$.

Note that $X_i \sim \text{Bin}(p_i, N)$ is a Bernoulli random variable. Thus,

$$\mathbb{E}[X_i] = p_i N, \quad \text{Var}(X_i) = N p_i (1 - p_i) < p_i N.$$

Thus, $\mathbb{E}[p_i - \frac{X_i}{N}] = 0$ and

$$\mathbb{E} \left| p_i - \frac{X_i}{N} \right|^2 = \text{Var} \left(p_i - \frac{X_i}{N} \right) \leq \frac{p_i}{N}.$$

Now using linearity of expectation we have,

$$\mathbb{E} \left[\sum_i \left| p_i - \frac{X_i}{N} \right|^2 \right] \leq \frac{\sum_i p_i}{N} = \frac{1}{N}$$

This bounds $\mathbb{E}[\|p - q\|_2]$ but since we use Cauchy Schwarz + Jensen to get a bound on $\mathbb{E}[d_{TV}(p, q)]$.

$$\sum_i \mathbb{E} \left[\left| p_i - \frac{X_i}{N} \right| \right] \cdot 1 \leq \sqrt{\sum_i \left(\mathbb{E} \left[\left| p_i - \frac{X_i}{N} \right|^2 \right] \right)} \cdot \sum_{i=1}^n 1 \leq \sqrt{\sum_i \mathbb{E} \left[\left| p_i - \frac{X_i}{N} \right|^2 \right]} \cdot \sum_{i=1}^n 1 \leq \sqrt{\frac{n}{N}}.$$

Thus, we have $\mathbb{E}[d_T V(p, q)] \leq \sqrt{\frac{n}{N}}$. Say if we choose N so that $\sqrt{\frac{n}{N}} \leq \epsilon/3$ then using Markov inequality we have $d_T V(p, q) < \epsilon$ with probability at least $2/3$. Thus,

$$N = O\left(\frac{n}{\epsilon^2}\right)$$

is sufficient.

This proves the upper bound on the number of samples.

5 Lower bound

We need to prove that any algorithm that with prob $2/3$ returns an ϵ -approximation of p uses $\gg \frac{n}{\epsilon^2}$ samples. We use information theory to prove this.

We use the adversary method. Let the adversary have a distribution \mathcal{D} over all possible p . The algorithm gets N samples from a random $p \in \mathcal{D}$. We choose \mathcal{D} wisely so that there is not enough information for the Algorithm to give the correct answer consistently. We prove this in the next Lecture.