

Non-negative matrix factorization (NMF)

How to approximate $X \approx VY$ for $X, V, Y \geq 0$?

- Types of approximation error:

$$E_{LS} = \|X - VY\|^2 = \sum_{in} (X_{in} - (VY)_{in})^2$$

$$E_{KL} = \sum_{in} \left[X_{in} \log \frac{X_{in}}{(VY)_{in}} - X_{in} + (VY)_{in} \right]$$

Minimization of E_{LS}

- Decomposition

$$E_{LS}^+ = \|X\|^2 + \|VY\|^2$$

$$E_{LS}^- = 2 \text{ trace}[XVY]$$

$$E_{LS} = E_{LS}^+ - E_{LS}^-$$

- Multiplicative update

$$V_{ix} \leftarrow V_{ix} \left[\frac{\left(\frac{\partial E_{LS}^-}{\partial V_{ix}} \right)}{\left(\frac{\partial E_{LS}^+}{\partial V_{ix}} \right)} \right]$$

- Properties of V-update

(1) preserves non-negativity because $V_{ix}, \frac{\partial E_{LS}^-}{\partial V_{ix}} \geq 0$

(2) increases V_{ix} when $\frac{\partial E_{LS}}{\partial V_{ix}} \leq 0$ } because

(3) decreases V_{ix} when $\frac{\partial E_{LS}}{\partial V_{ix}} \geq 0$ } $\frac{\partial E_{LS}}{\partial V_{ix}} = \frac{\partial E_{LS}^+}{\partial V_{ix}} - \frac{\partial E_{LS}^-}{\partial V_{ix}}$

(4) fixed points at $V_{ix} = 0$ or $\frac{\partial E_{LS}}{\partial V_{ix}} = 0$

(5) no learning rate

(6) monotonically decreases E_{LS} (prove later)

- Multiplicative update of Y

$$Y_{an} \leftarrow Y_{an} \left[\frac{\left(\frac{\partial E_{LS}^-}{\partial Y_{an}} \right)}{\left(\frac{\partial E_{LS}^+}{\partial Y_{an}} \right)} \right]$$

Analogous properties hold by symmetry.

Minimization of E_{KL}

- Decomposition

$$E_{KL}^+ = \sum_{in} [X_{in} \log X_{in} + (VY)_{in}]$$

$$E_{KL}^- = \sum_{in} [X_{in} \log (VY)_{in} + X_{in}]$$

$$E_{KL} = E_{KL}^+ - E_{KL}^-$$

- Non-negative gradients

$$\frac{\partial E_{KL}^+}{\partial V_{i\alpha}} = \sum_n Y_{\alpha n} \geq 0$$

$$\frac{\partial E_{KL}^-}{\partial V_{i\alpha}} = \sum_n X_{in} \frac{Y_{\alpha n}}{(VY)_{in}} \geq 0$$

similar for $\frac{\partial E_{KL}^\pm}{\partial Y_{\alpha n}} \dots$

- Multiplicative update

$$V_{i\alpha} \leftarrow V_{i\alpha} \left[\frac{\left(\frac{\partial E_{KL}^-}{\partial V_{i\alpha}}\right)}{\left(\frac{\partial E_{KL}^+}{\partial V_{i\alpha}}\right)} \right]$$

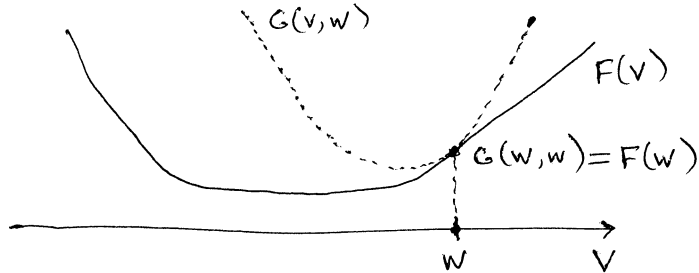
As before, updates converge monotonically to local minimum of E_{KL}

Proofs of convergence

• Def: $G(v, w)$ is an auxiliary function for $F(v)$ if:

(i) $G(v, v) = F(v)$ for all v

(ii) $G(v, w) \geq F(v)$ for all v, w

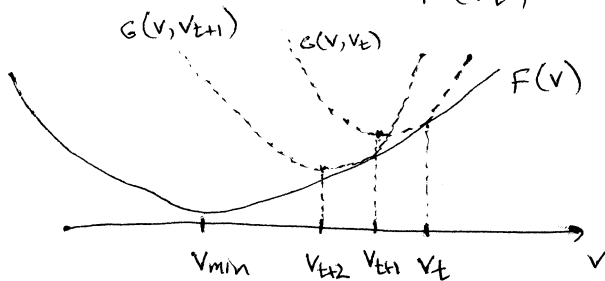


• Thm = if $G(v, w)$ is an auxiliary function for $F(v)$, then $F(v)$ is non-increasing under the update

$$v_{t+1} = \underset{v}{\operatorname{argmin}} G(v, v_t)$$

Proof:

$$\begin{aligned} F(v_{t+1}) &\leq G(v_{t+1}, v_t) && \text{by property (ii)} \\ &\leq G(v_t, v_t) && \text{b/c } v_{t+1} = \underset{v}{\operatorname{argmin}} G(v, v_t) \\ &= F(v_t) && \text{by property (i)} \end{aligned}$$

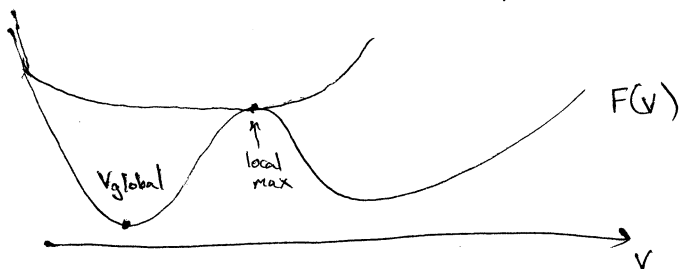


By iteration:

$$F(v_0) \geq F(v_1) \geq \dots \geq F(v_t) \geq F(v_{t+1}) \geq \dots \geq F(v_{\text{final}})$$

In practice, for smooth $F(v)$ and $G(v, w)$, updates converge to local (not necessarily global) minimum.

In theory, convergence is possible to any stationary point.



converging to local maximum...

← this is rare

• Auxiliary function for EKL

$$\text{Let } F(v) = \sum_{in} \left[x_{in} \log \frac{x_{in}}{(vY)_{in}} - x_{in} + (vY)_{in} \right]$$

$$\text{Let } G(v, w) = \sum_{in} \left[x_{in} \log \frac{x_{in}}{(wY)_{in}} - x_{in} + (vY)_{in} - x_{in} \underbrace{\sum_{\alpha} \frac{w_{\alpha} Y_{\alpha}}{(wY)_{in}} \log \left(\frac{v_{\alpha}}{w_{\alpha}} \right)}_{\text{last term on RHS vanishes if } v=w} \right]$$

Trivially: (i) $G(v, v) = F(v)$

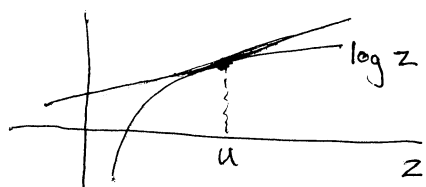
How to prove $G(v, w) \geq F(v)$?

• Lemma: Jensen's inequality

Let z be a nonnegative random variable.

Then: $E[\log z] \leq \log E[z]$

• Proof of lemma:



\log is a concave function

$$\log z \leq \log u + \frac{1}{u}(z-u) \quad \text{FOR ALL } z, u \geq 0$$

$$E[\log z] \leq E\left[\log u + \frac{1}{u}(z-u)\right] \quad \text{for all constant } u$$

$$= \log u + \frac{1}{u}(E[z] - u) \quad \text{by linearity of } E[\]$$

$$= \log E[z] \quad \text{by setting } u = E[z]$$

Equivalently: if $p_{\alpha} \geq 0$ and $\sum_{\alpha} p_{\alpha} = 1$,

$$\text{then } \sum_{\alpha} p_{\alpha} \log z_{\alpha} \leq \log \sum_{\alpha} p_{\alpha} z_{\alpha}$$

- Proof of auxiliary function bound

$$G(v, w) = \sum_{in} \left[x_{in} \log \frac{x_{in}}{(wY)_{in}} - x_{in} + (vY)_{in} - x_{in} \sum_{\alpha} \frac{w_{\alpha} Y_{\alpha in}}{(wY)_{in}} \log \left(\frac{v_{\alpha}}{w_{\alpha}} \right) \right]$$

Apply Jensen's inequality with $p_{\alpha} = \frac{w_{\alpha} Y_{\alpha in}}{(wY)_{in}}$ and $z_{\alpha} = \frac{v_{\alpha}}{w_{\alpha}}$

$$\begin{aligned} G(v, w) &\geq \sum_{in} \left[x_{in} \log \frac{x_{in}}{(wY)_{in}} - x_{in} + (vY)_{in} - x_{in} \log \sum_{\alpha} \frac{w_{\alpha} Y_{\alpha in} v_{\alpha}}{(wY)_{in} w_{\alpha}} \right] \\ &= \sum_{in} \left[x_{in} \log \frac{x_{in}}{(wY)_{in}} - x_{in} \log \frac{(vY)_{in}}{(wY)_{in}} - x_{in} + (vY)_{in} \right] \\ &= \sum_{in} \left[x_{in} \log \frac{x_{in}}{(wY)_{in}} - x_{in} + (vY)_{in} \right] \\ &= F(v) \end{aligned}$$

- Update from $G(v, w)$

How to minimize $G(v, w)$ for fixed w ?

$$\frac{\partial G}{\partial v_{\alpha}} = \sum_n Y_{\alpha n} - \sum_n x_{in} \frac{w_{\alpha} Y_{\alpha in}}{(wY)_{in}} \cdot \frac{1}{v_{\alpha}}$$

$$\frac{\partial G}{\partial v_{\alpha}} = 0 \longrightarrow v_{\alpha} = w_{\alpha} \left[\frac{\sum_n x_{in} Y_{\alpha in} / (wY)_{in}}{\sum_n Y_{\alpha n}} \right]$$

Update rule:

$$v_{t+1} = \operatorname{argmin}_v G(v, v_t)$$

$$v_{\alpha} \leftarrow v_{\alpha} \left[\frac{\sum_n \frac{x_{in} Y_{\alpha in}}{(wY)_{in}}}{\sum_n Y_{\alpha n}} \right]$$

To think about

- Given $G(v, w)$ and $F(v)$, it is easy to verify that (i) $G(v, v) = F(v)$ and (ii) $G(v, w) \geq F(v)$
- Given a cost function $F(v)$, how to derive an auxiliary function $G(v, w)$?
- In addition to properties (i)-(ii), the update $v_{t+1} = \operatorname{argmin}_v G(v, v_t)$ is easy to compute (in closed form).