Lecture 8: Scheduling & Deadlock

CSE 120: Principles of Operating Systems
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Lab 1 Due Thur 5/1
Scheduling

- The **scheduler** (aka dispatcher) is the module that manipulates the queues, moving jobs to and fro.
- The **scheduling algorithm** determines which jobs are chosen to run next and what queues they wait on.
- In general, the scheduler runs:
  - When a job switches states (running, waiting, etc.)
  - When an interrupt occurs
  - When a job is created or terminated
- We’ll discuss scheduling algorithms in two contexts:
  - A **preemptive** scheduler can interrupt a running job.
  - A **non-preemptive** scheduler waits for running job to block.
Priority Scheduling

- Priority Scheduling
  - Choose next job based on priority
    - Airline checkin for first class passengers
  - Can implement SJF, priority = 1/(expected CPU burst)
  - Also can be either preemptive or non-preemptive
  - This is what you’re implementing in Nachos in Project 1

- Problem
  - Starvation – low priority jobs can wait indefinitely

- Solution
  - “Age” processes
    - Increase priority as a function of waiting time
    - Decrease priority as a function of CPU consumption
Combining Algorithms

- Scheduling algorithms can be combined
  - Have multiple queues
  - Use a different algorithm for each queue
  - Move processes among queues
- Example: Multiple-level feedback queues (MLFQ)
  - Multiple queues representing different job types
    - Interactive, CPU-bound, batch, system, etc.
  - Queues have priorities, jobs on same queue scheduled RR
  - Jobs can move among queues based upon execution history
    - Feedback: Switch from interactive to CPU-bound behavior
The canonical Unix scheduler uses a MLFQ
- 3-4 classes spanning ~170 priority levels
  - Timesharing: first 60 priorities
  - System: next 40 priorities
  - Real-time: next 60 priorities
  - Interrupt: next 10 (Solaris)

Priority scheduling across queues, RR within a queue
- The process with the highest priority always runs
- Processes with the same priority are scheduled RR

Processes dynamically change priority
- Increases over time if process blocks before end of quantum
- Decreases over time if process uses entire quantum
The idea behind the Unix scheduler is to reward interactive processes over CPU hogs.

Interactive processes (shell, editor, etc.) typically run using short CPU bursts.
- They do not finish quantum before waiting for more input.

Want to minimize response time:
- Time from keystroke (putting process on ready queue) to executing keystroke handler (process running).
- Don’t want editor to wait until CPU hog finishes quantum.

This policy delays execution of CPU-bound jobs.
- But that’s ok.
Scheduling Summary

- Scheduler (dispatcher) is the module that gets invoked when a context switch needs to happen
- Scheduling algorithm determines which process runs, where processes are placed on queues
- Many potential goals of scheduling algorithms
  - Utilization, throughput, wait time, response time, etc.
- Various algorithms to meet these goals
  - FCFS/FIFO, SJF, Priority, RR
- Can combine algorithms
  - Multiple-level feedback queues
  - Unix example
Deadlock

- Processes that acquire multiple resources are dependent on those resources
  - E.g., locks, semaphores, monitors, etc.
- What if one process tries to allocate a resource that a second process holds, and vice-versa?
  - Neither can ever make progress!
- We call this situation **deadlock**, and we’ll look at:
  - Definition and conditions necessary for deadlock
  - Representation of deadlock conditions
  - Approaches to dealing with deadlock
Deadlock Definition

- Deadlock is a problem that can arise:
  - When processes compete for access to limited resources
  - When processes are incorrectly synchronized

- Definition:
  - Deadlock exists among a set of processes if every process is waiting for an event that can be caused only by another process in the set.

```cpp
lockA->Acquire();
...
lockB->Acquire();

lockB->Acquire();
...
lockA->Acquire();
```
Deadlock can exist if and only if four conditions hold:

1. **Mutual exclusion** – At least one resource must be held in a non-sharable mode. *(i.e., only one instance)*

2. **Hold and wait** – There must be one process holding one resource and waiting for another resource

3. **No preemption** – Resources cannot be preempted *(i.e., critical sections cannot be aborted externally)*

4. **Circular wait** – There must exist a set of processes \( \{P_1, P_2, P_3, \ldots, P_n\} \) such that \( P_1 \) is waiting for a resource held by \( P_2 \), \( P_2 \) is waiting for \( P_3 \), \( \ldots \), and \( P_n \) for \( P_1 \)
Resource Allocation Graph

- Deadlock can be described using a resource allocation graph (RAG)
- The RAG consists of sets of vertices $P = \{P_1, P_2, \ldots, P_n\}$ of processes and $R = \{R_1, R_2, \ldots, R_m\}$ resources
  - A directed edge from a process to a resource, $P_i \rightarrow R_j$, implies that $P_i$ has requested $R_j$
  - A directed edge from a resource to a process, $R_i \rightarrow P_j$, implies that $R_j$ has been acquired by $P_i$
  - Each resource has a fixed number of units
- If the graph has no cycles, deadlock cannot exist
- If the graph has a cycle, deadlock may exist
RAG Example

A cycle...and deadlock!

Same cycle...but no deadlock. Why?
Dealing With Deadlock

There are four ways to deal with deadlock:

- **Ignore it**
  - How lucky do you feel?

- **Prevention**
  - Make it impossible for deadlock to happen

- **Avoidance**
  - Control allocation of resources

- **Detection and recovery**
  - Look for a cycle in dependencies
Deadlock Prevention

Prevent at least one condition from happening:

- Mutual exclusion
  - Make resources sharable (not generally practical)

- Hold and wait
  - Process cannot hold one resource when requesting another
  - Process requests, releases all needed resources at once

- Preemption
  - OS can preempt resource (costly)

- Circular wait
  - Impose an ordering (numbering) on the resources and request them in order (popular implementation technique)
Deadlock Avoidance

- **Avoidance**
  - Provide information in advance about what resources will be needed by processes to guarantee that deadlock will not happen
  - System only grants resource requests if it knows that the process can obtain all resources it needs in future requests
  - Avoids circularities (wait dependencies)

- **Tough**
  - Hard to determine all resources needed in advance
  - Good theoretical problem, not as practical to use
The Banker’s Algorithm is the classic approach to deadlock avoidance for resources with multiple units.

1. Assign a credit limit to each customer (process)
   - Maximum credit claim must be stated in advance

2. Reject any request that leads to a dangerous state
   - A dangerous state is one where a sudden request by any customer for the full credit limit could lead to deadlock
   - A recursive reduction procedure recognizes dangerous states

3. In practice, the system must keep resource usage well below capacity to maintain a resource surplus
   - Rarely used in practice due to low resource utilization
Detection and Recovery

- Detection and recovery
  - If we don’t have deadlock prevention or avoidance, then deadlock may occur
  - In this case, we need to detect deadlock and recover from it
- To do this, we need two algorithms
  - One to determine whether a deadlock has occurred
  - Another to recover from the deadlock
- Possible, but expensive (time consuming)
  - Implemented in VMS
  - Run detection algorithm when resource request times out
Deadlock Detection

- **Detection**
  - Traverse the resource graph looking for cycles
  - If a cycle is found, preempt resource (force a process to release)

- **Expensive**
  - Many processes and resources to traverse

- Only invoke detection algorithm depending on
  - How often or likely deadlock is
  - How many processes are likely to be affected when it occurs
Once a deadlock is detected, we have two options…

1. Abort processes
   - Abort all deadlocked processes
     » Processes need start over again
   - Abort one process at a time until cycle is eliminated
     » System needs to rerun detection after each abort

2. Preempt resources (force their release)
   - Need to select process and resource to preempt
   - Need to rollback process to previous state
   - Need to prevent starvation
Deadlock occurs when processes are waiting on each other and cannot make progress
- Cycles in Resource Allocation Graph (RAG)

Deadlock requires four conditions
- Mutual exclusion, hold and wait, no resource preemption, circular wait

Four approaches to dealing with deadlock:
- Ignore it – Living life on the edge
- Prevention – Make one of the four conditions impossible
- Avoidance – Banker’s Algorithm (control allocation)
- Detection and Recovery – Look for a cycle, preempt or abort
Next time…

- Work on Project 1
- We’ll review material for the midterm on Thursday